

# Lecture 1: Review of Basic Probability

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# Outline

- Syllabus
- Brief review of basic probability and statistics
  - Why is a random variable?
  - Transformations; independence; expectation
  - Important distributions
  - Some statistics

## Terms

- Sample space; Measure; Random variable
- Transformation; Independence; Expectation; Conditional expectation; Variance retur Standard deviation; Moment Generating Function; Characteristic function
- Common distributions
- Sample mean; Sample variance; Sample distribution
- Moment inequalities

**W**

- We construct an experiment, yet the result of the experiment has many possibilities.
  - Flip a coin, the result can be either head or tail
- Although we can not know the result beforehand, we do have some information about the result.
  - Approximately, there is equal chance for a head and a tail
- Randomness: the **uncertainty** of experiment results

Question: How to describe our **information**?

# Sample space and Measure

- Information 1. Possible outcomes

## Definition 1 (Sample space (Outcome space))

Let  $\Omega$  be a sample space, which is a set containing all possible outcomes.

- Information 2. Probabilities for these possible outcomes
  - $\sigma$  – field  $\mathcal{F}$ : a set of subsets of  $\Omega$  which satisfies 3 rules.
    - Measurable space:  $(\Omega, \mathcal{F})$
    - Event(measurable sets): element of  $\mathcal{F}$
  - Probability measure  $P$ : for any element in the  $\sigma$ -field, assign it a probability, indicating the chance this event will happen
- $(\Omega; \mathcal{F}; P)$  (Probability space, measure space) is our information about the possible outcomes of this experiment. In short, we write it as the sample space  $\Omega$  with probability  $P$ , or just  $\Omega$  if there is no confusion.

## Definition 2 ( $\sigma$ -field)

Let  $\mathcal{F}$  be a collection of subsets of a sample space.  $\mathcal{F}$  is called a  $\sigma$ -field (or  $\sigma$ -algebra) if and only if it has the following properties.

- The empty set  $\phi \in \mathcal{F}$ .
- If  $A \in \mathcal{F}$ , then the complement  $A^c \in \mathcal{F}$
- If  $A_i \in \mathcal{F}, i = 1, 2, \dots$ , then their union  $\cup A_i \in \mathcal{F}$ .

- **Measurable space:**  $(\Omega, \mathcal{F})$
- Event (measurable sets): element of  $\mathcal{F}$
- $\sigma(A) = \{\phi, A, A^c, \Omega\}$ .
- Flip a coin, the result can be either head or tail  
 $\Omega = \{H, T\}, \mathcal{F} = \{\dots\}$

### Definition 3 (Measure)

Let Measurable space  $(\Omega, \mathcal{F})$ ,  $A$  be a measurable space. A set function  $\nu$  defined on  $\mathcal{F}$  is called a measure if and only if it has the following properties.

- $0 \leq \nu(A) \leq \infty$ , for any  $A \in \mathcal{F}$
- $\nu(\emptyset) = 0$
- If  $A_i \in \mathcal{F}$ ,  $i = 1, 2, \dots$ , and  $A_i$ 's are disjoint, i.e.  $A_i \cap A_j = \emptyset$  for any  $i \neq j$ , then  $\nu(\cup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} \nu(A_i)$
- measure space:  $(\Omega, \mathcal{F}, \nu)$
- probability measure  $\nu(\Omega) = 1$ . We usually denote it by  $P$  instead of  $\nu$ ,  $(\Omega, \mathcal{F}, P)$ .
- Flip a coin, the result can be either head or tail  
 $\Omega = \{H, T\}$ ,  $\mathcal{F} = \{\dots\}$ 
  - $\nu(A) = |A|$  the number of elements in  $A \in \mathcal{F}$ .
  - $P(A) = \frac{|A|}{|\Omega|}$

# Random Variables

What is of interest?

- Manufacturers  $\Omega$ : all the combinations of good light bulbs and defective light bulbs. Need: proportion of defective light bulbs from a lot
- Market researchers  $\Omega$ : survey results of all consumers for one product. Need: preference of all consumers about this product, with a scale 1-10.

Our interest:

- Not the details of  $\Omega$ , but a special measurable characteristic of the outcomes!
- A random variable, is a mapping from  $\Omega$  to  $R$ , which draws the measurable characteristic of interest

Example: an opinion poll. 50 people; 1: agree; 0 disagree:

- $\Omega$  has  $2^{50}$  elements.
- interest: the number of people who agree out of 50.  $X$  = number of 1s recorded out of 50.  $\chi = \{0, 1, 2, \dots, 50\}$



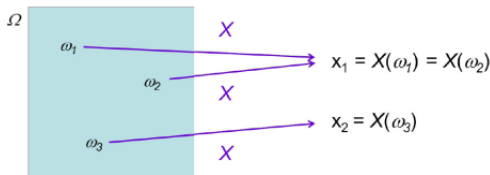
# Random Variable

## Definition 4 (Random Variable)

- Let  $(\Omega, \mathcal{F})$  and  $(\mathcal{R}, \mathcal{B})$  ( $\mathcal{B}$ : Borel  $\sigma$ -field) be measurable spaces
- $X$  is a function from  $\Omega$  to  $\mathcal{R}$ . The function  $X$  is called a **random variable** (r.v.; measurable function) if and only if

$$X^{-1}(B) = \{\omega \in \Omega : X(\omega) \in B\} \subset \mathcal{F}$$

for any  $B \in \mathcal{B}$ .



# Random Variable

- Suppose we have a sample space

$$\Omega = \{\omega_1, \dots, \omega_n\}$$

with a probability function  $P$ .

- We defined a random variable  $X$  with range  $\chi = \{x_1, \dots, x_m\}$ .
- We write

$$P_X(X = x_i) = P(\{\omega_j \in \Omega : X(\omega_j) = x_i\})$$

$$P_X(X \in B) = P(\{\omega \in \Omega : X(\omega) \in B\})$$

where  $P_X$  is an induced probability function  $\chi$ .

- Notations:
  - Upper-case letters  $X, Y, Z \dots$  to denote r.v.'s
  - Lower-case letters  $x, y, z \dots$  to denote their possible values.

# Example: Random variable

## Example 1

- Consider the experiment of tossing a coin three times.
- $H$ : Head;  $T$ : Tail.
- $X$ : the number of heads obtained in the three tosses.

$\omega$	$HHH$	$HHT$	$HTH$	$THH$	$TTH$	$THT$	$HTT$	$TTT$
$X(\omega)$	3	2	2	2	1	1	1	0

- $\chi = \{0, 1, 2, 3\}$ . The induced probability function on  $\chi$  is given by

$x$	0	1	2	3
$P_X(x)$	$\frac{1}{8}$	$\frac{3}{8}$	$\frac{3}{8}$	$\frac{1}{8}$

$$P_X(X = 1) = P(\{HTT, THT, TTH\}) = \frac{3}{8}$$

# Cumulative Density Function

## Definition 5 (Cumulative Density Function)

The cumulative distribution function (CDF) of a random variable is defined by

$$F(x) = P(X \leq x); -\infty < x < \infty$$

For all CDF's;there is

- $F(x)$  is right-continuous. At each  $x$ ,  $\lim_{n \rightarrow \infty} F(y_n) = F(x)$  for any sequence  $y_n \rightarrow x$  with  $y_n > x$ .
- $F(x)$  is non-decreasing.
- $\lim_{x \rightarrow -\infty} F(x) = 0, \lim_{x \rightarrow \infty} F(x) = 1$ .

Any  $F(x)$  satisfying Properties 1-3 is a CDF for some random variable.

# Example: Logistic distribution.

## Example 2

$$F_X(x) = \frac{1}{1 + e^{-x}}$$

- $\lim_{x \rightarrow -\infty} F_X(x) = 0$

- $\lim_{x \rightarrow \infty} F_X(x) = 1$

- 

$$f_X(x) = \frac{d}{dx} F_X(x) = \frac{e^{-x}}{(1 + e^{-x})^2} > 0$$

# Discrete v.s. Continuous r.v.

- If  $X$  is discrete, then its **probability mass function (pmf)** is


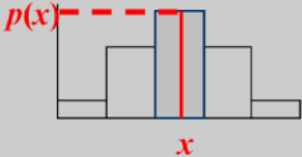

$$p_X(x) = p(x) = P(X = x)$$

- If  $X$  is continuous, then its **probability density function (pdf)** satisfies

$$P(X \in A) = \int_A f_X(x) dx = \int_A f(x) dx = \int_A dF(x)$$

and  $f_X(x) = f(x) = F'(x)$ .

- We say that  $X$  and  $Y$  have the same distribution (i.e.  $X \stackrel{D}{=} Y$ ) if  $P(X \in A) = P(Y \in A)$  for all  $A$ .  $X \stackrel{D}{=} Y$  if and only if  $F_X(t) = F_Y(t)$

RANDOM VARIABLE, $X$		
Type	Discrete	Continuous
Values	A finite/countable set of numbers $x_1, x_2, x_3, \dots$	All numbers in an interval 
Probability	Probability Mass Function, $p$ <i>pmf</i> $P(X = x) = p(x)$ 	Probability Density Function, $f$ <i>pdf</i> $P(a < X < b) = \left[ \begin{array}{l} \text{area} \\ \text{under the} \\ \text{graph of } f \\ \text{over } (a, b) \end{array} \right]$ 

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### Example 3

Suppose  $X$  has a uniform distribution on the interval  $(0, 2\pi)$ , that is

$$f_X(x) = \begin{cases} 1/2\pi, & 0 < x < 2\pi, \\ 0, & \text{otherwise} \end{cases} \quad (2)$$

Consider  $Y = \sin^2(X)$

$$\begin{aligned} P(Y \leq y) &= P(X \leq x_1) + P(x_2 \leq X \leq x_3) + P(X \geq x_4) \\ &= 2P(X \leq x_1) + 2P(x_2 \leq X \leq \pi) \end{aligned} \quad (3)$$

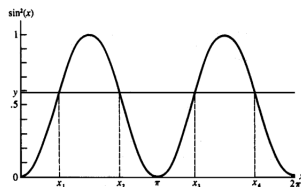


Figure 2.1.1. Graph of the transformation  $y = \sin^2(x)$  of Example 2.1.2

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## Example 4

$X \sim f_X(x) = 1/(0 < x < 1)$ ,  $F_X(x) = x$ .  $Y = g(x) = -\log x$ , find its distribution.

Proof:

- $Y = g(x) = -\log x \Rightarrow x = e^{-y}, g^{-1}(y) = e^{-y}$
- $g$  is decreasing function.

$$\frac{d}{dx}g(x) = \frac{d}{dx}(-\log x) = \frac{-1}{x} < 0, 0 < x < 1$$

•

$$\begin{aligned} F_Y(y) &= P_Y(Y \leq y) = P_X(g(x) \leq y) \\ &= P_X(X \geq g^{-1}(y)) \\ &= 1 - P_X(X \leq g^{-1}(y)) \\ &= 1 - e^{-y} \end{aligned}$$

## Example 5

Let

$$f_X(x) = \frac{1}{(n-1)!\beta^n} x^{n-1} e^{-x/\beta}, 0 < x < \infty$$

be the Gamma pdf  $Y = 1/X$ . Find the pdf of  $Y$

Proof.  $g^{-1}(y) = 1/y, \mathcal{Y} = (0, \infty), |\frac{d}{dy}g^{-1}(y)| = 1/y^2$ . Therefore for all  $y > 0$ ,

$$\begin{aligned} f_Y(y) &= f_X(g^{-1}(y)) \left| \frac{d}{dy}g^{-1}(y) \right| \\ &= \frac{1}{(n-1)!\beta^n} \left(\frac{1}{y}\right)^{n-1} e^{-1/(\beta y)} \frac{1}{y^2} \\ &= \frac{1}{(n-1)!\beta^n} \left(\frac{1}{y}\right)^{n+1} e^{-1/(\beta y)} \end{aligned} \quad (5)$$

- A special case of a pdf known as the inverted Gamma distribution.

## Theorem 7

Let  $X$  have pdf  $f_X(x)$ , let  $Y = g(X)$ . Suppose there exists a partition  $A_0, A_1, \dots, A_k$  such that  $P(X \in A_0) = 0$  and  $f_X(x)$  is continuous on each  $A_i$ .

$$P(X \in \cup_{i=1}^k A_i) = 1.$$

Futher, we have  $g(\cdot)$  is monotone if restricted to  $A_i, i = 1, 2, \dots, k$ . Let

$$g_i^{-1}(y) = \{x \in A_i : g(x) = y\}$$

and assume  $g_i^{-1}(y)$  has continuous derivative on  $\mathcal{Y}$  for each  $i$ . Then

$$f_Y(y) = \begin{cases} \sum_{i=1}^k f_X(g_i^{-1}(y)) \left| \frac{d}{dy} g_i^{-1}(y) \right|, & y \in \mathcal{Y}, \\ 0, & \text{otherwise} \end{cases}$$

- **Remark** Unfortunately, I found the above Theorem has very little practical use.

## Example 6

Let  $X \sim N(0, 1)$ ,  $Y = X^2$ , we may use the above theorem to find the pdf of  $Y$ .

Proof:

- $g(x) = x^2$  is monotone on  $(-\infty, 0)$  and on  $(0, \infty)$ .
- $\mathcal{Y} = (0, \infty)$ .

$$A_0 = \{0\}$$

$$A_1 = (-\infty, 0), g_1(x) = x^2, g_1^{-1}(y) = -\sqrt{y}$$

$$A_2 = (0, \infty), g_2(x) = x^2, g_2^{-1}(y) = \sqrt{y}$$

The pdf  $Y$  is

$$f_Y(y) = \frac{d}{dy} F_Y(y) = \Phi(\sqrt{y}) \frac{1}{2} \frac{1}{\sqrt{y}} + \Phi(-\sqrt{y}) \frac{1}{2} \frac{1}{\sqrt{y}} = \frac{1}{\sqrt{y}} \phi(\sqrt{y})$$

# Probability integral transform

## Theorem 8 (Probability integral transform)

Let  $X$  have continuous cdf  $F_X(x)$  and define the random variable  $Y$  as  $Y = F_X(X)$ . Then  $Y$  is uniformly distributed on  $(0, 1)$ , that is

$$P(Y \leq y) = y, 0 < y < 1.$$

- $F_X^{-1}(\tau) = \inf\{x : F_X(x) \geq \tau\}$
- Proof:

$$\begin{aligned} P_Y(Y \leq y) &= P_X(F_X(x) \leq y) \\ &= P_X(F_X^{-1}[F_X(x)] \leq F_X^{-1}(y)) \\ &= P_X(X \leq F_X^{-1}(y)) \\ &= F_X(F_X^{-1}(y)) \\ &= y \end{aligned}$$

## Theorem 9

Two r.v.'s  $X$  and  $Y$  are *independent* if and only if

$$P(X \in A; Y \in B) = P(X \in A)P(Y \in B)$$

for all  $A$  and  $B$ .

- $F(x, y) = F(x)F(y)$  for any  $x$  and  $y$ ,  $f(x, y) = f(x)f(y)$  or  $p(x, y) = p(x)p(y)$
- When  $X$  and  $Y$  are independent,  $h(X)$  and  $g(Y)$  are also independent, if  $h$  and  $g$  are well-defined functions.



# Expection

- Definition:

$$E(X) = \sum_x xp(x)$$

$$E(X) = \int_{-\infty}^{\infty} xf(x)dx$$

- Properties:

- $E(g(X)) = \int_{-\infty}^{\infty} g(x)f(x)dx$
- $E(g(X, Y)) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g(x, y)f(x, y)dxdy$
- If  $X_1, \dots, X_n$  are independent, then

$$E\left(\prod_{i=1}^n X_i\right) = \prod_{i=1}^n E(X_i)$$

- Example 2.2.2

$X \sim \exp(\lambda),$

$$f_X(x) = \frac{1}{\lambda} e^{-x/\lambda} x > 0.$$

Then  $E[X] = \lambda.$

- Example 2.2.3

$X \sim \text{Binomial}(n, p),$

$$f_X(x) = \binom{n}{x} p^x (1-p)^{n-x} \quad x = 0, 1, \dots.$$

Then  $E[X] = np.$

- Example 2.2.4

$X \sim \text{Cauchy},$

$$f_X(x) = \frac{1}{\pi} \cdot \frac{1}{1+x^2} \quad -\infty < x < \infty.$$

Then  $E[X]$  is not defined!(or do not exist).

## • Mixed normal distribution

$$X = 0.5N(-1, 0.5^2) + 0.5N(1, 0.5^2)$$

\_\_\_\_\_ Mixed normal distribution \_\_\_\_\_

```
1 rm(list=ls())
2 n <- 1000
3 x <- rnorm(n, mean = ifelse(comp == 0, -1, 1),
4 sd = ifelse(comp == 0, 0.5, 0.5))
5 plot(density(x), main="")
```

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- **Theorem 2.2.5** Let  $X$  be a r.v. and let  $a, b$  and  $c$  be constants. Then for any functions  $g_1(x)$  and  $g_2(x)$  whose expectations exist.

$$(1) E[ag_1(X) + bg_2(X) + c] = aE[g_1(X)] + bE[g_2(X)] + c$$

$$(2) \text{ If } g_1(x) \geq 0 \text{ for all } x, \text{ then } E[g_1(X)] \geq 0.$$

$$(3) \text{ If } g_1(x) \geq g_2(x) \text{ for all } x, \text{ then } E[g_1(X)] \geq E[g_2(X)]$$

$$(4) \text{ If } a \leq g_1(x) \leq b \text{ for all } x, \text{ then } a \leq E[g_1(x)] \leq b$$

- **Example 2.2.6**

$E(X)$  is the "center" of a distribution (or its r.v.) in the sense that

$$\min_b E(X - b)^2 = E[X - EX]^2.$$

- Homework

$$\min_b E_{\rho_\tau}(X - b)$$

**Remark:**  $\rho_\tau(t) = \tau t I(t \geq 0) + (\tau - 1) t I(t \leq 0).$

# Variance & Standard Deviation

- Motivation: Describe the "spread" of r.v.
- Definition.  $Var(x) = E[(x - \mu)^2]$ , where  $\mu = E(X)$ ,  $sd(X) = \sqrt{Var(x)}$ .
- Properties.
  - $Var(X) = E(X^2) - [E(X)]^2$
  - If  $X_1, \dots, X_n$  are independent, then

$$Var\left(\sum_{i=1}^n X_i\right) = \sum_{i=1}^n Var(X_i)$$

- The covariance is

$$Cov(X, Y) = E[(X - E(X))(Y - E(Y))] = E(XY) - E(X)E(Y)$$

and the **correlation coefficient** is

$$Corr(X, Y) = \frac{Cov(X, Y)}{\sqrt{Var(X)Var(Y)}}$$

- For any two r.v.s with variance existed,

$$Var(X + Y) = Var(X) + Var(Y) + 2Cov(X, Y)$$

# Conditional Expectation

- Conditional Expectation of  $X$  when  $Y$  is given as  $y$  is that
  - $E(X|Y = y) = \sum_x x p_{X|Y}(X|Y)$  for discrete r.v.
  - $E(X|Y = y) = \int_{-\infty}^{\infty} x f_{X|Y}(x|Y) dx$  for cont.r.v.
  - Interpretation: Note that  $X|Y = y$  is a new r.v.,  $E(X|Y = y)$  is the expectation on this r.v.
- Law of Total Expectation

$$E[E(X|Y)] = E(X)$$

- Law of Total Variance

$$\text{Var}(X) = \text{Var}[E(X|Y)] + E[\text{Var}(X|Y)]$$

## Theorem 10

If  $X$  and  $Y$  are any two r.vs, then

$$E(X) = E[E(X|Y)]$$

Proof:

$$\begin{aligned} EX &= \int \int xf(x, y) dx dy \\ &= \int \left[ \int xf(x|y) dx \right] f_Y(y) dy \\ &= \int E(X|y) f_Y(y) dy = E[E(X|Y)] \end{aligned}$$

In general, the conditional expectation  $E[X|Y]$  can be defined as r.v.  $g(Y)$  such that

$$E[(X - g(Y))^2] = \inf_{\text{among all reasonable function } h} E[(X - h(Y))^2]$$

or  $E[X|Y]$  is the function of  $Y$  which is "closest" to  $X$  in terms of mean square error.

## Theorem 11

*$Y \sim$  Number of eggs lay by a mother fish, and  $X \sim$  Number of survivors(young fish). On the average, how many eggs will survive?*

Then it is reasonable to assume

$$Y \sim \text{Poisson}(\lambda)$$

$$X|Y \sim \text{Binomial}(Y, p)$$

So,

$$\begin{aligned} EX &= E[E(X|Y)] \\ &= E(pY) \\ &= p\lambda \end{aligned}$$



## Example 7

$$X|Y \sim \text{Binomial}(Y, p)$$

$$Y|\Lambda \sim \text{Poisson}(\Lambda)$$

$$\Lambda \sim \text{exponential}(\beta)$$

Proof:

$$\begin{aligned} E[X] &= E[E(X|Y)] \\ &= pE(Y) \\ &= pE[E(Y|\Lambda)] \\ &= pE[\Lambda] \\ &= p\beta. \end{aligned}$$

## Theorem 12

*For any two random variables  $X$  and  $Y$ .*

$$\text{Var}(X) = E[\text{Var}(X|Y)] + \text{Var}[E(X|Y)]$$

*provided that the expectation exist.*

Proof:

$$\begin{aligned} \text{Var}(X) &= E[X - E(X|Y) + E(X|Y) - EX]^2 \\ &= E\{[X - E(X|Y)]^2 + [E(X|Y) - EX]^2 \\ &\quad + 2[X - E(X|Y)][E(X|Y) - EX]\} \\ &= E[X - E(X|Y)]^2 + E[E(X|Y) - EX]^2 \\ &= E[\text{Var}(X|Y)] + \text{Var}[(EX|Y)] \end{aligned}$$

# Moment Generating Function and Characteristic Function

## • Moment Generating Function(MGF)

- Definition:  $M_X(t) = E(e^{tX})$ : a function of  $t$ , not r.v.
- If  $Y = aX + b$ ,  $M_Y(t) = e^{bt} M_X(at)$
- If  $X$  and  $Y$  are independent, then  $M_{X+Y}(t) = M_X(t) M_Y(t)$

## • Characteristic Function

- Definition:  $\phi_X(t) = E[e^{itX}]$ : a function of  $t$ ;  $i = \sqrt{-1}$ .
- Bounded:  $|\phi(t)| \leq 1$
- If  $X$  and  $Y$  are independent, then  $\phi_{X+Y}(t) = \phi_X(t) \phi_Y(t)$ .

An example of two distribution functions but with the same moments.

### Example 8

Consider the two pdfs given by

$$f_1(x) = \frac{1}{\sqrt{2\pi x}} e^{-(\log x)^2/2}, 0 \leq x < \infty,$$

$$f_2(x) = f_1(x)[1 + \sin(2\pi \log x)], 0 \leq x < \infty.$$

Then it can be shown if  $X_1 \sim f_1(x)$ ,

$$E[X_1^r] = e^{r^2/2}, r = 0, 1, \dots$$

Now suppose that  $X_2 \sim f_2(x)$ , we have for  $r = 0, 1, \dots$

$$\begin{aligned} E[X_2^r] &= \int_0^\infty x^r f_1(x)[1 + \sin(2\pi \log x)] dx \\ &= E[X_1^r] + \int_0^\infty x^r f_1(x) \sin(2\pi \log x) dx \end{aligned}$$

$$\begin{aligned}
& \int_0^\infty x^r \frac{1}{\sqrt{2\pi \log x}} dx \\
&= \int_{-\infty}^\infty e^{(y+r)r} \frac{1}{\sqrt{2\pi}} e^{-(y+r)^2/2} \sin(2\pi(y+r)) dy \\
&= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^\infty e^{-\frac{1}{2}(y^2-r^2)} \sin(2\pi y) dy \cdot \cos(2\pi r) \\
&\quad + \frac{1}{\sqrt{2\pi}} \int_{-\infty}^\infty e^{-\frac{1}{2}(y^2-r^2)} \cos(2\pi y) dy \cdot \sin(2\pi r) \\
&= 0 \quad r = 0, 1, \dots
\end{aligned}$$

since  $e^{-\frac{1}{2}(y^2-r^2)} \sin(2\pi y)$  is an odd function.

However, we have the following theorem.

### Theorem 13

*Let  $F_X(x)$  and  $F_Y(y)$  be two cdfs all of whose moments exist.*

*(a) If  $F_X$  and  $F_Y$  have bounded support, then  $F_X(u) = F_Y(u)$  for all  $u$  iff  $EX^r = EY^r$  for all  $r = 0, 1, 2, \dots$*

*(b) If the moment generating functions exist and  $M_X(t) = M_Y(t)$  for all  $t$  in some neighborhood of 0, then  $F_X(u) = F_Y(u)$  for all  $u$ .*

# Differentiating Under An Integral Sign

If  $a, b$  are finite and  $f(x, \theta)$  is differential with respect to  $\theta$ . Then we have

$$\frac{d}{d\theta} \int_a^b f(x, \theta) dx = \int_a^b \frac{\alpha}{\alpha\theta} f(x, \theta) dx$$

But in statistics, we often need to evaluate  $\frac{d}{d\theta} \int_{-\infty}^{\infty} f(x, \theta) dx$ , which may or may not be  $\int_{-\infty}^{\infty} \frac{\alpha}{\alpha\theta} f(x, \theta) dx$ .

## Theorem 14

Suppose the function  $h(x, y)$  is continuous at  $y_0$  for each  $x$ , and there exists a function  $g(x)$  satisfying

a)  $|h(x, y)| \leq g(x)$ , for all  $x$  and  $y$ ;

b)  $\int_{-\infty}^{\infty} g(x) dx < \infty$ .

Then

$$\lim_{y \rightarrow y_0} \int_{-\infty}^{\infty} h(x, y) dx = \int_{-\infty}^{\infty} \lim_{y \rightarrow y_0} h(x, y) dx$$

Apply the above Theorem to the differentiation case, then we have

- **Theorem 2.4.3** Suppose  $f(x, \theta)$  is differentiable at  $\theta = \theta_0$ , and there exists a function  $g(x, \theta_0)$  and a constant  $\delta > 0$  such that

a)  $\left| \frac{f(x, \theta_0 + \Delta) - f(x, \theta_0)}{\Delta} \right| \leq g(x, \theta_0)$ , for all  $x$  and  $|\Delta| \leq \delta$ ;

b)  $\int_{-\infty}^{\infty} g(x, \theta_0) dx < \infty$ . Then

$$\frac{d}{d\theta} \int_{-\infty}^{\infty} f(x, \theta) dx \Big|_{\theta=\theta_0} = \int_{-\infty}^{\infty} \left[ \frac{\partial}{\partial \theta} f(x, \theta) \Big|_{\theta=\theta_0} \right] dx \quad (*)$$

- **Corollary** Suppose that there exists  $\delta > 0$  and function  $g(x, \theta)$  such that  $\left| \frac{\partial}{\partial \theta} f(x, \theta) \Big|_{\theta=\theta'} \right| \leq g(x, \theta)$ , for all  $\theta'$  with  $|\theta' - \theta| < \delta$ , and  $\int_{-\infty}^{\infty} g(x, \theta) dx < \infty$ . Then  $(*)$  holds.



- **Remark** Finding bound  $g(x, \theta)$  is cumbersome. We need to know that differentiating under the integral sign is not always automatic. In most situations, we just do it!!
- **Example 2.4.6**  $X \sim N(\mu, 1)$ ,

$$M_X(t) = E(e^{tX}) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{tx} e^{-(x-\mu)^2/2} dx,$$

$$\frac{d}{dt} M_X(t) = \frac{d}{dt} E(e^{tX}) = E\left(\frac{\alpha}{\alpha t} e^{tX}\right) = E(X e^{tX}).$$

For the exchange of operation of **differentiation** and **summation**, we have

- **Theorem 2.4.8** Suppose that the series  $\sum_{x=0}^{\infty} h(\theta, x)$  converges for all  $\theta$  in an interval  $(a, b)$  and
  - $\frac{\alpha}{\alpha\theta} h(\theta, x)$  is continuous in  $\theta$  for each  $x$ ;
  - $\sum_{x=0}^{\infty} \frac{\alpha}{\alpha\theta} h(\theta, x)$  converges uniformly on every closed bounded subinterval of  $(a, b)$ .

Then

$$\frac{d}{d\theta} \sum_{x=0}^{\infty} h(\theta, x) = \sum_{x=0}^{\infty} \frac{\alpha}{\alpha\theta} h(\theta, x)$$

- **Theorem 2.4.10** Suppose that the series  $\sum_{x=0}^{\infty} h(\theta, x)$  converges uniformly on  $[a, b]$  and that, for each  $x$ ,  $h(\theta, x)$  is a continuous function of  $\theta$ . Then

$$\int_a^b \sum_{x=0}^{\infty} h(\theta, x) d\theta = \sum_{x=0}^{\infty} \int_a^b h(\theta, x) d\theta$$

# Important Distribution

- Discrete distributions:

- Bernoulli r.v.:  $X \sim \text{Bernoulli}(p)$ ,  $p(1) = p$ ,  $p(0) = 1 - p$ ,  $p(x) = 0$  if  $x \neq 0$  and  $x \neq 1$ . It can be written as  $p^x(1-p)^{1-x}$  for  $x = 0, 1$ .

- Binomial r.v.:  $X \sim \text{Binomial}(n, p)$ ,  $p(x) = \binom{n}{x} p^x q^{n-x}$ ,  $x = 0, 1, 2, \dots, n$ . Summation of  $n$  Bernoulli random variables.

- Poisson r.v.:  $X \sim \text{Pois}(\lambda)$ ,  $p(x) = \frac{\lambda^x}{x!} e^{-\lambda}$ ,  $x = 0, 1, 2, \dots, n$ .

- Continuous distribution

- Uniform r.v.:  $X \sim \text{Unif}(a, b)$ ,  $f(x) = \frac{1}{b-a}$ ,  $x \in (a, b)$
- Exponential r.v.:  $X \sim \text{Exp}(\lambda)$ ,  $f(x) = \lambda e^{-\lambda x}$
- Normal r.v.:  $X \sim N(\mu, \sigma^2)$ ,  $f(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)$

# Multivariate Normal Distribution

- The  $d$  random vector  $X \sim N(\mu, \Sigma)$ ,

$$f(x) = \frac{1}{(2\pi)^{d/2} |\Sigma|^{\frac{1}{2}}} \exp\left(-\frac{1}{2}(x - \mu)^T \Sigma^{-1}(x - \mu)\right)$$

- $AX + b \sim N(A\mu + b, A\Sigma^{-1}A^T)$
- Conditional distribution.

$$X = \begin{pmatrix} X_1 \\ X_2 \end{pmatrix}$$

$$\mu = \begin{pmatrix} \mu_1 \\ \mu_2 \end{pmatrix}$$

$$\Sigma = \begin{pmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{pmatrix}$$

then

$$X_1 | Y_2 \sim N(\mu_1 + \Sigma_{11} \Sigma_{22}^{-1} (Y_2 - \mu_2), \Sigma_{11} - \sigma_{12} \Sigma_{22}^{-1} \Sigma_{21})$$

# Stastic

- Sample mean  $\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$
- Sample variance:  $S_n^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X}_n)^2$
- Sampling distribution of  $\bar{X}_n$ :  $G_n(t) = P(\bar{X}_n \leq t)$

When it is normal:

- If  $X \sim N(\mu, \Sigma^2)$ , then  $\bar{X}_n$  and  $S_n^2$  are independent,

$$\bar{X}_n \sim N\left(\mu, \frac{\sigma^2}{n}\right)$$

$$\frac{(n-1)S_n^2}{\sigma^2} \sim \chi_{n-1}^2$$

# Moment inequalities

## Lemma 15

Let  $a$  and  $b$  be any two positive numbers, and let  $p$  and  $q$  be any positive numbers satisfying

$$\frac{1}{p} + \frac{1}{q} = 1$$

. Then

$$\frac{1}{p}a^p + \frac{1}{q}b^q \geq ab$$

with equality holds if and only if  $a^p = b^q$ .

- **Proof:** Consider for fixed  $b$  (or  $a$ ),

$$g(a) = \frac{1}{p}a^p + \frac{1}{q}b^q - ab$$

with equality if and only if  $a^p = b^q$ .

## Theorem 16

Let  $X$  and  $Y$  be any two random variables. Let  $p$  and  $q$  be any positive numbers satisfying

$$\frac{1}{p} + \frac{1}{q} = 1$$

Then

$$|E(XY)| \leq E|XY| \leq (E|X|^p)^{\frac{1}{p}} (E|Y|^q)^{\frac{1}{q}}$$

Proof: In the inequality (1), let

$$a = \frac{|X|}{(E|X|^p)^{\frac{1}{p}}}, b = \frac{|Y|}{(E|Y|^q)^{\frac{1}{q}}}$$

After some simplification, and take expectation on the two sides of the inequality. The result can be obtained.

- Theorem 4.7.3(Cauchy-Schwarz Inequality)

For any two random variables  $X$  and  $Y$ ,

$$|E(XY)| \leq E|XY| \leq (E|X|^2)^{\frac{1}{2}}(E|Y|^2)^{\frac{1}{2}}$$

- Example 4.7.4 (Covariance Inequality)

If  $X$  and  $Y$  have means  $\mu_X$  and  $\mu_Y$ , and variances  $\sigma_X^2$  and  $\sigma_Y^2$ , respectively. We can apply the Cauchy-Schwarz Inequality to get

$$(\text{Cov}(X, Y))^2 \leq \sigma_X^2 \sigma_Y^2$$



- **Example**

Let  $p > 1$ , then apply Holders Inequality. For any random variables  $X$ ,

$$E|X| \leq \{E|X|^p\}^{\frac{1}{p}}$$

If  $1 < r < s$ , we have (Liapounovs Inequality)

$$(E|X|^r)^{\frac{1}{r}} \leq (E|X|^p)^{\frac{1}{p}}$$

- **Proof** Let  $q$  be such that  $\frac{1}{p} + \frac{1}{q} = 1$ , then

$$E|X| = E|X| \cdot 1 \leq (E|X|^p)^{\frac{1}{p}} (E1^q)^{\frac{1}{q}} = (E|X|^p)^{\frac{1}{p}}$$

- **Proof** Let  $s$  be such that  $s = pr$ , then  $s > 1$ .

$$E(|X|^r) \leq (E|X|^s)^{\frac{1}{p}}$$

## Theorem 17 (Minkowskis Inequality)

Let  $X$  and  $Y$  be any two random variables. Then for  $1 < p < \infty$

$$[E|X + Y|^p]^{\frac{1}{p}} \leq (E|X|^p)^{\frac{1}{p}} + (E|Y|^p)^{\frac{1}{p}}$$

Proof:

$$\begin{aligned} E|X + Y|^p &= E(|X + Y||X + Y|^{p-1}) \\ &\leq E(|X||X + Y|^{p-1}) + E(|Y||X + Y|^{p-1}) \end{aligned} \quad (6)$$

Using Holder's Inequality,

$$E(|X||X + Y|^{p-1}) \leq (E|X|^p)^{\frac{1}{p}} [E|X + Y|^{q(p-1)}]^{\frac{1}{q}} \quad (7)$$

where  $q$  is such that  $\frac{1}{p} + \frac{1}{q} = 1$  or  $\frac{1}{q} = 1 - \frac{1}{p}$ , i.e.  $q = \frac{p}{p-1}$  or  $q(p-1) = p$ . Similarly,

$$E(|Y||X + Y|^{p-1}) \leq (E|Y|^p)^{\frac{1}{p}} [E|X + Y|^{q(p-1)}]^{\frac{1}{q}} \quad (8)$$

So combine (6) and (8) with (7), divide through by  $[E(|X + Y|^{q(p-1)})]^{\frac{1}{q}}$ , we have

$$E|X + Y|^p \leq (E|X + Y|^p)^{\frac{p-1}{p}} [(E|X|^p)^{\frac{1}{p}} + (E|Y|^p)^{\frac{1}{p}}]$$

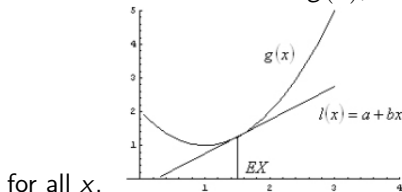
## Theorem 18 (Jensens Inequality)

For any random variable  $X$ , if  $g(x)$  is a convex function, then

$$Eg(X) \geq g(EX)$$

- Equality holds if and only if, for any line  $a + bx$  that is tangent to  $g(x)$  at  $x = EX$ ,  $P(g(X) = a + bX) = 1$ .
- If  $g(x)$  is linear,  $g(EX) = a + bEX = Eg(X)$ .

**Remark** For any twice differentiable function  $g(x)$ , it is convex if  $g''(x) \geq 0$



for all  $x$ .

### Example 9 (An inequality for means)

Let  $a_1, a_2, \dots, a_n$  be  $n$  non-negative numbers. Define

$$a_A = \frac{1}{n}(a_1 + a_2 + \dots + a_n)$$

$$a_G = [a_1 a_2 \dots a_n]^{1/n} a_H = \frac{1}{\frac{1}{n}(\frac{1}{a_1} + \dots + \frac{1}{a_n})}$$

An inequality relating these means is

$$a_H \leq a_G \leq a_A$$

**Remark** The above inequality gives a reason for Maximum Likelihood Estimation (MLE).

Proof: Let  $X$  be a random variable with range  $a_1, \dots, a_n$ , and  $P(X = a_i) = 1/n$ ,  $n = 1, \dots, n$ . Since  $\log x$  is a concave function,  $E \log X \leq \log(EX)$ , hence

$$\begin{aligned} \log a_G &= \frac{1}{n} \sum_{i=1}^n \log a_i = E \log X \leq \log(EX) \\ &= \log\left(\frac{1}{n} \sum_{i=1}^n a_i\right) = \log a_A \end{aligned}$$

So,  $a_G \leq a_A$ . Furthermore,

$$\begin{aligned} \log \frac{1}{a_H} &= \log\left(\frac{1}{n} \sum_{i=1}^n \frac{1}{a_i}\right) = E \log \frac{1}{X} \geq E\left(\log \frac{1}{X}\right) = -\log(EX) \\ &= -\log a_G = \log\left(\frac{1}{a_G}\right). \end{aligned}$$

So,  $a_G \geq a_H$ .

# Markovs Inequality

## Theorem 19 (Markovs(Chebyshevs) Inequality)

- If  $g$  is strictly increasing and positive on  $(0, \infty)$ ,  $g(x) = g(-x)$ .
- $X$  is a r.v. such that  $E[g(X)] < \infty$ , then for each  $a > 0$

$$P(|X| \geq a) \leq \frac{E[g(X)]}{g(a)}$$

Proof:

$$\begin{aligned} E[g(X)] &\geq E[g(X)I_{\{g(X) \geq g(a)\}}] \\ &\geq g(a)E[I_{\{g(X) \geq g(a)\}}] \\ &= g(a)E[I_{|X| \geq a}] \\ &= g(a)P(|X| \geq a) \end{aligned}$$

# Some special cases: Markovs Inequality

$$g(x) = |x| \Rightarrow P(|X| \geq a) \leq \frac{E|X|}{a}$$

$$g(x) = x^p \Rightarrow P(|X| \geq a) \leq \frac{E|g(X^p)|}{a^p}$$

$$g(x) = x^2 \Rightarrow P(|X - EX| \geq a) \leq \frac{Var(X)}{a^2}$$

$$g(x) = e^{t|x|} \Rightarrow P(|X| \geq a) \leq \frac{E[e^{t|X|}]}{e^{ta}}$$

for some constant  $t \geq 0$

# Homework

- If  $\mu = EX \geq 0$  and  $0 \leq \lambda \leq 1$ , then

$$P(X > \lambda\mu) \geq \frac{(1 - \lambda)^2 \mu^2}{EX^2}$$

Consequently, if  $E|Y| = 1$ ,  $P(|Y| > \lambda) \geq (1 - \lambda) \geq (1 - \lambda)^2 / EY^2$  (This gives a lower bound complementing Chebyshevs inequality.)





Thanks !