Lecture 7 Point Estimation

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Outline

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- Methods of Finding Estimators
 - Method of Moments
 - Maximum Likelihood Estimations
 - Bayes Estimators
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- Methods of Evaluating Estimators
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Introduction

• Suppose X_1, X_2, \cdots, X_n is a sample from $f(x|\theta)$, we want to find a statistic $W(X_1, X_2, \cdots, X_n)$ which is an estimator of θ .

Let X_1, X_2, \dots, X_n be a sample from $f(x|\theta_1, \dots, \theta_k)$. Define

$$m_{1} = \frac{1}{n} \sum_{i=1}^{n} X_{i}^{1}, \qquad \mu_{1} = EX^{1}$$

$$m_{2} = \frac{1}{n} \sum_{i=1}^{n} X_{i}^{2}, \qquad \mu_{2} = EX^{2}$$

$$\vdots$$

$$m_{k} = \frac{1}{n} \sum_{i=1}^{n} X_{i}^{k}, \qquad \mu_{k} = EX^{k}$$

Then we equate $m_1 = \mu_1(\theta_1, \dots, \theta_k)$, $m_2 = \mu_2(\theta_1, \dots, \theta_k)$, \dots , $m_k = \mu_k(\theta_1, \dots, \theta_k)$ to find $\hat{\theta}_1, \dots, \hat{\theta}_k$.

Example 7.2.1 (Normal Method of Moments)

If X_1 , X_2 , \cdots , X_n , $\sim N(\theta, \sigma^2)$. Then we have $\mu_1 = \theta$, $\mu_2 = \sigma^2 + \theta^2$. Using method of moments, we equate

$$\bar{X} = \theta, \qquad \frac{1}{n} \sum_{i=1}^{n} X_i^2 = \sigma^2 + \theta^2$$

$$\implies \hat{\theta} = \bar{X}, \qquad \hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^{n} (X_i - \bar{X})^2$$

Example 7.2.2 (Binomial Method of Moments)

Let X_1, X_2, \dots, X_n be i.i.d. Bin(k, p), where both k and p are unknown. Equate the first two moments:

$$\bar{X} = kp$$

$$\frac{1}{n} \sum_{i=1}^{n} X_i^2 = kp(1-p) + k^2 p^2.$$

After a little algebra, we have

$$\hat{k}=rac{ar{X}^2}{ar{X}-(1/n)\sum(X_i-ar{X})^2}$$
 and $\hat{p}=ar{X}/\hat{k}.$

Maximum Likelihood Estimations

Let
$$X_1, X_2, \cdots, X_n$$
 be i.i.d. from $f(x|\theta_1, \cdots, \theta_k)$. Let $L(\boldsymbol{\theta}|\boldsymbol{x}) = L(\theta_1, \cdots, \theta_k|x_1, \cdots, x_k) = \prod_{i=1}^n f(x_i|\theta_1, \cdots, \theta_k)$ be the likelihood function.

Definition 7.2.4

For each sample point x, let $\hat{\theta}(x)$ be a parameter value at which $L(\theta|x)$ attains its maximum as a function of θ , with x held fixed. Then $\hat{\theta}(x)$ is a maximum likelihood estimator of θ .

Remark Sometime maximizing $l(\theta|x) = \log(L(\theta|x))$ is much easier than maximizing $L(\theta|x)$.

• Theorem 7.2.10 (Invariance Property of MLE) If $\hat{\theta}$ is the MLE of θ , then for any function $\tau(\theta)$, the MLE of $\tau(\hat{\theta})$ is $\tau(\hat{\theta})$.

Remark X_1, \dots, X_n in most cases do not have to be identically distributed.

Bayes Estimators

Let $X \sim f(x|\theta)$, $\theta \sim \pi(\theta)$, where $\pi(\theta)$ is the prior distribution of θ . Then after observing X = x, the posterior distribution of θ is

$$\pi(\theta|\mathbf{x}) = \frac{f(\mathbf{x}|\theta)\pi(\theta)}{m(\mathbf{x})}$$

where $m({m x})$ is the marginal distribution of ${m X}$,

$$m(\mathbf{x}) = \int f(\mathbf{x}|\theta)\pi(\theta)d\theta.$$

Example 7.2.14

Let X_1, X_2, \cdots, X_n be i.i.d. Bernoulli(p). Then $Y = \sum_{i=1}^n X_i$ is Bin(n, p).

We assume the prior distribution on p is $Beta(\alpha, \beta)$. Then

$$f(y,p) = \begin{bmatrix} \binom{n}{y} p^y (1-p)^{n-y} \end{bmatrix} \begin{bmatrix} \frac{\Gamma(\alpha+\beta)}{\Gamma(\alpha)\Gamma(\beta)} p^{\alpha-1} (1-p)^{\beta-1} \end{bmatrix}$$
$$= \binom{n}{y} \frac{\Gamma(\alpha+\beta)}{\Gamma(\alpha)\Gamma(\beta)} p^{y+\alpha-1} (1-p)^{n-y+\beta-1}$$
$$f(y) = \int_0^1 f(y,p) dp = \binom{n}{y} \frac{\Gamma(\alpha+\beta)}{\Gamma(\alpha)\Gamma(\beta)} \cdot \frac{\Gamma(y+\alpha)\Gamma(n-y+\beta)}{\Gamma(n+\alpha+\beta)}$$

Therefore $f(p|y)=\frac{\Gamma(n+\alpha+\beta)}{\Gamma(y+\alpha)\Gamma(n-y+\beta)}p^{y+\alpha-1}(1-p)^{n-y+\beta-1}$, which is $\mathrm{Beta}(y+\alpha,n-y+\beta)$. Bayes estimator of p is the mean of f(p|y), which is

$$\hat{p}_B = \frac{y + \alpha}{\alpha + \beta + n}.$$

Definition 7.2.6 (Conjugate Family)

Let $\mathcal F$ denote the class of pdf or pmf $f(x|\theta)$ (indexed by θ). A class Π of prior distribution is a conjugate family of $\mathcal F$ if the posterior distribution is in the class Π for all $f\in \mathcal F$, all prior in Π , and all $x\in \mathcal X$

$$P(\theta) = \pi(\theta|\mathbf{y}) = \frac{f(\mathbf{y}|\theta)\pi(\theta)}{\int_{\theta} f(\mathbf{y}|\theta)\pi(\theta)d\theta}$$
(12.3')

- Estimating the normalising constant
- Markov chain Monte Carlo (MCMC): Monte Carlo integration and Markov chain sampling

we estimated unknown parameters using the methods:

- Maximum likelihood : Newton Raphson(NR)
- MCMC
- NR比MCMC收敛的快。
- 对于多峰分布,NR只能找到一个,而MCMC可以找到多个。
- NW对于固定的似然初始值,它的路径是一样的;而MCMC即使初始值相同,它的路径也是随机的。

- Target density $P(\theta)$ is not always achievable because it may have a complex, or even unknown, form.
- Markov chains provide a method of drawing samples from target densities (regardless of their complexity).
- Using these conditional steps, we build up a chain of samples $(\theta^1,\cdots,\theta^M)$ after specifying a starting value θ^0

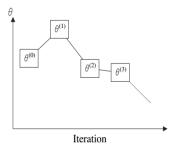


Figure 13.3 A simple example of a Markov chain.

$$P(\theta^{i} = a | \theta^{i-1}, \theta^{i-2}, \dots, \theta^{0}) = P(\theta^{i} = a | \theta^{i-1})$$

An algorithm for creating a Markov chain for a target probability density $P(\theta)$ is:

- 1 Choose an initial value θ^0 . The restriction on the initial value is that it needs to be within the distribution of P(.), so that $P(\theta) > 0$
- 2 Create a new sample using $\theta^1 \sim \pi(\theta^1|\theta^0,\mathbf{y})$
- 3 Repeat step 2 M times, each time increasing both indices by 1.

Transitional density: $\pi(\theta^{i+1}|\theta^i)$, Normal distribution.

The Metropolis - Hastings sampler

- The Metropolis Hastings sampler works by randomly **proposing a** new value θ^*
- If this proposed value is **accepted** (according to a criterion below), $\theta^{i+1} = \theta^*$
- If this proposed value is **rejected** (according to a criterion below), $\theta^{i+1} = \theta^i$
- Another proposal is made and the chain progresses by assessing this new proposal

• The acceptance criterion is:

$$\theta^{i+1} = \begin{cases} \theta^* & \text{if } U < \alpha \\ \theta^i & \text{otherwise} \end{cases}$$

where $U \sim U[-1,1]$ and

$$\alpha = \min \{ \frac{\pi(\theta^* | \mathbf{y})}{\pi(\theta^i | \mathbf{y})} \cdot \frac{Q(\theta^i | \theta^*)}{Q(\theta^* | \theta^i)}, 1 \}$$

where $P(\theta|\mathbf{y})$ is the probability of θ given the data \mathbf{y} (the likelihood) If the proposal density is symmetric(Q(a|b) = Q(b|a)), then

$$\alpha = \min\{\frac{\pi(\theta^*|\mathbf{y})}{\pi(\theta^i|\mathbf{y})}, 1\}$$

例1: The Metropolis - Hastings sampler

设
$$Y_1,Y_2,\cdots,Y_n\sim^{iid}N(\mu,\sigma^2)$$
, (μ,σ^2) 的先验分布为 $\pi(\mu,\sigma^2)\propto \frac{1}{\sigma^2}$ 。 计算 $E(\mu|Y=y)$ 和 $E(\sigma^2|Y=y)$ 。

解: (μ, σ^2) 后验分布为

$$\pi(\mu, \sigma^2 | Y = y) \propto (\frac{1}{\sigma^2})^{\frac{n}{2}+1} \exp\{-\frac{\sum_{i=1}^n (y_1 - \mu)^2}{2\sigma^2}\}$$

- 《统计模拟及其R实现》P203
- 为了比较方法,假设 $Y_1,Y_2,\cdots,Y_n\sim^{iid}N(2,4^2)$

The Gibbs sampler

- The Gibbs sampler is another way of generating a Markov chain.
- It splits the parameters into a number of components and then updates each one in turn.
- For the beetle mortality example, a Gibbs sampler to update the two unknown parameters would be:
 - 1 Assign an initial value to the two unknowns: β_1^0 and β_2^0
 - 2 (a) Generate $\beta_2^1 \sim \pi(\beta_2|\mathbf{y},\beta_1^0)$
 - (b) Generate $eta_1^{ ilde{1}} \sim \pi(eta_1|\mathbf{y},eta_2^{ ilde{0}})$
 - 3 Repeat the step 2 M times, each time increasing the sample indices by 1.

上面举例比较简单,复杂的见《统计模拟及其R实现》P199 例8.4

例1续: The Gibbs sampler

设
$$Y_1,Y_2,\cdots,Y_n\sim^{iid}N(\mu,\sigma^2)$$
, (μ,σ^2) 的先验分布为 $\pi(\mu,\sigma^2)\propto \frac{1}{\sigma^2}$ 。计算 $E(\mu|Y=y)$ 和 $E(\sigma^2|Y=y)$ 。

解: (μ, σ^2) 后验分布为

$$\pi(\mu, \sigma^2 | Y = y) \propto (\frac{1}{\sigma^2})^{\frac{n}{2} + 1} exp\{-\frac{\sum_{i=1}^n (y_i - \mu)^2}{2\sigma^2}\}$$

则:

$$\pi(\mu|\sigma^2, y) \propto exp\{-\frac{\sum_{i=1}^n (y_1 - \mu)}{2\sigma^2}\} \propto N(\overline{y}, \frac{\sigma^2}{n})$$
 (1)

$$\pi(\sigma^2|\mu, y) \propto (\frac{1}{\sigma^2}) exp\{-\frac{\sum_{i=1}^n (y_1 - \mu)^2}{2\sigma^2}\} \propto IG(\frac{n}{2}, \frac{\sum_{i=1}^n (y_1 - \mu)^2}{2}) \quad (2)$$

例:考虑54个老人智力得分。

Table 7.8 Symptoms of senility (s=1 if symptoms are present and s=0 otherwise) and WAIS scores (x) for N=54 people.

x	s	x	s	\boldsymbol{x}	s	\boldsymbol{x}	s	\boldsymbol{x}	s
9	1	7	1	7	0	17	0	13	0
13	1	5	1	16	0	14	0	13	0
6	1	14	1	9	0	19	0	9	0
8	1	13	0	9	0	9	0	15	0
10	1	16	0	11	0	11	0	10	0
4	1	10	0	13	0	14	0	11	0
14	1	12	0	15	0	10	0	12	0
8	1	11	0	13	0	16	0	4	0
11	1	14	0	10	0	10	0	14	0
7	1	15	0	11	0	16	0	20	0
9	1	18	0	6	0	14	0		

注:中科大张伟平《计算统计讲义》

考虑Logit模型:

$$Y_i \sim Bin(1, \pi_i), \ log \frac{\pi_i}{1 - \pi_i} = \beta_0 + \beta_1 x_i, \ i = 1, 2, \dots, 54$$

则似然函数为:

$$f(\mathbf{y}|\beta_0, \beta_1) = \prod_{i=1}^n \left(\frac{e^{\beta_0 + \beta_1 x_i}}{1 + e^{\beta_0 + \beta_1 x_i}}\right)^{y_i} \left(\frac{1}{1 + e^{\beta_0 + \beta_1 x_i}}\right)^{1 - y_i}$$
$$= exp\left\{\sum_{i=1}^n \left[(\beta_0 + \beta_1 x_i)y_i - \log(1 + e^{\beta_0 + \beta_1 x_i}) \right] \right\}$$

考虑 β_0,β_1 的先验分布为独立的正态分布:

$$\beta_j \sim N(\mu_j, \sigma_j^2)$$

$$f(\beta_0, \beta_1 | \mathbf{y}) \propto f(\mathbf{y} | \beta_0, \beta_1) \pi(\beta_0, \beta_1)$$

$$\propto exp\{ \sum_{i=1}^{n} [(\beta_0 + \beta_1 x_i) y_i - log(1 + e^{\beta_0 + \beta_1 x_i})] - \frac{(\beta_0 - \mu_0)^2}{\sigma_0^2} - \frac{(\beta_1 - \mu_1)^2}{\sigma_1^2} \}$$

- Assumption: the sample densities for the unknown parameters were good estimates of the target densities.
- If this assumption is incorrect, then inferences could be invalid.
- We can only make valid inference when a chain has converged to the target density.
 - Chain history
 - Chain autocorrelation
 - Multiple chains

Chain history

A chain that has converged should show a **reasonable degree of randomness** between iterations, signifying that the Markov chain has found an area of high likelihood and is integrating over the target density (known as mixing).

- $\operatorname{logit}(\pi_i) = \beta_1 + \beta_2 x_1$
- $\operatorname{logit}(\pi_i) = \beta_1 + \beta_2(x_1 \overline{x})$

Note: By centring the dose covariate we have greatly improved the convergence because centring reduces the correlation between the parameter estimates β_1 and β_2

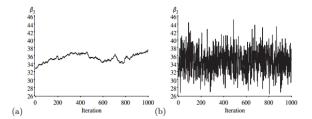


Figure 13.11 Example of a chain showing (a) poor convergence and (b) reasonable convergence (first 1,000 iterations using Gibbs sampling). Estimate for β_2 using the logit link using two different parameterizations.

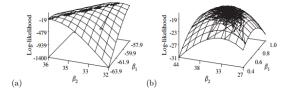


Figure 13.12 Three-dimensional plots of the log-likelihood and 200 Gibbs samples for the betle mortality data using the logit link function and [a] uncentered dose or [b] centered dose. The initial value is shown as an open circle and subsequent estimates as closed circles.

13.5.2 Chain autocorrelation

- Autocorrelation is a useful diagnostic because it summarizes the dependence between neighbouring samples.
- Ideally we would like neighbouring samples to be completely independent, as this would be the most efficient chain possible.
- In practice we usually accept some autocorrelation, but large values (greater than 0.4) can be problematic.
- Autocorrelation function (ACF)

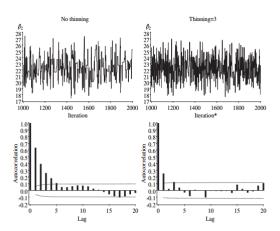


Figure 13.13 Reduction in autocorrelation of Metropolis-Hastings samples after thinning. Chain history (top row) and ACF (bottom row) for the estimate of β_2 from the beetle mortality example using the extreme value model and a centered dose.

Multiple chains

Advantage:

- Using multiple chains is a good way to assess convergence.
- If we start multiple chains at widely varying starting values and each chain converges to the same solution, this would increase our confidence in this solution.
- This method is particularly good for assessing the influence of initial values.

Drawback: It may be difficult to generate suitably varied starting values, particularly for complex problems with many unknown parameters and multi-dimensional likelihoods.

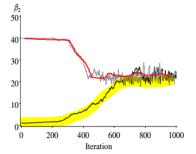


Figure 13.14 Two chains with different starting values. Estimates of β_2 using Metropolis–Hastings sampling for the extreme value model using the beetle mortality data.

EM Algorithm

Consider a mixture model:

$$Z_i \sim Bernoulli(\theta), \quad X_i | Z_i \sim N(Z_i, \sigma^2).$$

However, our observations are X_i 's only.

- ullet Since Z_i 's are missing. We call it as missing data problem
- The MLE is difficult to solve analytically for this problem.
- One generally used procedure is EM algorithm.

- \bullet Now there are two unknown things: the missing data z and the parameters θ
- If we know z, the MLE is found by

$$\arg\max_{\theta} \log f(x, z|\theta).$$

• If we know θ , then we have the conditional distribution for z, which is

$$f(z|x,\theta) = \frac{f(x,z|\theta)}{f(x|\theta)} = \frac{f(x,z|\theta)}{\int f(x,z|\theta)dz}$$

ullet Combine these two things, find heta as

$$\arg \max_{\theta} Q(\theta, \theta') = \arg \max_{\theta} E_Z \Big[\log f(x, z|\theta) | x; \theta' \Big]$$

where the expectation is taken with respect to the conditional distribution of Z, $f(z|x,\theta')$.

Procedure

- Set initial value $\theta^0, N = 1$.
- Expectation step:
 - With θ^{N-1} , find $f(z|x;\theta^{N-1})$
 - $\bullet \ \ \mathsf{Compute} \ Q(\theta,\theta^{N-1}) = E_Z \Big[\log f(x,z;\theta) | x;\theta' \Big], \ \ \mathsf{where} \ \ Z \sim f(z|x;\theta').$
- **1** Maximization step: Find θ^N as

$$\theta^N = \arg\max_{\theta} Q(\theta, \theta^{N-1})$$

③ Repeat Steps 2-3 until $\|\theta^{N-1} - \theta^N\| \le \epsilon$, where ϵ is a pre-set threshold. Or, stop the algorithm when N is large enough.

Remark:

- Very popular method, since very good for complicated models
- Seems different in different applications
- However, maybe trapped by local maxima

The EM Algorithm: Example

Suppose we observe $Z_{1:n}$ and $Y_{1:n}$ both independent random variables and independent of each other. In particular, $Y_i \sim Poission(\tau_i)$ and $Z_i \sim Poisson(\tau_i)$, where $\theta = (\beta, \tau_1, \dots, \tau_n) \in \mathbb{R}^{n+1}_+$ are the parameters.

If we have the full data, then the joint density is

$$f_Y(y|\theta) = \prod_{i=1}^n \frac{(\beta \tau_i)^{y_i}}{y_i!} e^{-\beta \tau_i} \quad f_Z(z|\theta) = \prod_{i=1}^n \frac{\tau_i^{Z_i}}{z_i!} e^{-\tau_i}$$

It is straightforward to find the MLEs;

$$\hat{\beta}_n = \frac{\sum_{i=1}^n y_i}{\sum_{i=1}^n \hat{z}_i}, \quad \hat{\tau}_i = \frac{y_i + z_i}{\hat{\beta}_n + 1}, i = 1, \dots, n.$$

• Now, if z_1 was missing, we have the marginal data likelihood of the observations:

$$f(y, z_{2:n}; \theta) = \frac{(\beta \tau_1)^{y_1}}{y_1!} e^{-\beta \tau_1} \left(\prod_{i=2}^n \frac{(\beta \tau_i)^{y_i}}{y_i!} e^{-\beta \tau_i} \frac{\tau_i^{z_i}}{z_i!} e^{-\tau_i} \right) \sum_{z_1=0}^{\infty} \frac{\tau_1^{z_1}}{z_1!} e^{-\tau_1}$$
$$= \frac{(\beta \tau_1)^{y_1}}{y_1!} e^{-\beta \tau_1} \left(\prod_{i=2}^n \frac{(\beta \tau_i)^{y_i}}{y_i!} e^{-\beta \tau_i} \frac{\tau_i^{z_i}}{z_i!} e^{-\tau_i} \right)$$

$$\begin{split} &Q(\theta, \theta') \\ &= \sum_{z_1=0}^{\infty} \log \left[\prod_{i=1}^{n} \frac{(\beta \tau_i)^{y_i}}{y_i!} e^{-\beta \tau_i} \frac{\tau_i^{z_i}}{z_i!} e^{-\tau_i} \right] \frac{(\tau_1')^{z_1}}{z_1!} e^{-\tau_1'} \\ &= \sum_{i=1}^{n} \left(-\beta \tau_i + y_i [\log \beta + \log \tau_i] - \log y_i \right) + \sum_{i=2}^{n} \left[-\tau_i + z_i \log \tau_i - \log z_i! \right] \\ &+ \sum_{z_1=0}^{\infty} \log \left(-\tau_1 + z_1 \log \tau_1 - \log z_1! \right) \frac{(\tau_1')^{z_1}}{z_1!} e^{-\tau_1'} \\ &= \sum_{i=1}^{n} \left(-\beta \tau_i + y_i [\log \beta + \log \tau_i] \right) + \sum_{i=2}^{n} \left[-\tau_i + z_i \log \tau_i \right] \\ &+ \sum_{z_1=0}^{\infty} \log \left(-\tau_1 + z_1 \log \tau_1 - \log z_1! \right) \frac{(\tau_1')^{z_1}}{z_1!} e^{-\tau_1'} + \sum_{i=1}^{n} - \log y_i \\ &+ \sum_{i=2}^{n} - \log z_i! \end{split}$$

$$\sum_{z_1=0}^{\infty} \log \left(-\tau_1 + z_1 \right) \frac{(\tau_1')^{z_1}}{z_1!} e^{-\tau_1'} = -\tau_1 + \tau_1' \log \tau_1$$

and the last term does not depend on θ , which can be denoted as C. So we have

$$Q(\theta, \theta')$$

$$= \sum_{i=1}^{n} \left(-\beta \tau_i + y_i [\log \beta + \log \tau_i] \right) + \sum_{i=2}^{n} \left[-\tau_i + z_i \log \tau_i \right] - \tau_1 + \tau_1' \log \tau_1 + C$$

Maximizing $Q(\theta, \theta')$ w.r.t. θ , the solution is

$$\beta = \frac{\sum_{i=1}^{n} y_i}{\tau_1' + \sum_{i=2}^{n} z_i} \ \tau_1 = \frac{\tau_1' + y_1}{\beta + 1}, \ \tau_i = \frac{y_1 + z_i}{\beta + 1}, i = 2, \dots, n$$

ious of Evaluating Estimators

The mean square error (MSE) of an estimator W of a parameter θ is the function of θ defined by

$$E_{\theta}(W-\theta)^2$$
.

 $\mathsf{Bias}_{\theta}W = E_{\theta}W - \theta$. If $\mathsf{Bias}_{\theta}W = 0$, then W is unbiased.

• Example 7.3.3 (Normal MSE) Let X_1, X_2, \cdots, X_n be i.i.d. $N(\mu, \sigma^2)$. Then statistics \bar{X} and S^2 are both unbiased.

$$\begin{split} MSE(\bar{X}) &=& E(\bar{X}-\mu)^2 = \mathrm{Var}(\bar{X}) = \sigma^2/n \\ E(S^2-\sigma^2)^2 &=& \mathrm{Var}(S^2) = \frac{2\sigma^4}{n-1}^1 \end{split}$$

1

$$\frac{(n-1)S^2}{\sigma^2} \sim \chi^2(n-1) \Rightarrow \mathrm{Var}\Big(\frac{(n-1)S^2}{\sigma^2}\Big) = 2(n-1)$$

Example 7.3.4 Maximum Eiker
$$\frac{1}{n} \sum_{i=1}^{n} (X_i - \bar{X})^2 = \frac{n-1}{n} S^2.$$

$$\operatorname{Var}\left(\frac{n-1}{n} S^2\right) =$$

$$\operatorname{Var}\left(\frac{n-1}{n}S^{2}\right) = \frac{(n-1)^{2}}{n^{2}} \cdot \frac{2\sigma^{4}}{n-1} = \frac{2(n-1)}{n^{2}}\sigma^{4}$$

$$MSE\left(\frac{n-1}{n}S^{2}\right) = \left(\frac{n-1}{n}ES^{2} - \sigma^{2}\right)^{2} + \frac{2(n-1)}{n^{2}}\sigma^{4}$$

$$= \sigma^{4}\left(\frac{n-1}{n} - 1\right)^{2} + \frac{2(n-1)}{n^{2}}\sigma^{4}$$

$$= \sigma^{4}\frac{2n-1}{n^{2}}$$

Since

$$\frac{2n-1}{n^2} < \frac{2}{n-1},$$

So in this case MLE has smaller MSE than the unbiased estimator S^2 .

Remark While MSE is a reasonable measurement for location parameters, it may not be a good to compare estimators of scale parameters with MSE.

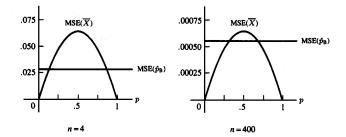
- Let $\hat{p} = \frac{X_1 + \dots + X_n}{n}$. $E_p(\hat{p} p)^2 = \mathsf{Var}_p(\bar{X}) = \frac{p(1-p)}{n}$.
- \bullet Let $\hat{p}_B = \frac{Y+\alpha}{\alpha+\beta+n}$ be the Bayes estimator. Here $Y = \sum_{i=1}^n X_i$

$$\begin{split} MSE\left(\hat{p}\right) &= \operatorname{Var}_{p}\left(\hat{p}_{B}\right) + \left(\operatorname{Bias}_{p}\left(\hat{p}_{B}\right)\right)^{2} \\ &= \operatorname{Var}\left(\frac{Y+\alpha}{\alpha+\beta+n}\right) + \left(E_{p}\left(\frac{Y+\alpha}{\alpha+\beta+n}\right) - p\right)^{2} \\ &= \frac{np(1-p)}{(\alpha+\beta+n)^{2}} + \left(\frac{np+\alpha}{\alpha+\beta+n} - p\right)^{2} \end{split}$$

In the absence of good prior information about p, we might choose α and β to make the MSE of \hat{p}_B constant. Choose $\alpha=\beta=\sqrt{n/4}$ gives

$$\hat{p}_B = \frac{Y + \sqrt{n/4}}{n + \sqrt{n}}, \ E(\hat{p}_B - p)^2 = \frac{n}{4(n + \sqrt{n})^2}$$

Figure 7.3.1 Comparison of $MSE(\hat{p})$ and $MSE(\hat{p}_B)$ for sample size n=4 and n=400 in Example 7.3.5



- For small n, \hat{p}_B is the better choice (unless there is a strong belief that p is near 0 or 1)
- For large n, \hat{p} is the better choice (unless there is a strong belief that p is close to $\frac{1}{2}$)

Best Unbiased Estimators

As we have discussed, there is usually no "best MSE" estimator. However, if we restrict our choice from unbiased estimators, then there exists best estimator in this class.

Definition 7.3.7 An estimator W^* is a best unbiased estimator of $\tau(\theta)$ if it satisfies $E_{\theta}W^* = \tau(\theta)$ for all θ and, for any other estimator W with $E_{\theta}W = \tau(\theta)$, we have

$$Var_{\theta}W^* \leq Var_{\theta}W$$
 for all θ .

 W^* is also called a uniform minimum variance unbiased estimator (UMVUE) of $\tau(\theta)$.

* Finding UMVUE is not easy.

• Theorem 7.3.9 (Cramér-Rao Inequality) Let X_1, X_2, \dots, X_n be a sample with pdf $f(x|\theta)$, and let W(X) be any estimator satisfying

$$\frac{d}{d\theta} E_{\theta} W(\boldsymbol{X}) = \int_{\mathcal{X}} \frac{\partial}{\partial \theta} \left[W(\boldsymbol{x}) f(\boldsymbol{x}|\theta) \right] d\boldsymbol{x}$$

and $Var_{\theta}W(X) < \infty$. Then

$$\mathsf{Var}_{\theta}W(m{X}) \geq rac{\left(rac{d}{d heta}E_{ heta}W(m{X})
ight)^2}{E_{ heta}\left(\left(rac{\partial}{\partial heta}\log f(m{X}| heta)
ight)^2
ight)}$$

In particular, if W(X) is an unbiased estimator of θ , then

$$\mathsf{Var}_{\theta}W(m{X}) \geq rac{1}{E_{ heta}\left(\left(rac{\partial}{\partial heta}\log f(m{X}| heta)
ight)^2
ight)}$$

• Corollary 7.3.10 (Cramér-Rao Inequality, iid case) If X_1, X_2 , \dots , X_n are i.i.d. $f(x|\theta)$, and the condition of Theorem 7.3.9 are satisfied, then

$$\mathsf{Var}_{\theta}\left(W(\boldsymbol{X})\right) \geq \frac{\left(\frac{d}{d\theta}E_{\theta}W(\boldsymbol{X})\right)^{2}}{nE_{\theta}\left(\left(\frac{\partial}{\partial\theta}\log f(\boldsymbol{X}|\theta)\right)^{2}\right)}$$

To evaluate $E_{ heta}\left(\left(\frac{\partial}{\partial heta}\log f(X| heta)\right)^2\right)$, we have the following Lemma.

• Lemma 7.3.11 If $f(x|\theta)$ satisfies

$$\frac{d}{d\theta} E_{\theta} \left(\frac{\partial}{\partial \theta} \log f(x|\theta) \right) = \int \frac{\partial}{\partial \theta} \left[\left(\frac{\partial}{\partial \theta} \log f(x|\theta) \right) f(x|\theta) \right] dx$$

(true for an exponential family), then

$$E_{\theta}\left(\left(\frac{\partial}{\partial \theta}\log f(X|\theta)\right)^{2}\right) = -E_{\theta}\left(\frac{\partial^{2}}{\partial \theta^{2}}\log f(X|\theta)\right).$$

• Example 7.3.12 \bar{X} is UMVUE for λ if X_1, \dots, X_n are i.i.d. Poisson(λ). From Theorem 7.3.9, we have for any unbiased estimator $W(\mathbf{X})$ of λ .

$$\operatorname{Var}_{\lambda}W(\boldsymbol{X}) \geq \frac{1}{-nE_{\lambda}\left[\frac{\partial^{2}}{\partial\lambda^{2}}\log f(\boldsymbol{x}|\lambda)\right]}$$

$$\log f(\boldsymbol{x}|\lambda) = \log\left[e^{-\lambda}\frac{\lambda^{x}}{x!}\right] = -\lambda + x\log\lambda - \log x!$$

$$\frac{\partial^{2}}{\partial\lambda^{2}}\log f(\boldsymbol{x}|\lambda) = -x\frac{1}{\lambda^{2}}.$$
(3.1)

Therefore, $-E_{\lambda}\left[\frac{\partial^2}{\partial \lambda^2}\log f(\boldsymbol{x}|\lambda)\right] = \frac{1}{\lambda^2}E_{\lambda}X = \frac{1}{\lambda}.$ (3.1) Becomes $\operatorname{Var}_{\lambda}(W(\boldsymbol{X})) \geq \frac{\lambda}{n}.$ But $\operatorname{Var}_{\lambda}(\bar{X}) = \frac{\lambda}{n}.$

• Example 7.3.13 (Unbiased Estimator for Scale Parameter) Let X_1, \dots, X_n be i.i.d. with pdf $f(x|\theta) = \frac{1}{a}, 0 < x < \theta$. Since $\frac{\partial}{\partial x} \log f(x|\theta) = -\frac{1}{\theta}$, we have

$$E_{\theta} \left[\frac{\partial}{\partial \lambda} \log f(x|\theta) \right] = \frac{1}{\theta^2}$$

So if W is unbiased for θ , then

$$\operatorname{Var}_{\theta}(W) \geq \frac{\sigma^2}{n}.$$

• On the other hand, $Y = \max(Y_1, \dots, Y_n)$ is a sufficient statistic. $f_{V}(y|\theta) = ny^{n-1}/\theta^{n}, \ 0 < y < \theta.$ So

$$E_{\theta}Y = \int_{0}^{\theta} y \cdot \frac{ny^{n-1}}{\theta^{n}} dy = \frac{n}{n+1} \theta,$$

showing that $\frac{n+1}{n}Y$ is an unbiased estimator of θ .

$$\begin{aligned} \operatorname{Var}_{\theta}\left(\frac{n+1}{n}Y\right) &= \left(\frac{n+1}{n}\right)^{2}\operatorname{Var}_{\theta}(Y) \\ &= \left(\frac{n+1}{n}\right)^{2}\left[E_{\theta}Y^{2} - (EY)^{2}\right] \\ &= \left(\frac{n+1}{n}\right)\left[\frac{n}{n+2}\theta^{2} - \left(\frac{n}{n+1}\theta\right)^{2}\right] \\ &= \frac{1}{n(n+2)}\theta^{2}, \end{aligned}$$

which is uniformly smaller than θ^2/n . Cramér-Rao lower bound Theorem is not applicable to this pdf since $\frac{d}{d\theta} \int_0^{\theta} h(x) f(x|\theta) dx \neq \int_0^{\theta} h(x) \frac{\partial}{\partial \theta} f(x|\theta) dx.$

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• Example 7.3.14 (Normal Variance Bound) Let X_1, \dots, X_n be i.i.d. $N(\mu, \sigma^2)$. The conditions of Cramér-Rao Theorem are satisfied. Let W be an unbiased estimator of σ^2 , then

$$Var(W|\mu, \sigma^2) \ge 2\sigma^4/n.$$

In Example 7.3.3 we see that ${\rm Var}(S^2|\mu,\sigma^2)\geq \frac{2\sigma^4}{n-1}.$ So S^2 does not attain the Cramér-Rao lower bound.

• Corollary 7.3.15 (Attainment) Let X_1, \cdots, X_n be i.i.d. $f(x|\theta)$, where $f(x|\theta)$ satisfies the conditions of the Cramér-Rao Theorem. Let $L(\theta|\mathbf{x})$ denote the likelihood function. If $W(\mathbf{X})$ is any unbiased estimator of $\tau(\theta)$, then $W(\mathbf{X})$ attains the Cramér-Rao lower bound if and only if

$$a(\theta)[W(\mathbf{x}) - \tau(\theta)] = \frac{\partial}{\partial \theta} \log L(\mathbf{x}|\theta)$$

for some function $a(\theta)$.

• **Proof** The Cramér-Rao inequality, can be written as

$$\begin{split} & \left[\mathsf{Cov}_{\theta} \left(W(\mathbf{X}), \frac{\partial}{\partial \theta} \log \prod_{i=1}^{n} f(X_{i} | \theta) \right) \right]^{2} \\ \leq & \mathsf{Var}_{\theta} W(\mathbf{X}) \cdot \mathsf{Var}_{\theta} \left(\frac{\partial}{\partial \theta} \log L(\mathbf{X}) \right) \end{split}$$

Using the condition for "=" in Cauchy-Schwarz inequality, we obtain the expression (3.1).

• Example 7.3.16 (Continuation of Example 7.3.14)

$$L(\boldsymbol{x}|\mu,\sigma^2) = \frac{1}{(2\pi\sigma^2)^{n/2}} \exp\left(-\frac{1}{2}\sum_{i=1}^n (x_i - \mu)^2/\sigma\right)$$

and hence

$$\frac{\partial}{\partial \sigma^2} \log L(\boldsymbol{x}|\mu, \sigma^2) = \frac{n}{2\sigma^4} \left(\sum_{i=1}^n \frac{(x_i - \mu)^2}{n} - \sigma^2 \right)$$

Taking $a(\sigma^2)=\frac{n}{2\sigma^4}$ shows that the best unbiased estimator of σ^2 is $\sum_{i=1}^n (x_i-\mu)^2/n$, which is calculable only if μ is known.

 So the question of finding best unbiased estimator are still unsolved for many common pdf's. Introduction

Methods of Evaluating Estimators
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