

MA2001 Assignment 2

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(i) Using Example 3.1.8 from text,

$$U = \{(3t - 2s, s, t) \mid s, t \in \mathbb{R}\}$$

$$V = \{(2t - 3s, s, t) \mid s, t \in \mathbb{R}\}$$

(ii) Implicit notation

$$U \cap V = \{(x, y, z) \mid x + 2y - 3z = x + 3y - 2z = 0\}$$

Since

$$\begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix} \times \begin{pmatrix} 1 \\ 3 \\ -2 \end{pmatrix} = \begin{pmatrix} 5 \\ -1 \\ 1 \end{pmatrix}$$

Explicit notation

$$U \cap V = \{(5t, -t, t) \mid t \in \mathbb{R}\}$$

(iii) Let $w = (t' - 2, t' + 1, t') \in W$ be arbitrary. Since

$$(t' - 2) + 2(t' + 1) - 3t' = t'(1 + 2 - 3) - 2 + 2 = 0$$

we have $w \in U$. Since the choice of w is arbitrary, $W \subseteq U$.

(iv)

$$(t - 2) + 3(t + 1) - 2t = 0 \implies 2t + 1 = 0 \implies t = -\frac{1}{2}$$

$$\begin{aligned} U \cap V \cap W &= V \cap W && \text{as } W \subseteq U \\ &= \{(t - 2, t + 1, t) \mid t \in \mathbb{R}, (t - 2) + 3(t + 1) - 2t = 0\} \\ &= \{(t - 2, t + 1, t) \mid t = -\frac{1}{2}\} \\ &= \{(-\frac{1}{2} - 2, -\frac{1}{2} + 1, -\frac{1}{2})\} \\ &= \{(-\frac{5}{2}, \frac{1}{2}, -\frac{1}{2})\} \end{aligned}$$

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(i)

$$\left(\begin{array}{cccc|ccc} 1 & -1 & 0 & 0 & 1 & 0 & 1 \\ 2 & 1 & 1 & 2 & 0 & 2 & 1 \\ 0 & -3 & 1 & -4 & 1 & -1 & 2 \\ -1 & 1 & 0 & 0 & -1 & 0 & -1 \end{array} \right) \xrightarrow{rref} \left(\begin{array}{cccc|ccc} 1 & 0 & 0 & 1 & 1/2 & 1/2 & 1/2 \\ 0 & 1 & 0 & 1 & -1/2 & 1/2 & -1/2 \\ 0 & 0 & 1 & -1 & -1/2 & 1/2 & 1/2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

Since the system is consistent, $S_1 \subseteq \text{span}(S_2)$. By Theorem 3.2.10, $\text{span}(S_1) \subseteq \text{span}(S_2)$.

- (ii) From above, the system S_2 represents is not always consistent since its row-echelon form contains a zero row. Therefore $\text{span}(S_2) \neq \mathbb{R}^4$. (Alternatively, it is easy to show that $(0, 0, 0, 1) \notin \text{span}(S_2)$.)

(iii)

$$\left(\begin{array}{ccc|ccc|c} 1 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 2 & 1 & 0 & 1 & 0 & 0 \\ 1 & -1 & 2 & 0 & 0 & 1 & 0 \\ -1 & 0 & -1 & 0 & 0 & 0 & 1 \end{array} \right) \xrightarrow{rref} \left(\begin{array}{ccc|ccc|c} 1 & 0 & 0 & \cdots & \cdots & \cdots & \cdots \\ 0 & 1 & 0 & \cdots & \cdots & \cdots & \cdots \\ 0 & 0 & 1 & \cdots & \cdots & \cdots & \cdots \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 \end{array} \right)$$

$$(a, b, c, d) \notin \text{span}(S_1) \iff \text{the system is not consistent} \iff a + d \neq 0.$$

(iv) Let

$$\mathbf{A} = ((S_2)_1 \ (S_2)_2 \ (S_2)_3 \ (S_2)_4)$$

be a square matrix. By above $\text{rank}(\mathbf{A}) = 3$. By rank-nullity theorem we can write $\text{span}(\{\mathbf{n}\}) = \text{null}(\mathbf{A}^T)$ for some $\mathbf{n} \in \mathbb{R}^4$. Now

$$\text{span}(S_2) = \{\mathbf{A}\mathbf{v} \mid \mathbf{v} \in \mathbb{R}^4\} = \mathbf{C}(\mathbf{A}) = \mathbf{R}(\mathbf{A}^T) = \{\mathbf{v} \mid \mathbf{v} \cdot \mathbf{n} = 0\}$$

Therefore such equation exists. In fact it is $x + w = 0$.

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(i)

$$\begin{aligned} V_1 &= \{(t - 2s, s + 3t, 3s, t) \mid s, t \in \mathbb{R}\} \\ &= \{(-2s, s, 3s, 0) + (t, 3t, 0, t) \mid s, t \in \mathbb{R}\} \\ &= \text{span}(\{(-2, 1, 3, 0), (1, 3, 0, 1)\}) \end{aligned}$$

is a subspace of \mathbb{R}^4 .

(ii) Let

$$W = \text{span}(\{(1, 10, 3, 3)\})$$

Clearly W contains a vector of form $(*, *, 3, 3)$ and is a subspace of \mathbb{R}^4 . Now since

$$\begin{pmatrix} 1 \\ 10 \\ 3 \\ 3 \end{pmatrix} = \begin{pmatrix} -2 \\ 1 \\ 3 \\ 0 \end{pmatrix} + 3 \begin{pmatrix} 1 \\ 3 \\ 0 \\ 1 \end{pmatrix}$$

but $(-2, 1, 3, 0) \notin W$ we have $W \subset V$.

- (iii) Note that $(0, 1, 0, -1) \in V_2$ and $(-1, 1, -1, 1) \in V_2$ but $(0, 1, 0, -1) + (-1, 1, -1, 1) = (-1, 2, -1, 0) \notin V_2$. Therefore V_2 is not a subspace of \mathbb{R}^4 .

- (iv) $\{(0, 0, 0, 0)\} \subseteq V_2$ since $\mathbf{0} \in V_2$. Clearly the zero space is closed under vector addition and scalar multiplication.

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- (i) Since $S \subseteq \text{span}(S) = V$, $\mathbf{x} = a\mathbf{u} + b\mathbf{v} + c\mathbf{w}$ for some $a, b, c \in \mathbb{R}$ as $\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}$ is a basis for V . Then $\mathbf{u} + \mathbf{v} + \mathbf{w} + \mathbf{x} = (a+1)\mathbf{u} + (b+1)\mathbf{v} + (c+1)\mathbf{w}$ is a linear combination of $\mathbf{u}, \mathbf{v}, \mathbf{w}$.
- (ii) If $\mathbf{x} = \mathbf{u}$ then $\{\mathbf{u}, \mathbf{v}, \mathbf{x}\}$ are not linearly independent.
- (iii) If $\mathbf{x} = \mathbf{u}$ then $\mathbf{0} \in \{\mathbf{u} - \mathbf{x}, \mathbf{v} - \mathbf{x}, \mathbf{w} - \mathbf{x}\}$ are not linearly independent and therefore not a basis for V .

- (iv) $\{\mathbf{v}, \mathbf{w}\} \subset \{\mathbf{v}, \mathbf{w}, \mathbf{x}\} \implies \text{span}(\{\mathbf{v}, \mathbf{w}\}) \subset \text{span}(\{\mathbf{v}, \mathbf{w}, \mathbf{x}\})$. Let $\mathbf{y} \in \text{span}(\{\mathbf{v}, \mathbf{w}, \mathbf{x}\}) \setminus \text{span}(\{\mathbf{v}, \mathbf{w}\})$. Then $a \neq 0$ since for any $g, h \in \mathbb{R}$,

$$\begin{aligned}\mathbf{y} &= a\mathbf{x} + b\mathbf{v} + c\mathbf{w} \\ &= a(d\mathbf{u} + e\mathbf{v} + f\mathbf{w}) + b\mathbf{v} + c\mathbf{w} \\ &= (ad)\mathbf{u} + (ae + b)\mathbf{v} + (af + c)\mathbf{w} \\ &\neq g\mathbf{v} + h\mathbf{w}\end{aligned}$$

Since $a \neq 0$ we have $\text{span}(\{\mathbf{v}, \mathbf{w}, \mathbf{x}\}) = \text{span}(\{\mathbf{v}, \mathbf{w}, a\mathbf{x} + b\mathbf{v} + c\mathbf{w}\}) = \text{span}(\{\mathbf{u}, \mathbf{v}, \mathbf{w}\}) = V$.

- (v) Let $\mathbf{a}, \mathbf{b} \in V$ be arbitrary, and $U = \{\mathbf{y} + \mathbf{z} \mid \mathbf{z} \in V\}$. Since $\mathbf{a} + \mathbf{b} \in V$ and $\mathbf{y} = (\mathbf{y} + \mathbf{a} + \mathbf{b}) - (\mathbf{a} + \mathbf{b}) \notin V$, $(\mathbf{y} + \mathbf{a} + \mathbf{b}) \notin V$. Since $(\mathbf{y} + \mathbf{a}), (\mathbf{y} + \mathbf{b}) \in U$ but $(\mathbf{y} + \mathbf{a}) + (\mathbf{y} + \mathbf{b}) = \mathbf{y} + (\mathbf{y} + \mathbf{a} + \mathbf{b}) \notin U$, U is not a subspace of \mathbb{R}^n .

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- (i) Since S spans V it suffices to prove that vectors in S are linearly independent. Now

$$\begin{pmatrix} 1 & 1 & 2 & 3 & 4 \\ 1 & 2 & 2 & 3 & 3 \\ 1 & 1 & 2 & 2 & 3 \end{pmatrix} \xrightarrow{\text{rref}} \begin{pmatrix} 1 & 0 & 2 & 0 & 2 \\ 0 & 1 & 0 & 0 & -1 \\ 0 & 0 & 0 & 1 & 1 \end{pmatrix}$$

Since after Gauss-Jordan elimination there are no zero rows, vectors in S are linearly independent and therefore S is a basis for V .

- (ii) Since

$$\left(\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 1 & 2 & 1 & -5 \\ 2 & 2 & 2 & 0 \\ 3 & 3 & 2 & -3 \\ 4 & 3 & 3 & 2 \end{array} \right) \xrightarrow{\text{rref}} \left(\begin{array}{ccc|c} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & -5 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

$\mathbf{v} = (0, -5, 0, -3, 2) \in V$ and its coordinate vector is $(2, -5, 3)$ with respect to S .

- (iii) Since

$$\left(\begin{array}{ccc|c|c|c} 3 & 2 & 2 & 1 & 1 & 1 \\ 3 & 3 & 3 & 1 & 2 & 1 \\ 6 & 4 & 4 & 2 & 2 & 2 \\ 7 & 5 & 6 & 3 & 3 & 2 \\ 10 & 6 & 7 & 4 & 3 & 3 \end{array} \right) \xrightarrow{\text{rref}} \left(\begin{array}{ccc|c|c|c} 1 & 0 & 0 & 1/3 & -1/3 & 1/3 \\ 0 & 1 & 0 & -2/3 & 2/3 & 1/3 \\ 0 & 0 & 1 & 2/3 & 1/3 & -1/3 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$S \subseteq \text{span}(T) \implies \text{span}(S) \subseteq \text{span}(T)$. Since

$$\left(\begin{array}{ccc|c|c|c} 1 & 1 & 1 & 3 & 2 & 2 \\ 1 & 2 & 1 & 3 & 3 & 3 \\ 2 & 2 & 2 & 6 & 4 & 4 \\ 3 & 3 & 2 & 7 & 5 & 6 \\ 4 & 3 & 3 & 10 & 6 & 7 \end{array} \right) \xrightarrow{\text{rref}} \left(\begin{array}{ccc|c|c|c} 1 & 0 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 0 & 1 & 1 \\ 0 & 0 & 1 & 2 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$T \subseteq \text{span}(S) \implies \text{span}(T) \subseteq \text{span}(S)$. Therefore $\text{span}(S) = \text{span}(T)$. The coordinate vectors of T with respect to S are $\{(1, 0, 2), (0, 1, 1), (1, 1, 0)\}$. Since

$$\begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \\ 1 & 1 & 0 \end{pmatrix} \xrightarrow{\text{rref}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \mathbf{I}$$

The set of vectors T is linearly independent. Therefore T is also a basis for V .

- (iv)

$$\mathbf{w} = (3, 3, 6, 7, 10) + (2, 3, 4, 5, 6) - (2, 3, 4, 6, 7) = (3, 3, 6, 6, 9)$$

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(i) For \mathbf{A} ,

$$\begin{pmatrix} 1 & 3 & 1 & 3 \\ 3 & -1 & 3 & -1 \\ 2 & 1 & 2 & 1 \end{pmatrix} \xrightarrow{rref} \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Basis of null space is of form

$$\begin{pmatrix} x_1 \\ x_2 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} x_1 \\ x_2 \\ 0 \\ 1 \end{pmatrix}$$

Reading off rows with pivots,

$$S = \left\{ s \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} 0 \\ -1 \\ 0 \\ 1 \end{pmatrix} \mid s, t \in \mathbb{R} \right\}$$

Likewise for \mathbf{B} ,

$$\begin{pmatrix} 1 & 1 & 2 & 2 \\ 2 & 1 & 1 & 2 \\ 0 & 1 & 3 & 2 \end{pmatrix} \xrightarrow{rref} \begin{pmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 3 & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Hence,

$$T = \left\{ s \begin{pmatrix} 1 \\ -3 \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} 0 \\ -2 \\ 0 \\ 1 \end{pmatrix} \mid s, t \in \mathbb{R} \right\}$$

(ii) Basis of S is

$$\{\mathbf{B}(S) = \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ -1 \\ 0 \\ 1 \end{pmatrix}\}$$

Basis of T is

$$\{\mathbf{B}(T) = \begin{pmatrix} 1 \\ -3 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ -2 \\ 0 \\ 1 \end{pmatrix}\}$$

(iii)

$$\begin{pmatrix} -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \\ 1 & -3 & 1 & 0 \\ 0 & -2 & 0 & 1 \end{pmatrix} \xrightarrow{rref} \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} = \mathbf{I}$$

Therefore $\mathbf{B}(S) \cup \mathbf{B}(T)$ spans \mathbb{R}^4 and is a basis of \mathbb{R}^4 . Then $\mathbf{v} = (a\mathbf{s}_1 + b\mathbf{s}_2) + (c\mathbf{t}_1 + d\mathbf{t}_2) = \mathbf{s} + \mathbf{t}$ for some $a, b, c, d \in \mathbb{R}$. These constants are uniquely determined, otherwise the basis vectors are linearly dependent, which contradicts. Hence here \mathbf{s}, \mathbf{t} are uniquely determined.

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(i) Since

$$\left(\begin{array}{ccc|c} 1 & 4 & 2 & 1 \\ 0 & 3 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 3 & -3 & 1 \end{array} \right) \xrightarrow{rref} \left(\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{array} \right)$$

The system is inconsistent. Therefore $S \not\subseteq \{ax + by + cz = 1 \mid a, b, c \in \mathbb{R}\}$. Hence no such plane exists.

(ii)

$$\begin{aligned} U &= \{\mathbf{u}_1 + s(\mathbf{u}_1 - \mathbf{u}_3) + t(\mathbf{u}_1 - \mathbf{u}_4) \mid s, t \in \mathbb{R}\} \\ &= \{\mathbf{x} \mid \mathbf{x} \cdot ((\mathbf{u}_1 - \mathbf{u}_3) \times (\mathbf{u}_1 - \mathbf{u}_4)) = \mathbf{u}_1 \cdot ((\mathbf{u}_1 - \mathbf{u}_3) \times (\mathbf{u}_1 - \mathbf{u}_4))\} \\ &= \{\mathbf{x} \mid \mathbf{x} \cdot 14(1, 0, 0) = \mathbf{u}_1 \cdot 14(1, 0, 0)\} \\ &= \{(x, y, z) \mid x = 1\} \end{aligned}$$

$$\begin{aligned} V &= \{\mathbf{u}_2 + s(\mathbf{u}_2 - \mathbf{u}_3) + t(\mathbf{u}_2 - \mathbf{u}_4) \mid s, t \in \mathbb{R}\} \\ &= \{\mathbf{x} \mid \mathbf{x} \cdot ((\mathbf{u}_2 - \mathbf{u}_3) \times (\mathbf{u}_2 - \mathbf{u}_4)) = \mathbf{u}_2 \cdot ((\mathbf{u}_2 - \mathbf{u}_3) \times (\mathbf{u}_2 - \mathbf{u}_4))\} \\ &= \{\mathbf{x} \mid \mathbf{x} \cdot 2(4, 2, 1) = \mathbf{u}_2 \cdot 2(4, 2, 1)\} \\ &= \{(x, y, z) \mid 4x + 2y + z = 7\} \end{aligned}$$

The system is

$$\left(\begin{array}{ccc|c} 1 & 0 & 0 & 1 \\ 4 & 2 & 1 & 7 \end{array} \right)$$

(iii) Choose the three points to be $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\}$. Then

$$\left(\begin{array}{ccc} 1 & 4 & 2 \\ 0 & 3 & 1 \\ 1 & 1 & 1 \end{array} \right) \xrightarrow{rref} \left(\begin{array}{ccc} 1 & 0 & 2/3 \\ 0 & 1 & 1/3 \\ 0 & 0 & 0 \end{array} \right)$$

Since the null space is $\text{span}((-2, -1, 3))$, the equation of plane P is $-2x - y + 3z = 0$ which is a subspace of \mathbb{R}^3 .

(iv) Three points lie on a plane that corresponds to a subspace if and only if they lie on a plane that contains the origin. (\Leftarrow): Let $\mathbf{u} = (a, b, c), \mathbf{v} = (d, e, f) \in P$. Then $pa + qb + rc = pd + qe + rf = 0$ for some p, q, r determined by P . Then $p(a + d) + q(b + e) + r(c + f) = 0 \implies \mathbf{u} + \mathbf{v} \in P$. Since the origin acts as additive identity and points on P are closed under addition and scalar multiplication, P corresponds to a subspace. (\Rightarrow): A subspace contains an additive identity which in this case corresponds to the origin.