

Machine Learning with Accelerometer and GPS Data

Deliverable #1

- Features:
 - Priority I features: to identify road hazards
 - Feature 1.1: potholes and speedbumps
 - Feature 1.2: curvature/inclination of roads
 - Priority II features: future functionality (nice to have)
 - Feature 2.1: sub-standard roads (flooding, mud, etc.)
 - Feature 2.2: deterioration analysis of roads over time
 - Feature 2.3: road debris
- Schedule of Deliverables (All deadlines are Los Angeles Time)
 - Deliverable 2
 - Deadline: 11:59 pm September 15th
 - Exploratory data analysis on kyrgyzstan.csv
 - More research on machine learning techniques
 - Decide on two machine learning models for potholes/speedbumps
 - Deliverable 3
 - Deadline: 11:59 pm September 29th
 - Two Trained potholes/speedbumps model that are ready to test
 - Decide on two machine learning models for inclination/curvature
 - Deliverable 4
 - Deadline: 11:59 pm October 13th
 - Two trained model for inclination/curvature that are ready to test
 - Deliverable 5
 - Deadline: 11:59 pm October 27th
 - Improvement/finalization of potholes/speedbumps model
 - Deliverable 6
 - Deadline: 11:59 pm November 10th
 - Improvement/finalization of inclination/curvature model
 - Deliverable 7
 - Deadline: 11:59 pm November 16th or 30th depending on our date of project presentation
 - Final model for potholes/speedbumps
 - Final model for inclination/curvature
 - Complete documentation for both models, including our recommendations of how to further train these models for Priority II features
 - Present this project during class
- What machine learning techniques we want to learn or apply on this project
 - Linear regression
 - Logistic regression (first to try for Priority I features)
 - Decision tree
 - Artificial neural networks
- What resources/help we need from Sandra/Kevin/Jens
 - HPC accounts with access to machine learning library, such as TensorFlow

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- First 50 rows of the raw dataset (kyrgyzstan.csv received)
- Guidance on machine learning techniques
- Requirements on documentation