

Econ 8307

Assignment 2 (Spring 2019)

Jonah Coste, Fred Xu
George Washington University

Question 1

```
1 beta = .97;
2 Δ = .1;
3 theta = .3;
4 steady=@(x) [ x(1) + beta*x(1)*(theta * x(2)^(theta-1) + 1 - Δ);
5               x(2)^theta - Δ*x(2) - x(1)];
6
7 initial_guess=[1;1];
8
9
10 steady_state=fsolve(steady,initial_guess)
```

Prints the steady state solution. The first entry is steady state consumption and the second entry is steady state capital.

```
1 steady_state =
2
3     1.0998
4     3.2690
```

Question 2

1. Define E as a row matrix with two variables. Each variable is an indicator for employed

or unemployed i.e. $E = [1, 0]$ if employed and $E = [0, 1]$ if unemployed. This is the state variable. Value function becomes $\text{Value}(E) = EV$ where V is a 1x2 column vector: $V = [\text{value if employed}; \text{value if unemployed}]$.

$$\text{Value}(E) = EV = EU + \beta * ETV$$

Where T is a transition matrix: $T = [p_{ie}, 1 - p_{ie}; 1 - p_{iu}, p_{iu}]$, and U is the column matrix $U = [u(w_h); u(w_l)]$

2.

```
1  w_h = 1;
2  w_l = .9;
3  beta = .96;
4  pi_e = .95;
5  pi_u = .9;
6  utility=@(c) log(c);
7
8  T = [pi_e, 1 - pi_e; 1 - pi_u, pi_u];
9  U = [utility(1); utility(.9)];
10 I = eye(2);
11
12 V=inv(I - beta*T)*U;
13 V
```

Prints value function vector.

```
1      V =
2
3      0.6871
4      1.2597
```

3.

```
1 steady2=@(x) (1 - pi_e)*(1 - x) + pi_u*x - x;
2 initial_guess2=.5;
3 unemployment_rate=fsolve(steady2,initial_guess2)
```

Prints steady state unemployment rate.

```
1      unemployment_rate =
2
3      0.3333
```

Question 3

$$n^*(z) = \left(\frac{w}{z^\alpha}\right)^{\frac{1}{\alpha-1}}$$

Let $S_{it} = [s_{it1}; s_{it2}; \dots; s_{itN}]$ be a $N \times 1$ column vector where $s_{itx} = 1$ if $z_{it} = z_x$ and 0 otherwise. Therefore, $S_{it}Z = z_{it}$. S is the state variable.

The value function is: $Value(S) = SV = S\pi + \beta(1 - \lambda)STV$ Where T is the $N \times N$ transition matrix i.e. $T_{jk} = f(z_{i,t+1} = k | z_{it} = j)$ and π is the optimal profit row vector $[\pi_1, \pi_2, \dots, \pi_N]$ where $\pi_x = z_x n^*(z_x)^\alpha - w n^*(z_x)$

Question 4

```
1.
1  N = 5;
2  p = .8;
3  w = 1;
4  alpha = .7;
5  beta = .95;
6  lambda = .1;
7
8  Z = zeros(1,N);
9  T = zeros(N);
10 nstar = zeros(N,1);
11 pi = zeros(N,1);
12 I = eye(N);
13 T=T+(1 p)/(N 1)+eye(N)*(p (1 p)/(N 1));
14 for i =1:N
15     Z(i) = i/N;
16     nstar(i) = (w/(Z(i)*alpha))^(1/(alpha 1));
17     pi(i)=Z(i)*nstar(i)^alpha - w*nstar(i);
18 end
19
20 V = inv(I beta*(1 lambda)*T)*pi
```

Prints value vector V^*

```
1      V =
2
```

```

3      0.1851
4      0.2005
5      0.2496
6      0.3563
7      0.5472

```

2.

```

1  Vguess = zeros(5,1);
2  for i= 1:2000
3      Vguess = pi + beta*(1-lambda)*T*Vguess;
4  end
5
6  Vguess

```

Prints 2000th iteration.

```

1      Vguess =
2
3      0.1851
4      0.2005
5      0.2496
6      0.3563
7      0.5472

```

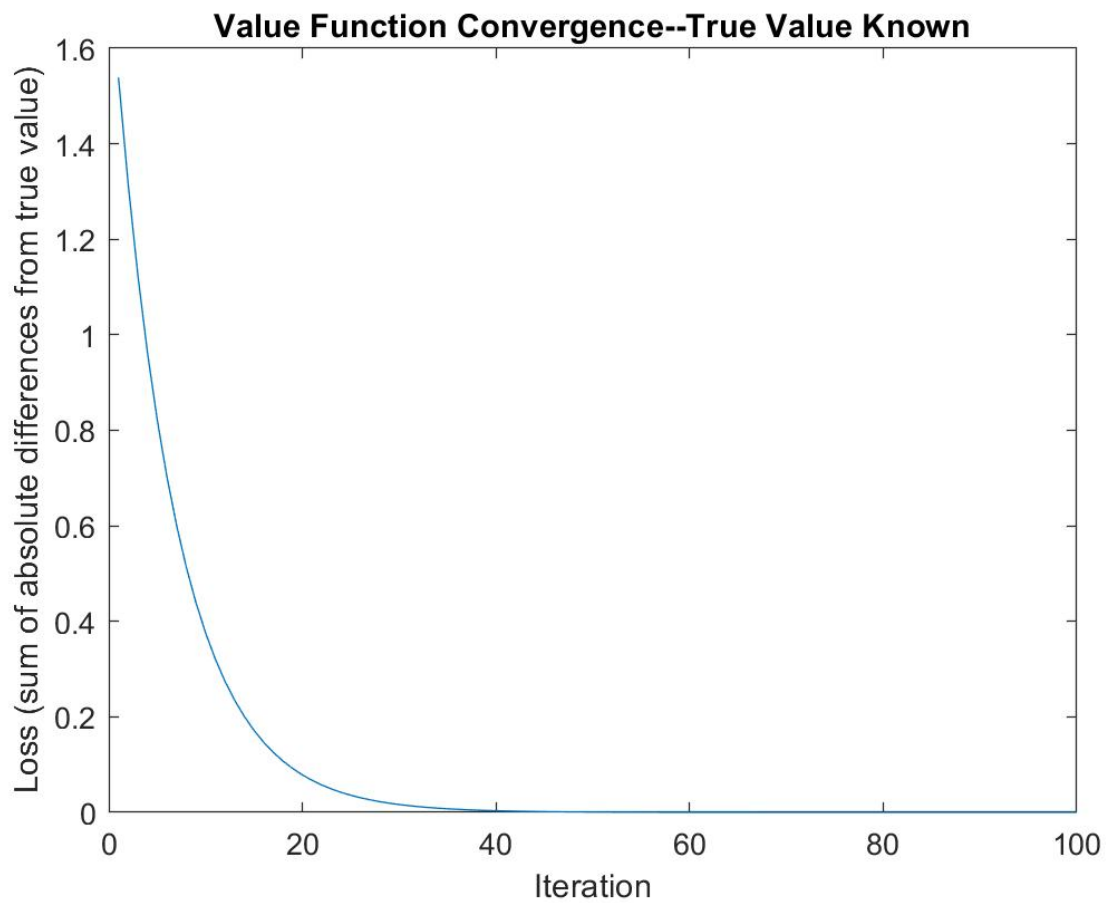
3.

```

1  iterations = 100;
2  loss = zeros(iterations,1);
3  Vguess = zeros(5,1);
4  for j =1:5
5      loss(1) = loss(1) + abs(V(j) - Vguess(j));
6  end
7  for i= 1:iterations-1
8      Vguess = pi + beta*(1-lambda)*T*Vguess;
9      for j =1:5
10         loss(i+1) = loss(i+1) + abs(V(j) - Vguess(j));
11     end
12 end
13
14 plot(loss)
15 title('Value Function Convergence - True Value Known')
16 xlabel('Iteration')

```

```
17 ylabel('Loss (sum of absolute differences from true value)')
```



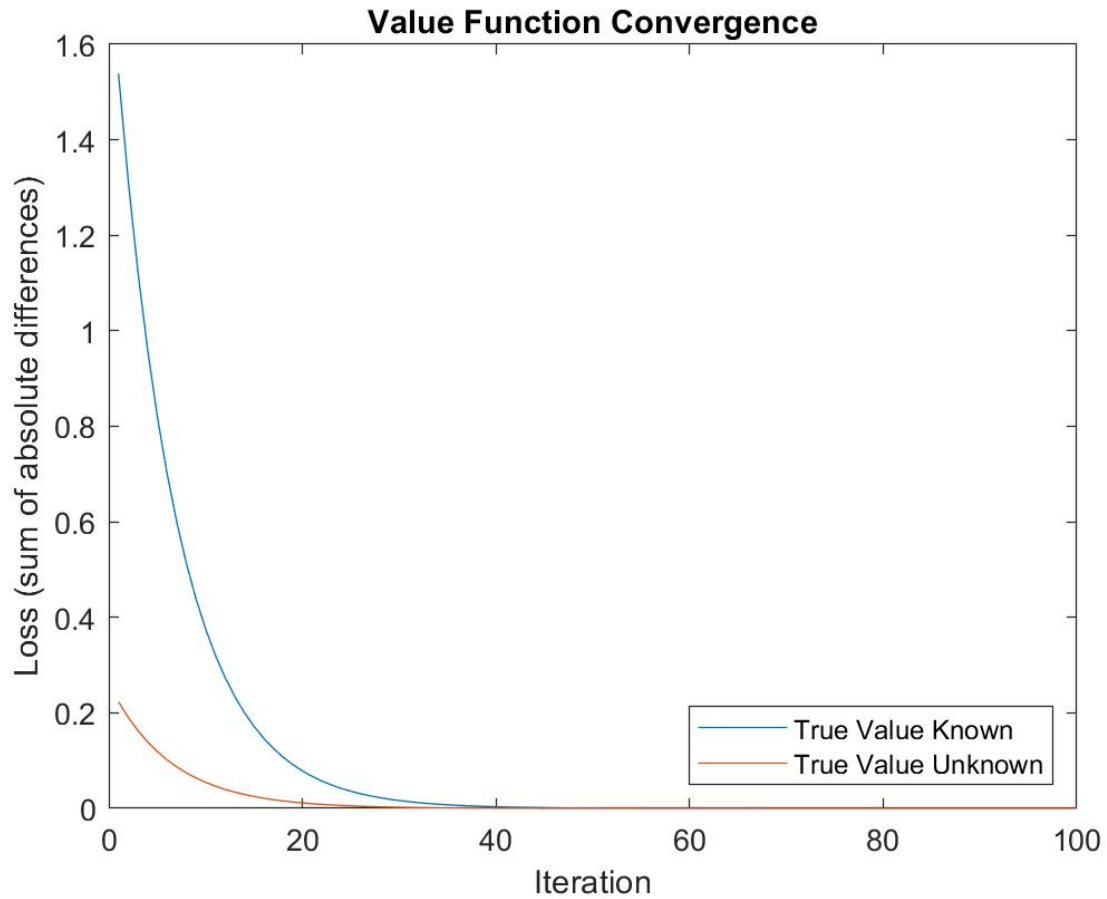
Around 67 iterations gives a fairly precise estimate of the value function. Note 67 is the first iteration where loss function rounds to .0000.

```
4.  
1 loss2 = zeros(iterations,2);  
2 Vold = zeros(5,1);  
3 Vnew = zeros(5,1);  
4 for i= 1:iterations  
5     loss2(i,1) = loss(i);  
6     Vold=Vnew;  
7     Vnew = pi + beta*(1-lambda)*T*Vold;  
8     for j =1:5  
9         loss2(i,2) = loss2(i,2) + abs(Vnew(j)-Vold(j));  
10    end  
11 end  
12  
13 plot(loss2)
```

```

14 title('Value Function Convergence')
15 xlabel('Iteration')
16 ylabel('Loss (sum of absolute differences)')
17 legend({'True Value Known', 'True Value ...
        Unknown'}, 'Location', 'southeast')

```



Now around 55 iterations appears to give a fairly precise estimate of the value function. Note 55 is the first iteration where the new loss function rounds to .0000.