

AI编译器-后端优化

Auto Tuning



ZOMI



BUILDING A BETTER CONNECTED WORLD

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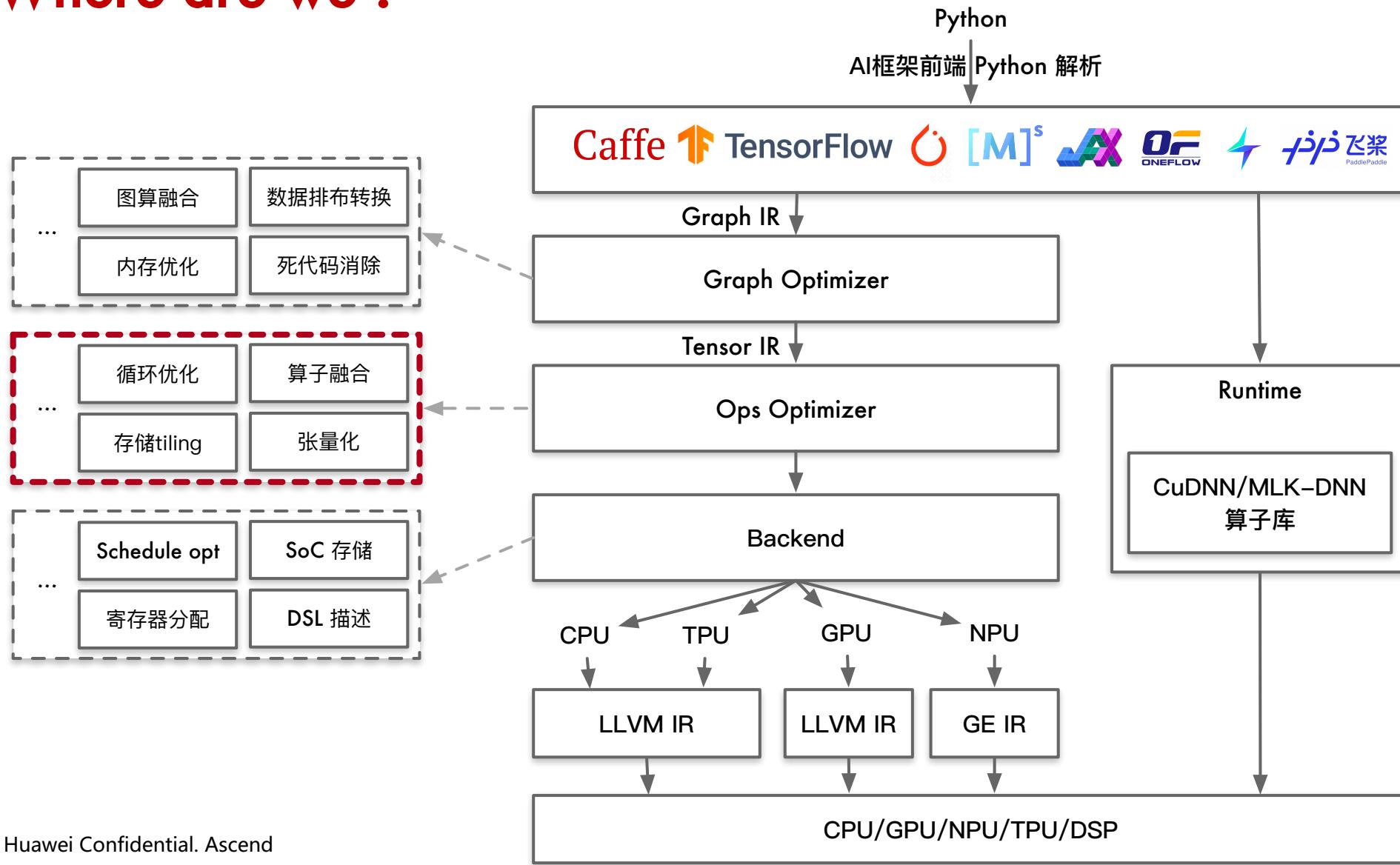
Talk Overview

I. AI 编译器后端优化

- 后端优化概念
- 算子计算与调度
- 算子调度优化
- Auto-Tuning

- Polyhedral

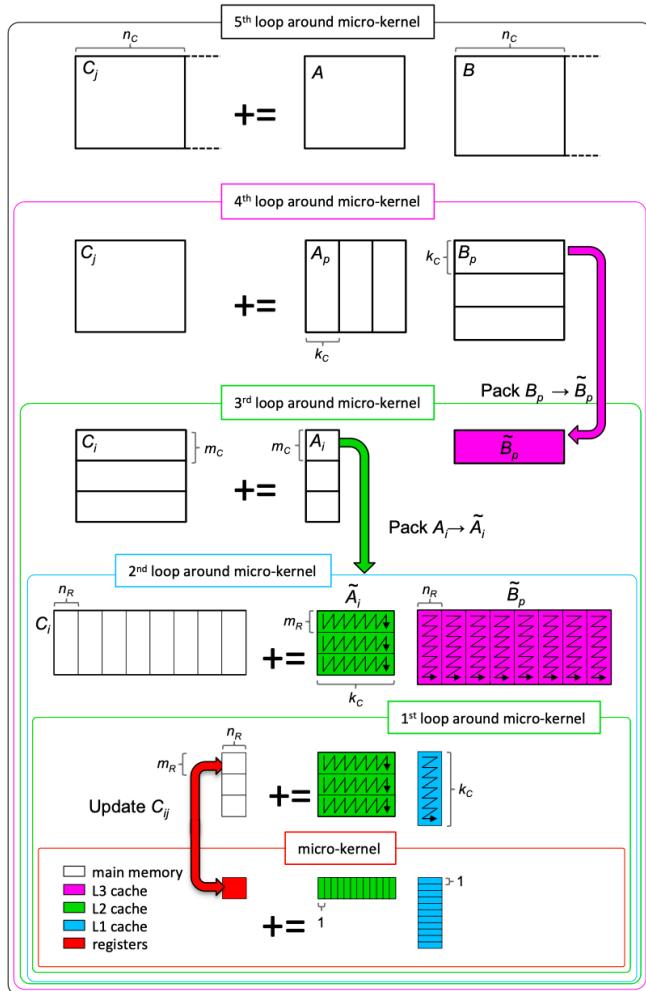
Where are we ?



Auto Tuning

- 对于给定的程序和目标架构，找到最优的编译优化方法。使用哪些优化方法？选择什么参数集？用什么顺序应用优化方法以达到最佳性能？

BLISlab: A Sandbox for Optimizing GEMM



```
Loop 5  for  $j_c=0 : n_c-1$  steps of  $n_c$ 
         $\mathcal{J}_c=j_c : j_c+n_c-1$ 
Loop 4  for  $p_c=0 : k_c-1$  steps of  $k_c$ 
         $\mathcal{P}_c=p_c : p_c+k_c-1$ 
         $B(\mathcal{P}_c, \mathcal{J}_c) \rightarrow B_c$  // Pack into  $B_c$ 
Loop 3  for  $i_c=0 : m_c-1$  steps of  $m_c$ 
         $\mathcal{I}_c=i_c : i_c+m_c-1$ 
         $A(\mathcal{I}_c, \mathcal{P}_c) \rightarrow A_c$  // Pack into  $A_c$ 
        // Macro-kernel
Loop 2  for  $j_r=0 : n_r-1$  steps of  $n_r$ 
         $\mathcal{J}_r=j_r : j_r+n_r-1$ 
Loop 1  for  $i_r=0 : m_r-1$  steps of  $m_r$ 
         $\mathcal{I}_r=i_r : i_r+m_r-1$ 
        // Micro-kernel
Loop 0   for  $k_r=0 : k_c-1$ 
         $C_c(\mathcal{I}_r, \mathcal{J}_r)$ 
         $+ = A_c(\mathcal{I}_r, k_r) \ B_c(k_r, \mathcal{J}_r)$ 
    endfor
endfor
endfor
endfor
endfor
```

Auto Tuning

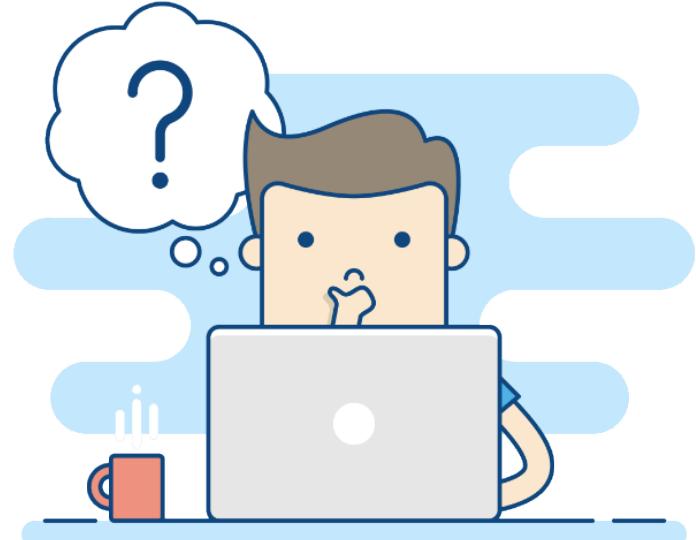
- 优化选择 Optimize Selection
- 优化顺序 Optimize Sequence

Auto Tuning in AI

- **更低实验开销**：1) 聚焦算子或者 kernel 级别的优化，而非整个程序。2) Cost Model 在CPU上模拟NPU执行，训练和推理推理的模拟速度要求足够快。
- **特定领域结构**：针对神经网络算子或者 kernel 级别的优化，1) 主要是高度循环化、张量化、并行化特点进行优化；2) 大量相类似的算子计算模式。

Question?

- 如何可以让机器匹配手写优化性能？
1. 建立一个足够大的搜索空间，保证可能的人工手写优化全部包含在这个搜索空间里面
 2. 快速地搜索这个空间，获取优化的实现



Auto Tuning in AI

1. 参数化 Parameterization
2. 成本模型 Cost Model
3. 搜索算法 Search Algorithm

```
1  for (int n = 0; n < o_n; ++n) {
2      for (int c = 0; c < o_c; ++c) {
3          for (int j = 0; j < o_h; ++j) {
4              for (int i = 0; i < o_w; ++i) {
5                  int d_start = n * i_c * i_h * i_w + j * i_w + i;
6                  int temp = 0;
7                  for (int kk = 0; kk < k_c; ++kk) {
8                      for (int kj = 0; kj < k_h; ++kj) {
9                          for (int ki = 0; ki < k_w; ++ki) {
10                             int k_idx = kk * k_h * k_w + kj * k_w + ki;
11                             int d_idx = d_start + kk * i_h * i_w + kj * i_w + ki;
12                             temp += inputs->data[d_idx] * kernel->data[k_idx];
13                         }
14                     }
15                 }
16                 res[n * o_c * o_h * o_w + j * o_w + i] = temp;
17             }
18         }
19     }
```

Auto Tuning in AI

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- 参数化 Parameterization：对调度优化问题进行建模，参数化优化空间一般由可参数化变换（`lop`）的可能参数取值组合构成，因此需要调度原语进行参数化表示。Halide 将算法和调度解耦，TVM 提供调度模板。

```
1
2     bx, tx = s[C].split(C.op.axis[0], factor=64)
3     s[C].bind(bx, tvm.te.thread_axis("blockIdx.x"))
4     s[C].bind(tx, tvm.te.thread_axis("threadIdx.x"))
5     fadd = tvm.build(s, [A, B, C], target)
6
```

Auto Tuning in AI

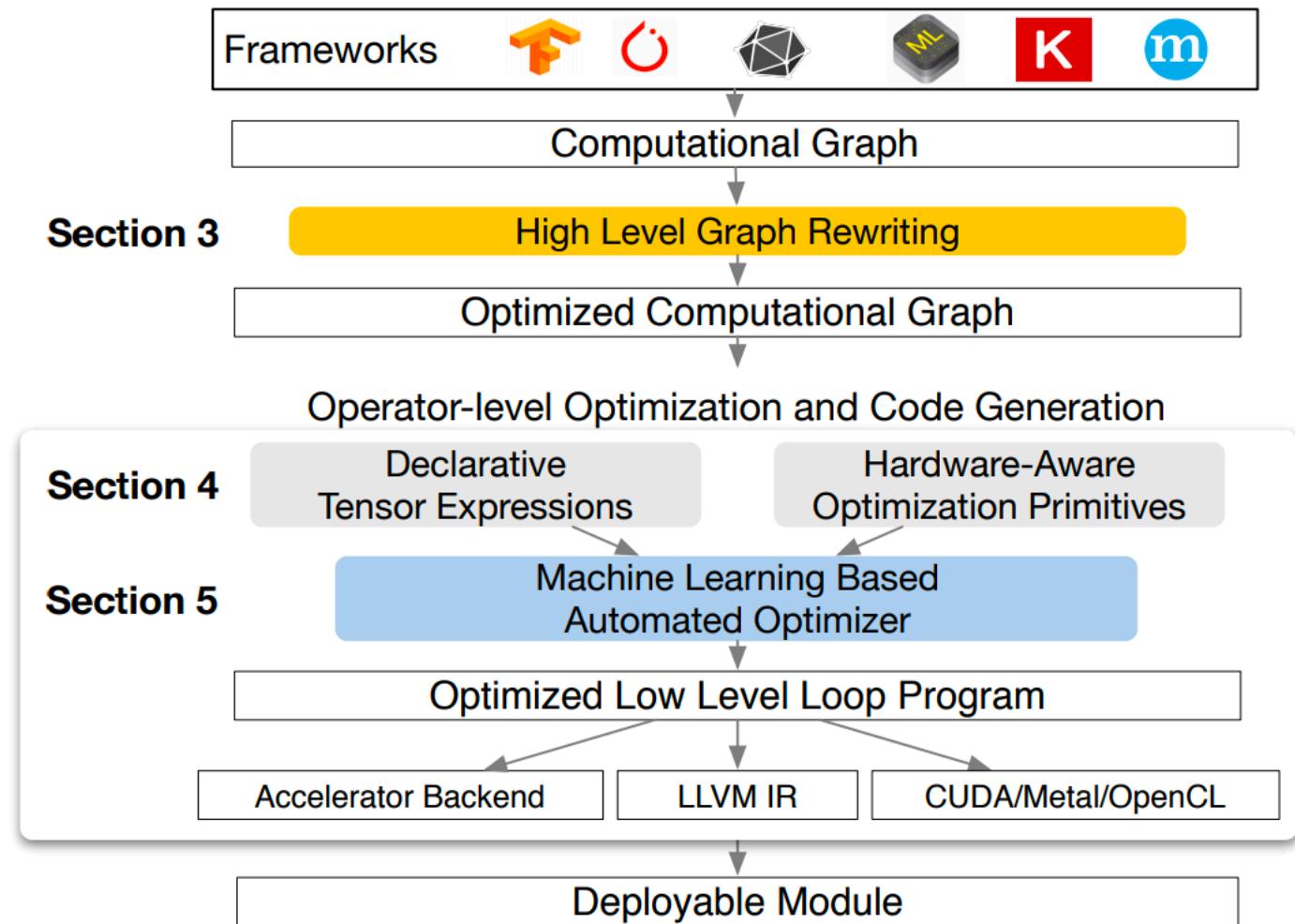
1. 参数化 Parameterization
 2. 成本模型 Cost Model
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- 成本模型 Cost Model : 用来评价某一参数化下的调度性能，根据对调度额评价来指导最搜索到最优的调度策略。可以从运行时间、内存占用、编译后指令数来评价。实现方式主要有1) 基于NPU硬件的黑盒模型；2) 基于模拟的预定义模型；3) ML-Base 模型，通过机器学习模型来对调度性能进行预测。

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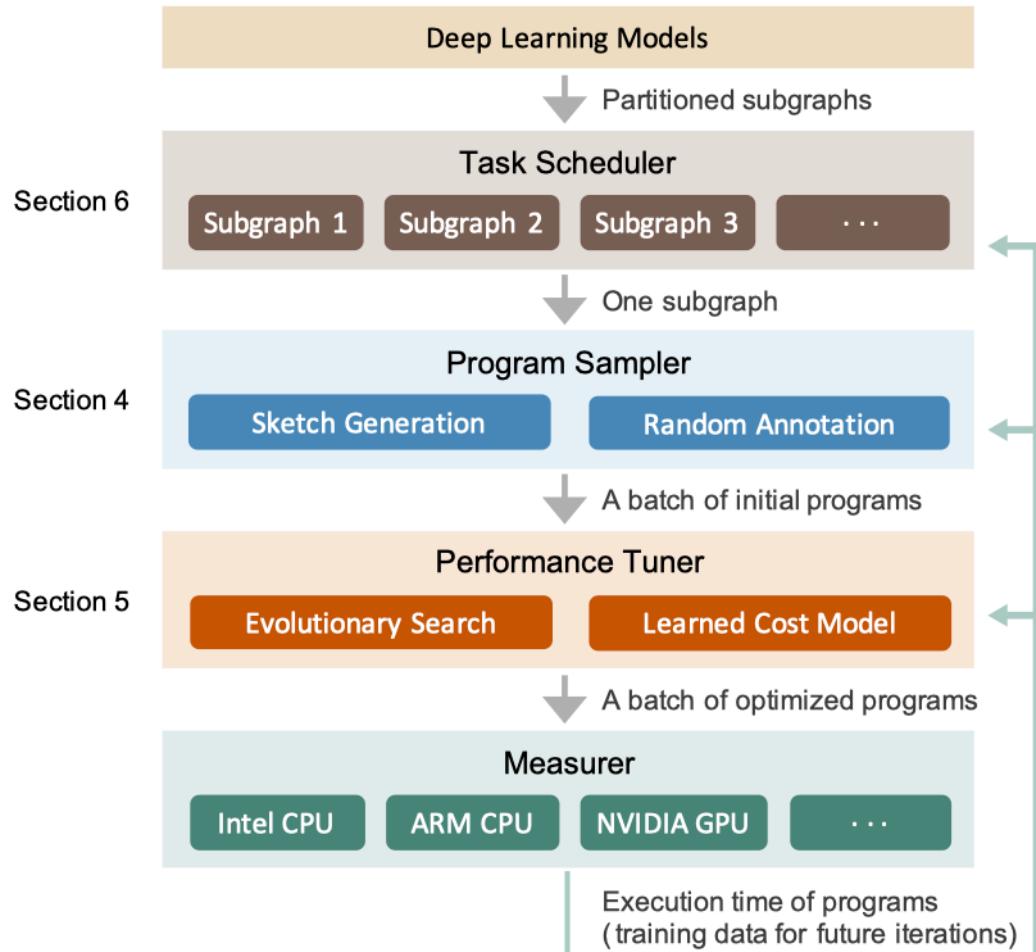
1. 参数化 Parameterization
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 3. 搜索算法 Search Algorithm
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- 搜索算法 Search Algorithm : 确定初始化和搜索空间后，在搜索空间找找到达到性能最优的参数配置。常用的搜索算法有1) 遗传算法、2) 模拟退火算法、3) 强化学习等。

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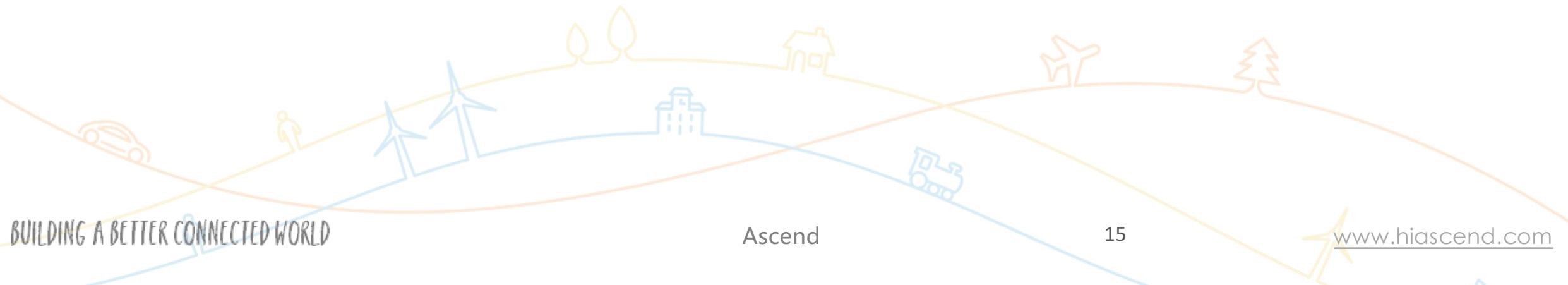


AnsoR : Generating High-Performance Tensor Programs for Deep Learning



Inference

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- Loop Optimizations: taking matters into your hands <https://johnysswlab.com/loop-optimizations-taking-matters-into-your-hands/>
- Understanding Latency Hiding on GPUs - UC Berkeley EECS. <https://www2.eecs.berkeley.edu/Pubs/TechRpts/2016/EECS-2016-143.pdf>
- Reinforcement Learning and Adaptive Sampling for Optimized DNN Compilation, <https://arxiv.org/abs/1905.12799>





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