

# **QF 604**

# **ECONOMETRICS OF**

# **FINANCIAL MARKETS**

## **LECTURE 8**

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# LECTURE OUTLINE

**01 NON-STATIONARY PROCESSES**

**02 SPURIOUS REGRESSION**

**03 UNIT ROOT PROCESSES**

**04 PURCHASING POWER PARITY**

**05 COINTEGRATION**

# 01 Non-Stationary Process

- Consider  $Y_t = \theta + \lambda Y_{t-1} + \varepsilon_t, \theta \neq 0$

where  $\varepsilon_t$  is a covariance-stationary process with  $E(\varepsilon_t) = 0, \text{Var}(\varepsilon_t) = \sigma_\varepsilon^2$ ,  
 $\text{Cov}(\varepsilon_t, \varepsilon_{t-k}) = 0 \quad \forall k \neq 0$ , and  $\text{Cov}(Y_{t-1}, \varepsilon_t) = 0$ .

- $Y_t$  is covariance stationary provided  $|\lambda| < 1$ .

If  $\lambda = 1$ , then, 
$$Y_t = \theta + Y_{t-1} + \varepsilon_t \quad (10.1)$$

- Or  $(1 - B)Y_t = \theta + \varepsilon_t$ , so  $(1 - B) = 0$  yields a unit root solution.

Thus,  $Y_t$  contains a unit root and  $\{Y_t\}$  is called a **unit root process**.

- By repeated substitution

$$\begin{aligned} Y_t &= \theta + (\theta + Y_{t-2} + \varepsilon_{t-1}) + \varepsilon_t \\ &= 2\theta + (\theta + Y_{t-3} + \varepsilon_{t-2}) + \varepsilon_t + \varepsilon_{t-1} \\ &\quad \vdots \\ &= t\theta + Y_0 + \varepsilon_t + \varepsilon_{t-1} + \varepsilon_{t-2} + \cdots + \varepsilon_2 + \varepsilon_1 \end{aligned}$$

# 01 Non-Stationary Process

- A unit root process in  $Y_t$  leads to

$Y_t$  having a **time trend**  $t\theta$  and a **stochastic trend**  $\sum_{j=0}^{t-1} \varepsilon_{t-j}$ .

- If  $E(Y_0) = \mu_0$ , then  $E(Y_t) = \mu_0 + t\theta \neq \mu_0$ , provided  $\theta \neq 0$ .
- The mean of  $Y_t$  increases (decreases) with time according to drift  $\theta > (<) 0$ .
- If  $Var(Y_0) = \sigma_0^2 < \infty$ ,

$$Var(Y_t) = \sigma_0^2 + Var\left[\sum_{j=0}^{t-1} \varepsilon_{t-j}\right] = \sigma_0^2 + t\sigma_\varepsilon^2 \neq \sigma_0^2$$

Variance of  $Y_t$  increases due to stochastic trend

Hence  $\{Y_t\}$  is not covariance-stationary or **non-stationary**

# 01 Trend Stationary Process

- Suppose random variable  $Y_t$  is trend stationary, i.e., stationary about a deterministic time trend  $\delta + t\theta$  :

$$Y_t = t\theta + \delta + \eta_t \quad (10.2)$$

$\eta_t$ : a stationary i.i.d. random variable with zero mean

Then,  $Var(Y_t) = Var(\eta_t) = \sigma_\eta^2$

- Then,  $Y_t = \theta + Y_{t-1} + \Delta\eta_t \quad (10.3)$

where  $Var(\Delta\eta_t) = Var(\eta_t - \eta_{t-1}) = 2\sigma_\eta^2$  since  $\eta_t$  is i.i.d.

- Eq. (10.3) looks like the unit root process in Eq. (10.1), but it is NOT

# 01 Trend Stationary Process

- Eq. (10.3) is not like the unit root process in Eq. (10.1) because the stationary noise term  $\Delta\eta_t$  carries a special structure.
- Iterate the process Eq. (10.3) through time:

$$\begin{aligned}
 Y_t &= \theta + (\theta + Y_{t-2} + \Delta\eta_{t-1}) + \Delta\eta_t \\
 &= 2\theta + (\theta + Y_{t-3} + \Delta\eta_{t-2}) + \Delta\eta_t + \Delta\eta_{t-1} \\
 &\quad \vdots \\
 &= t\theta + Y_0 + \Delta\eta_t + \Delta\eta_{t-1} + \Delta\eta_{t-2} + \cdots + \Delta\eta_2 + \Delta\eta_1 \\
 &= t\theta + Y_0 + \eta_t - \eta_0
 \end{aligned}$$

where  $Var(\eta_t - \eta_0) = 2\sigma_\eta^2$

- If  $Var(Y_0) = \sigma_0^2 < \infty$ ,  $Var(Y_t) = \sigma_0^2 + 2\sigma_\eta^2$

For trend stationary process,  $Var(Y_t)$  stays the same even as  $t$  increases

- Big difference between Eq. (10.3) and Eq. (10.1):  $\Delta\eta_t$  does not add up variance, unlike stochastic trend in a unit root process

# 01 Unit Root vs. Trend Stationary Process

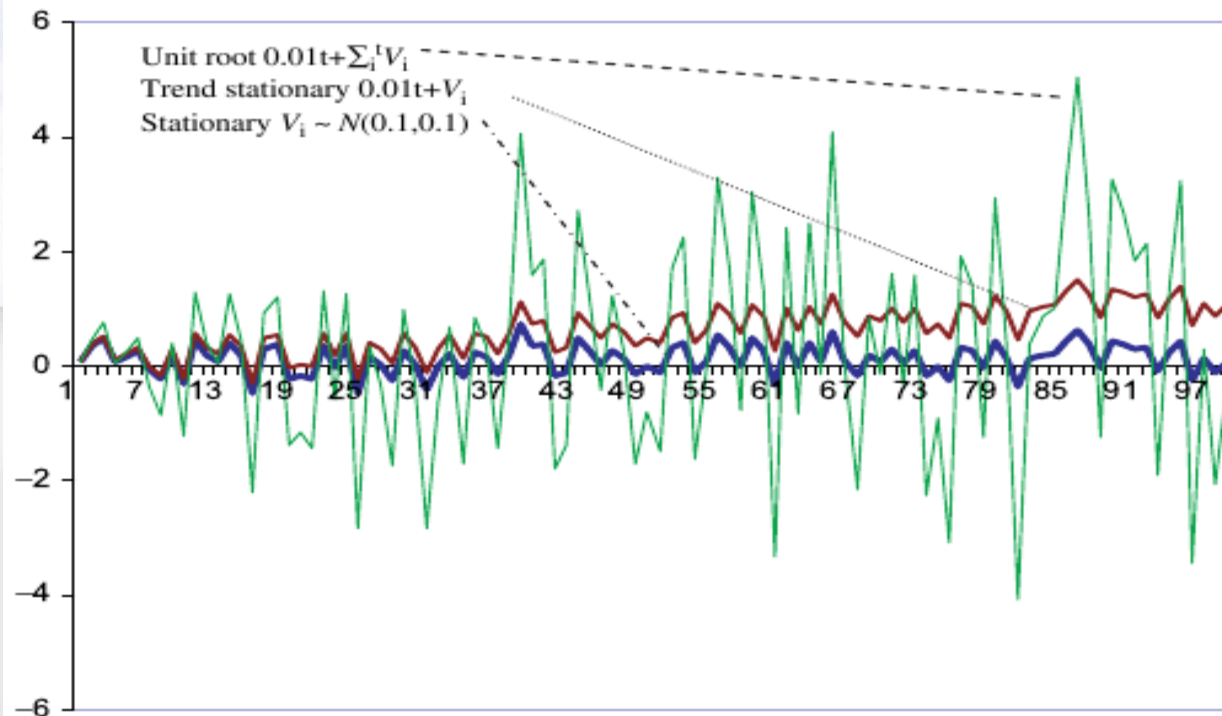


Figure 10.1: Time Series Graphs of Stochastic Processes

- A unit root process contains a deterministic time trend + a stochastic trend  $\sum_{j=1}^{t-1} \varepsilon_j$
- A trend stationary process contains a deterministic time trend + stationary noise  $\eta_t - \eta_0$
- Both processes display time trend but unit root process displays increasing volatility over time



# 02 Spurious Regression

- Suppose

$$Y_t = \theta + Y_{t-1} + e_t, \quad e_t \sim \text{stationary with mean 0}$$

$$Z_t = \mu + Z_{t-1} + u_t, \quad u_t \sim \text{stationary with mean 0}$$

$e_t$  and  $u_t$  are independent of each other, also not correlated with  $Y_{t-1}$  and  $Z_{t-1}$

$\{Y_t\}$  and  $\{Z_t\}$  are unit root processes with drifts  $\theta$  and  $\mu$ , respectively

- Then,

$$Y_t = t\theta + Y_0 + (e_t + e_{t-1} + \dots + e_1)$$

$$Z_t = t\mu + Z_0 + (u_t + u_{t-1} + \dots + u_1)$$

- Let  $Y_0$  and  $Z_0$  be independent,

$$\text{Cov}(Y_t, Z_t) = \text{Cov}(Y_0, Z_0) + \text{Cov}\left(\sum_{j=1}^t e_j, \sum_{k=1}^t u_k\right) = 0$$



# 02 Spurious Regression

- $Y_t, Z_t$  are independent

Consider a linear regression of  $Y_t$  on  $Z_t$  :

$$Y_t = a + bZ_t + \eta_t \quad (10.4)$$

$\eta_t$  is independent of  $Z_t$ .  $\eta_t$  is a unit root process,  $\eta_t = \eta_{t-1} + \epsilon_t$ , with stationary  $\epsilon_t$ ,  $E(\epsilon_t) = 0$ ,  $Var(\epsilon_t) < \infty$ .

- The slope  $b = \frac{Cov(Y_t, Z_t)}{Var(Z_t)} = 0$  since  $Cov(Y_t, Z_t) = 0$
- Expand the regression into its time trend and additive stochastic component:

$$t\theta + Y_0 + \sum_{j=0}^{t-1} e_{t-j} = a + b \left( t\mu + Z_0 + \sum_{j=0}^{t-1} u_{t-j} \right) + \left( \eta_0 + \sum_{j=0}^{t-1} \epsilon_{t-j} \right)$$

# 02 Spurious Regression

- Divide through by  $t$

$$\theta + \frac{Y_0}{t} + \frac{1}{t} \sum e_{t-j} = \frac{a}{t} + b\mu + \frac{bZ_0}{t} + \frac{b}{t} \sum u_{t-j} + \frac{\eta_0}{t} + \frac{1}{t} \sum \epsilon_{t-j}$$

- $\text{Var}\left(\frac{Y_0}{t}\right)$ ,  $\text{Var}\left(\frac{Z_0}{t}\right)$  and  $\text{Var}\left(\frac{\eta_0}{t}\right)$  all  $\downarrow 0$  as  $t \uparrow \infty$

As  $t$  increases, the time-averages of the noise terms in  $e_t$ ,  $u_t$ ,  $\epsilon_t$  converge to zeros.

Then, in regression Eq. (10.4),  $\theta \approx b\mu$ , so  $b \approx \frac{\theta}{\mu} \neq 0$ .

- The regression in Eq. (10.4) between two independent processes produces an estimated slope coefficient  $\hat{b}$  which is  $\widehat{Cov}(Y_t, Z_t) / \widehat{Var}(Z_t)$ .

Numerator and denominator yield sampling averages giving  $\approx \frac{\theta}{\mu} \neq 0$ .

- This is termed a **spurious** (seemingly true yet false) regression result:  $\hat{b} \neq 0$  is obtained from linear regression when theoretically  $b = 0$ .

## 02 Spurious Regression

- The spurious regression above applies also to  $Y_t$  and  $Z_t$  if they are trend stationary instead of being unit root processes. Consider

$$Y_t = t\theta + \delta + \eta_t$$

$$Z_t = t\mu + \gamma + \xi_t$$

where  $\eta_t$  and  $\xi_t$  are mean zero i.i.d. random variables that have zero correlation.

- Even though  $Y_t$  and  $Z_t$  are not correlated,

$$Y_t = \delta + \theta \left[ \frac{Z_t - \gamma - \xi_t}{\mu} \right] + \eta_t = \left( \delta - \frac{\theta\gamma}{\mu} \right) + \frac{\theta}{\mu} Z_t + \left( \eta_t - \frac{\theta}{\mu} \xi_t \right)$$

- So, OLS regression of  $Y_t$  on  $Z_t$  will give a spurious estimate of  $\theta/\mu \neq 0$ .
- Spurious non-zero correlation between  $Y_t$ ,  $Z_t$ , even when they are independent processes, comes from their deterministic trend, not stochastic trend

## 02 Linear Combinations of I(1) Processes

- Suppose

$$Z_t = \mu + Z_{t-1} + u_t, \quad u_t \sim \text{stationary with mean 0}$$

$$w_t = \gamma + w_{t-1} + \xi_t, \quad \xi_t \sim \text{stationary with mean 0}$$

are independent unit root processes.

- In general, a **linear combination of the unit root processes**  $Z_t$  and  $w_t$ ,  $Y_t$  is also a unit root process:

$$\begin{aligned} Y_t &= c + dZ_t + w_t \\ &= (c + \gamma) + d\mu + dZ_{t-1} + du_t + w_{t-1} + \xi_t \\ &= (\gamma + d\mu) + Y_{t-1} + (du_t + \xi_t) \end{aligned}$$

for constants  $c, d$ .  $Y_t$  is correlated with  $Z_t$  where  $d \neq 0$ .

## 02 Spurious Regression of related Unit Root Processes

- Perform OLS of  $Y_t$  on  $Z_t$ :

$$Y_t = c + dZ_t + w_t$$

where  $d \neq 0$  and  $w_t$  is independent unit root process.

- OLS estimate of  $d$  will involve

$$\text{Cov}(Y_t, Z_t) = \text{Cov}(c + dZ_t + w_t, Z_t) = d \text{Var}(Z_t) + \text{Cov}(c + w_t, Z_t)$$

The latter is a covariance of two independent unit root processes each with a deterministic trend (and a stochastic trend as well), that produces spurious sampling estimate (seen earlier) that is not zero.

- The sampling estimate of  $\text{Cov}(Y_t, Z_t)$  under OLS will also be spurious regardless of the value of  $d$ , due to  $\text{Cov}(c + w_t, Z_t) \neq 0$ .

## 02 Spurious Regression of related Unit Root Processes

- When OLS on two **related** unit root processes such as  $Y_t$  and  $Z_t$  can or cannot be feasible, it has to do with the covariance of the explanatory variable and the residual variable,  $\text{cov}(w_t, Z_t)$ .

If both are unit root processes, then there is spuriousness.

- If  $w_t$  is a stationary process, and not a unit root process, independent of  $Z_t$ .  
Then, the sample estimate of  $\text{cov}(w_t, Z_t) = 0$ .  
In this case, the OLS estimate of  $d$  converges correctly.

- In general, whether unit root processes  $Y_t$  and  $Z_t$  **are truly related or not**:

$$Y_t = c + dZ_t + w_t$$

If disturbance  $w_t$  has a unit root and is not correlated with  $Z_t$

Then Not appropriate to perform OLS of  $Y_t$  on  $Z_t$  since  $w_t$  is not stationary

OLS result will be spurious



# 03 Unit Root Test

- Suppose  $Y_t = Y_{t-1} + \varepsilon_t, \varepsilon_t \sim \text{stationary}$  (10.5)

First difference  $\Delta Y_t \equiv Y_t - Y_{t-1} = \varepsilon_t$  stationary

$Y_t$ : integrated order 1 or  $I(1)$  process

$\Delta Y_t$ : integrated order 0 or  $I(0)$  process, stationary

In general,  $I(k)$  is integrated order  $k$  process if after the  $k^{\text{th}}$  differencing, process first becomes stationary

- Suppose  $Y_t = \delta + Y_{t-1} + \varepsilon_t, \varepsilon_t \sim \text{stationary}$  (10.6)

First difference  $\Delta Y_t \equiv Y_t - Y_{t-1} = \delta + \varepsilon_t$  is stationary

- Suppose  $Y_t = \delta + \theta t + Y_{t-1} + \varepsilon_t, \varepsilon_t \sim \text{stationary}$  (10.7)

First difference  $\Delta Y_t = \delta + \theta t + \varepsilon_t \sim \text{stationary after detrending}$

- Eqs. (10.5), (10.6), (10.7) represent unit root processes.



# 03 Unit Root Test

- The alternative stationary autoregressive hypotheses to Eqs. (10.5), (10.6), (10.7) are respectively:

$$Y_t = \lambda Y_{t-1} + \varepsilon_t \quad (|\lambda| < 1) \quad (10.8)$$

$$Y_t = \delta + \lambda Y_{t-1} + \varepsilon_t \quad (|\lambda| < 1) \quad (10.9)$$

$$Y_t = \delta + \theta t + \lambda Y_{t-1} + \varepsilon_t \quad (|\lambda| < 1) \quad (10.10)$$

- Correspondingly

$$\Delta Y_t = \gamma Y_{t-1} + \varepsilon_t \quad (10.11)$$

$$\Delta Y_t = \delta + \gamma Y_{t-1} + \varepsilon_t \quad (10.12)$$

$$\Delta Y_t = \delta + \theta t + \gamma Y_{t-1} + \varepsilon_t \quad (10.13)$$

where  $\gamma = \lambda - 1$ .

- For  $I(1)$  processes in Eqs. (10.5), (10.6), (10.7),  $\gamma \equiv \lambda - 1 = 0$ . Then test the null hypothesis of a unit root process,  $H_0: \gamma = 0$ . Since for stationary alternatives,  $|\lambda| < 1$ , more negatively estimated  $\gamma \Rightarrow$  higher likelihood of stationarity.

## 03 Unit Root Test

- Specifications (10.11), (10.12), (10.13) are generalized to include lags of  $\Delta Y_t$  to whiten the noise term  $\varepsilon_t$  (we use the strong case of making residual noise i.i.d.)

$$\Delta Y_t = \gamma Y_{t-1} + \beta_1 \Delta Y_{t-1} + \beta_2 \Delta Y_{t-2} + \cdots + \beta_k \Delta Y_{t-k} + e_t \quad (\text{no constant}) \quad (10.14)$$

$$\Delta Y_t = \delta + \gamma Y_{t-1} + \sum_{j=1}^k \beta_j \Delta Y_{t-j} + e_t \quad (\text{constant}) \quad (10.15)$$

$$\Delta Y_t = \delta + \theta t + \gamma Y_{t-1} + \sum_{j=1}^k \beta_j \Delta Y_{t-j} + e_t \quad (\text{constant and time trend}) \quad (10.16)$$

where  $e_t$  is i.i.d.

- To test if Eqs. (10.14), (10.15), (10.16) are unit root processes, run OLS (for some  $k$ )
- If  $\hat{\gamma}$  significantly  $< 0$ , then reject  $H_0$  of unit root. If not, there is evidence of a unit root process

## 03 Unit Root Test

Augmented Dickey-Fuller (ADF) tests: Tests using specifications with lagged  $\Delta Y_t$

- Compute 
$$x = \frac{\hat{\gamma}_{OLS}}{\text{OLS s.e.}(\hat{\gamma}_{OLS})}$$

It is the usual formula for  $t$ -value function, but in this case, is not distributed as Student- $t_{T-n}$  statistic where  $T$  is sample size and  $n$  is number of parameters

- It is a non-standard nondegenerate distribution.
- For a correctly specified  $k$  in Eqs. (10.14), (10.15), or (10.16), the probability distribution of the  $x$ -statistic (independent of  $k$ ) is found by simulations.

The distribution is reported by Dickey and Fuller.

See **pages 288 – 290 of book** for an explanation of how this distribution is derived.

# 03 Unit Root Test

- From the Dickey-Fuller table: if sample size  $T = 250$ 
  - No constant: computed  $x$ -statistic  $< -2.58$ , then reject  $H_0: \gamma = 0$  (or  $\lambda = 1$ )  $\rightarrow$  no unit root at 1% significance level
  - Constant:  $-3.14 < \text{computed } x\text{-statistic} < -2.88$ , then reject  $H_0: \gamma = 0$  (or  $\lambda = 1$ )  $\rightarrow$  no unit root at 5% significance level but cannot reject at 2.5% significance level.
  - Constant and time trend:  $-3.42 < \text{computed } x\text{-statistic} < -3.13$ , then cannot reject  $H_0: \gamma = 0$  (or  $\lambda = 1$ ) at 5% significance level
- Another check for unit root: autocorrelation function (ACF) is highly persistent or slow decay for unit root process

 Table 10.1: Critical Values for Dickey-Fuller  $t$ -Test

		Sample Size	$p$ -Values (probability of a smaller test value)			
Case:	T		0.01	0.025	0.05	0.10
No constant Eq. (10.14)	25		-2.65	-2.26	-1.95	-1.60
	50		-2.62	-2.25	-1.95	-1.61
	100		-2.60	-2.24	-1.95	-1.61
	250		-2.58	-2.24	-1.95	-1.62
	500		-2.58	-2.23	-1.95	-1.62
	$\infty$		-2.58	-2.23	-1.95	-1.62
Case:	T		0.01	0.025	0.05	0.10
Constant Eq. (10.15)	25		-3.75	-3.33	-2.99	-2.64
	50		-3.59	-3.23	-2.93	-2.60
	100		-3.50	-3.17	-2.90	-2.59
	250		-3.45	-3.14	-2.88	-2.58
	500		-3.44	-3.13	-2.87	-2.57
	$\infty$		-3.42	-3.12	-2.86	-2.57
Case:	T		0.01	0.025	0.05	0.10
Constant and time trend Eq. (10.16)	25		-4.38	-3.95	-3.60	-3.24
	50		-4.16	-3.80	-3.50	-3.18
	100		-4.05	-3.73	-3.45	-3.15
	250		-3.98	-3.69	-3.42	-3.13
	500		-3.97	-3.67	-3.42	-3.13
	$\infty$		-3.96	-3.67	-3.41	-3.13

Source: Fuller, W., "Introduction to Statistical Time Series , Second Edition," New York: Wiley, 1996.

# 04 Purchasing Power Parity

$P_t$  : UK national price index in £

$P_t^*$  : U.S. national price index in USD

$e_t$  : spot exchange rate: number of £ per \$

- Absolute purchasing power parity (PPP) version:  $P_t = e_t P_t^*$  or  $e_t = P_t / P_t^*$

$$\ln P_t = \ln e_t + \ln P_t^*$$

$$d \ln P_t = d \ln e_t + d \ln P_t^*$$

$$\frac{dP_t}{P_t} = \frac{de_t}{e_t} + \frac{dP_t^*}{P_t^*}$$

$$\frac{\Delta P_t}{P_t} = \frac{\Delta e_t}{e_t} + \frac{\Delta P_t^*}{P_t^*} \quad \text{or} \quad \frac{\Delta e_t}{e_t} = \frac{\Delta P_t}{P_t} - \frac{\Delta P_t^*}{P_t^*}$$

- Relative PPP version: Percent change in exchange rate = Inflation rate difference



# 04 Purchasing Power Parity

Example:

If U.S. inflation rate is 5%, UK inflation rate is 10%, both over horizon  $T$  years, then

$\Delta e_t / e_t = 10\% - 5\% = 5\%$ , \$ is expected to appreciate by 5% against £ over  $T$  years.

- The real exchange rate (real £ per \$):  $r_t = e_t P_t^* / P_t$

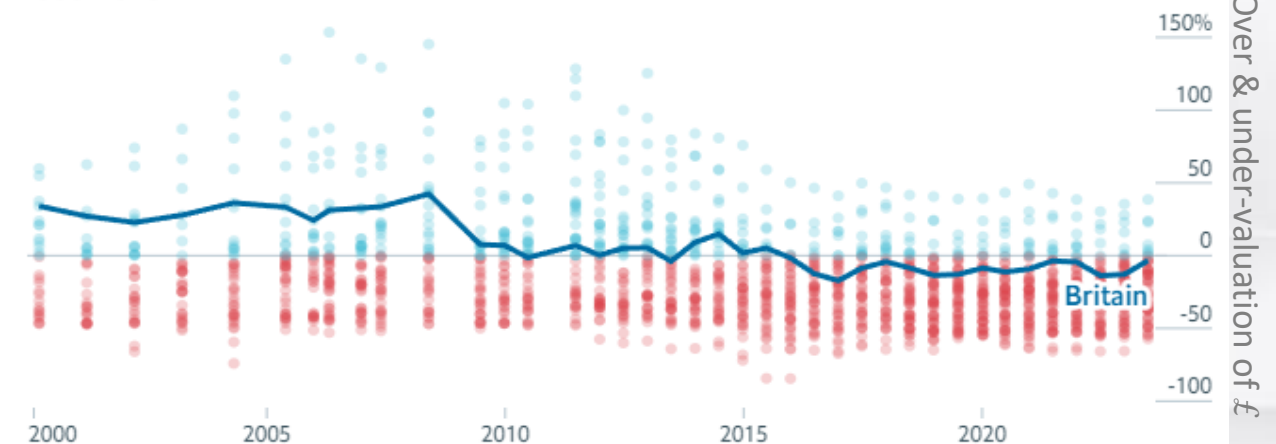
$$r_t = \frac{\text{price of US burger in } \pounds}{\text{price of UK burger in } \pounds}$$

$$\text{or} = \frac{\text{price of US good in } \pounds}{\text{price of UK good in } \pounds}$$

Implication: If US can sell US goods and fetch more Pounds than pay Pounds for similar UK goods, then US has positive or better terms of trade. Real £ per \$  $> 1$  (£ undervalued)

A Big Mac costs £4.19 in Britain and US\$5.58 in the United States. The implied exchange rate is 0.75. The difference between this and the actual exchange rate, 0.78, suggests the British pound is 3.4% undervalued

2000-2023



Source: The Economist, Aug 3, 2023

# 04 Purchasing Power Parity

- The real exchange rate (log form):  $\ln r_t = \ln e_t + \ln P_t^* - \ln P_t$

Under absolute PPP,  $r_t = 1$ ,  $\ln r_t = 0$ . But more generally,  $\ln r_t$  is a random variable.

- Suppose the linear combination:

$$\ln r_t = \begin{pmatrix} 1 & 1 & -1 \end{pmatrix} \begin{pmatrix} \ln e_t \\ \ln P_t^* \\ \ln P_t \end{pmatrix}$$

Is stationary and not a unit root process

Then  $\ln e_t$ ,  $\ln P_t^*$  and  $\ln P_t$ : cointegrated with cointegrating vector  $\begin{pmatrix} 1 & 1 & -1 \end{pmatrix}$

- Interpretation of PPP/ Long-run PPP:  $\ln r_t$  may deviate from 0 but will over time revert back to its mean at 0.
- If long-run PPP does not hold  $\Rightarrow \ln r_t$  may deviate from 0 and not return to it. It can then be described as a unit root process:  $\ln r_t = \ln r_{t-1} + \eta_t$  (10.25)  
 where  $\eta_t$  is stationary with zero mean



# 04 Purchasing Power Parity

- Check the validity of the long-run PPP using Eq. (10.25)
- Run OLS on

$$\Delta \ln r_t = \delta + \theta t + \gamma \ln r_{t-1} + \sum_{j=1} \beta_j \Delta \ln r_{t-j} + \xi_t$$

$$\Delta \eta_t = \sum_{j=1} \beta_j \Delta \ln r_{t-j} + \xi_t, \xi_t \text{ is i.i.d.}$$

- The null hypothesis of unit root process of  $\ln r_t$  is  $H_0: \gamma = 0$   
If unit root is rejected (accepted)  $\Rightarrow$  long-run PPP holds (does not hold)

# 04 Purchasing Power Parity, 1960-2001

Table 10.2: Augmented DF Unit Root Test of  $\ln e_t$ .

$$\Delta \ln e_t = \delta + \theta t + \gamma \ln e_{t-1} + \sum_{j=1} \beta_j \Delta \ln e_{t-j} + \xi_t. \text{ Sample size 42}$$

ADF Test Statistic	-1.776037	1% Critical Value		-4.16
Coefficient	Estimate	Std. Error	<i>t</i> -Statistic	Prob.
$\gamma$	-0.280485	0.157928	-1.776037	0.0859
$\beta_1$	0.392861	0.192132	2.044747	0.0497
$\beta_2$	0.121412	0.185310	0.655185	0.5173
$\beta_3$	-0.191780	0.184113	-1.041640	0.3059
$\beta_4$	-0.081663	0.187675	-0.435129	0.6666
Constant $\delta$	-0.272398	0.178452	-1.526448	0.1374
Time Trend $\theta$	0.004542	0.003192	1.423116	0.1650
<i>R</i> -squared	0.385694	Mean dependent var		1.017981
Adjusted <i>R</i> -squared	0.262833	S.D. dependent var		0.083637
S.E. of regression	0.071809	Akaike info criterion		-2.260947
Sum squared resid.	0.154697	Schwarz criterion		-1.955179

- (1) The ADF test-statistic with constant and trend of  $-1.7760 > -4.16$  at 1% critical level.
- (2) It is also greater than  $-3.18$  at 10% critical level.
- (3) Cannot reject  $H_0$ :  $\ln e_t$  during 1960-2001 follows a unit root process.

# 04 Purchasing Power Parity, 1960-2001

Table 10.6: Augmented DF Unit Root Test of  $\ln r_t$ .

$\Delta \ln r_t = \delta + \theta t + \gamma \ln r_{t-1} + \sum_{j=1} \beta_j \Delta \ln r_{t-j} + \xi_t$  vide Eq. (10.26). Sample size 42

ADF Test Statistic	-3.096016	1% Critical Value		-4.16
Variable	Coefficient	Std. Error	<i>t</i> -Statistic	Prob.
$\gamma$	-0.663089	0.214175	-3.096016	0.0042
$\beta_1$	0.560278	0.192777	2.906358	0.0068
$\beta_2$	0.360211	0.185043	1.946631	0.0610
$\beta_3$	0.054125	0.188122	0.287711	0.7755
$\beta_4$	0.091169	0.188378	0.483969	0.6319
Constant $\delta$	0.006824	0.027781	0.245636	0.8076
Time Trend $\theta$	0.004848	0.002017	2.403897	0.0226
<i>R</i> -squared	0.422015	Mean dependent var		0.002645
Adjusted <i>R</i> -squared	0.306418	S.D. dependent var		0.084680
S.E. of regression	0.070523	Akaike info criterion		-2.297094
Sum squared resid	0.149205	Schwarz criterion		-1.992326

- (1)  $\ln r_t$ : Cannot reject null of unit root (for constant + time trend) at 10% significance level
- (2) In real exchange rate  $r_t$  with a unit root: long-run PPP does not hold and that disequilibrium from PPP or deviations  $r_t$  from 0 do not have tendency to revert back toward 0.

# 04 Purchasing Power Parity, 1960-2001



Figure 10.2: Log Real Exchange 1960 till 2001,  $\ln r_t = \ln e_t + \ln P_t^* - \ln P_t$

Fig. 10.2 shows log real exchange rate in £ per \$ are mostly negative  $\Rightarrow$  better terms of trade and competitiveness favoring UK from 1960 to 2001. £ over-valued.

# 05 Test of Cointegration

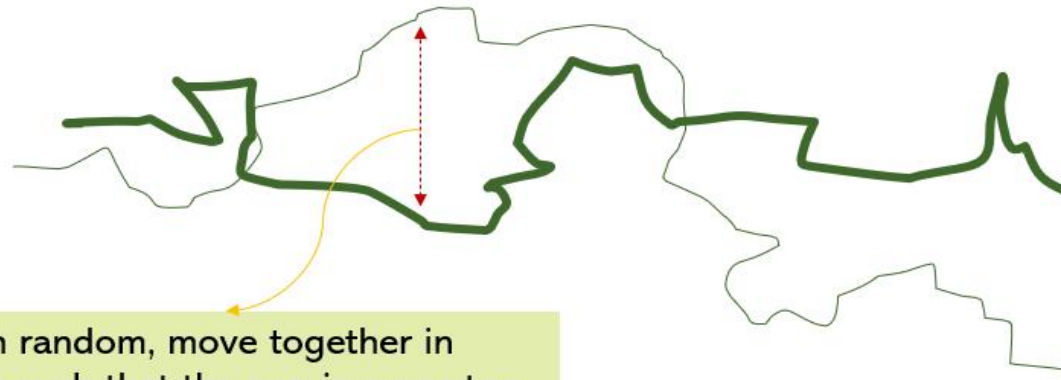
## A Drunk and Her Dog: An Illustration of Cointegration and Error Correction

Michael P. Murray

The American Statistician

[Vol. 48, No. 1 \(Feb., 1994\)](#), pp. 37-39 (3 pages)

Published By: Taylor & Francis, Ltd.



Paths though random, move together in some fashion such that the gap is never too wide – paths are cointegrated, gap is error correction



From [open source web](#). I could only find picture of a "he"

# 05 Test of Cointegration

- If  $Y_t$  and  $Z_t$  are unit root processes

$$Y_t = c + dZ_t + w_t$$

$d \neq 0$  and  $w_t$  is stationary  $\Rightarrow Y_t$  and  $Z_t$  can be cointegrated with cointegrating vector  $(1, -d)$

- In a more general setup, we could have a vector of either unit root  $I(1)$  or root-stationary  $I(0)$  r.v.'s  $X_t$  of order  $n \times 1$  whereby there are a number of combinations of the elements that could be co-integrated.
- We can employ the **Johansen maximum eigenvalue test statistic** and/or the **Johansen trace test statistic** to verify the number of cointegrating vectors present in  $X_t$ .



# 05 Test of Cointegration

- Consider two different stochastic processes:

$$X_{1,t} = a_1 + b_1 t + c_1 X_{1,t-1} + d_1 X_{2,t-1} + e_{1,t}$$

$$X_{2,t} = a_2 + b_2 t + c_2 X_{1,t-1} + d_2 X_{2,t-1} + e_{2,t}$$

where  $e_{1,t}$ ,  $e_{2,t}$  are independent white noises

$$\Delta X_{1,t} = a_1 + b_1 t + (c_1 - 1)X_{1,t-1} + d_1 X_{2,t-1} + e_{1,t}$$

$$\Delta X_{2,t} = a_2 + b_2 t + c_2 X_{1,t-1} + (d_2 - 1)X_{2,t-1} + e_{2,t}$$

- Univariate stationary  $\Delta X_{1,t}$ ,  $\Delta X_{2,t}$  stochastic processes can be stated as Vector Autoregressive (VAR) process

$$\begin{pmatrix} \Delta X_{1,t} \\ \Delta X_{2,t} \end{pmatrix} = \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} + \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} t + \begin{pmatrix} c_1 - 1 & d_1 \\ c_2 & d_2 - 1 \end{pmatrix} \begin{pmatrix} X_{1,t-1} \\ X_{2,t-1} \end{pmatrix} + \begin{pmatrix} e_{1,t} \\ e_{2,t} \end{pmatrix}$$

Or write as  $\Delta X_t = \mu_0 + \mu_1 t + \Pi X_{t-1} + e_t$

- Suppose  $X_{1,t}$  and  $X_{2,t}$  are unit root I(1) processes. Hence are  $X_{1,t-1}$  and  $X_{2,t-1}$ .

If  $X_{1,t}$  and  $X_{2,t}$  are not cointegrated, then  $\Pi = 0$ , or  $c_1 = d_2 = 1$  and  $d_1 = c_2 = 0$ .

If there is one cointegrating vector, then either one of  $(c_1 - 1 \quad d_1)$  or  $(c_2 \quad d_2 - 1)$  is zero while the other is not, so  $\Pi$  is of rank 1.

If there are two cointegrating vectors, then rank of  $\Pi$  is 2.



# 05 Test of Cointegration

- More generally, consider a  $n \times 1$  dimension Vector Autoregressive Process VAR(p) with possible constant and time trend:

$$X_t = \mu_0 + \mu_1 t + \Phi_1 X_{t-1} + \dots + \Phi_p X_{t-p} + a_t \quad (10.30)$$

where  $a_t$ : i.i.d. vector  $\sim N(0, \Omega)$

Elements of  $X_t$ : either  $I(1)$  or  $I(0)$

Dimension of  $\Phi_i : n \times n$

- An (vector) error correction model (ECM) for the VAR(p) process  $X_t$  by re-arranging Eq.(10.30):

$$\Delta X_t = \mu_0 + \mu_1 t + \Pi X_{t-1} + \Phi_1^* \Delta X_{t-1} + \dots + \Phi_{p-1}^* \Delta X_{t-p+1} + a_t \quad (10.31)$$

where  $\Phi_j^* = -\sum_{i=j+1}^p \Phi_i$  and  $\Pi_{n \times n} = \sum_{i=1}^p \Phi_i - I_{n \times n}$

- $\sum_{k=1}^{p-1} \Phi_k^* \Delta X_{t-k}$  is the autoregressive distributed lags, captures short-run impact on LHS  $\Delta X_t$
- $\Pi_{n \times n} X_{t-1} = (\sum_{k=1}^{p-1} \Phi_k - I) X_{t-1}$  is the error correction, captures the deviation and adjustment toward the long-run equilibrium since it is stationary and will revert to zeros at some points

# 05 Test of Cointegration

- If all elements of  $X_t$  are  $I(0)$ , then in Eq.(10.31), add  $X_{t-1}$  to both sides.

Then LHS  $X_t$  is stationary

so RHS (except for time-trend) has stationary terms in  $\Delta X_{t-i}$ 's +  $(I + \Pi) X_{t-1}$

$\Rightarrow$  Any  $n$  linear combinations of  $X_{t-1}$  is stationary, hence  $\Pi$  is of full rank  $n$

- If some elements (at least one) of  $X_t$  are  $I(1)$ :

LHS  $\Delta X_t$  is stationary

If there is no linear combination of  $X_{t-1}$  that is stationary, i.e., elements of  $X_{t-1}$  are **not cointegrated**, then for RHS to be stationary, **rank**  $(\Pi) = 0$  or  $\Pi = 0$

# 05 Test of Cointegration

- The intermediate case: if some elements of  $X_t$  are  $I(1)$ , and there **exists  $m < n$  number of cointegrating  $n \times 1$  vectors**, then can find  $m < n$  numbers of independent rows of  $\Pi$  such that  $\Pi X_{t-1}$  is stationary.
  - **Rank( $\Pi$ ) =  $m$**

- Write Eq.(10.31) for detrended  $X_t$ s:

$$\Delta X_t = \mu_0 + \alpha \beta^T X_{t-1} + \Phi_1^* \Delta X_{t-1} + \cdots + \Phi_{p-1}^* \Delta X_{t-p+1} + a_t \quad (10.32)$$

where  $\Pi_{n \times n} = \alpha_{n \times m} \beta_{n \times m}^T$  ( $m \leq n$ ), so rank of  $\Pi$  is at most  $m$  ( $m$  can also be equal to  $n$  here). Rank of  $\Pi$  can still = 0, or  $< m$  if the elements in  $\alpha$  or  $\beta$  have linear dependencies.

- The log likelihood function of sample observations on detrended  $X_t$  is:

$$\ln L = -\frac{Tp}{2} \ln(2\pi) - \frac{T}{2} \ln|\Omega| - \frac{1}{2} \sum_{t=1}^T a_t^T \Omega^{-1} a_t$$

# 05 Test of Cointegration

- Perform two auxiliary ML (or OLS) regression :

$$\Delta X_t = \mu_c + C_1^* \Delta X_{t-1} + \cdots + C_{p-1}^* \Delta X_{t-p+1} + u_t \quad (10.34)$$

$$X_{t-1} = \mu_d + D_1^* \Delta X_{t-1} + \cdots + D_{p-1}^* \Delta X_{t-p+1} + v_t \quad (10.35)$$

From Eqs. (10.34), (10.35), obtain

$$u_t = \alpha \beta^T v_t + a_t$$

- OLS fitted residuals  $\hat{u}_t$  and  $\hat{v}_t$  from Eqs. (10.34), (10.35), given  $\Pi = \alpha \beta^T$ , are used to construct the maximum likelihood estimator of  $\Omega$ ,  $\hat{\Omega}$

$$\hat{\Omega} = \frac{1}{T} \sum_{t=1}^T (\hat{u}_t - \Pi \hat{v}_t) (\hat{u}_t - \Pi \hat{v}_t)^T = \hat{R}_{uu} - \Pi \hat{R}_{vu} - \hat{R}_{uv} \Pi^T + \Pi \hat{R}_{vv} \Pi^T$$

$$\text{where } \hat{R}_{uu} = \frac{1}{T-p} \sum_{t=p+1}^T \hat{u}_t \hat{u}_t^T, \hat{R}_{uv} = \frac{1}{T-p} \sum_{t=p+1}^T \hat{u}_t \hat{v}_t^T, \text{ and } \hat{R}_{vv} = \frac{1}{T-p} \sum_{t=p+1}^T \hat{v}_t \hat{v}_t^T$$

- Ignoring constants, asymptotically, concentrating out  $\alpha$  (see **details** in pages 299 – 304 of book):

$$\ln L = -\frac{T}{2} \ln |\hat{\Omega}| = -\frac{T}{2} \ln |\hat{R}_{uu}| \left| \beta^T \left( \hat{R}_{vv} - \hat{R}_{vu} \hat{R}_{uu}^{-1} \hat{R}_{uv} \right) \beta \right| / \left| \beta^T \hat{R}_{vv} \beta \right|$$

# 05 Test of Cointegration

- Let the  $m \leq n$  eigenvectors of  $\hat{R}_{vv}^{-1} \hat{R}_{vu} \hat{R}_{uu}^{-1} \hat{R}_{uv}$  be estimate  $\hat{\beta}_{n \times m}$  and the corresponding eigenvalues be contained in diagonal  $\hat{\Lambda}_{m \times m}$  where

$$\left( \hat{R}_{vv}^{-1} \hat{R}_{vu} \hat{R}_{uu}^{-1} \hat{R}_{uv} \right) \hat{\beta}_{n \times m} = \hat{\beta}_{n \times m} \hat{\Lambda}_{m \times m}$$

- Then  $\hat{\beta}^T \hat{R}_{vu} \hat{R}_{uu}^{-1} \hat{R}_{uv} \hat{\beta} = \hat{\beta}^T \hat{R}_{vv} \hat{\beta} \hat{\Lambda}$
- Normalize  $\hat{\beta}$  so  $\hat{\beta}^T \hat{R}_{vv} \hat{\beta} = I$ , then  $\hat{\beta}^T \hat{R}_{vu} \hat{R}_{uu}^{-1} \hat{R}_{uv} \hat{\beta} = \hat{\Lambda}$

and 
$$\frac{|\beta^T (\hat{R}_{vv} - \hat{R}_{vu} \hat{R}_{uu}^{-1} \hat{R}_{uv}) \beta|}{|\beta^T \hat{R}_{vv} \beta|} = \frac{|I - \hat{\Lambda}|}{|I|} = \begin{vmatrix} 1 - \hat{\lambda}_1 & 0 & 0 & \dots & 0 \\ 0 & 1 - \hat{\lambda}_2 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & \dots & 1 - \hat{\lambda}_m & 0 \end{vmatrix}$$

- Hence the likelihood becomes

$$\ln L = -\frac{T}{2} \ln |I - \hat{\Lambda}|$$

# 05 Test of Cointegration

- In Johansen's **maximum eigenvalue** test:

$$H_0: \text{Rank}(\Pi) = m \text{ vs } H_A: \text{Rank}(\Pi) = m + 1$$

Under  $H_0$ , the  $(m+1)^{\text{th}}$  eigenvalue  $\lambda_{m+1} = 0$ , hence  $\ln(1 - \lambda_{m+1}) = 0$ .

Testing  $H_0$  is testing the restriction  $\ln(1 - \lambda_{m+1}) = 0$ .

- Restricted log likelihood under  $H_0$  is  $\ln L^r = -\frac{T}{2} \ln |I_{m \times m} - \hat{\Lambda}_{m \times m}|$

$$\text{Unrestricted log likelihood is } \ln L = -\frac{T}{2} \ln |I_{m+1 \times m+1} - \hat{\Lambda}_{m+1 \times m+1}|$$

- Likelihood ratio test involves the restricted  $\ln L^r$  and unrestricted  $\ln L$

$$-2 \ln \left[ \frac{L^r}{L} \right] = T (\ln |I_{m \times m} - \hat{\Lambda}_{m \times m}| - \ln |I_{m+1 \times m+1} - \hat{\Lambda}_{m+1 \times m+1}|) = -T \ln(1 - \hat{\lambda}_{m+1})$$

or  $-(T - p) \ln(1 - \hat{\lambda}_{m+1})$  which is positive as eigenvalues are positive and less than 1

- Test statistic  $-T \ln(1 - \hat{\lambda}_{m+1}) > 0$  has a non-standard (not chi-sq) distribution. If test statistic is too large, reject  $H_0$ , accept  $H_A$



# 05 Test of Cointegration

- In Johansen's **trace cointegration** test:

$$H_0: \text{Rank}(\Pi) = m \text{ vs } H_A: \text{Rank}(\Pi) > m$$

Under  $H_0$ , all  $(m+1)^{\text{th}}$  to  $n^{\text{th}}$  eigenvalue = 0.

Testing  $H_0$  is testing the restriction  $\sum_{i=m+1}^n \ln(1 - \lambda_i) = 0$ .

- Restricted log likelihood under  $H_0$  is  $\ln L^r = -\frac{T}{2} \ln |I_{m \times m} - \hat{\Lambda}_{m \times m}|$

Unrestricted log likelihood is  $\ln L = -\frac{T}{2} \ln |I_{n \times n} - \hat{\Lambda}_{n \times n}|$

- Likelihood ratio test involves the restricted  $\ln L^r$  and unrestricted  $\ln L$

$$-2 \ln \left[ \frac{L^r}{L} \right] = T \left( \ln |I_{m \times m} - \hat{\Lambda}_{m \times m}| - \ln |I_{n \times n} - \hat{\Lambda}_{n \times n}| \right) = -T \sum_{i=m+1}^n \ln(1 - \hat{\lambda}_i)$$

or  $-(T - p) \sum_{i=m+1}^n \ln(1 - \hat{\lambda}_i)$  which is positive as eigenvalues are positive and less than 1

- Test statistic  $-T \sum_{i=m+1}^n \ln(1 - \hat{\lambda}_i) > 0$  has a non-standard (not chi-sq) distribution. If test statistic is too large, reject  $H_0$ , accept  $H_A$



# 05 Application

- We illustrate the use of the Johansen method with an application to test the Fisher hypothesis. The Fisher hypothesis posits that in the long run, nominal interest rate and inflation rate move together, so real interest rate (nominal interest rate less inflation rate) are cointegrated.
- In the study by Hjalmasson and Pär Österholm (2007), they used monthly data on US short nominal interest rate  $i_t$  and CPI inflation rate  $\pi_t$  from January 1974 to October 2006. They found that the null hypothesis of a unit root cannot be rejected for inflation rate.
- However, they find that the nominal interest rate is “near to unit root”. (The power of ADF unit root test is not strong when processes are close to unit root, i.e., the test tends to accept unit root when it may not be.) They then set out to estimate the cointegrating rank of the vector  $(\pi_t, i_t)$ . Based on Akaike Information Criterion, they used  $p - 1 = 10$  distributed lags.
- As there are only two stochastic processes, the number of cointegration,  $r$ , is 0, 1, or 2 between the two variables  $\pi_t$  and  $i_t$ . Suppose  $r = 0$ , then  $\Pi = 0$  and there is no cointegration. Suppose  $r = 2$ , then this is the case where all elements of  $X_t$ , i.e. both  $\pi_t$  and  $i_t$  here are  $I(0)$ .

# 05 Application

The p-values are in brackets.

Table 10.7: Johansen Cointegration Tests

Null Hypothesis	$J$ trace-statistic	$J$ max eigenvalue statistic
$r = 0$	22.045 (0.028)	16.402 (0.042)
$r = 1$	5.642 (0.220)	5.642 (0.220)

- Suppose  $r = 1$ , then  $i_t - b\pi_t$  is stationary (ignoring constant and trend) for some  $b \neq 0$ , i.e. there exists a cointegrating vector  $\beta^T = (1, -b)$ . This is then consistent with the Fisher hypothesis.
- Using Johansen trace and max eigenvalue tests, the study found one cointegrating vector, i.e.  $r = 1$ , cannot be rejected, where  $\Pi = \alpha\beta^T$  and cointegrating vector  $\beta^T$  has dimension  $r \times n$  or  $1 \times 2$  in this case. Usually both the Johansen trace test and the maximum eigenvalue test proceed from a null of  $r = 0$  upward to a null of  $r = 1$ , and so on, until the null is not rejected. The two test results should be consistent and are complementary.
- Their Johansen tests showed that the null of  $H_0 : r = 0$  is rejected for trace test (i.e. alternative is  $r > 0$ ) and rejected for maximum eigenvalue test (i.e. alternative is  $r = 1$ ). Next, their Johansen tests showed that the null of  $H_0 : r = 1$  is not rejected for trace test (i.e. alternative  $r > 1$  is not acceptable) and not rejected for maximum eigenvalue test (i.e. alternative is  $r = 2$  is not acceptable). Hence the test conclusion is that  $r = 1$ . However, their study indicated that when nominal interest rate is nearly  $I(1)$  but could be  $I(0)$ , the cointegrating test may have low power.

# Practice Exercise (not graded)

+PPP.ipynb

POUND\_USD.csv

US\_CPI.csv

UK\_CPI.csv