

# Introduction

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## What is Functional analysis? A brief introduction

Functional analysis is known as modern analysis or soft analysis.

- In classical analysis (like mathematical analysis, real analysis, complex analysis) We mainly concern the quantitative properties of individual functions. (e.g. the value, the integral, the derivative, estimate)
- In functional analysis we study qualitative properties in space of functions. We will treat functions as "points" in some sort of abstract space, e.g.

$L_2(\mathbb{R})$  = the space of all square-integral functions on  $\mathbb{R}$

Functional analysis is infinite dimensional linear algebra.

- In (finite dimensional) linear algebra we study properties of  $\mathbb{R}_n$  and linear maps from  $\mathbb{R}^n$  to  $\mathbb{R}^m$  (or  $\mathbb{C}^n$  to  $\mathbb{C}^m$ ). For example, one of the major theorems in linear algebra is

**Theorem.** Let  $\mathcal{F} : \mathbb{R}^n \rightarrow \mathbb{R}^n$  be a linear map whose matrix is symmetric. then we can find orthogonal set of vectors  $\vec{v}_1, \dots, \vec{v}_n$  and scalars  $\lambda_1, \dots, \lambda_n$ , so that  $\mathcal{F}\vec{v}_i = \lambda_i \vec{v}_i$ . In particular, any vector  $\vec{v} \in \mathbb{R}^n$  can be written as  $\vec{v} = \alpha_1 \vec{v}_1 + \dots + \alpha_n \vec{v}_n$  and we have  $\mathcal{F}\vec{v} = \alpha_1 \lambda_1 \vec{v}_1 + \dots + \alpha_n \lambda_n \vec{v}_n$ .

- In (linear) functional analysis we study properties of infinite dimensional vector spaces, and "linear maps" between them. For example,

1.  $L^2(\mathbb{R})$  is a vector space:  $f, g \in L^2(\mathbb{R}) \Rightarrow \lambda f + \mu g \in L^2(\mathbb{R})$

2. The map  $\int : L^1(\mathbb{R}) \rightarrow \mathbb{R}, f \rightarrow \int_{\mathbb{R}} |f(x)| dx$  is a linear map.

We will see how to extend the above theorem to infinite dimensional case.

Functional analysis was developed in early 20 centuries, originated by problems in calculus of variation, integral equations and quantum physics. It was deeply influenced by the idea of axiomatization at that time. It has vast applications in PDE, probability, computational math, applied math and in mathematical physics. Note: We mainly work on linear functional analysis.

# 1 Infinite dimensional vector spaces

**Remark.** A vector space (over  $\mathbb{R}$  or  $\mathbb{C}$ )  $V$  is a set, together with two operations:

- $+: V \times V \rightarrow V$
- $\cdot: \mathbb{R}(\text{or } \mathbb{C}) \times V \rightarrow V$

such that all the properties that we are familiar with hold, e.g.

- $x + y = y + x$
- $(x + y) + z = x + (y + z)$
- $x + 0 = x$
- $x + (-x) = 0$
- $\alpha(x + y) = \alpha x + \alpha y$
- $(\alpha + \beta)x = \alpha x + \beta x$
- $1 \cdot x = x$
- $(\alpha\beta)x = \alpha(\beta x)$

A set of vectors  $u_1, \dots, u_n$  is called the basis of  $V$  if every  $x \in V$  can be written uniquely as  $x = \alpha_1 u_1 + \dots + \alpha_n u_n$ . In this case we say  $\dim V = n$ . If  $V$  has no finite basis, then we say  $V$  is infinite dimensional.

**Example.**  $\mathcal{P}$  = the set of all polynomials in variable  $x$ . Easy to see:

- $\mathcal{P}$  is a vector space.
- $\mathcal{P}$  has no finite basis.

*Proof.* If polynomials  $p_1, \dots, p_n$  is any set of polynomials. Let  $N = \max\{\deg(p_1), \dots, \deg(p_n)\}$ . Then any polynomials of degree  $N + 1$  is NOT a linear combination of  $p_i$ 's. So  $p_1, \dots, p_n$  is NOT a basis of  $\mathcal{P}$ . So  $V$  is an infinite dimensional vector space.  $\square$

A Hamel basis for a vector space  $V$  is a set of linearly independent vectors in  $V$  so that every  $x \in V$  can be written uniquely as a finite linear combination of elements in this set.

**Example.**  $\{1, x, x_2, \dots, x_n\}$  is Hamel basis of  $\mathcal{P}$  in previous example.

Every vector space admits a Hamel basis (by the axiom of choice). (see proof in appendix) But for most interesting infinite dimensional vector spaces, its Hamel basis has uncountable cardinality. There are other conceptions of basis for infinitely dimensional vector spaces. We will not study them in this course, except for Hilbert spaces.

**Example.**

- $C^\infty(\mathbb{R}), L^2(\mathbb{R}), C^\infty([0, 1]), L^2([0, 1])$  etc. They all contain  $\mathcal{P}$  in the previous example, with the exception  $L^2(\mathbb{R})$ . But for any  $p(x) \in \mathcal{P}, p(x)e^{-x^2} \in L^2(\mathbb{R})$ .
- $l_2 = \{x = (a_1, a_2, \dots, a_n) \mid a_i \in \mathbb{R}, \sum_{i=1}^\infty a_i^2 < \infty\}$

As in the course linear algebra, one can define the conception of vector subspace and prove theorems like "the intersection of vector subspace is a vector space".

## 2 Metric structures on vector spaces

We would introduce distance between elements in an abstract vector space.

**Definition.** A metric on a vector space  $X$  is a real-valued function  $d : X \times X \rightarrow \mathbb{R}$  so that

1. (positivity)  $d(x, y) \geq 0$  with equality iff  $x = y$ .
2. (symmetry)  $d(x, y) = d(y, x)$
3. (triangle inequality)  $d(x, y) \leq d(x, z) + d(z, y)$

**Remark.** One can define metric on any set.

**Example.**  $X = C([0, 1])$ , the space of all continuous functions on  $[0, 1]$

- $d_0(f, g) = \max_{0 \leq x \leq 1} |f(x) - g(x)|$  is a metric.
- $d_1(f, g) = \left(\int_0^1 |f(x) - g(x)|^2\right)^{\frac{1}{2}}$  is also a metric.

In mathematics, usually compatible structures are more interesting. (Q): What are the metrics on  $X$  that are compatible with vector space operations?

**Definition.** A metric on a vector space  $X$  is called translation-invariant if  $d(x + z, y + z) = d(x, y), \forall x, y, z \in X$ .

Obviously the distances in the above examples are translation-invariant, positive homogeneity.

**Definition.** A metric on a vector space  $X$  is called positively homogeneous if  $d(\alpha x, \alpha y) = |\alpha|d(x, y)$ .

Now suppose  $X$  is a vector space and  $d(\cdot, \cdot)$  is a metric compatible with  $+$  and  $\cdot$ , i.e.

- a)  $d(x + z, y + z) = d(x, y)$
- b)  $d(\alpha x, \alpha y) = |\alpha|d(x, y)$

We define a function  $\|\cdot\| : X \rightarrow \mathbb{R}$  by  $\|x\| = d(x, 0)$ .

**Property.** *The function  $\|\cdot\|$  satisfies*

1.  $\|x + y\| \leq \|x\| + \|y\|$
2.  $\|\alpha x\| = |\alpha| \|x\|$
3.  $\|x\| > 0$  if  $x \neq 0$

*Proof.*

- $\|x + y\| = d(x + y, 0) \leq d(x + y, y) + d(y, 0) = d(x, 0) + d(y, 0) = \|x\| + \|y\|$
- $\|\alpha x\| = d(\alpha x, \alpha 0) = |\alpha| d(x, 0) = |\alpha| \|x\|$
- if  $x \neq 0$ , then  $\|x\| = d(x, 0) > 0$

□

**Definition.** *Let  $X$  be a vector space. A function  $\|\cdot\| : X \rightarrow \mathbb{R}$  is called a norm if it satisfies the property (1), (2), (3), we call the pair  $(X, \|\cdot\|)$  a normed vector space.*

**Property.** *If  $(X, \|\cdot\|)$  is a normed vector space, then the function  $d(x, y) := \|x - y\|$  defines a metric on  $X$  which is compatible with vector space structures. i.e.  $d$  satisfies (1), (2), (3), (a), (b).*

*Proof.* Exercise.

□

**normed vector space = vector space with a compatible metric.**