## Xuanlin (Simon) Li

Website: xuanlinli17.github.io Github: github.com/xuanlinli17

**EDUCATION** 

**University of California - San Diego**PhD in Computer Science and Engineering, 2021 - now

Advisor: Prof. Hao Su

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Twitter: @XuanlinLi2

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University of California - Berkeley B.A. Computer Science (honors) & Mathematics (honors), 2017-2021

Technical GPA: 4.0

EXPERIENCE

UC San Diego Center for Visual Computing & Contextual Robotics Institute

La Jolla, CA

PhD Student & Researcher

Sep 2021 - Now

Primary interests: Embodied AI, Vision-Language, Robotics. In particular, I'm interested in building (2D/3D) vision-language
models and policies with generic perception and reasoning capabilities. When combined with large-scale robotic learning systems,
this empowers robots to acquire generalizable skills and excel in diverse task scenarios.

**Qualcomm AI Research** 

San Diego, CA

Research Intern Mar 2023 - Sep 2023

• Worked on situated real-time interactions with large language models via multimodal (vision-audio) stream conditioning.

**Berkeley Artificial Intelligence Research** 

Berkeley, CA

Undergraduate Researcher

Mar 2019 - May 2021

• Advised by Prof. Trevor Darrell. Worked on non-monotonic sequence generation on vision & language tasks, reinforcement learning, and neural network architecture learning.

PUBLICATIONS (\* = EQUAL CONTRIBUTION)

As of Sep. 2023

· OpenShape: Scaling Up 3D Shape Representation Towards Open-World Understanding

M. Liu\*, R. Shi\*, K. Kuang\*, Y. Zhu, X. Li, S. Han, H. Cai, F. Porikli, H. Su

NeurIPS 2023

Category: Vision-Language

• Deductive Verification of Chain-of-Thought Reasoning

Z. Ling\*, Y. Fang\*, X. Li, Z. Huang, M. Lee, R. Memisevic, H. Su

NeurIPS 2023

Category: Language

• Situated Real-time Interaction with a Virtually Embodied Avatar

S. Panchal, G. Berger, A. Mercier, C. Bohm, F. Dietrichkeit, X. Li, R. Pourreza,

P. Madan, A. Bhattacharyya, M. Lee, M. Todorovich, I. Bax, R. Memisevic

CVPR 2023 Embodied AI Workshop (Preprint)

Category: Vision-Language, Embodied AI

 $\bullet \ \ Distilling \ Large \ Vision-Language \ Model \ with \ Out-of-Distribution \ Generalizability$ 

X. Li\*, Y. Fang\*, M. Liu, Z. Ling, Z. Tu,, H. Su

ICCV 2023

Category: Vision-Language, Embodied AI

• Reparameterized Policy Learning for Multimodal Trajectory Optimization

Z. Huang, L. Liang, Z. Ling, X. Li, C. Gan, H. Su

ICML 2023 (Oral)

Category: Robotics, Embodied AI

· On the Efficacy of 3D Point Cloud Reinforcement Learning

Z. Ling\*, Y. Yao\*, X. Li, H. Su

Preprint

Category: Vision, Embodied AI, Robotics

Frame Mining - A Free Lunch for Learning Robotic Manipulation from 3D Point Clouds

M. Liu\*, **X. Li**\*, Z. Ling\*, Y. Li, H. Su

CoRL 2022

Category: Vision, Embodied AI, Robotics

• ManiSkill2: A Unified Benchmark for Generalizable Manipulation Skills

J Gu<sup>+</sup>, F. Xiang<sup>+</sup>, **X. Li**\*, Z. Ling\*, X. Liu\*, T. Mu\*, Y. Tang\*, S. Tao\*, X. Wei\*, Y. Yao\*, X. Yuan, P. Xie, Z. Huang, R. Chen, H. Su

ICLR 2023

Category: Vision, Embodied AI, Robotics

• ManiSkill: Generalizable Manipulation Skill Benchmark with Large-Scale Demonstrations

T. Mu\*, Z. Ling\*, F. Xiang\*, D. Yang\*, X. Li\*, S. Tao, Z. Huang, Z. Jia, H. Su

NeurIPS 2021

(Dataset & Benchmarks Track)

Category: Vision, Embodied AI, Robotics

• Improving Policy Optimization with Generalist-Specialist Learning

Z. Jia, X. Li, Z. Ling, S. Liu, Y. Wu, H. Su

ICML 2022 Category: Robotics, Embodied AI

• Discovering Non-Monotonic Autoregressive Orderings with Variational Inference

X. Li\*, B. Trabucco\*, D.H. Park, Y. Gao, M. Luo, S. Shen, T. Darrell

ICLR 2021

Category: Vision-Language

• Regularization Matters in Policy Optimization - An Empirical Study on Continuous Control

Z. Liu\*, X. Li\*, B. Kang, T. Darrell

ICLR 2021 (Spotlight) Category: Robotics

## HONORS AND AWARDS

- Jacobs School of Engineering PhD Fellowship, UC San Diego, 2021
- Arthur M. Hopkin Award, UC Berkeley EECS, 2021

## TECHNICAL SKILLS

- Languages: Python, Java, C/C++, Bash, LaTeX, Golang, HTML/CSS
- Libraries / Softwares: PyTorch, Tensorflow, Numpy/Scipy/Pandas/Matplotlib/Scikit-learn, Jax, Open3D/Trimesh, Blender
- Developer Tools: Git, Docker, Kubernetes, Vim, VSCode
- Selected CourseWork:
  - Graduate: Computer Vision, ML for 3D Geometry, Deep Unsupervised Learning, ML for Robotics, Deep Reinforcement Learning,
     Advanced Robotics, Natural Language Processing, Theoretical Statistics, Topology and Real Analysis, Functional Analysis
  - Undergraduate: Machine Learning, Operating Systems, Probability Theory and Random Processes, Optimization, Algorithms, Data Structures, Machine Structures, Real Analysis, Linear Algebra, Abstract Algebra, Complex Analysis, Numerical Analysis, Differential Geometry, PDE

## **SERVICE**

- Reviewer:
  - o Computer Vision: CVPR'22'23, ECCV'22, ICCV'23
  - o Machine Learning: NeurIPS'22'23, ICML'22'23, ICLR'22'24
- Teaching Assistant: Fall 2022 UCSD CSE 291 ML for 3D Geometry