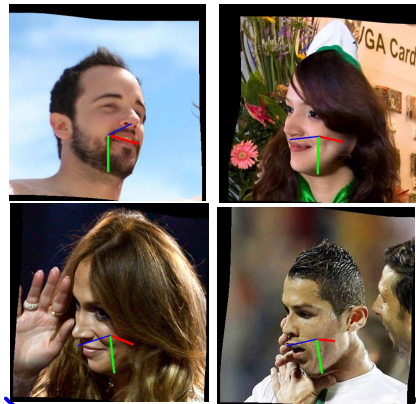


# Our approach

*Dataset*



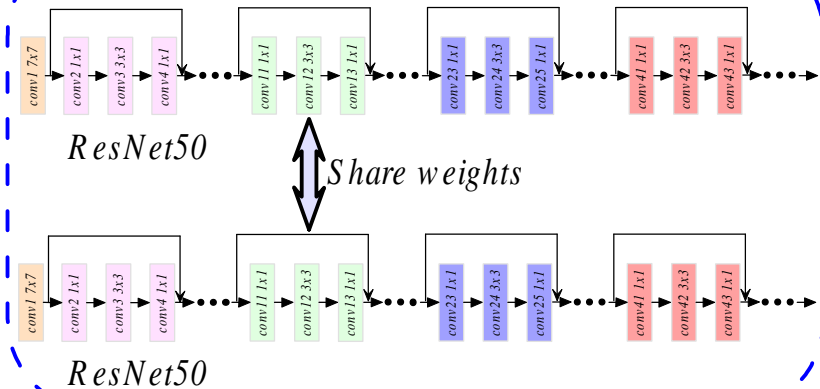
*Rank Label*

*yaw*

*pitch*

*roll*

*Siamese Network*



*Rank*

*Yaw*

*Pitch*

*Roll*

*Continue Pose Label*

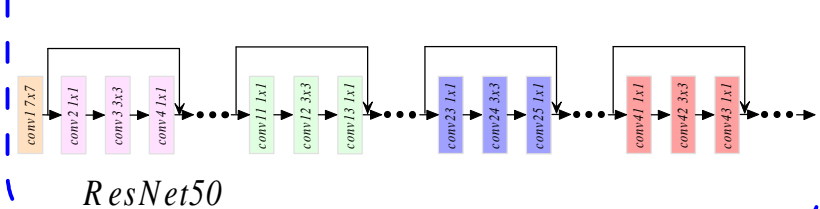
*yaw*

*pitch*

*roll*

*Initializing*

*Normal Network*



*Regression*

*Yaw*

*Pitch*

*Roll*