

# 氢原子解

球坐标系的薛定谔方程

径向方程和角向方程

束缚态和散射态

径向波函数和球谐函数

电子云

反射对称性和宇称

# 球坐标系中的薛定谔方程

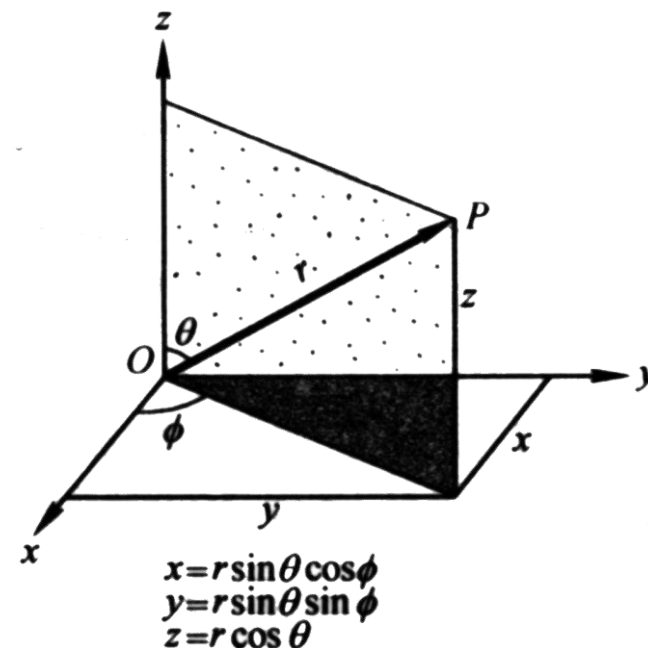


库伦势

$$V(r) = -\frac{e^2}{4\pi\epsilon_0 r}$$

哈密顿算符

$$\hat{H} = \frac{\hat{p}^2}{2m} - \frac{e^2}{4\pi\epsilon_0 r}$$



定态薛定谔方程：

$$-\frac{\hbar^2}{2m} \nabla^2 u(r, \theta, \phi) - \frac{e^2}{4\pi\epsilon_0 r} u(r, \theta, \phi) = E u(r, \theta, \phi)$$



Hermann Klaus Hugo Weyl

德国数学家、物理学家、哲学家  
曾帮助薛定谔求解氢原子波函数

# 拉普拉斯算符\*

$$\begin{cases} x = r \sin \theta \cos \varphi \\ y = r \sin \theta \sin \varphi \\ z = r \cos \theta \end{cases}$$

雅可比矩阵

$$\frac{\partial(r, \theta, \varphi)}{\partial(x, y, z)} = \begin{pmatrix} \sin \theta \cos \varphi & \sin \theta \sin \varphi & \cos \theta \\ \frac{1}{r} \cos \theta \cos \varphi & \frac{1}{r} \cos \theta \sin \varphi & -\frac{1}{r} \sin \theta \\ -\frac{1}{r} \csc \theta \sin \varphi & \frac{1}{r} \csc \theta \cos \varphi & 0 \end{pmatrix}$$

梯度

$$\frac{\partial}{\partial r_j} = \frac{\partial \xi^\alpha}{\partial r_j} \frac{\partial}{\partial \xi^\alpha}$$



$$\begin{cases} \frac{\partial}{\partial x} = \sin \theta \cos \varphi \frac{\partial}{\partial r} + \frac{1}{r} \cos \theta \cos \varphi \frac{\partial}{\partial \theta} - \frac{1}{r} \csc \theta \sin \varphi \frac{\partial}{\partial \varphi} \\ \frac{\partial}{\partial y} = \sin \theta \sin \varphi \frac{\partial}{\partial r} + \frac{1}{r} \cos \theta \sin \varphi \frac{\partial}{\partial \theta} + \frac{1}{r} \csc \theta \cos \varphi \frac{\partial}{\partial \varphi} \\ \frac{\partial}{\partial z} = \cos \theta \frac{\partial}{\partial r} - \frac{1}{r} \sin \theta \frac{\partial}{\partial \theta} \end{cases}$$

$$\nabla^2 = \frac{\partial}{\partial r_j} \frac{\partial}{\partial r_j} = \frac{\partial}{\partial x} \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \frac{\partial}{\partial y} + \frac{\partial}{\partial z} \frac{\partial}{\partial z}$$

$$\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} r^2 \frac{\partial}{\partial r} + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \sin \theta \frac{\partial}{\partial \theta} + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \varphi^2}$$

# 拉普拉斯算符-微分几何\*

$$\begin{cases} x = r \sin \theta \cos \varphi \\ y = r \sin \theta \sin \varphi \\ z = r \cos \theta \end{cases}$$

$$\partial_\alpha \stackrel{\text{def}}{=} \frac{\partial}{\partial \xi^\alpha}$$

梯度

$$\frac{\partial}{\partial r_j} = \frac{\partial \xi^\alpha}{\partial r_j} \frac{\partial}{\partial \xi^\alpha}$$

$$\nabla^2 = \frac{\partial}{\partial r_j} \frac{\partial}{\partial r_j} = \frac{\partial \xi^\alpha}{\partial r_j} \partial_\alpha \frac{\partial \xi^\beta}{\partial r_j} \partial_\beta = \cdots = \frac{1}{\sqrt{g}} \partial_\alpha \sqrt{g} g^{\alpha\beta} \partial_\beta$$

$$\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} r^2 \frac{\partial}{\partial r} + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \sin \theta \frac{\partial}{\partial \theta} + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \varphi^2}$$

雅可比矩阵

$$J = (\partial_\alpha \vec{r}) = \frac{\partial(x, y, z)}{\partial(r, \theta, \varphi)} = \begin{pmatrix} \sin \theta \cos \varphi & r \cos \theta \cos \varphi & -r \sin \theta \sin \varphi \\ \sin \theta \sin \varphi & r \cos \theta \sin \varphi & r \sin \theta \cos \varphi \\ \cos \theta & -r \sin \theta & 0 \end{pmatrix}$$

弧长

$$ds^2 = dx^2 + dy^2 + dz^2 = g_{\alpha\beta} d\xi^\alpha d\xi^\beta$$

度规矩阵

$$(g_{\alpha\beta}) \stackrel{\text{def}}{=} (\partial_\alpha \vec{r}) \cdot (\partial_\beta \vec{r}) = J^T J = \begin{pmatrix} 1 & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & r^2 \sin^2 \theta \end{pmatrix}$$

逆矩阵

$$(g^{\alpha\beta}) \stackrel{\text{def}}{=} (g_{\mu\nu})^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1/r^2 & 0 \\ 0 & 0 & 1/(r^2 \sin^2 \theta) \end{pmatrix}$$

行列式

$$g \stackrel{\text{def}}{=} \det(g_{\mu\nu}) = r^4 \sin^2 \theta$$
$$\sqrt{g} = r^2 \sin \theta$$

# 分离变量

$$-\frac{\hbar^2}{2m}\nabla^2 u(r, \theta, \varphi) - \frac{e^2}{4\pi\epsilon_0 r} u(r, \theta, \varphi) = Eu(r, \theta, \varphi)$$

$$\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} r^2 \frac{\partial}{\partial r} + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \sin \theta \frac{\partial}{\partial \theta} + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \varphi^2}$$

$$\frac{\sin^2 \theta}{R} \frac{\partial}{\partial r} \left( r^2 \frac{\partial R}{\partial r} \right) + \frac{\sin \theta}{\Theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial \Theta}{\partial \theta} \right) + \frac{2mr^2}{\hbar^2} \sin^2 \theta \left( E + \frac{e^2}{4\pi\epsilon_0 r} \right) = -\frac{1}{\Phi} \frac{\partial^2 \Phi}{\partial \varphi^2}$$



$$\frac{1}{R} \frac{\partial}{\partial r} \left( r^2 \frac{\partial R}{\partial r} \right) + \frac{2mr^2}{\hbar^2} \left( E + \frac{e^2}{4\pi\epsilon_0 r} \right) = \frac{m_l^2}{\sin^2 \theta} - \frac{1}{\Theta \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial \Theta}{\partial \theta} \right)$$

分离变量:

$$u(r, \theta, \varphi) = R(r)\Theta(\theta)\Phi(\varphi)$$



$$\frac{\partial^2 \Phi}{\partial \varphi^2} + m_l^2 \Phi = 0$$

## 继续分离变量

$$\frac{1}{R} \frac{\partial}{\partial r} \left( r^2 \frac{\partial R}{\partial r} \right) + \frac{2mr^2}{\hbar^2} \left( E + \frac{e^2}{4\pi\epsilon_0 r} \right) = \frac{m_l^2}{\sin^2 \theta} - \frac{1}{\Theta \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial \Theta}{\partial \theta} \right)$$



$$\frac{m_l^2}{\sin^2 \theta} \Theta - \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial \Theta}{\partial \theta} \right) = l(l+1) \Theta$$

把 $\Theta$ 对 $\theta$ 展开为Taylor series, 代入方程,  
考虑 $\theta = 0, \pi$ 处,  $\Rightarrow$ 欲使波函数有限,  $l$ 必须取非负整数

$$\frac{\partial}{\partial r} \left( r^2 \frac{\partial R}{\partial r} \right) + \frac{2mr^2}{\hbar^2} \left( E + \frac{e^2}{4\pi\epsilon_0 r} \right) R = l(l+1) R$$

径向方程

# 径向运动的有效势

$$\frac{\partial}{\partial r} \left( r^2 \frac{\partial R}{\partial r} \right) + \frac{2mr^2}{\hbar^2} \left( E + \frac{e^2}{4\pi\epsilon_0 r} \right) R = l(l+1)R$$

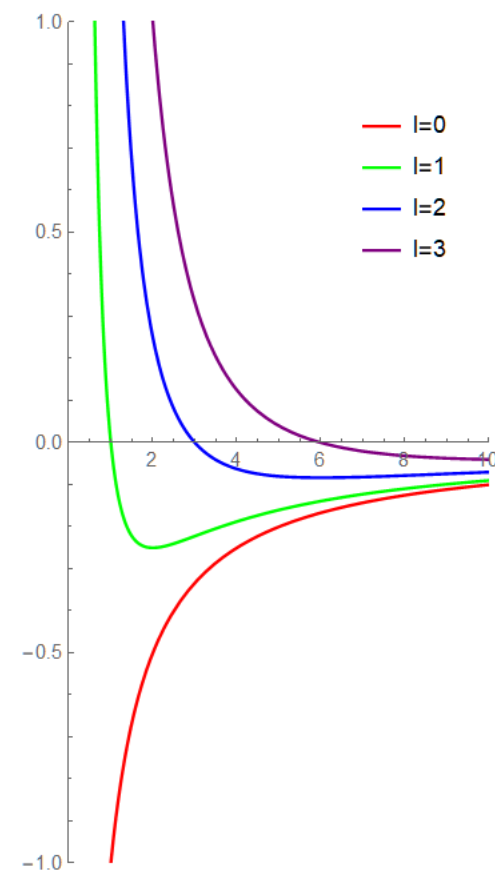


$$\left\{ -\frac{\hbar^2}{2mr^2} \frac{d}{dr} \left( r^2 \frac{d}{dr} \right) + \frac{l(l+1)\hbar^2}{2mr^2} - \frac{e^2}{4\pi\epsilon_0 r} \right\} R(r) = E R(r)$$

惯性离心势 中心位垒  
Centrifugal barrier

等效势

$$V_{\text{effective}}(r) \stackrel{\text{def}}{=} \frac{l(l+1)\hbar^2}{2mr^2} - \frac{e^2}{4\pi\epsilon_0 r}$$



# 求解1

$$\frac{\partial^2 \Phi}{\partial \varphi^2} + m_l^2 \Phi = 0$$



$$\Phi(\varphi) = Ae^{im_l \varphi}$$

波函数单值

$$\Phi(\varphi) = \Phi(\varphi + 2\pi)$$

$$m_l \in \mathbb{Z}$$



$$\Phi(\varphi) = \frac{1}{\sqrt{2\pi}} e^{im_l \varphi}, \quad m_l = 0, \pm 1, \pm 2, \dots$$



## 求解2

$$\frac{m_l^2}{\sin^2 \theta} \Theta - \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial \Theta}{\partial \theta} \right) = l(l+1) \Theta$$



$$\Theta(\theta) = B \cdot P_l^{m_l}(\theta)$$

associated Legendre polynomial

$$P_n^m(x) = (-1)^m (1-x^2)^{m/2} (d^m/dx^m) P_n(x)$$

$$l = |m_l|, |m_l| + 1, |m_l| + 2, \dots$$



$$\begin{cases} l = 0, 1, 2, \dots \\ m_l = 0, \pm 1, \pm 2, \dots, \pm l \end{cases}$$

# 球谐函数 spherical harmonic function

$$P_l^m(\theta)\Phi_m(\varphi) \propto Y_{lm}(\theta, \varphi) \quad \text{参看数理方程教材}$$

$$Y_{lm}(\theta, \varphi) = (-1)^m \sqrt{\frac{2l+1}{4\pi} \frac{(l-m)!}{(l+m)!}} P_l^m(\theta) e^{im\varphi}$$
$$l = 0, 1, 2, \dots; \quad m = -l, -l+1, \dots, l-1, l.$$

$$\int_0^\pi \int_0^{2\pi} Y_{l'm'}^*(\theta, \phi) Y_{lm}(\theta, \phi) d\Omega = \delta_{ll'} \delta_{mm'}$$

球面上平方可积函数的完备基  
多极展开, 分波展开

# 角向波函数

$l$	$m_l$	$\Theta_{lm_l}$	$\Phi_{m_l}$	$l$	$m_l$	$\Theta_{lm_l}$	$\Phi_{m_l}$
0	0	$\frac{1}{\sqrt{2}}$	$\frac{1}{\sqrt{2\pi}}$	3	0	$\frac{\sqrt{14}}{4}(-3\cos\theta + 5\cos^3\theta)$	$\frac{1}{\sqrt{2\pi}}$
1	0	$\sqrt{\frac{3}{2}}\cos\theta$	$\frac{1}{\sqrt{2\pi}}$	3	$\pm 1$	$\mp \frac{\sqrt{42}}{8}(-1 + 5\cos^2\theta)\sin\theta$	$\frac{1}{\sqrt{2\pi}}e^{\pm i\varphi}$
1	$\pm 1$	$\mp \frac{\sqrt{3}}{2}\sin\theta$	$\frac{1}{\sqrt{2\pi}}e^{\pm i\varphi}$	3	$\pm 2$	$\frac{\sqrt{105}}{4}\cos\theta\sin^2\theta$	$\frac{1}{\sqrt{2\pi}}e^{\pm 2i\varphi}$
2	0	$\frac{\sqrt{10}}{4}(3\cos^2\theta - 1)$	$\frac{1}{\sqrt{2\pi}}$	3	$\pm 3$	$\mp \frac{\sqrt{70}}{8}\sin^3\theta$	$\frac{1}{\sqrt{2\pi}}e^{\pm 3i\varphi}$
2	$\pm 1$	$\mp \frac{\sqrt{15}}{2}\sin\theta\cos\theta$	$\frac{1}{\sqrt{2\pi}}e^{\pm i\varphi}$				
2	$\pm 2$	$\frac{\sqrt{15}}{4}\sin^2\theta$	$\frac{1}{\sqrt{2\pi}}e^{\pm 2i\varphi}$			$Y_{lm}(\theta, \varphi) = \Theta_{lm}(\theta)\Phi_m(\varphi)$	

# 求解3

$$\left\{ -\frac{\hbar^2}{2mr^2} \frac{d}{dr} \left( r^2 \frac{d}{dr} \right) + \frac{l(l+1)\hbar^2}{2mr^2} - \frac{e^2}{4\pi\epsilon_0 r} \right\} R(r) = E R(r)$$



$$\chi(\rho) \stackrel{\text{def}}{=} rR(r), n \stackrel{\text{def}}{=} \frac{1}{\hbar} \sqrt{\frac{m}{2|E|}} \frac{e^2}{4\pi\epsilon_0}$$
$$\rho \stackrel{\text{def}}{=} \frac{2}{\hbar} \sqrt{2m|E|} r = \frac{2r}{na_0}, a_0 \stackrel{\text{def}}{=} \frac{4\pi\epsilon_0 \hbar^2}{me^2}$$

$$\frac{d^2\chi}{d\rho^2} + \left\{ \frac{n}{\rho} \pm \frac{1}{4} - \frac{l(l+1)}{\rho^2} \right\} \chi = 0$$

其中  $E > 0$  时取 “+”， $E < 0$  时取 “-”

## 散射态解( $E > 0$ )

$$\frac{d^2\chi}{d\rho^2} + \left\{ \frac{n}{\rho} + \frac{1}{4} - \frac{l(l+1)}{\rho^2} \right\} \chi = 0$$

$n$ 可以取连续的正数,  $E$ 可以取任何正值

相当于单电子原子电离的情形,

电子可以运动到距离原子核无穷远处

解略

# 束缚态解 ( $E < 0$ )

$$\frac{d^2\chi}{d\rho^2} + \left\{ \frac{n}{\rho} - \frac{1}{4} - \frac{l(l+1)}{\rho^2} \right\} \chi = 0 \quad \longrightarrow \quad R_{nl} = C_{nl} e^{-\frac{\rho}{2}} \rho^l L_{n-l-1}^{2l+1}(\rho) \quad \begin{array}{l} \text{缔合拉盖尔多项式} \\ \text{associated Laguerre polynomials} \end{array}$$

波函数的归一化条件

$$dx dy dz = r^2 \sin \theta dr d\theta d\varphi$$

$$= r^2 dr d\Omega$$

$$\int_0^\infty |R|^2 r^2 dr = 1$$

并且  $n$  为  $\geq l+1$  的整数时，  
才能使径向波函数在无穷远有限

合流超几何函数  
confluent hypergeometric function

$$R_{n,l}(r) = N_{n,l} e^{-\rho/2} \rho^l F(-n+l+1, 2l+2, \rho)$$

$$N_{n,l} \equiv \frac{2}{a_0^{3/2} n^2 (2l+1)!} \sqrt{\frac{(n+l)!}{(n-l-1)!}}, \quad \rho \stackrel{\text{def}}{=} \frac{2r}{na_0}, \quad a_0 \stackrel{\text{def}}{=} \frac{4\pi\epsilon_0\hbar^2}{me^2}$$

径向波函数正交归一:  $\int_0^\infty R_{n',l'}^*(r) R_{n,l}(r) r^2 dr = \delta_{n'n} \delta_{l'l}$

正交: 哈密顿算符是厄密的, 厄密算符的本征态相互正交

归一: 做了归一化

# 定态径向波函数

$n$	$l$	$R_{nl}$	$n$	$l$	$R_{nl}$
1	0	$\frac{2}{a_0^{3/2}} \exp\left(-\frac{r}{a_0}\right)$	4	0	$\frac{1}{768a_0^{3/2}} \left(192 - 144\frac{r}{a_0} + 24\frac{r^2}{a_0^2} - \frac{r^3}{a_0^3}\right) \exp\left(-\frac{r}{4a_0}\right)$
2	0	$\frac{1}{(2a_0)^{3/2}} \left(2 - \frac{r}{a_0}\right) \exp\left(-\frac{r}{2a_0}\right)$	4	1	$\frac{1}{256\sqrt{15}a_0^{3/2}} \left(80\frac{r}{a_0} - 20\frac{r^2}{a_0^2} + \frac{r^3}{a_0^3}\right) \exp\left(-\frac{r}{4a_0}\right)$
2	1	$\frac{1}{2\sqrt{6}a_0^{3/2}} \frac{r}{a_0} \exp\left(-\frac{r}{2a_0}\right)$	4	2	$\frac{1}{768\sqrt{5}a_0^{3/2}} \left(12\frac{r^2}{a_0^2} - \frac{r^3}{a_0^3}\right) \exp\left(-\frac{r}{4a_0}\right)$
3	0	$\frac{2}{81\sqrt{3}a_0^{3/2}} \left(27 - 18\frac{r}{a_0} + 2\frac{r^2}{a_0^2}\right) \exp\left(-\frac{r}{3a_0}\right)$	4	3	$\frac{1}{768\sqrt{35}a_0^{3/2}} \frac{r^3}{a_0^3} \exp\left(-\frac{r}{4a_0}\right)$
3	1	$\frac{4}{81\sqrt{6}a_0^{3/2}} \left(6\frac{r}{a_0} - \frac{r^2}{a_0^2}\right) \exp\left(-\frac{r}{3a_0}\right)$			
3	2	$\frac{4}{81\sqrt{30}a_0^{3/2}} \frac{r^2}{a_0^2} \exp\left(-\frac{r}{3a_0}\right)$			

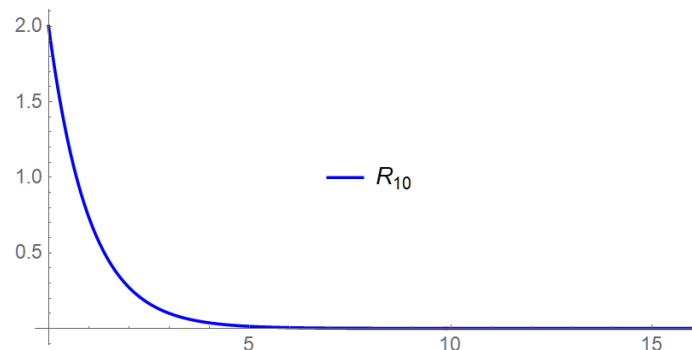
指数因子上，分母的系数为n

多项式因子中r的最低幂次为l

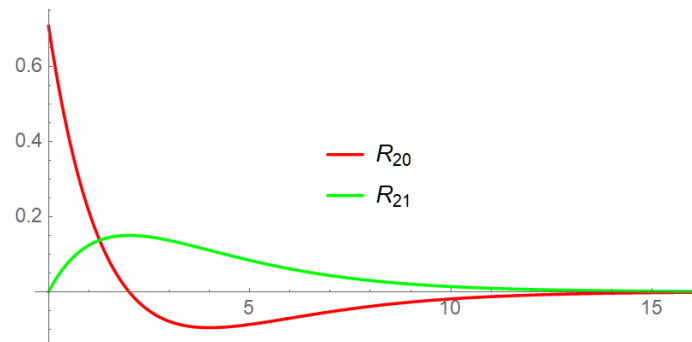
# 定态径向波函数图

零点的数目随 $n$ 递增  
节点数 $n_r = n - l - 1$

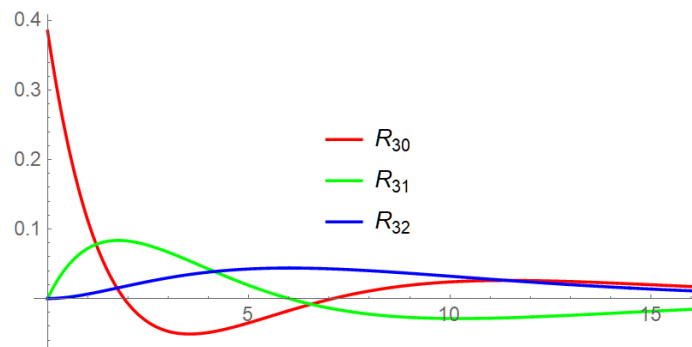
$R_{32}$ 的零点是重根



$n = 1, 0$ 个



$n = 2, 1$ 个



$n = 3, 2$ 个



# 总波函数

定态空间波函数

$$u_{nlm_l}(r, \theta, \varphi) = R_{nl}(r)Y_{lm_l}(\theta, \varphi)$$

$$n = 1, 2, 3, \dots$$

$$l = 0, 1, 2, \dots, n - 1$$

$$m_l = -l, -l + 1, \dots, l - 1, l$$

定态波函数

$$\psi_{nlm_l}(\vec{r}, t) = u_{nlm_l}(r, \theta, \varphi)e^{-\frac{iE_n}{\hbar}t}$$

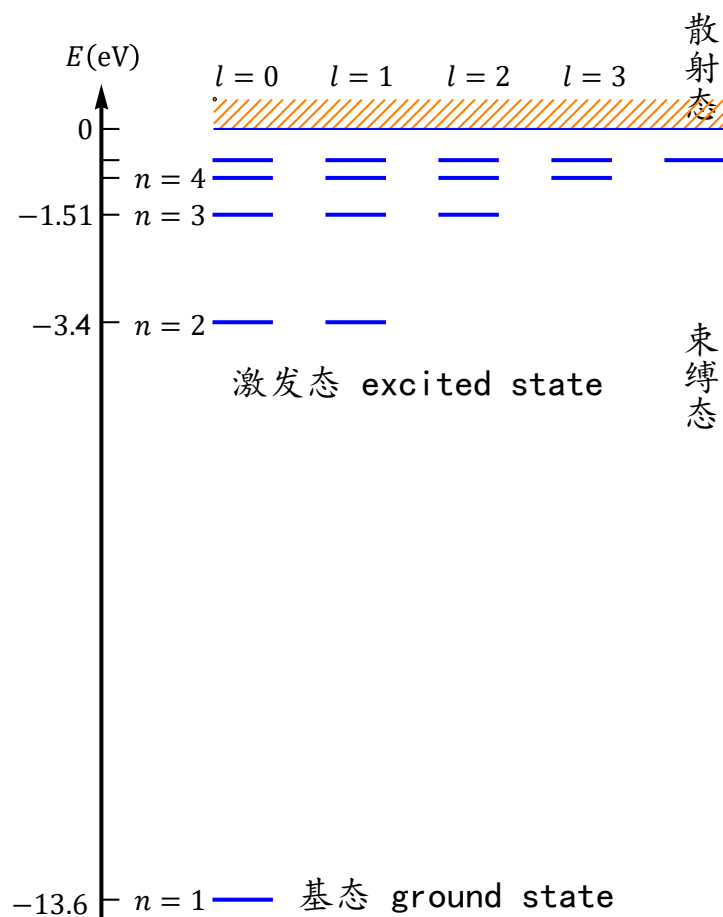
含时波函数的一般解

$$\psi(\vec{r}, t) \equiv \sum_{n,l,m_l} c_{nlm_l} \psi_{nlm_l}(\vec{r}, t)$$

展开系数 $c_{nlm_l}$ 由初值决定

# 量子数的物理解释-主量子数

能量只依赖于主量子数



$$\hat{H}u_{nlm_l}(r, \theta, \phi) = E u_{nlm_l}(r, \theta, \phi)$$

$$\frac{\partial}{\partial r} \left( r^2 \frac{\partial R_{nl}}{\partial r} \right) + \frac{2m_e r^2}{\hbar^2} \left( E + \frac{e^2}{4\pi\epsilon_0 r} \right) R_{nl} = l(l+1) R_{nl}$$

$$E_n = -\alpha^2 \frac{mc^2 Z^2}{2n^2} = -\frac{\hbar^2}{2ma_0^2 n^2}$$

$$= -13.6 \text{ eV} \cdot \frac{Z^2}{n^2}$$

$$\alpha \stackrel{\text{def}}{=} \frac{e^2}{4\pi\epsilon_0 \hbar c} \approx \frac{1}{137}$$

$n^2$ 重简并（不同状态具有相同能量；考虑自旋后 $2n^2$ ），

$$m_l = 0, \pm 1, \dots, \pm l$$

$$\sum_{l=0}^{n-1} (2l+1) = n^2$$

# 量子数的物理解释-

## 轨道角动量量子数和磁量子数

$l, m_l$  和轨道角动量的本征值有关,

$l$ : 角动量量子数

$m_l$ : 磁量子数 (原子磁矩与它成正比)

$$n = 1, 2, 3 \dots$$

$$l = 0, 1, 2, \dots, n - 1$$

$$m_l = 0, \pm 1, \pm 2, \pm l$$

$l$  可以取 0, 与玻尔模型不同

# 特征

指数因子上，分母的系数为 $n$   
指数因子前 $r$ 最高幂次项为 $n-1$ 次  
相因子上 $i\varphi$ 的倍数为 $m$

solid spherical harmonic  
function

$r^l Y_{lm}(\theta, \varphi)$   
是关于 $x, y, z$ 的 $l$ 次齐次多项式

多项式因子中 $r$ 的最低幂次为 $l$

从定态波函数读出量子数  
或用算符作用，求出量子数

表 3.1.3 类氢离子的波函数

$n$	$l$	$m_l$	$u_{n,l,m_l}(r,\theta,\varphi)$
1	0	0	$\frac{1}{\sqrt{\pi}}\left(\frac{Z}{a_0}\right)^{3/2}\exp\left(-\frac{Zr}{a_0}\right)$
2	0	0	$\frac{1}{4\sqrt{2\pi}}\left(\frac{Z}{a_0}\right)^{3/2}\left(2-\frac{Zr}{a_0}\right)\exp\left(-\frac{Zr}{2a_0}\right)$
2	1	0	$\frac{1}{4\sqrt{2\pi}}\left(\frac{Z}{a_0}\right)^{3/2}\frac{Zr}{a_0}\cos\theta\exp\left(-\frac{Zr}{2a_0}\right)$
2	1	$\pm 1$	$\frac{1}{8\sqrt{2\pi}}\left(\frac{Z}{a_0}\right)^{3/2}\frac{Zr}{a_0}\sin\theta\exp\left(-\frac{Zr}{2a_0}\right)e^{\pm i\varphi}$
3	0	0	$\frac{1}{81\sqrt{3\pi}}\left(\frac{Z}{a_0}\right)^{3/2}\left(27-18\frac{Zr}{a_0}+\frac{Z^2r^2}{a_0^2}\right)\exp\left(-\frac{Zr}{3a_0}\right)$
3	1	0	$\frac{\sqrt{2}}{81\sqrt{\pi}}\left(\frac{Z}{a_0}\right)^{3/2}\left(6-\frac{Zr}{a_0}\right)\frac{Zr}{a_0}\cos\theta\exp\left(-\frac{Zr}{3a_0}\right)$
3	1	$\pm 1$	$\frac{1}{81\sqrt{\pi}}\left(\frac{Z}{a_0}\right)^{3/2}\left(6-\frac{Zr}{a_0}\right)\frac{Zr}{a_0}\sin\theta\exp\left(-\frac{Zr}{3a_0}\right)e^{\pm i\varphi}$
3	2	0	$\frac{1}{81\sqrt{6\pi}}\left(\frac{Z}{a_0}\right)^{3/2}\left(\frac{Zr}{a_0}\right)^2(3\cos^2\theta-1)\exp\left(-\frac{Zr}{3a_0}\right)$
3	2	$\pm 1$	$\frac{1}{81\sqrt{\pi}}\left(\frac{Z}{a_0}\right)^{3/2}\left(\frac{Zr}{a_0}\right)^2\sin\theta\cos\theta\exp\left(-\frac{Zr}{3a_0}\right)e^{\pm i\varphi}$
3	2	$\pm 2$	$\frac{1}{162\sqrt{\pi}}\left(\frac{Z}{a_0}\right)^{3/2}\left(\frac{Zr}{a_0}\right)^2\sin^2\theta\exp\left(-\frac{Zr}{3a_0}\right)e^{\pm 2i\varphi}$

# 角向概率分布

定态波函数

$$u_{nlm}(r, \theta, \varphi) = R_{n,l}(r) \Theta_{lm}(\theta) \Phi_m(\varphi)$$

$$R_{n,l}(r) = N_{n,l} e^{-\xi/2} \xi^l F(-n + l + 1, 2l + 1, \xi)$$

$$\Theta_{lm}(\theta) = P_l^m(\theta)$$

$$\Phi_m(\varphi) = \frac{1}{\sqrt{2\pi}} e^{im\varphi}$$

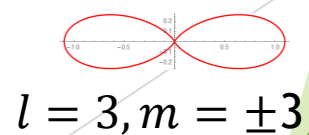
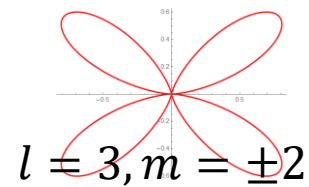
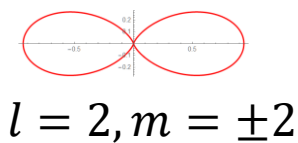
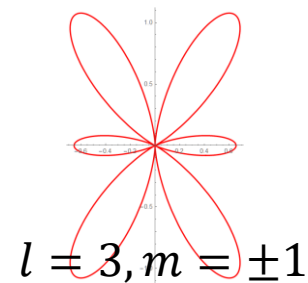
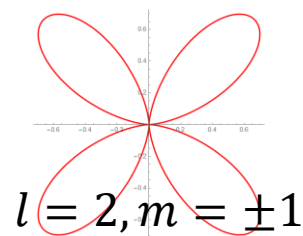
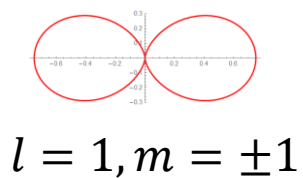
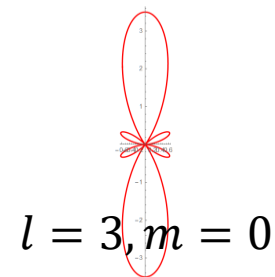
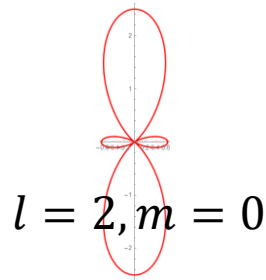
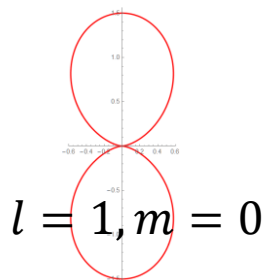
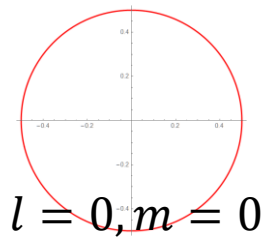
定态的几率密度

$$\rho dx dy dz = |u_{nlm}|^2 r^2 dr \sin \theta d\theta d\varphi$$

$$P_\theta d\theta = |\Theta_{lm}|^2 \sin \theta d\theta \iint |R_{nl}(r)|^2 |\Phi_m|^2 r^2 dr d\varphi = |\Theta_{lm}|^2 \sin \theta d\theta$$

$$P_\varphi d\varphi = |\Phi_m|^2 d\varphi \iint |R_{nl}(r)|^2 |\Theta_{lm}|^2 r^2 dr \sin \theta d\theta = \frac{1}{2\pi} d\varphi$$

# 角向概率分布图



$\rho_{\Omega} \stackrel{\text{def}}{=} |Y_{lm}(\theta, \varphi)|^2$   
 $xz$ 平面剖面  
 绕 $z$ 轴旋转对称

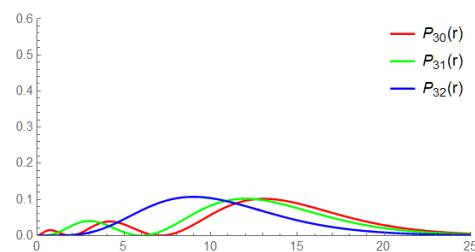
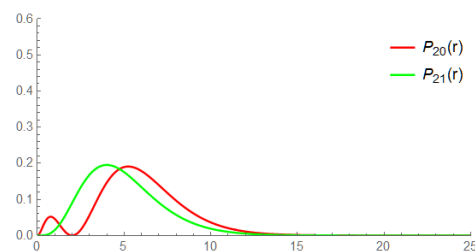
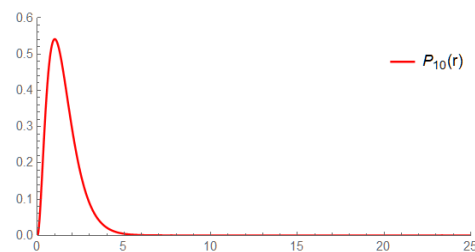
# 径向概率密度

$$P_r dr = |R_{nl}(r)|^2 r^2 dr \iint |Y_{lm}(\theta, \varphi)|^2 \sin \theta d\theta d\varphi$$

$$= |R_{nl}(r)|^2 r^2 dr$$

公式：

$$\langle r^k \rangle = \iiint u_{nlm}^* r^k u_{nlm} r^2 dr d\Omega = \int_0^\infty R_{nl}^* r^k R_{nl} r^2 dr = \left(\frac{n}{2}\right)^k \frac{J_{n+l, 2l+1}^{(k+1)}}{J_{n+l, 2l+1}^{(1)}}$$



$$J_{\lambda, \mu}^{(\sigma)} \stackrel{\text{def}}{=} \begin{cases} (-1)^\sigma \frac{\lambda! \sigma!}{(\lambda - \mu)!} \sum_{\beta=0}^{\sigma} (-1)^\beta \binom{\sigma}{\beta} \binom{\lambda + \beta}{\sigma} \binom{\lambda + \beta - \mu}{\sigma}, & \sigma \geq 0; \\ \frac{\lambda!}{(\lambda - \mu)! (s + 1)!} \sum_{\gamma=0}^s (-1)^{s-\gamma} \frac{\binom{s}{\gamma} \binom{\lambda - \mu + \gamma}{s}}{\binom{\mu + s - \gamma}{s + 1}}, & \sigma = -(s + 1) \leq -1. \end{cases}$$

H. A. Bethe and E. E. Salpeter. Quantum Mechanics of One- and Two-Electron Atoms. Academic Press, New York, 1957.

$$\bar{r} = \frac{1}{2} \{3n^2 - l(l + 1)\} \frac{a_0}{Z}$$

$$\overline{r^2} = \frac{1}{2} \{5n^2 + 1 - 3l(l + 1)\} n^2 \left(\frac{a_0}{Z}\right)^2$$

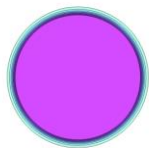
$$\overline{r^{-1}} = \frac{1}{n^2} \left(\frac{a_0}{Z}\right)^{-1}$$

$$\overline{r^{-2}} = \frac{1}{n^3 \left(l + \frac{1}{2}\right)} \left(\frac{a_0}{Z}\right)^{-2}$$

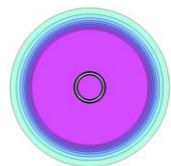
$$\overline{r^{-3}} = \frac{1}{n^3 (l + 1) \left(l + \frac{1}{2}\right) l} \left(\frac{a_0}{Z}\right)^{-3}, \quad l > 0.$$



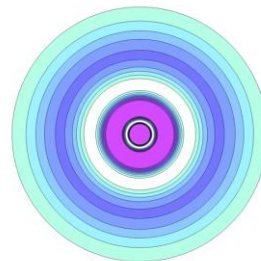
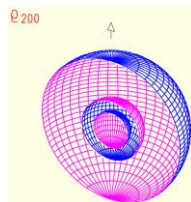
# 电子云图



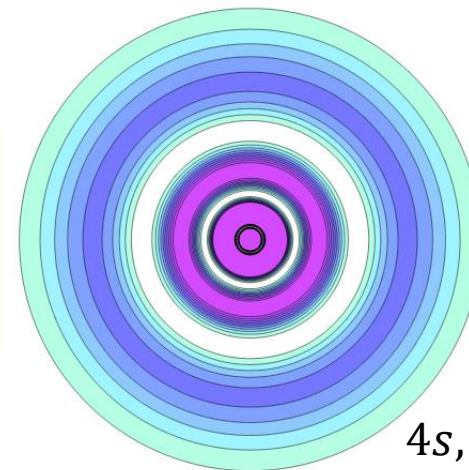
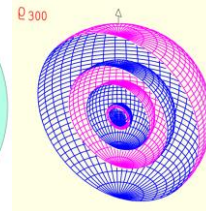
$1s, m = 0$



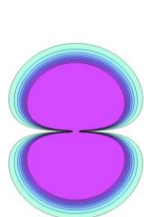
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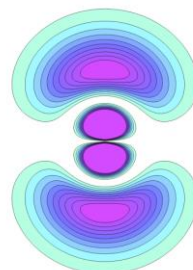
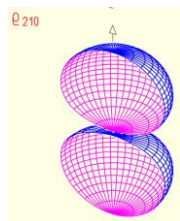
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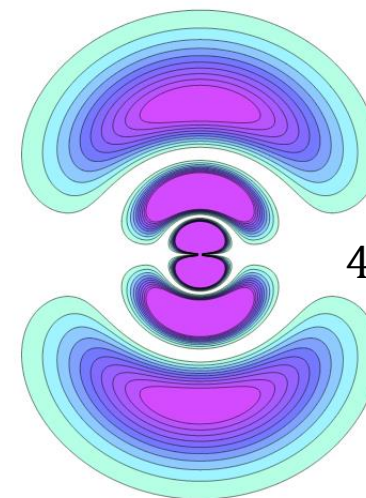
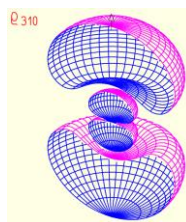
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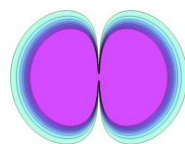
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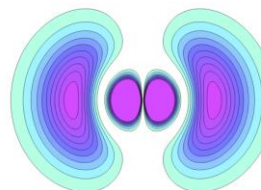
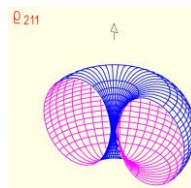
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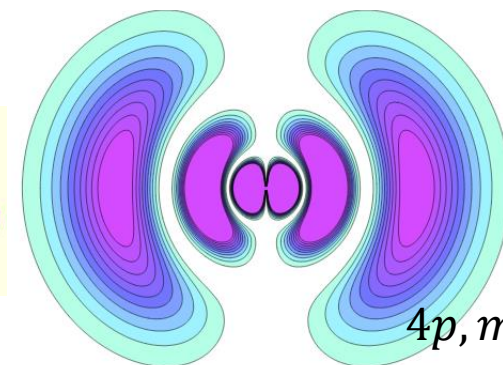
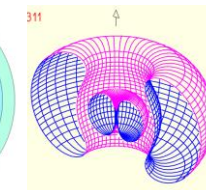
$4p, m = 0$



$2p, m = \pm 1$



$3p, m = \pm 1$



$4p, m = \pm 1$

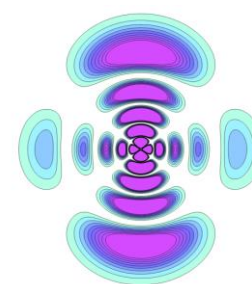
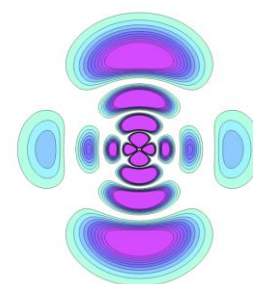
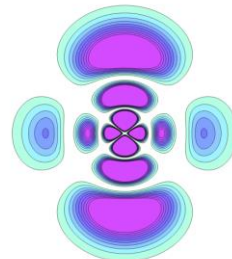
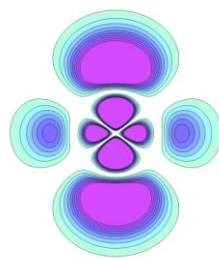
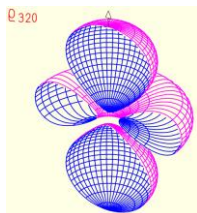
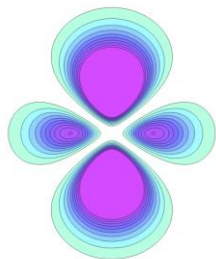
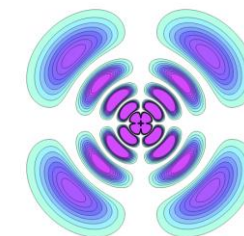
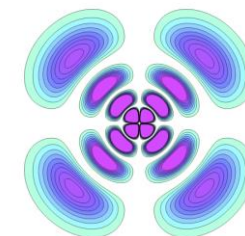
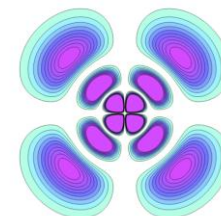
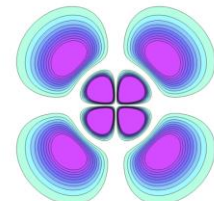
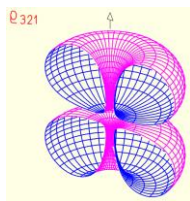
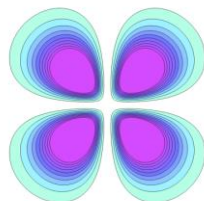
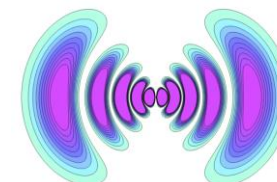
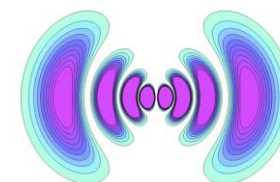
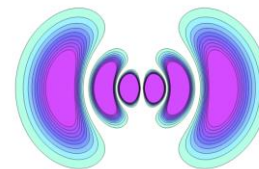
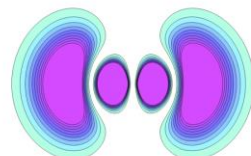
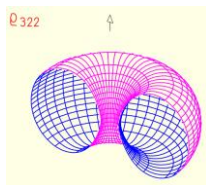
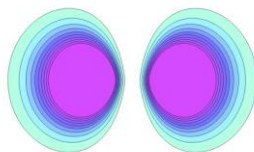
等密度面，截断，xz平面剖面

$$\rho(r, \theta) = |u_{nlm}(r, \theta, \varphi)|^2$$

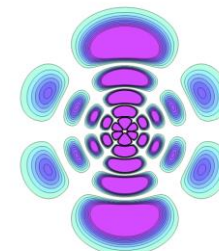
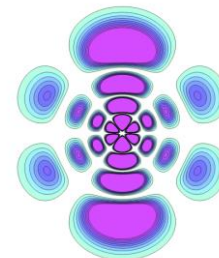
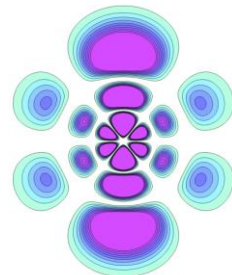
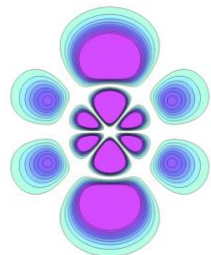
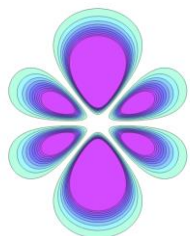
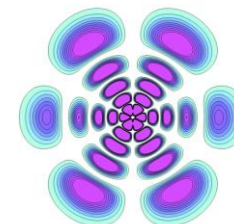
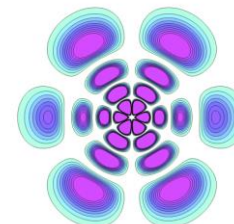
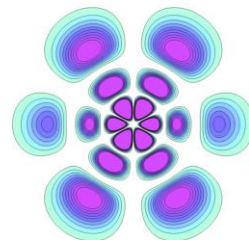
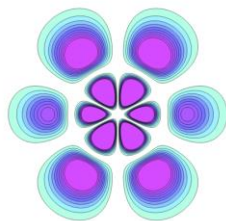
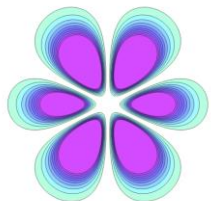
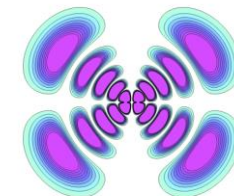
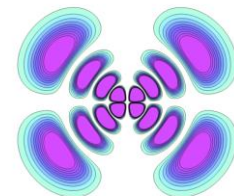
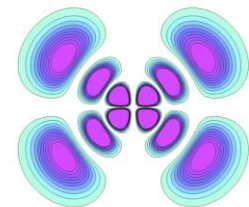
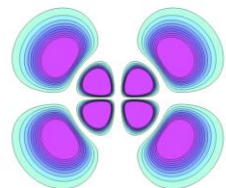
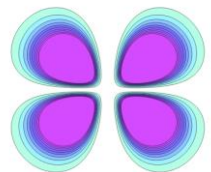
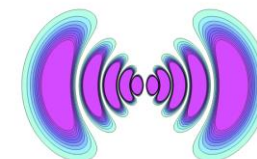
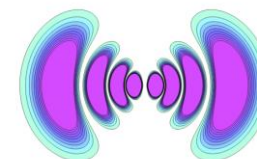
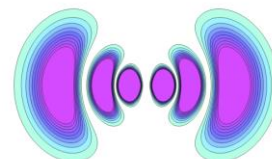
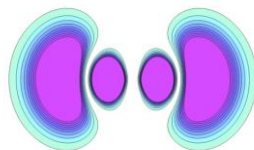
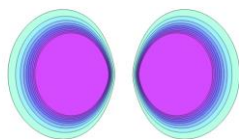
本征态绕z-轴旋转对称

光谱学记号  $s, p, d, f$   
 $l = 0, 1, 2, 3$



$3d$  $4d$  $5d$  $6d$  $7d$  $m = 0$  $|m| = 1$  $|m| = 2$ 

本页未按实际比例绘制

$4f$  $5f$  $6f$  $7f$  $8f$  $m = 0$  $|m| = 1$  $|m| = 2$  $|m| = 3$ 

本页未按实际比例绘制

# 空间反射和宇称 Space Reflection Parity

空间反射

$$\vec{r} = P\vec{r}$$
$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} \rightarrow \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -x \\ -y \\ -z \end{pmatrix}$$

在球坐标系,

$$(r, \theta, \varphi) \rightarrow (r, \pi - \theta, \varphi + \pi)$$

两次反射为恒等操作:  $P^2 = \mathbf{1}_{3 \times 3}$

量子力学中空间反射为算符  $\hat{P}$

$\hat{P}^2 = 1 \Rightarrow$  特征值为

$$\eta = \pm 1$$

用之于氢原子的定态波函数

$$u_{nlm}(r, \theta, \varphi) = R_{n,l}(r)Y_{l,m}(\theta, \varphi)$$

$$\hat{P}u_{nlm}(r, \theta, \varphi) = R_{n,l}(r)\hat{P}Y_{l,m}(\theta, \varphi)$$

$r^l Y_{lm}$  是  $x, y, z$  的  $l$  次多项式, 所以

$$\hat{P}Y_{l,m}(\theta, \varphi) = Y_{l,m}(\pi - \theta, \varphi + \pi)$$

$$= (-1)^l Y_{l,m}(\theta, \varphi)$$

$u_{nlm}(r, \theta, \varphi)$  的宇称为  $(-1)^l$

$$Y_{0,0} = \frac{1}{\sqrt{4\pi}}$$

$$rY_{1,0} = \sqrt{\frac{3}{8\pi}}z$$

$$rY_{1,\pm 1} = \mp \sqrt{\frac{3}{8\pi}}(x \pm iy)$$

$$r^2Y_{2,0} = \sqrt{\frac{5}{16\pi}}(2z^2 - x^2 - y^2)$$

$$r^2Y_{2,\pm 1} = \mp \sqrt{\frac{15}{8\pi}}(x \pm iy)z$$

$$r^2Y_{2,\pm 2} = \mp \sqrt{\frac{15}{32\pi}}(x \pm iy)^2$$

$$r^3Y_{3,0} = \sqrt{\frac{7}{16\pi}}[2z^3 - 3(x^2 + y^2)z]$$

$$r^3Y_{3,\pm 1} = \mp \sqrt{\frac{21}{64\pi}}(x \pm iy)(4z^2 - x^2 - y^2)$$

$$r^3Y_{3,\pm 2} = \sqrt{\frac{105}{32\pi}}(x \pm iy)^2z$$

$$r^3Y_{3,\pm 3} = \mp \sqrt{\frac{35}{64\pi}}(x \pm iy)^3$$

# 反射对称和宇称守恒\*

态矢的空间反射

$$|\psi\rangle \rightarrow \hat{P}|\psi\rangle$$

算符的空间反射

$$\hat{A} \rightarrow \hat{P}\hat{A}\hat{P}^{-1}$$

电磁相互作用反射对称

$$\hat{P}\hat{H}\hat{P}^{-1} = \hat{H}$$

$$[\hat{P}, \hat{H}] = 0$$

$$\frac{d}{dt}A_{fi} = \left\langle \psi_f \left| \frac{\partial \hat{A}}{\partial t} + \frac{1}{i\hbar} [\hat{A}, \hat{H}] \right| \psi_i \right\rangle$$

$$\frac{d\bar{P}}{dt} = \left\langle \frac{\partial \hat{P}}{\partial t} + \frac{1}{i\hbar} [\hat{P}, \hat{H}] \right\rangle = 0$$

反射对称 $\Leftrightarrow$ 宇称守恒

跃迁选择定则

对称性主导理论物理学：

爱因斯坦（广义相对论）杨振宁（规范场）

WS模型、QCD、超对称……

分析力学中的诺特定理：

作用量的可微对称性与守恒量一一对应

人们对自然界的各种对称性，连续的和分立的，一直深信不疑



Emmy Noether



李政道和杨振宁

1956年 弱相互作用宇称不守恒

1957年 诺贝尔物理学奖

先有对称性，后有物理学