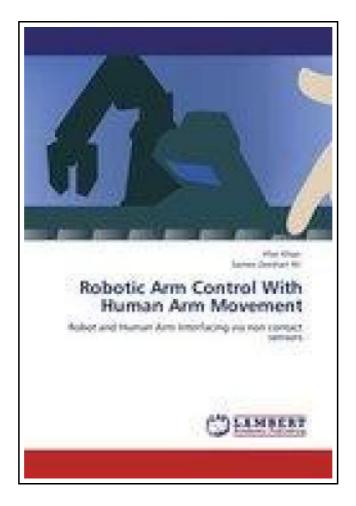
# Robotic Arm Control With Human Arm Movement



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(Prof. Damon Kautzer III)

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