1. My implementation here depends on A. I take A as an input and find a from A. The implementation is the same as the algrithm in 17-2 on note with simplification excluding all 0 entries in A.

The weight  $W=\frac{2}{3}$ , the eigenvalues are  $1-\frac{4}{3}\sin^2\frac{1}{24\pi m}$ ]. For  $\frac{2}{3} \le k \le n$ , these lie in the interval  $[-\frac{1}{3}, \frac{1}{3}]$ ; which is the closest to 0 among w t [0,1].

The implementation is in the Matlab files.

2. The reason it is a good test is because the numbers are random and there would be extreme cases with enough tests, Also, the actual answer is easy to calculate (x=0).

The conversing rational 116-AxxIII seems to converge

to a number  $d \le 1$ , and d seems related to d.

This might be explained by the change of eigan values with the growth in size of matrix. When  $d \to 1$ ,  $d \to 1$ . In general, the speed of convergent is quite related to  $d \to 1$ . A speed  $d \to 1$ .

The ratio R 11 b-Ax KII seems to be related to both 12 and N. K1 RV; n1 RV of n1 RV the jumps should be ignored, it might reach the min the computer could recognized?

What's more for weighted Jacobi 3/3 converges quickly.