

Proving tree algorithms for succinct data structures

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The paper

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Succinct Data Structures

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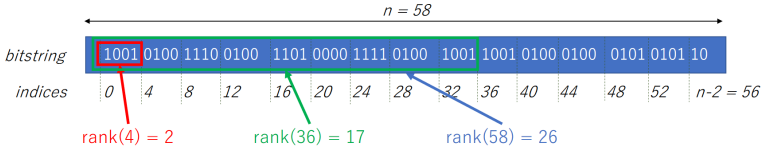
The paper

- Representation optimized for both time and space
- *“Compression without need to decompress”*
- Much used for Big Data
- Application examples
 - Compression for Data Mining
 - Mozc, the engine behind Google’s Japanese IME

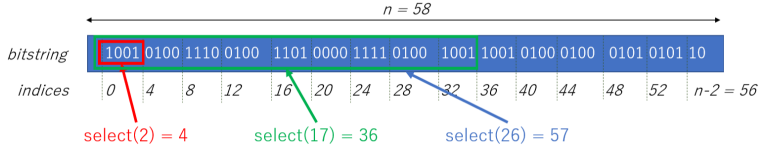
Rank and Select

To allow fast access, two primitive functions are heavily optimized. They can be computed in constant time.

- $\text{rank}(i)$ = number of 1's up to position i



- $\text{select}(i)$ = position of the i^{th} 1: $\text{rank}(\text{select}(i)) = i$



Proved implementation in [Tanaka A., Affeldt, Garrigue 2016]

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Trees in Succinct Data Structures

Featuring two views

As data Efficient encoding of trees using rank and select

As tool Implementation of dynamic succinct data structures
using red-black trees

- Both are proved in COQ/SSREFLECT
- They can be combined together

Basic Coq definitions

`rank` is easily defined. `select` is its (minimal) inverse.

Variables (T : eqType) (b : T) (n : nat).

Definition rank i s := count_mem b (take i s).

Definition Rank (i : nat) (B : n.-tuple T) :=
#|[set k : [1,n] | (k <= i) && (tacc B k == b)]|.

Lemma select_spec (i : nat) (B : n.-tuple T) :
exists k, ((k <= n) && (Rank b k B == i)) ||
(k == n.+1) && (count_mem b B < i).

Definition Select i (B : n.-tuple T) :=
ex_minn (select_spec i B).

`pred s y` = last `b` up to `y`. `succ s y` = first `b` from `y` on.

Definition pred s y := select (rank y s) s.

Definition succ s y := select (rank y.-1 s).+1 s.

Getting the indexing right is a nightmare.

Here **indices start from 1**, but there is no fixed convention.

Level-Order Unary Degree Sequence
[Navarro 2016, Chapter 8]

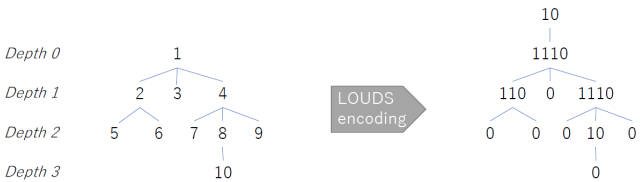
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Depth 0	Depth 1	Depth 2	Depth 3		Depth 0	Depth 1	Depth 2	Depth 3
1	234	56789	10	10	1110	11001110	000100	0

- Unary coding of node arities, put in breadth-first order
- Each node is arity 1's followed by a 0
- The structure of a tree uses just $2n + 2$ bits
- Useful for dictionaries (Google Japanese IME)

Implementation of primitives

We define an isomorphism between valid **paths** in the tree, and valid **positions** in the LOUDS.

The basic operations are

- Position of the root (2 with virtual root, **counting from 0**)
- Position of the i^{th} child of a node
- Position of its parent
- Number of children

Variable B : seq bool.

Definition LOUDS_child v i :=
 select false (rank true (v + i) B).+1 B.

Definition LOUDS_parent v :=
 pred false B (select true (rank false v B) B).

Definition LOUDS_children v :=
 succ false B v.+1 - v.+1.

First attempt

$\text{count_smaller } t \ p = \text{number of nodes appearing before the path } p \text{ in breadth first order.}$

Definition $\text{LOUDS_position } (t : \text{tree}) \ (p : \text{seq nat}) :=$
 $(\text{count_smaller } t \ p + (\text{count_smaller } t \ (\text{rcons } p \ 0)).-1).+2.$
 $(* \quad \text{number of 0's} \quad \text{number of 1's} \quad \text{virtual root} *)$

Definition $\text{LOUDS_subtree } B \ (p : \text{seq nat}) :=$
 $\text{foldl } (\text{LOUDS_child } B) \ 2 \ p.$

Theorem $\text{LOUDS_positionE } t \ (p : \text{seq nat}) :$
 $\text{let } B := \text{LOUDS } t \text{ in valid_position } t \ p \rightarrow$
 $\text{LOUDS_position } t \ p = \text{LOUDS_subtree } B \ p.$

Theorem $\text{LOUDS_parentE } t \ (p : \text{seq nat}) \ x :$
 $\text{let } B := \text{LOUDS } t \text{ in valid_position } t \ (\text{rcons } p \ x) \rightarrow$
 $\text{LOUDS_parent } B \ (\text{LOUDS_position } t \ (\text{rcons } p \ x)) = \text{LOUDS_position } t \ p.$

Theorem $\text{LOUDS_childrenE } t \ (p : \text{seq nat}) :$
 $\text{let } B := \text{LOUDS } t \text{ in valid_position } t \ p \rightarrow$
 $\text{children } t \ p = \text{LOUDS_children } B \ (\text{LOUDS_position } t \ p).$

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Various problems

- Breadth first traversal does not follow the tree structure
- Cannot use structural induction
- No **natural correspondence** to use in proofs
- Oh, the indices!

As a result

- LOUDS related proofs take more than 800 lines
- Many lemmas have proofs longer than 50 lines
- There should be a better approach...

Second try

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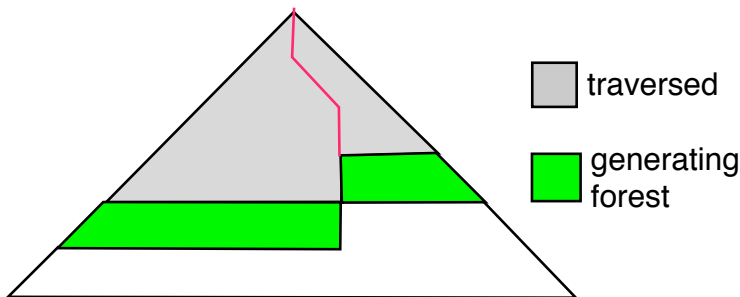
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The paper

- Introduce **traversal up to a path**
- For easy induction, work on forests rather than trees
- A generating forest need not be on the same level!



Traversal and remainder

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Variable (A B : Type) (f : tree A -> B).

(* Traversal of nodes before path p *)

Fixpoint lo_traversal_lt (w : forest A) (p : seq nat) : seq B.

(* Generating forest for nodes following path p *)

Fixpoint lo_traversal_res (w : forest A) (p : seq nat) : forest A.

(* Relation between them *)

Lemma lo_traversal_lt_cat w p1 p2 :

lo_traversal_lt w (p1 ++ p2) =

lo_traversal_lt w p1 ++ lo_traversal_lt (lo_traversal_res w p1) p2.

(* Complete traversals are all equal *)

Theorem lo_traversal_lt_max t p :

size p >= height t ->

lo_traversal_lt [:: t] p = lo_traversal_lt [:: t] (nseq (height t) 0).

All paths lead to Rome !

Indices and positions in LOUDS

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(* LOUDS_lt is a path-indexed traversal *)

Definition LOUDS_lt w p := flatten
(lo_traversal_lt (node_description \o children_of_node) w p).

(* This corresponds to the standard definition of LOUDS *)

Theorem LOUDS_lt_ok (t : tree A) p :
size p >= height t -> LOUDS t = true :: false :: LOUDS_lt [:: t] p.

(* Position of a node in the LOUDS *)

Definition LOUDS_position w p := size (LOUDS_lt w p).

(* Index of a node in level-order *)

Definition LOUDS_index w p := size (lo_traversal_lt id w p).

Lemma LOUDS_position_select w p p' :
valid_position (head dummy w) p ->
LOUDS_position w p =
select false (LOUDS_index w p) (LOUDS_lt w (p ++ p')).

Lemma LOUDS_index_rank w p p' n :
valid_position (head dummy w) (rcons p n) ->
LOUDS_index w (rcons p n) =
size w + rank true (LOUDS_position w p + n) (LOUDS_lt w (p ++ n :: p')).

Properties proved

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Theorem LOUDS_childE (t : tree A) (p p' : seq nat) x :
`let B := LOUDS_lt [:: t] (rcons p x ++ p') in`
`valid_position t (rcons p x) ->`
`LOUDS_child B (LOUDS_position [:: t] p) x =`
`LOUDS_position [:: t] (rcons p x).`

Theorem LOUDS_parentE (t : tree A) p p' x :
`let B := LOUDS_lt [:: t] (rcons p x ++ p') in`
`valid_position t (rcons p x) ->`
`LOUDS_parent B (LOUDS_position [:: t] (rcons p x)) =`
`LOUDS_position [:: t] p.`

Theorem LOUDS_childrenE (t : tree A) (p p' : seq nat) :
`let B := LOUDS_lt [:: t] (rcons p 0 ++ p') in`
`valid_position t p ->`
`children t p = LOUDS_children B (LOUDS_position [:: t] p).`

Bonus: a structural traversal

Breadth-first traversal uses induction on the height:

```
Variable f : tree A -> B.
Fixpoint lo_traversal'' n (l : forest A) :=
  if n is n'.+1 then
    map f l ++ lo_traversal'' f n' (children_of_forest l)
  else [].
Definition lo_traversal t := lo_traversal'' (height t) [:: t].
```

We can avoid that by doing the traversal in 2 steps;
1st, build a list of levels, and then catenate them.

```
Fixpoint level_traversal t :=
  let: Node a cl := t in
  [:: f t] :: foldr (fun t1 => merge1 (level_traversal t1)) nil cl.
```

```
Fixpoint level_traversal_cat (t : tree A) ss {struct t} :=
  let: (s, ss) :=
    if ss is s :: ss then (s, ss) else (nil, nil) in
  let: Node a cl := t in
  (f t :: s) :: foldr level_traversal_cat ss cl.
Definition lo_traversal_cat t := flatten (level_traversal_cat t nil).
```

level_traversal is structural, but its complexity is bad.

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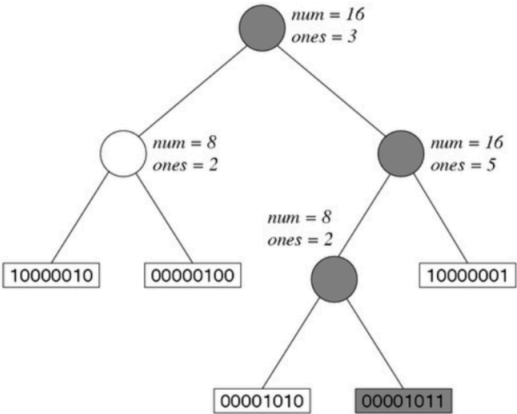
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- The most optimized representation of succinct data structures use arrays, and are not suitable for dynamic operations (insertions, etc.)
- However, we often want to modify our bit vectors.
- To minimize the cost of insertion and deletion, we must make a tradeoff: we no longer can access bits (or calculate rank or select) in constant time.
- However, representing the vector as a balanced binary tree, we can implement all operations in $O(\log n)$ time.

[Navarro 2016, Chapter 12]

Representing dynamic bit vectors



$B = 10000010 \ 00000100 \ 00001010 \ 00001011 \ 10000001$

num is the number of bits in the left branch and *ones* is the number of 1's in the left branch.

Our approach

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- Red-black tree as our underlying data structure
 - The complexity results do not depend on the specific type of balanced binary tree used
 - Red-black trees are easy to implement purely functionally
 - Already multiple formalizations in Coq
 - However, due to the different data internals, we had to reimplement them
- We attempted two different approaches, using types in different ways:
 - ① using ML types, i.e. only ML-style polymorphic ADTs
 - ② using dependent types, all trees are correct by construction
- Proving the correctness of rank, insert and select

Implementation using ML types

Using red-black trees for bit vectors

Inductive color := Red | Black.

Inductive btree (D A : Type) : Type :=
| Bnode of color & btree D A & D & btree D A
| Bleaf of A.

Definition dtree := btree (nat * nat) (seq bool).

Assigning “meaning” to trees using dflatten

Fixpoint dflatten (B : dtree) :=
 match B with
 | Bnode _ l _ r => dflatten l ++ dflatten r
 | Bleaf s => s
 end.

Invariants of the internal data

Fixpoint wf_dtree (B : dtree) :=
 match B with
 | Bnode _ l (num, ones) r =>
 [&& num == size (dflatten l), ones == count_mem true (dflatten l),
 wf_dtree l & wf_dtree r]
 | Bleaf arr => (w ^ 2) ./ 2 <= size arr < (w ^ 2) . * 2
 end.

Basic operations, using ML types

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```
Fixpoint drank (B : dtree) (i : nat) :=
  match B with
  | Bnode _ l (num, ones) r =>
    if i < num then drank l i
    else ones + drank r (i - num)
  | Bleaf s =>
    rank true i s
  end.
```

```
Lemma dtree_ind (P : dtree -> Prop) :
  (forall c l r num ones,
    num = size (dflatten l) ->
    ones = count_mem true (dflatten l) ->
    wf_dtree l /\ wf_dtree r ->
    P l -> P r -> P (Bnode c l (num, ones) r)) ->
  (forall s, (w ^ 2). / 2 <= size s < (w ^ 2). * 2 -> P (Bleaf _ s)) ->
  forall B, wf_dtree B -> P B.
```

```
Lemma drankE (B : dtree) i :
  wf_dtree B -> drank B i = rank true i (dflatten B).
```

All those lemmas were proved in just a few lines.

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```
Fixpoint dselect_1 (B : dtree) (i : nat) :=
  match B with
  | Bnode _ l (num, ones) r =>
    if i <= ones then dselect_1 l i
    else num + dselect_1 r (i - ones)
  | Bleaf s => select true i s
  end.
```

```
Fixpoint dselect_0 (B : dtree) (i : nat) :=
  match B with
  | Bnode _ l (num, ones) r =>
    let zeroes := num - ones in
    if i <= zeroes then dselect_0 l i
    else num + dselect_0 r (i - zeroes)
  | Bleaf s => select false i s
  end.
```

```
Lemma dselect_1E B i :
  wf_dtree B -> dselect_1 B i = select true i (dflatten B).
```

```
Lemma dselect_0E B i :
  wf_dtree B -> dselect_0 B i = select false i (dflatten B).
```

Insertion, using ML types

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```

Fixpoint dins (B : dtree) b i w : dtree :=
  match B with
  | Bleaf s =>
    let s' := insert1 s b i in
    if size s + 1 == 2 * (w ^ 2)
    then let n := (size s') %/ 2 in
         let sl := take n s' in
         let sr := drop n s' in
         Bnode Red (Bleaf _ sl)
              (size sl, rank true (size sl) sl)
              (Bleaf _ sr)
    else Bleaf _ s'
  | Bnode c l (num, ones) r =>
    if i < num then balancel c (dins l b i w) r
    else balanceR c l (dins r b (i - num) w)
  end.

Definition dininsert (B : dtree) b i w : dtree :=
  match dins B b i w with
  | Bleaf s => Bleaf _ s
  | Bnode _ l d r => Bnode Black l d r
  end.
  
```

Maintaining balance

- Much of the difficulties with red-black trees comes from the numerous cases arising in balancing operations.
- In the function `balanceL`, 11 goals were generated.
- We proved those using as little automation as possible, in idiomatic `SSREFLECT` style.

```
Ltac decompose_rewrite :=  
  let H := fresh "H" in  
  case/andP || (move=>H; rewrite ?H ?(eqP H)).
```

```
Lemma balanceL_wf c (l r : dtree) :  
  wf_dtree l -> wf_dtree r -> wf_dtree (balanceL c l r).
```

```
Proof.  
case: c => /= wf_l wfr. by rewrite wf_l wfr ?(dsizeE,donesE,eqxx).  
case: l wf_l =>  
  [[[[[] lll [lln llo] llr|llA] [ln lo] [[] lrl [lrn lro] lrr|lrA]  
    |ll [ln lo] lr]|lA] /=;  
  rewrite wfr; repeat decompose_rewrite;  
  by rewrite ?(dsizeE,donesE,size_cat,count_cat,eqxx).
```

Qed.

Definitions, using dependent types

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Invariants are guaranteed by the data constructors:

- as dynamic bit vectors
- as red-black trees

Definition `is_black c := if c is Black then true else false.`

Definition `color_ok parent child :=
is_black parent || is_black child.`

Inductive `tree : nat -> nat -> nat -> color -> Type :=`
`| Leaf : forall (arr : seq bool),`
`(w ^ 2). / 2 <= size arr < (w ^ 2). * 2 ->`
`tree (size arr) (count_one arr) 0 Black`
`| Node : forall {s1 o1 s2 o2 d c1 cr c},`
`color_ok c c1 -> color_ok c cr ->`
`tree s1 o1 d c1 -> tree s2 o2 d cr ->`
`tree (s1 + s2) (o1 + o2) (d + is_black c) c.`

Operations, using dependent types

- The code and proofs for the basic queries are mostly unchanged
- No more `dtree_ind!`
- We defined `dins` using the **Program** environment

```
Program Fixpoint dinsert' {n m d c} (B : tree n m d c) (b : bool) i
  {measure (size_of_tree B)} : { B' : near_tree n.+1 (m + b) d c
    | dflattenn B' = insert1 (dflatten B) b i } := ...
```

20 obligations were generated, and were proved in 90 lines.

- Implementing `balanceL` & `balanceR`
 - At first, we could not seem to be able to define those using **Program**. Each was defined using 17 lines of tactics.
 - Later, we found out workarounds that enabled us to define them using **Program**. (**Program** is flaky.)

```
Definition balanceL {nl ml d cl cr nr mr} (p : color)
  (l : near_tree nl ml d cl) (r : tree nr mr d cr) :
  color_ok p (fix_color l) -> color_ok p cr ->
  {tr : near_tree (nl + nr) (ml + mr) (inc_black d p) p
    | dflattenn tr = dflattenn l ++ dflatten r}.
destruct r as [s1 o1 s2 o2 s3 o3 d' x y z | s o d' c' cc r'].
+ case: p => // = cpl cpr.
(* ... *)
```

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- Deletion from purely-functional red-black trees is known to be a difficult problem [Germane & Might 2014, Kahrs 2001]
- How to handle deletion gracefully while keeping all invariants intact?
- **Take 1:** directly transcribe [Kahrs 2001] to Coq
- **Result:** Our red-black tree deviates significantly from the standard version, making this transcription very hard

Dependent types to the rescue

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Idea: use dependent types to guide our search for invariants, and transcribe the result to use ML types

- We code out the needed invariants for delete, and use dependent types to guide our search for a version of deletion that is right.
- First version: defined using 626 lines of Ltac (works, but ugly).
- Later rewritten using **Program**.

Back to deletion

- Insertion can be implemented just by adding a re-balancing operation.
- Deletion, on the other hand, require an intermediate structure.
 - dtree is not enough to represent unbalanced, intermediate states resulting from removing a bit.
 - We need to know whether the black height has decreased!
 - **Solution:** using a record to trace the extra information
- Also, we handled “bit borrowing”.

```
Record deleted_dtree: Type := MkD { d_tree :> dtree;  
  d_down: bool; d_del: nat * nat }.
```

```
Definition balanceL' (c: color) (l: deleted_dtree)  
  (d: nat*nat) (r: dtree): deleted_dtree.
```

```
Definition balanceR' (c: color) (l: dtree)  
  (d: nat*nat) (r: deleted_dtree): deleted_dtree.
```

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- Small-scale reflection is mainly used for mathematical proofs via MathComp
- However, recently becoming more popular for proofs of programs as well [Sergey, Sergey & Nanevski 2015]
- Good built-in library support for doing mathematics, but less so for inductive data

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- Small-scale reflection uses boolean predicates (instead of inductive propositions) to model program properties
- Our experience with boolean predicates is very positive: simplify reasoning, “built-in” automation

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- Small-scale reflection uses boolean predicates (instead of inductive propositions) to model program properties
- Our experience with boolean predicates is very positive: simplify reasoning, “built-in” automation
- One downside: they don’t decompose naturally in inductive proofs

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- Small-scale reflection uses boolean predicates (instead of inductive propositions) to model program properties
- Our experience with boolean predicates is very positive: simplify reasoning, “built-in” automation
- One downside: they don’t decompose naturally in inductive proofs
- Solution: alternative inductive principle (`dtree_ind`)

Automation for SSREFLECT

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- Basic approach: case analysis, then “crush” (à la [Chlipala 2013]) all goals
- We wrote our own SSREFLECT-style tactic for crushing boolean predicate goals:

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Ltac decompose_rewrite :=  
  let H := fresh "H" in  
  move/andP => [] || (move => H; try rewrite H; try rewrite (eqP H)).
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- Result: worked very well in general; only one lemma seems to not be handled well by this approach.
- Also, SSREFLECT lacked arithmetic automation, which turned out to be very useful.

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Advantages of the new approach

- All proofs are by induction on paths
- Common lemmas arise naturally
- Down to about 500 lines in total, long proofs about 25

Remaining problems

- There are still long lemmas (`lo_traversal_lt_max, ...`)
- Paths all over the place

Future work

- Can we apply that to other breadth-first traversals

Dynamic bit-vector formalization

- Summary
 - SSREFLECT helped immensely, and we were able to write proofs in an idiomatic SSREFLECT style.
 - Our proof of red-black tree balance was especially clear and concise (compare [Appel 2011] and [Chlipala 2013]).
 - However, there were a lot of small lemmas.
 - Crushing approach worked very well as always
 - Dependent types: good experiment resulting in clean lemma environment, but dirty code
- Future work
 - Can we improve the dependently typed version?
 - Proofs about complexity
 - Time complexity: do we need to amortize? (Amortization can be tricky)
 - Space complexity: no previous work on this; how to define the correct predicates?

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Proofs

<https://github.com/affeldt-aist/succinct>

Preprint available on the arXiv (CoRR).

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Reynald Affeldt, Jacques Garrigue, Xuanrui (Ray) Qi, Kazunari Tanaka. Proving Tree Algorithms for Succinct Data Structures. arXiv:1904.02809 [cs.PL].

<https://arxiv.org/abs/1904.02809>

More in the paper

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- Details of the algorithms we formalized
- Important lemmas in our proof development
- More discussion on the benefits/drawbacks to using SSREFLECT