

253 Sheng Xu 1205525 HW1 P<sub>1</sub>

1 (a) ①

$$\frac{V_{k,t+1} - V_{k,t}}{h_t} = \frac{1}{h_t} [V_t h_t] + \frac{1}{h_t} O(h_t^2) = V_t + O_1(h_t)$$

$$\begin{aligned} \frac{V_{k+1,t} - V_{k,t}}{2h_x} &= \frac{1}{2h_x} [V_{k,t} + V_x h_x + \frac{1}{2!} h_x^2 + O_x(h_x^3)] \\ &= \frac{1}{2h_x} [V_{k,t} - V_x h_x + \frac{1}{2!} h_x^2 + O_x(h_x^3)] \end{aligned}$$

$$O_1 = O_\alpha + O_\beta = V_x + O_1(h_x^2)$$

$$O'_1 = a \cdot O_1 \text{ so } \mathbb{E}_{x,t} = V_t + O_2(h_t) + a V_x + O'_1(h_x^2)$$

$$= O_2(h_t) + O'_1(h_x^2) = O(h_t, h_x^2)$$

$$\text{Since } V_t + a V_x = 0$$

$$\text{stability (b) } V_{k,t+1} = \frac{a h_t}{2 h_x} V_{k-1,t} + V_{k,t} - \frac{a h_t}{2 h_x} V_{k+1,t}$$

$$\begin{aligned} \text{so } e_{t+1}^{(j)} \exp(i j k h_x) &= \lambda e_{t+1}^{(j)} \exp(i j (k-1) h_x) + e_{t+1}^{(j)} \exp(i j k h_x) - \\ &\quad \lambda e_{t+1}^{(j)} \exp(i j (k+1) h_x) \\ \lambda &= \frac{a h_t}{2 h_x} \end{aligned}$$

$$\begin{aligned} \text{so } S(j) &= \lambda \exp(-i j h_x) + 1 - \lambda \exp(i j h_x) \\ &= 1 - i 2 \lambda \sin \theta \quad (\theta = j h_x) \end{aligned}$$

$$\text{so } |S(j)| > 1 \text{ when } \theta \neq k\pi, \lambda > 0, \text{ unstable}$$

$$1 (b) ① \frac{V_{k,l+1} - V_{k,l}}{h_t}$$

$$= V_t(x_k, t_v) + \frac{1}{2} V_{tt}(x_k, t_v) \cdot h_t + \frac{1}{6} V_{ttt}(x_k, t_v) \cdot h_t^2 + O(h_t^3)$$

$$\left( \frac{V_{k,l+1} - V_{k,l}}{2 h_x} \right)$$

$$= \frac{1}{2 h_x} [V_{k,l} + V_{x,k,l} h_x + V_{t,k,l} h_t + \frac{1}{2!} V_{xx,k,l} h_x^2 + \frac{1}{1!1!} V_{xt,k,l} h_x h_t$$

$$+ \frac{1}{2!} V_{tt,k,l} h_t^2 + \frac{1}{3!} V_{xxx,k,l} h_x^3 + \frac{1}{2!} V_{xxt,k,l} h_x^2 h_t + \frac{1}{2!} V_{xtt,k,l} h_x h_t^2 + \frac{1}{3!} V_{ttt,k,l} h_t^3]$$

$$- \frac{1}{2 h_x} [V_{k,l} - V_{x,k,l} h_x + V_{t,k,l} h_t - \frac{1}{2!} V_{xx,k,l} h_x^2 + \frac{1}{1!} V_{xt,k,l} h_x h_t$$

$$+ \frac{1}{2!} V_{tt,k,l} h_t^2 - \frac{1}{3!} V_{xxx,k,l} h_x^3 + \frac{1}{2!} V_{xxt,k,l} h_x^2 h_t - \frac{1}{2!} V_{xtt,k,l} h_x h_t^2 + \frac{1}{3!} V_{ttt,k,l} h_t^3]$$

\* All  $h_t^n$  term are cancelled out.

$$+ \frac{1}{2 h_x} O_2(h_x^4, h_t h_x^3, h_t^2 h_x^2, h_t^3 h_x)$$

$$= \frac{1}{h_x} [V_x h_x + V_{xt} h_x h_t + \frac{1}{3!} V_{xxx} h_x^3 + \frac{1}{2!} V_{xtt} h_x h_t^2]$$

$$+ O_2(h_x^3, h_t h_x^2, h_t^2 h_x, h_t^3) \leftarrow$$

$$\frac{V_{k+1,l} - V_{k,l}}{2 h_x}$$

$$= \frac{1}{2 h_x} [V_{k,l} + V_{x,k,l} h_x + \frac{1}{2} V_{xx,k,l} h_x^2 + \frac{1}{3!} V_{xxx,k,l} h_x^3]$$

$$- \frac{1}{2 h_x} [V_{k,l} - V_{x,k,l} h_x + \frac{1}{2} V_{xx,k,l} h_x^2 - \frac{1}{3!} V_{xxx,k,l} h_x^3] + \frac{1}{2 h_x} O_3(h_x^4)$$

$$= \frac{1}{h_x} [V_x h_x + \frac{1}{3!} V_{xxx} h_x^3] + O_3(h_x^3) \leftarrow$$

Now we combine everything :

$$O_2' = \frac{\alpha}{2} \cdot O_2$$

$$O_3' = \frac{\alpha}{2} O_3$$

$$T_{xt} = V_t + \frac{1}{2} V_{tt} h_t + \frac{1}{6} V_{ttt} h_t^2 + O_1(h_t^3)$$

$$+ \alpha V_x + \frac{\alpha}{2} V_{xt} h_t + \frac{\alpha}{6} V_{xxx} h_x^3 + \frac{\alpha}{4} V_{xtt} h_t^2 +$$

$$O_2'(h_x^3, h_t h_x^2, h_t^2 h_x, h_t^3) + O_3'(h_x^3)$$

$$= (V_t + \alpha V_x) + \frac{1}{2} h_t (V_{tt} + \alpha V_{xt}) + O_4(h_t^2) + O_5(h_t^2, h_x^2)$$

$$O_6(h_x^3, h_t h_x^2, h_t^2 h_x, h_t^3) \leftarrow$$

We know  $V_t + \alpha V_x = 0$ ,  $V_{tt} + \alpha V_{xt} = (V_t + \alpha V_x)_t = 0_t = 0$

$$\text{So } T_{xt} = O_4(h_t^2) + O_6(h_x^3, h_t h_x^2, h_t^2 h_x, h_t^3) + O_5(h_t^2, h_x^2)$$

$$= O(h_t^2, h_x^2)$$

253 sheng Xu HW1 P3

(c) ② stability For C-N.

$$-\frac{aht}{4hx} V_{k+1,l+1} + V_{k,l+1} + \frac{aht}{4hx} V_{k+1,l+1} = \frac{aht}{4hx} V_{k+1,l} + V_{k,l} - \frac{aht}{4hx} V_{k,l}$$

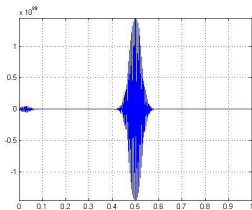
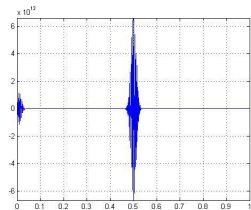
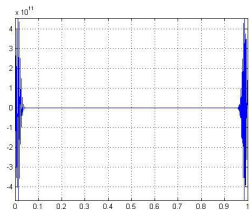
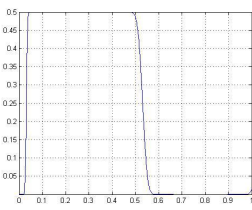
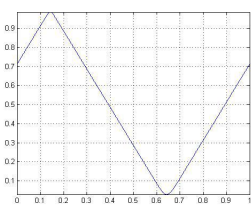
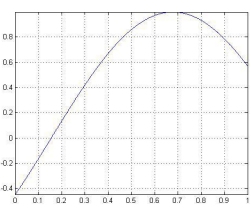
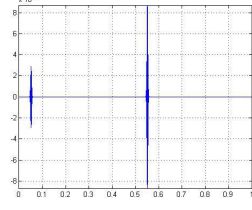
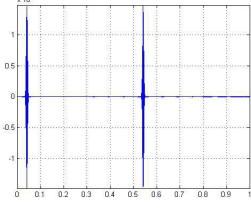
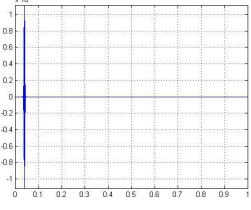
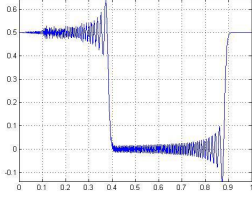
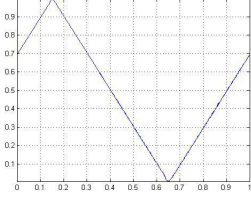
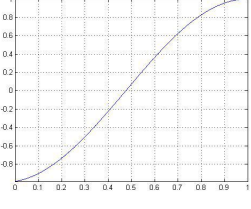
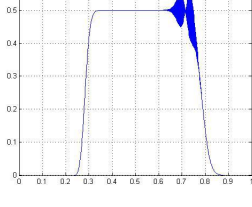
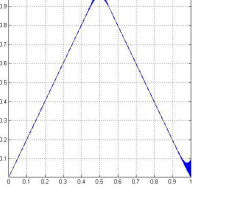
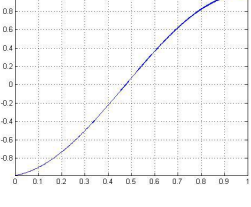
$$\text{so } \hat{S}(j) = \frac{1 - iz\lambda \sin \theta}{1 + iz\lambda \sin \theta} \quad (\lambda = \frac{aht}{4hx} > 0)$$

$$\text{so } |\hat{S}(j)| = 1 \quad \text{unconditionally stable}$$

✓ Add one step jumped:

$$\begin{aligned} & -\lambda e_{k+1}^{(j)} \exp[ij(k-1)h\pi] + e_{k+1}^{(j)} \exp[ijkh\pi] + \lambda e_{k+1}^{(j)} \exp[ij(k+1)h\pi] \\ & = \lambda e_{k+1}^{(j)} \exp[ij(k-1)h\pi] + e_{k+1}^{(j)} \exp[ijkh\pi] - \lambda e_{k+1}^{(j)} \exp[ij(k+1)h\pi] \end{aligned}$$

# Problem 2 Sum\_up Sheng Xu

	Discontinuous	$C^0$	$C^\infty$
FSCT	Unstable 	Unstable 	Unstable 
1 <sup>st</sup> Upwind CFL	Stable with dissipation 	Stable with dissipation 	Stable 
1 <sup>st</sup> Upwind non-CFL	Unstable 	Unstable 	Unstable 
Crank-Nicholson	Stable with Dispersion 	Stable with dissipation 	Stable 
BSCT	Stable with Dispersion 	Stable with Dispersion 	Stable 

Functions	Discontinuous	$C^0$	$C^\infty$
	$F=0$ when $-1 \leq x < -0.5$ $0 \leq x < 0.5$ $F=0.5$ when $-0.5 \leq x < 0$ $0.5 \leq x < 1$	$F=2x+2$ when $x \leq -0.5$ $F=-2x$ when $-0.5 \leq x < 0$ $F=2x$ when $0 \leq x < 0.5$ $F=2-2x$ when $0.5 \leq x \leq 1$	$\cos(3x)$

Conclusion:

All stable methods exhibit certain dissipation with  $C^\infty$  functions. FSCT and First Order Upwind method without CFL are never stable.

For Discontinuity and  $C^1$  functions, both implicit methods(C-N and BSCT) exhibits dispersion, making pictures less smooth. BSCT is more effected in  $C^1$  function, while C-N is more effected in Discontinuity function.