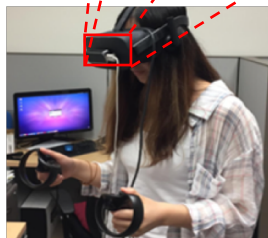
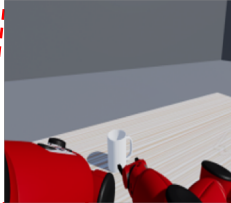
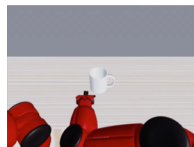
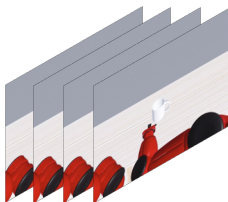
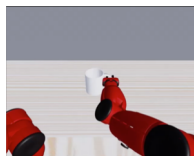
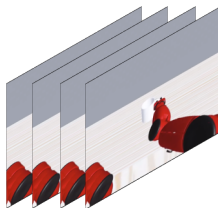


First
Person
View

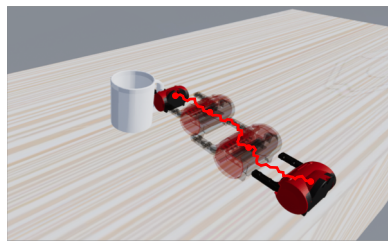


Successful Demonstrations

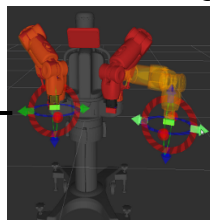


Failed Demonstrations

Grasping Trajectories



Motion Planning



BIRLF