

# Graphs and Flows in Networks

## Lecture 1

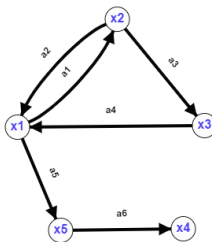
St. Petersburg State University, Russia

St. Petersburg, 2022

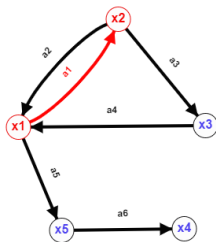
## Definition

A graph  $G = (X, A)$  is a set of vertices  $x_1, x_2, \dots, x_n$  (denoted by the set  $X$ ), and a set of edges  $a_1, a_2, \dots, a_m$  (denoted by the set  $A$ ) joining all or some of these vertices.

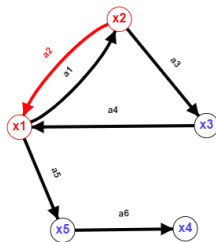
If the edges in  $A$  have a direction - which is usually shown by an arrow - they are called **arcs** and the resulting graph is called a **directed graph**.



An arc is denoted by the pair of initial and final vertices, its direction will be assumed to be from the first vertex to the second.

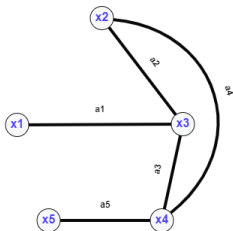


$$a_1 \longrightarrow (x_1, x_2)$$



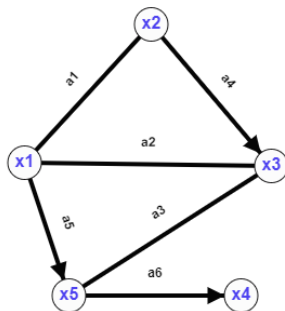
$$a_2 \longrightarrow (x_2, x_1)$$

If the edges have no orientation the are called **links** and the graph is **nondirected**.



In the case where  $G = (X, A)$  is a directed graph, but we want to disregard the direction of the arcs in  $A$ , the nondirected counterpart to  $G$  will be written as  $\overline{G} = (X, \overline{A})$ .

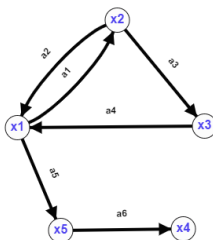
## Mixed graphs



## Correspondence $\Gamma$

An alternative way to describe a direct graph  $G = (X, \Gamma)$ , is by specifying:

- the set  $X$  of vertices
- a correspondence  $\Gamma : X \rightarrow X$  which shows how the vertices are related to each other.



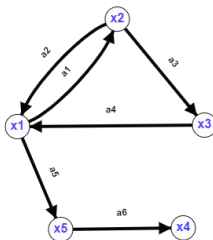
$$\Gamma(x_1) = \{x_2, x_5\}, \Gamma(x_2) = \{x_1, x_3\}$$

$$\Gamma(x_3) = ?, \Gamma(x_4) = ?, \Gamma(x_5) = ?$$

## Correspondence $\Gamma$

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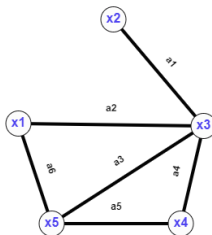
- the set  $X$  of vertices
- a correspondence  $\Gamma : X \rightarrow X$  which shows how the vertices are related to each other.



$$\Gamma(x_1) = \{x_2, x_5\}, \Gamma(x_2) = \{x_1, x_3\}$$

$$\Gamma(x_3) = \{x_1\}, \Gamma(x_4) = \emptyset, \Gamma(x_5) = \{x_4\}$$

In the case of nondirected or mixed graph, the correspondence  $\Gamma$  will be assumed to be those as for an equivalent directed graph in which every link has been replaced by two arcs in opposite directions.

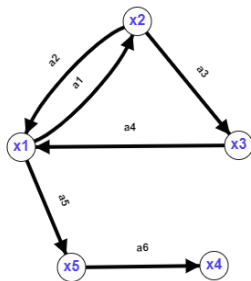


$$\Gamma(x_5) = \{x_1, x_3, x_4\}, \quad \Gamma(x_1) = \{x_3, x_5\}$$



## Inverse correspondence

$\Gamma^{-1}(x_i)$  – the set of those vertices  $x_k$  for which an arc  $(x_k, x_i)$  exists in  $G$ .

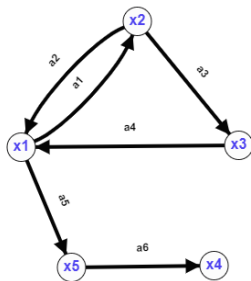


$$\Gamma^{-1}(x_1) = \{x_2, x_3\}, \quad \Gamma^{-1}(x_2) = \{x_1\}$$

$$\Gamma^{-1}(x_3) = ?, \quad \Gamma^{-1}(x_4) = ?, \quad \Gamma^{-1}(x_5) = ?$$

## Inverse correspondence

$\Gamma^{-1}(x_i)$  – the set of those vertices  $x_k$  for which an arc  $(x_k, x_i)$  exists in  $\Gamma$ .

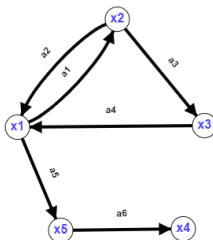


$$\Gamma^{-1}(x_1) = \{x_2, x_3\}, \Gamma^{-1}(x_2) = \{x_1\}$$

$$\Gamma^{-1}(x_3) = \{x_2\}, \Gamma^{-1}(x_4) = \{x_5\}, \Gamma^{-1}(x_5) = \{x_1\}$$

$$X_q = \{x_1, x_2, \dots, x_q\}$$

$$\Gamma(X_q) = \Gamma(x_1) \cup \Gamma(x_2) \cup \dots \cup \Gamma(x_q)$$



$$\Gamma(\{x_2, x_5\}) = \{x_1, x_3, x_4\}, \quad \Gamma(\{x_1, x_3\}) = ?$$

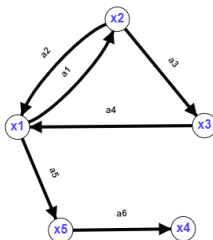
The double correspondence

$$\Gamma^2(x_1) = \Gamma(\Gamma(x_1)) = \Gamma(\{x_2, x_5\}) = \{x_1, x_3, x_4\}$$

$$\Gamma^3(x_1) = ?, \quad \Gamma^{-2}(x_1) = ?$$

$$X_q = \{x_1, x_2, \dots, x_q\}$$

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$$\Gamma(\{x_2, x_5\}) = \{x_1, x_3, x_4\}, \quad \Gamma(\{x_1, x_3\}) = \{x_1, x_2, x_5\}$$

The double correspondence

$$\Gamma^2(x_1) = \Gamma(\Gamma(x_1)) = \Gamma(\{x_2, x_5\}) = \{x_1, x_3, x_4\}$$

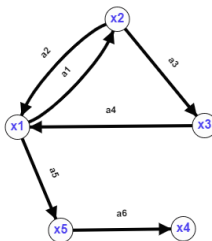
$$\Gamma^3(x_1) = \{x_2, x_5, x_1\}, \quad \Gamma^{-2}(x_1) = \{x_1, x_2\}$$

## Definition

Arcs which have a common terminal vertex are called **adjacent**.

## Definition

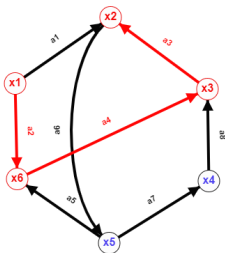
Two vertices  $x_i$  and  $x_j$  are called **adjacent** if either arc  $(x_i, x_j)$  or arc  $(x_j, x_i)$  or both exist in the graph.



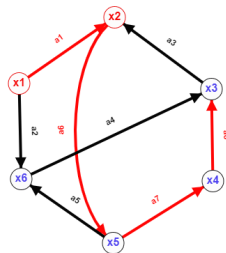
$a_2, a_4;$     $a_2, a_5;$     $x_2, x_3;$     $x_4, x_5$

# Definition

A **path** in a directed graph is any sequence of arcs where the final vertex of one is the initial vertex of the next one.



$a_2, a_4, a_3$



$a_1, a_6, a_7, a_8$

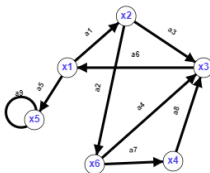
$a_3, a_6, a_5, a_2$ —?

## Definition

A **simple** path is a path which does not use the same **arc** more than once.

## Definition

An **elementary** path is a path which does not use the same **vertex** more than once.

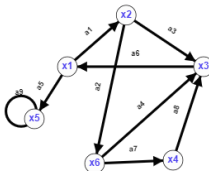


## Definition

A **loop** is an arc whose initial and final vertices are the same

## Definition

A **circuit** is a path  $a_1, a_2, \dots, a_q$  in which the initial vertex of  $a_1$  coincides with the final vertex of  $a_q$ .



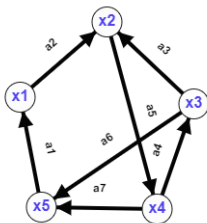
$a_2, a_7, a_8, a_6, a_1$

$a_1, a_3, a_6$



## Definition

An elementary circuit which passes through all the  $n$  vertices of a graph  $G$  is called a **Hamiltonian circuit**.



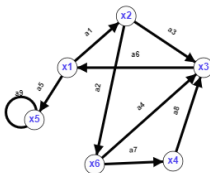
example - ?

## Definition

A **chain** is a sequence of links  $(\bar{a}_1, \bar{a}_2, \dots, \bar{a}_q)$  in which every link  $\bar{a}_i$ , except perhaps the first and last links, is connected to the links  $\bar{a}_{i-1}$  and  $\bar{a}_{i+1}$  by its two terminal vertices.

## Definition

A **cycle** is a chain  $x_1, x_2, \dots, x_q$  in which the beginning and end vertices are the same, i.e. in which  $x_1 = x_q$ .



$$\bar{a}_1, \bar{a}_3, \bar{a}_4;$$

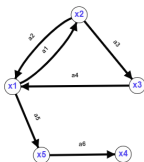
$$\bar{a}_3, \bar{a}_4, \bar{a}_2$$

## Definition

The number of arcs which have a vertex  $x_i$  as their initial vertex is called the **outdegree** of vertex  $x_i$ .

## Definition

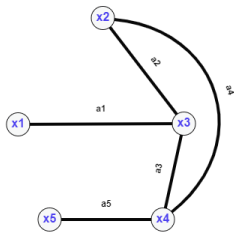
The number of arcs which have a vertex  $x_i$  as their final vertex is called the **indegree** of vertex  $x_i$ .



$$d_o(x_2) = |\Gamma(x_2)| = 2, \quad d_t(x_2) = |\Gamma^{-1}(x_2)| = 1$$

$$\sum_{i=1}^n d_o(x_i) = \sum_{i=1}^n d_t(x_i) = m$$

For a nondirected graph:  $d(x_i) = |\Gamma(x_i)|$  – the degree of a vertex  $x_i$ .



$$d(x_3) = 3$$

Let  $G = (X, A)$ .

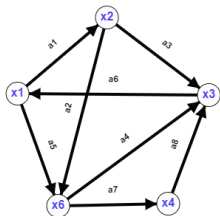
### Definition

A **partial** graph  $G_p$  of  $G$  is the graph  $(X, A_p)$  with  $A_p \subset A$ . Thus a partial graph is a graph with the same number of vertices but with only a subset of the arcs of the original graph.

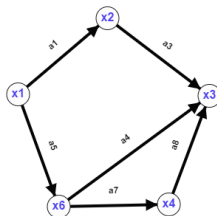
### Definition

A **subgraph**  $G_s$  is the graph  $(X_s, \Gamma_s)$  with  $X_s \subset X$  and for every  $x_i \in X_s$ ,  $\Gamma_s(x_i) = \Gamma(x_i) \cap X_s$ . Thus, a subgraph has only a subset  $X_s$  of the set of vertices of the original graph but contains all the arcs whose initial and final vertices are both within this subset.

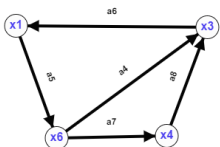
A partial subgraph is a partial graph of the subgraph.



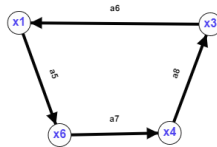
Graph



Partial graph



Subgraph

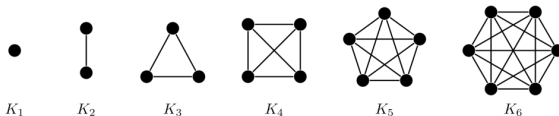


Partial subgraph

## Definition

A graph  $G = (X, A)$  is said to be **complete** if for every pair of vertices  $x_i$  and  $x_j$  in  $X$ , there exists a link  $\overline{(x_i, x_j)}$  in  $\overline{G} = (X, \overline{A})$  i.e. there must be at least one arc joining every pair of vertices.

The complete nondirected graph on  $n$  vertices is denoted by  $K_n$ .

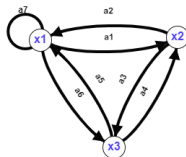


## Definition

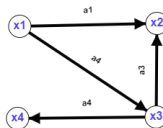
A graph  $(X, A)$  is said to be **symmetric** if, whenever an arc  $(x_i, x_j)$  is one of the arcs in the set  $A$  of arcs, the opposite arc  $(x_j, x_i)$  is also in the set  $A$ .

## Definition

An **antisymmetric** graph is a graph in which whenever an arc  $(x_i, x_j) \in A$ , the opposite arc  $(x_j, x_i) \notin A$ .



Symmetric graph

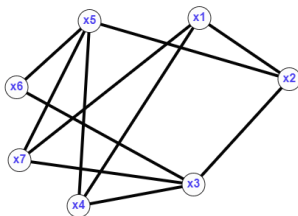


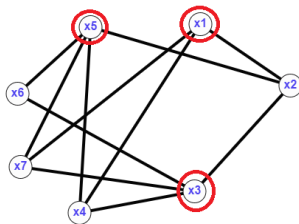
Antisymmetric graph

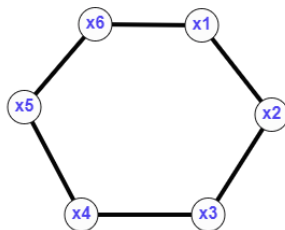


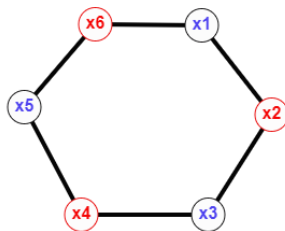
## Definition

A nondirected graph  $G = (X, A)$  is said to be bipartite, if the set  $X$  of its vertices can be partitioned into two subsets  $X^a$  and  $X^b$  so that all arcs have one terminal vertex in  $X^a$  and the other in  $X^b$ . A directed graph  $G$  is said to be bipartite if its nondirected counterpart  $G$  is bipartite.









## Theorem

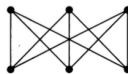
*A nondirected graph  $G$  is bipartite if and only if it contains no circuits of odd cardinality.*

# Definition

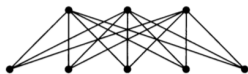
A bipartite graph  $G = (X^a \cup X^b, A)$  is said to be complete if for every two vertices  $x_i \in X^a$  and  $x_j \in X^b$  there exists a link  $(x_i, x_j)$  in  $G = (X, A)$ .



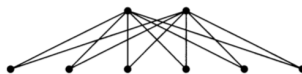
$K_{2,3}$



$K_{3,3}$



$K_{3,5}$

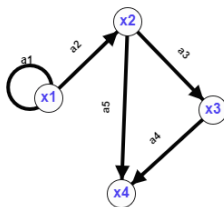


$K_{2,6}$

## The adjacency matrix

Given a graph  $G$ , its **adjacency matrix** is denoted by  $A = [a_{ij}]$  and is given by:

- $a_{ij} = 1$  if arc  $(x_i, x_j)$  exists in  $G$
- $a_{ij} = 0$  if arc  $(x_i, x_j)$  does not exist in  $G$ .



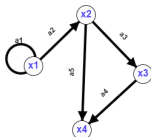
$$A = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

## The incidence matrix

Given a graph  $G$  of  $n$  vertices and  $m$  arcs, **the incidence matrix** of  $G$  is denoted by  $B = [b_{ij}]$  and is an  $n \times m$  matrix defined as follows.

- $b_{ij} = 1$  if  $x_i$  is the initial vertex of arc  $a_j$
- $b_{ij} = -1$  if  $x_i$  is the final vertex of arc  $a_j$

and  $b_{ij} = 0$  if  $x_i$  is not a terminal vertex of arc  $a_j$  or if  $a_j$  is a loop.



$$B = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & -1 & 1 & 0 & 1 \\ 0 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & -1 & -1 \end{pmatrix}$$