

# Hard Attack on Penrose 1973

## Weak IMCF + Viscosity Methods

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### Abstract

We attempt a rigorous proof of Penrose 1973 using weak inverse mean curvature flow with viscosity solution techniques. We identify precisely where each approach succeeds or fails, with explicit calculations.

## Contents

### 1 Setup and Strategy

**Goal:** Prove  $M_{\text{ADM}} \geq \sqrt{A(\Sigma_0)/(16\pi)}$  for any trapped surface  $\Sigma_0$ .

**Given:**

- $(M^3, g, k)$  asymptotically flat initial data, DEC holds
- $\Sigma_0$  closed trapped surface:  $\theta^+ = H +_{\Sigma} k \leq 0$ ,  $\theta^- = H -_{\Sigma} k < 0$
- Hence  $H = \frac{1}{2}(\theta^+ + \theta^-) < 0$  on  $\Sigma_0$

**The Obstruction:** Standard IMCF  $\partial_t \Sigma = \frac{\nu}{H}$  undefined when  $H < 0$ .

**Strategy:** Construct a *weak solution* that jumps over the  $H < 0$  region.

### 2 Attempt 1: Elliptic Regularization

#### 2.1 The Regularized Problem

Following Huisken-Ilmanen, we seek  $u : M \setminus \Sigma_0 \rightarrow \mathbb{R}$  with level sets  $\Sigma_t = \{u = t\}$  satisfying a regularized equation.

**Standard IMCF equation:**  $\div \left( \frac{\nabla u}{|\nabla u|} \right) = |\nabla u|$

This is the level set formulation: if  $\Sigma_t = \{u = t\}$ , then  $H = |\nabla u| \div (\nabla u / |\nabla u|)$  and velocity  $= 1/H$ , giving the equation.

**Problem:** When  $H < 0$ , we need  $|\nabla u| < 0$  which is impossible.

#### 2.2 Regularization with Sign Flip

Define the *signed regularization*:

$$\div \left( \frac{\nabla u}{\sqrt{|\nabla u|^2 + \epsilon^2}} \right) = \sqrt{|\nabla u|^2 + \epsilon^2} \quad (1)$$

**Lemma 2.1** (Existence for Regularized Problem). *For each  $\epsilon > 0$ , there exists a unique solution  $u_\epsilon \in C^{2,\alpha}(M \setminus \Sigma_0)$  to (??) with  $u_\epsilon|_{\Sigma_0} = 0$  and  $u_\epsilon \rightarrow \infty$  at spatial infinity.*

*Proof.* This is a quasilinear elliptic equation with uniformly elliptic principal part (the  $\epsilon^2$  removes degeneracy). Standard theory (Gilbarg-Trudinger, Theorem 13.8) gives existence and regularity.

**Ellipticity check:** The linearization at  $u$  has principal symbol

$$a^{ij}(\nabla u) = \frac{\delta^{ij}}{\sqrt{|\nabla u|^2 + \epsilon^2}} - \frac{\partial_i u \partial_j u}{(|\nabla u|^2 + \epsilon^2)^{3/2}}$$

Eigenvalues:  $\lambda_1 = (|\nabla u|^2 + \epsilon^2)^{-3/2}\epsilon^2 > 0$  (in  $\nabla u$  direction),  $\lambda_2 = \lambda_3 = (|\nabla u|^2 + \epsilon^2)^{-1/2}$  (perpendicular). Uniform ellipticity:  $\lambda_{\min}/\lambda_{\max} \geq \epsilon^2/(|\nabla u|^2 + \epsilon^2) > 0$ .  $\square$

### 2.3 The $\epsilon \rightarrow 0$ Limit

**Proposition 2.2** (Compactness). *There exists a subsequence  $\epsilon_j \rightarrow 0$  and  $u \in W_{\text{loc}}^{1,1}(M \setminus \Sigma_0)$  such that  $u_{\epsilon_j} \rightarrow u$  in  $L^1_{\text{loc}}$ .*

*Proof.* We need uniform bounds on  $u_\epsilon$  and  $\nabla u_\epsilon$ .

**Step 1: Maximum principle bound on  $u_\epsilon$ .** The maximum principle gives  $0 \leq u_\epsilon \leq C \cdot \text{dist}(\cdot, \Sigma_0)$  near  $\Sigma_0$ .

At infinity, the equation becomes approximately  $\Delta u \approx |\nabla u|$ , giving  $u_\epsilon \sim \log r$  growth.

**Step 2: Gradient bound.** Multiply (??) by a test function  $\phi^2$  and integrate:

$$\int_M \phi^2 (|\nabla u|^2 + \epsilon^2) dV = \int_M \phi^2 \frac{\nabla u}{\sqrt{|\nabla u|^2 + \epsilon^2}} \cdot \nabla u dV + \text{boundary}$$

This gives  $\int |\nabla u_\epsilon|^2 \leq C$  uniformly in  $\epsilon$ .

**Step 3: Compactness.** By Rellich-Kondrachov,  $W^{1,2} \hookrightarrow L^2$  compactly, giving the result.  $\square$

### 2.4 Critical Analysis: What is the Limit?

*GAP* (Limit Behavior Near  $H < 0$  Region). The limit  $u$  satisfies the IMCF equation weakly where  $|\nabla u| > 0$ . But what happens at points where  $H < 0$ ?

**Possibilities:**

1.  $|\nabla u| = 0$  on a set of positive measure (jump)
2.  $u$  is constant on the  $H < 0$  region
3. The limit develops a discontinuity

**The Problem:** The regularized equation (??) has RHS  $\geq \epsilon > 0$ , so level sets always move outward. But the *rate* depends on the geometry.

In the  $H < 0$  region, the regularized flow moves slowly (velocity  $\sim 1/\epsilon$ ), and as  $\epsilon \rightarrow 0$ , the time to cross this region  $\rightarrow \infty$ .

**Conclusion:** Elliptic regularization does NOT naturally produce the jump we need.

### 3 Attempt 2: Parabolic IMCF with Jump Prescription

#### 3.1 Modified Flow

Consider the flow:

$$\frac{\partial \Sigma_t}{\partial t} = \frac{\nu}{\max(H, \delta)} \quad (2)$$

where  $\delta > 0$  is a cutoff.

**Idea:** When  $H < \delta$ , the surface moves at rate  $1/\delta$ . As  $\delta \rightarrow 0$ , surfaces with  $H \approx 0$  (MOTS) become stationary while  $H < 0$  surfaces move fast.

**Lemma 3.1** (Short-time Existence). *For  $\delta > 0$  fixed, the flow (??) exists for short time  $t \in [0, T_\delta]$ .*

*Proof.* Standard parabolic theory. The velocity  $V = 1/\max(H, \delta) \geq 1/\delta$  is bounded, so the flow is uniformly parabolic.  $\square$

#### 3.2 Area Evolution

**Lemma 3.2** (Area Formula). *Along the modified flow:*

$$\frac{dA}{dt} = \int_{\Sigma_t} \frac{H}{\max(H, \delta)} dA \quad (3)$$

*Proof.* First variation:  $\frac{dA}{dt} = \int H \cdot V dA = \int \frac{H}{\max(H, \delta)} dA$ .  $\square$

**Analysis of (??):**

- Where  $H \geq \delta$ : contribution is  $\int_{H \geq \delta} 1 dA = A(H \geq \delta) > 0$
- Where  $H < \delta$ : contribution is  $\int_{H < \delta} \frac{H}{\delta} dA$ 
  - If  $H > 0$ : positive contribution
  - If  $H < 0$ : **negative contribution**  $= \frac{1}{\delta} \int_{H < 0} H dA < 0$

**GAP** (Sign of Area Derivative). For a trapped surface with  $H < 0$  everywhere:

$$\frac{dA}{dt} = \frac{1}{\delta} \int_{\Sigma_t} H dA < 0$$

**Area still decreases!** The modification doesn't help.

### 4 Attempt 3: Null Flow Approach

#### 4.1 The Null Mean Curvature Flow

Instead of spacelike IMCF, use *null* evolution. Given  $\Sigma_0$ , flow along the outgoing null direction  $\ell^+$  (the null normal with  $\theta^+$  as expansion).

**Definition 4.1** (Null Flow). *The null mean curvature flow evolves  $\Sigma_t$  by:*

$$\frac{\partial \Sigma}{\partial t} = \frac{\ell^+}{\theta^+} \quad (4)$$

when  $\theta^+ < 0$ .

**Key difference from spacelike IMCF:** The denominator is  $\theta^+ = H +_{\Sigma} k$ , not  $H$  alone.

## 4.2 Area Evolution Under Null Flow

**Lemma 4.2** (Null Raychaudhuri). *Along the null flow (??):*

$$\frac{dA}{dt} = \int_{\Sigma_t} \frac{\theta^+}{\theta^+} dA - \text{shear terms} = A(\Sigma_t) - \int \frac{|\sigma|^2}{\theta^+} dA \quad (5)$$

where  $\sigma$  is the null shear.

Wait, this isn't right. Let me recalculate.

**Correct calculation:** Under null flow with velocity  $\phi = 1/\theta^+$  along  $\ell^+$ :

$$\frac{dA}{dt} = \int_{\Sigma_t} \theta^+ \cdot \phi dA = \int_{\Sigma_t} 1 dA = A(\Sigma_t)$$

**This looks promising!** Area grows linearly if we use the null flow.

*GAP* (Existence of Null Flow). The flow (??) is singular when  $\theta^+ = 0$  (MOTS). As the surface approaches the MOTS,  $\theta^+ \rightarrow 0^-$  and velocity  $\rightarrow -\infty$ .

**Problem:** The flow accelerates to infinite speed as it approaches the MOTS, potentially overshooting or becoming ill-defined.

## 4.3 Viscosity Solution for Null Flow

Define the null arrival time function  $\tau : M \rightarrow \mathbb{R}$  by:

$$\tau(p) = \inf\{t \geq 0 : p \in J^+(\Sigma_t)\}$$

where  $J^+$  is the causal future.

**Definition 4.3** (Viscosity Solution).  $\tau$  is a viscosity solution of the null flow if:

1. (*Subsolution*) At any point  $p$  where  $\tau$  has a smooth upper contact  $\phi$ :

$$g^{\mu\nu} \partial_\mu \phi \partial_\nu \phi \leq 0 \quad (\text{null or timelike})$$

2. (*Supersolution*) At any point where  $\tau$  has a smooth lower contact: the analogous inequality.

**Theorem 4.4** (Existence of Viscosity Solution). There exists a unique viscosity solution  $\tau$  with  $\tau|_{\Sigma_0} = 0$ .

*Proof Sketch.* Use Perron's method. Define:

$$\tau(p) = \sup\{v(p) : v \text{ is a subsolution, } v|_{\Sigma_0} \leq 0\}$$

**Step 1:** The function  $\tau_0(p) =$  (Lorentzian distance from  $\Sigma_0$  to  $p$ ) is a subsolution.

**Step 2:** Comparison principle holds for the eikonal equation  $g^{\mu\nu} \partial_\mu \tau \partial_\nu \tau = 0$ .

**Step 3:** The supremum is a viscosity solution.  $\square$

*GAP* (Connection to Area). Even with a viscosity solution  $\tau$ , we need to prove:

$$A(\{\tau = t\}) \geq A(\{\tau = 0\}) = A(\Sigma_0)$$

For smooth null flows, we showed  $dA/dt = A$ , giving  $A(t) = A(0)e^t$ . But for the viscosity solution:

1. Level sets  $\{\tau = t\}$  may not be smooth
2. The “area” of a non-smooth set needs careful definition
3. Monotonicity may fail at jump points

## 5 Attempt 4: Capacity Method

### 5.1 The Key Insight

The Riemannian Penrose inequality (Bray, Huisken-Ilmanen) uses:

$$M_{\text{ADM}} \geq \frac{C(\Sigma)}{4\pi}$$

where  $C(\Sigma)$  is the capacity. For MOTS,  $C(\Sigma^*) = \sqrt{4\pi A(\Sigma^*)}$ .

**Idea:** Find a modified capacity  $\tilde{C}$  such that:

1.  $\tilde{C}(\Sigma_0) \geq \sqrt{4\pi A(\Sigma_0)}$  for trapped  $\Sigma_0$
2.  $M_{\text{ADM}} \geq \tilde{C}(\Sigma_0)/(4\pi)$

### 5.2 Weighted Capacity

**Definition 5.1** (Trapping-Weighted Capacity).

$$\tilde{C}(\Sigma) := \inf_{u \in \mathcal{A}} \int_M w(x)^2 |\nabla u|^2 dV \quad (6)$$

where  $\mathcal{A} = \{u : u|_\Sigma = 1, u \rightarrow 0 \text{ at } \infty\}$  and  $w(x) = e^{-\psi(x)}$  for some function  $\psi$  to be determined.

**Goal:** Choose  $\psi$  so that  $\tilde{C}(\Sigma) \geq \sqrt{4\pi A(\Sigma)}$ .

### 5.3 Euler-Lagrange and Monotonicity

The minimizer  $u$  satisfies:

$$\div(w^2 \nabla u) = 0 \quad \text{in } M \setminus \Sigma$$

**Lemma 5.2.** If  $\psi$  satisfies  $\Delta\psi \geq |\nabla\psi|^2 + f$  for some  $f \geq 0$ , then  $\tilde{C}$  has good monotonicity properties.

*GAP* (Choice of Weight). The natural choice related to trapping would be  $\psi \sim \int \theta^+$ , but:

1.  $\theta^+$  is only defined on surfaces, not in bulk
2. Any extension of  $\theta^+$  to bulk is non-canonical
3. The PDE for  $\psi$  may not have solutions with required sign

## 6 Attempt 5: Jang Equation with Different Blow-up

### 6.1 Review of Jang Approach

The Jang equation  $H_{\text{graph}(f)} - \text{graph}(f) k = 0$  has solutions that blow up at MOTS. The induced metric  $\hat{g}$  on the graph satisfies:

$$R_{\hat{g}} \geq 2(\mu - J(\nu)) \geq 0 \quad (\text{DEC})$$

**The Problem:** At blow-up surface  $\Sigma$ , the jump in mean curvature is:

$$[H_{\hat{g}}] = 2|\Sigma k|$$

This has the WRONG SIGN when  $\Sigma k < 0$ .

## 6.2 Modified Jang Equation

Consider the *dual Jang equation*:

$$H_{\text{graph}(f)} +_{\text{graph}(f)} k = 0 \quad (7)$$

This blows up where  $\theta^- = H - k = 0$  (past MOTS).

**Lemma 6.1.** *Solutions to (??) blow up to  $-\infty$  at surfaces where  $\theta^- = 0$ .*

**Issue:** Trapped surfaces have  $\theta^- < 0$ , so they are NOT blow-up surfaces of the dual Jang equation.

## 6.3 Interpolated Jang

Try interpolating:

$$H_{\text{graph}(f)} - \lambda_{\text{graph}(f)} k = 0 \quad (8)$$

for  $\lambda \in [-1, 1]$ .

Blow-up occurs where  $H - \lambda k = 0$ , i.e., where  $\lambda = H/k$ .

For a trapped surface:  $\theta^+ = H + k \leq 0$  and  $\theta^- = H - k < 0$ .

If  $k > 0$ :  $H/k < 1$  (from  $\theta^- < 0$ ) and  $H/k \leq -1$  (from  $\theta^+ \leq 0$ ), so  $\lambda = H/k \leq -1$ .

If  $k < 0$ :  $H/k > 1$  (from  $\theta^- < 0$ ), so  $\lambda = H/k > 1$ .

*GAP (No  $\lambda \in [-1, 1]$ . Works) For a generic trapped surface, there is no  $\lambda \in [-1, 1]$  such that the  $\lambda$ -Jang equation blows up exactly at that surface.*

## 7 Attempt 6: Direct Spacetime Argument

### 7.1 Setup

Embed  $(M, g, k)$  into spacetime  $(N^4, \bar{g})$ . Let  $\Sigma_0 \subset M$  be trapped.

**Assume:** Weak cosmic censorship holds, so there exists event horizon  $\mathcal{H}^+$ .

**Goal:** Prove  $A(\Sigma_0) \leq A(\mathcal{H}^+ \cap M)$ .

### 7.2 Causal Argument

**Lemma 7.1** (Penrose's Original Observation). *If  $\Sigma_0$  is trapped, then  $\Sigma_0 \subset \overline{J^-(\mathcal{H}^+)}$ .*

*Proof.* By definition, trapped surfaces cannot communicate with  $\mathcal{I}^+$ , hence lie in the black hole region  $B = N \setminus J^-(\mathcal{I}^+)$ . The event horizon  $\mathcal{H}^+ = \partial B$ , so  $\Sigma_0 \subset B \subset \overline{J^-(\mathcal{H}^+)}$ .  $\square$

### 7.3 Area Comparison

We want:  $A(\Sigma_0) \leq A(\mathcal{H}^+ \cap M)$ .

**Attempt via null geodesics:** Fire null geodesics from  $\Sigma_0$  toward  $\mathcal{H}^+$ .

If we use outgoing null geodesics (along  $\ell^+$ ): - Initial expansion  $\theta^+ \leq 0$  - Raychaudhuri:  $\frac{d\theta^+}{d\lambda} = -\frac{1}{2}(\theta^+)^2 - |\sigma|^2 - R_{\mu\nu}\ell^\mu\ell^\nu$  - Under NEC:  $\frac{d\theta^+}{d\lambda} \leq -\frac{1}{2}(\theta^+)^2$  - So  $\theta^+$  becomes more negative, area decreases.

*GAP (Wrong Direction).* Outgoing null geodesics from a trapped surface go INTO the black hole, not toward the horizon. They don't reach  $\mathcal{H}^+$ .

**Attempt via ingoing null geodesics (along  $\ell^-$ ):** - Initial expansion  $\theta^- < 0$  - These go toward the horizon, but  $\theta^-$  is already negative - Area evolution:  $\frac{dA}{d\lambda} = \int \theta^- dA < 0$  - Area DECREASES along ingoing null geodesics too!

*GAP* (Both Directions Fail). For a trapped surface, BOTH null expansions are negative, so area decreases in BOTH null directions. There is no direction in which area increases!

## 8 Attempt 7: Optimal Transport

### 8.1 Riemannian Optimal Transport Review

In Riemannian geometry, if  $\text{Ric} \geq (n-1)K$ , then for probability measures  $\mu_0, \mu_1$  on  $M$ :

$$W_2(\mu_0, \mu_1) \leq (\text{diameter bound})$$

and entropy is convex along geodesics.

### 8.2 Lorentzian Optimal Transport

For spacetime  $(N, \bar{g})$  with timelike Ricci bound, Mondino-Suhr define a Lorentzian Wasserstein distance using the cost  $c(x, y) = -\tau(x, y)^2$  where  $\tau$  is the time separation.

**Theorem 8.1** (Mondino-Suhr, 2022). *If  $(N, \bar{g})$  satisfies timelike curvature-dimension condition  $TCD_p(K, N)$ , then certain entropy functionals are convex along timelike geodesics.*

### 8.3 Application Attempt

Let  $\mu_0$  = uniform measure on  $\Sigma_0$  (trapped surface). Let  $\mu_1$  = uniform measure on  $\mathcal{H}^+ \cap M$  (horizon cross-section).

**Idea:** Use optimal transport to compare  $A(\Sigma_0)$  and  $A(\mathcal{H}^+ \cap M)$ .

*GAP* (Technical Issues). 1. TCD requires **timelike** geodesics between supports. But  $\Sigma_0$  and  $\mathcal{H}^+ \cap M$  may not be connected by timelike geodesics (the horizon is null).

2. The curvature-dimension condition TCD requires something like SEC (strong energy condition), not just DEC or NEC.
3. The entropy functional in Lorentzian OT is not directly related to area.

## 9 Attempt 8: Variational Approach

### 9.1 The Maximum Area Problem

Consider:

$$A_{\max} := \sup\{A(\Sigma) : \Sigma \text{ trapped}, \Sigma \supset \Sigma_0\}$$

If the supremum is achieved by some  $\Sigma_{\max}$ , what can we say?

**Lemma 9.1** (First Variation). *If  $\Sigma_{\max}$  achieves the supremum among trapped surfaces, then:*

$$H = 0 \quad \text{at any point where } \theta^+ = 0, \theta^- < 0$$

*Proof.* Vary in the direction  $\phi\nu$ . First variation of area:  $\delta A = \int H\phi dA$ . For  $\Sigma_{\max}$  to be critical among trapped surfaces, we need  $\delta A = 0$  for all variations preserving trappedness.

If  $\theta^+ = 0$  (boundary of trapped condition) and we vary inward ( $\phi < 0$ ), then  $\theta^+$  can increase (become positive), violating trappedness. So we can only vary outward at such points, giving  $H \geq 0$ . But  $H = \frac{1}{2}(\theta^+ + \theta^-) = \frac{1}{2}\theta^- < 0$  at such points. Contradiction.

Thus  $\Sigma_{\max}$  cannot have  $\theta^+ = 0$  points interior to the trapped region. It must be a MOTS itself.  $\square$

*GAP* (Existence of Maximum). The supremum  $A_{\max}$  may not be achieved!

**Example:** The trapped region may be unbounded, with surfaces of arbitrarily large area. Or the maximizing sequence may “escape to infinity” or develop singularities.

## 10 Synthesis: The Core Obstruction

After all attempts, the obstruction is clear:

**Theorem 10.1** (Fundamental Obstruction). *For a trapped surface  $\Sigma_0$  with  $\theta^+ < 0$  and  $\theta^- < 0$  everywhere:*

1. Any smooth outward evolution decreases area (since  $H < 0$ )
2. Any smooth inward evolution also decreases area (since  $\theta^- < 0$ )
3. Any null evolution decreases area in both directions
4. The Jang equation cannot produce favorable jump

There is NO smooth flow that increases area starting from  $\Sigma_0$ .

### 10.1 What Would Be Needed

To prove Penrose 1973 unconditionally, one would need:

**Option A: Discontinuous Flow** A weak solution theory where:

- Area can “jump up” at certain instants
- The jump is controlled by the geometry
- The final area equals  $A(\text{MOTS})$

**Option B: Different Monotone Quantity** A functional  $F(\Sigma)$  such that:

- $F$  is monotone along some flow
- $F(\Sigma_0) =$  something depending only on  $A(\Sigma_0)$
- $F(\text{MOTS}) =$  something giving  $M_{\text{ADM}} \geq \sqrt{A/(16\pi)}$

**Option C: Direct Argument** A proof that bypasses flows entirely, perhaps using:

- Spinorial methods (Witten-style)
- Index theory
- Algebraic/topological arguments

## 11 A New Attempt: Conformal Flow

### 11.1 Idea

Instead of moving the surface, conformally change the metric to make  $H > 0$ .

Let  $\tilde{g} = e^{2\phi}g$  for some function  $\phi$ . The mean curvature transforms as:

$$\tilde{H} = e^{-\phi}(H + 2\partial_\nu\phi)$$

To make  $\tilde{H} > 0$ , we need  $\partial_\nu\phi > -H/2 > 0$  (since  $H < 0$ ).

### 11.2 The Conformal Factor

Solve:

$$\Delta\phi = f, \quad \phi|_\infty = 0, \quad \partial_\nu\phi|_{\Sigma_0} = -H/2 + \epsilon \quad (9)$$

This is a mixed boundary value problem.

**Lemma 11.1.** *There exists  $\phi$  solving (??) for appropriate  $f$ .*

### 11.3 Effect on Mass

Under conformal change  $\tilde{g} = e^{2\phi}g$ , the ADM mass transforms.

*GAP* (Mass Change). The ADM mass is NOT conformally invariant.

$$\tilde{M} = M + (\text{terms involving } \phi)$$

If  $\phi$  is significant near infinity, the mass can increase or decrease arbitrarily.

## 12 Final Assessment

### Status after hard analysis:

All eight approaches encounter fundamental obstructions:

Approach	Obstruction
Elliptic regularization	Limit doesn't produce jump
Parabolic IMCF	Area still decreases
Null flow	Singular at MOTS, direction issues
Capacity method	No canonical weight function
Modified Jang	No $\lambda$ produces blow-up at trapped surface
Spacetime causal	Both null directions decrease area
Optimal transport	TCD needs SEC, not applicable
Variational	Existence of maximum unproven
Conformal	Changes mass, not helpful

### Honest Conclusion:

The 1973 Penrose conjecture for arbitrary trapped surfaces remains **OPEN**. The fundamental issue is geometric: trapped surfaces have  $H < 0$ , and no known technique can overcome this without additional assumptions.

The most promising directions for future work:

1. Viscosity solutions for null flows with rigorous existence theory
2. New monotone quantities beyond area
3. Spinorial methods avoiding flows entirely