









Machine-Level Programming IV: Data

Today

Arrays

-  One-dimensional
-  Multi-dimensional (nested)
-  Multi-level

Structures

-  Allocation
-  Access
-  Alignment

Floating Point

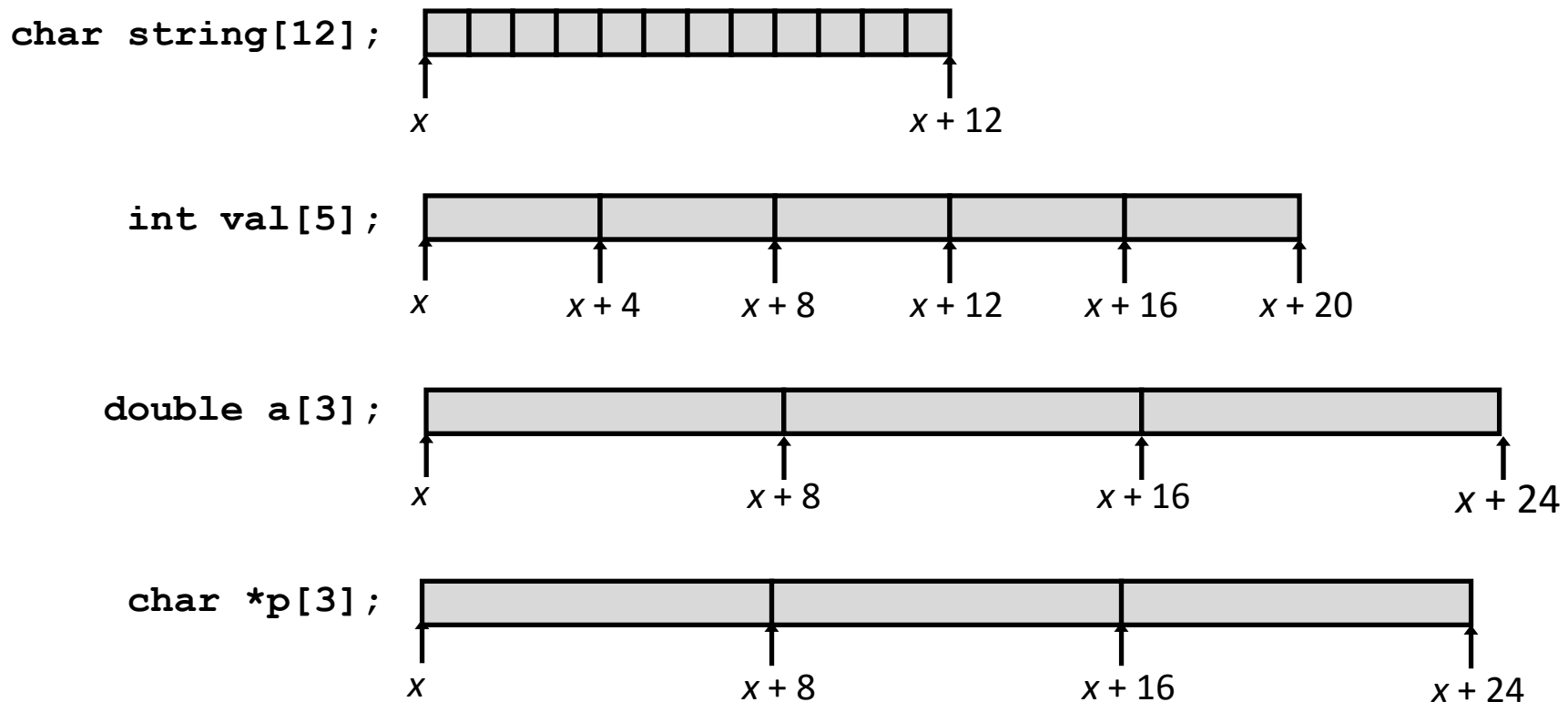
Array Allocation

Basic Principle

$T \ A[L];$

Array of data type T and length L

Contiguously allocated region of $L * \text{sizeof}(T)$ bytes in memory



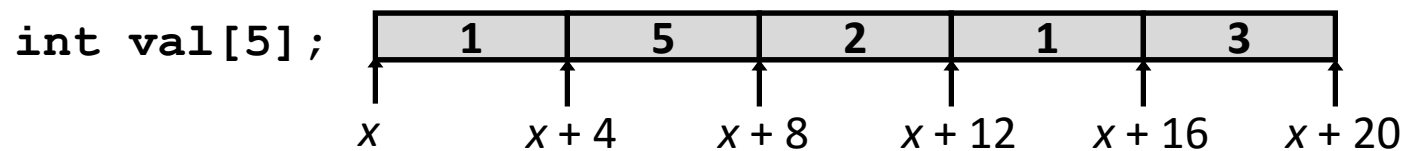
Array Access

Basic Principle

T **A**[L] ;

Array of data type T and length L

Identifier **A** can be used as a pointer to array element 0: Type T^*

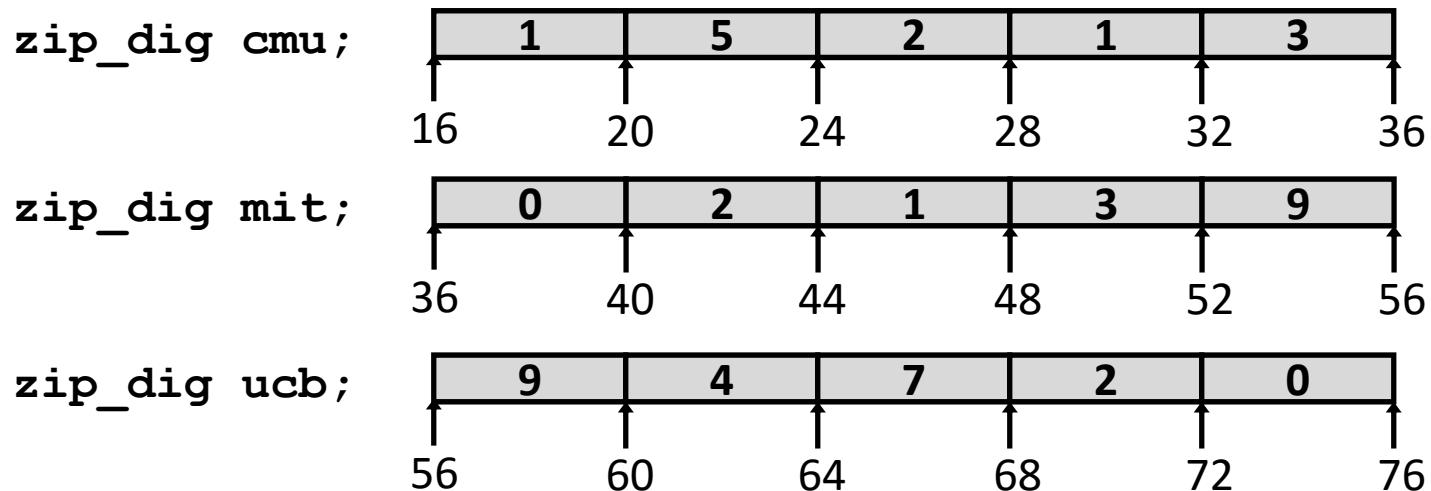


Reference	Type	Value
<code>val[4]</code>	<code>int</code>	3
<code>val</code>	<code>int *</code>	x
<code>val+1</code>	<code>int *</code>	$x+4$
<code>&val[2]</code>	<code>int *</code>	$x+8$
<code>val[5]</code>	<code>int</code>	??
<code>*(val+1)</code>	<code>int</code>	5
<code>val + i</code>	<code>int *</code>	$x+4i$

Array Example

```
#define ZLEN 5
typedef int zip_dig[ZLEN];

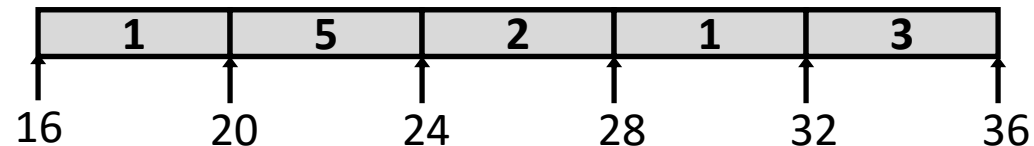
zip_dig cmu = { 1, 5, 2, 1, 3 };
zip_dig mit = { 0, 2, 1, 3, 9 };
zip_dig ucb = { 9, 4, 7, 2, 0 };
```



- Declaration “`zip_dig cmu`” equivalent to “`int cmu[5]`”
- Example arrays were allocated in successive 20 byte blocks
 - Not guaranteed to happen in general

Array Accessing Example

zip_dig cmu;



```
int get_digit
(zip_dig z, int digit)
{
    return z[digit];
}
```

IA32

```
# %rdi = z
# %rsi = digit
movl (%rdi,%rsi,4), %eax # z[digit]
```

- Register `%rdi` contains starting address of array
- Register `%rsi` contains array index
- Desired digit at `%rdi + 4*%rsi`
- Use memory reference `(%rdi,%rsi,4)`

Array Loop Example

```
void zincr(zip_dig z) {  
    size_t i;  
    for (i = 0; i < ZLEN; i++)  
        z[i]++;  
}
```

```
# %rdi = z  
movl    $0, %eax          # i = 0  
jmp     .L3               # goto middle  
.L4:                      # loop:  
    addl    $1, (%rdi,%rax,4) # z[i]++  
    addq    $1, %rax        # i++  
.L3:                      # middle  
    cmpq    $4, %rax        # i:4  
    jbe     .L4             # if <=, goto loop  
rep; ret
```

Multidimensional (Nested) Arrays

Declaration

$T \ A[R][C];$

2D array of data type T

R rows, C columns

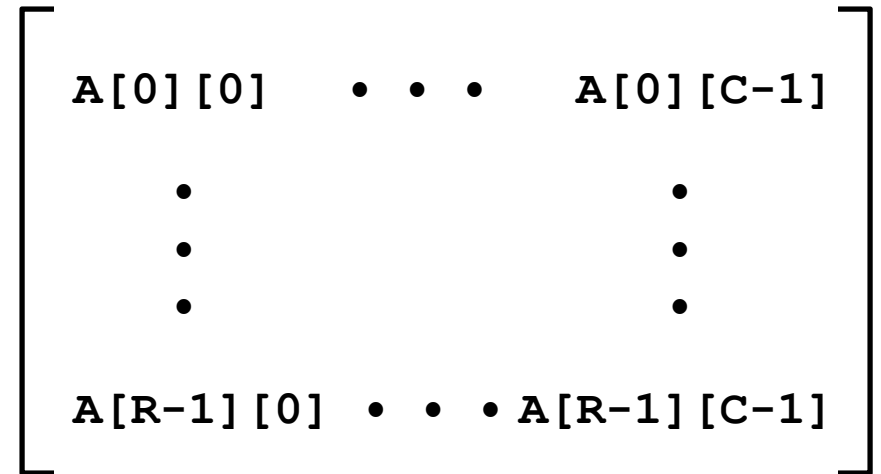
Type T element requires K bytes

Array Size

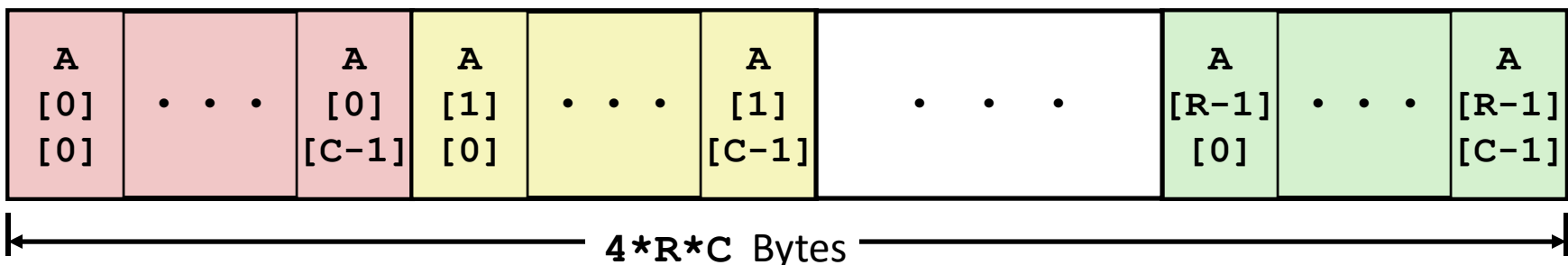
$R * C * K$ bytes

Arrangement

Row-Major Ordering

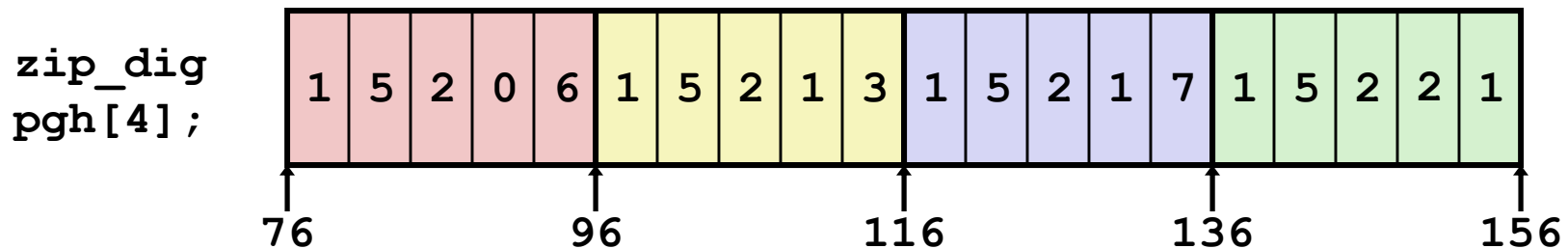


`int A[R][C];`



Nested Array Example

```
#define PCOUNT 4
zip_dig pgh[PCOUNT] =
    {{1, 5, 2, 0, 6},
     {1, 5, 2, 1, 3 },
     {1, 5, 2, 1, 7 },
     {1, 5, 2, 2, 1 }};
```



🌀 “zip_dig pgh[4]” equivalent to “int pgh[4][5]”

- 🌀 Variable **pgh**: array of 4 elements, allocated contiguously
- 🌀 Each element is an array of 5 **int**’s, allocated contiguously

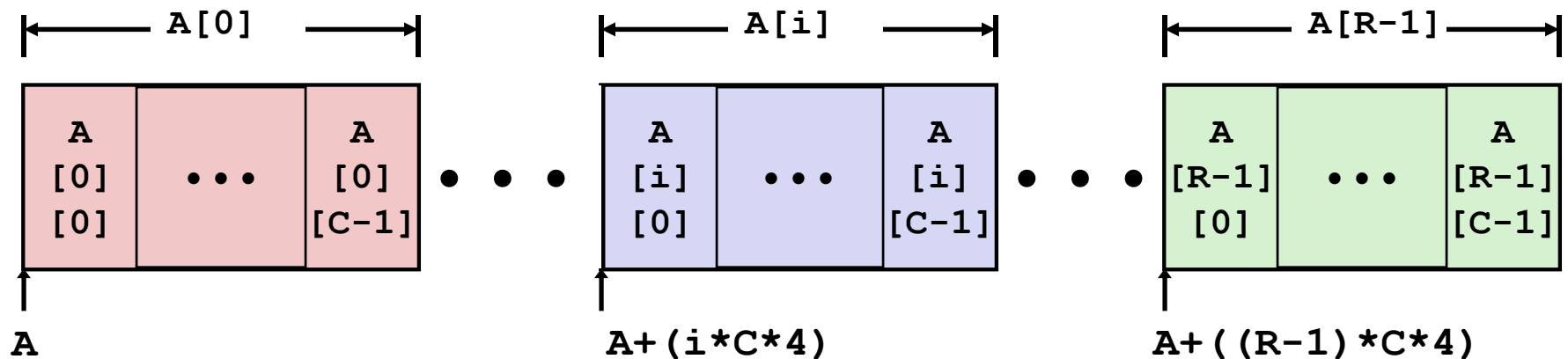
🌀 “Row-Major” ordering of all elements in memory

Nested Array Row Access

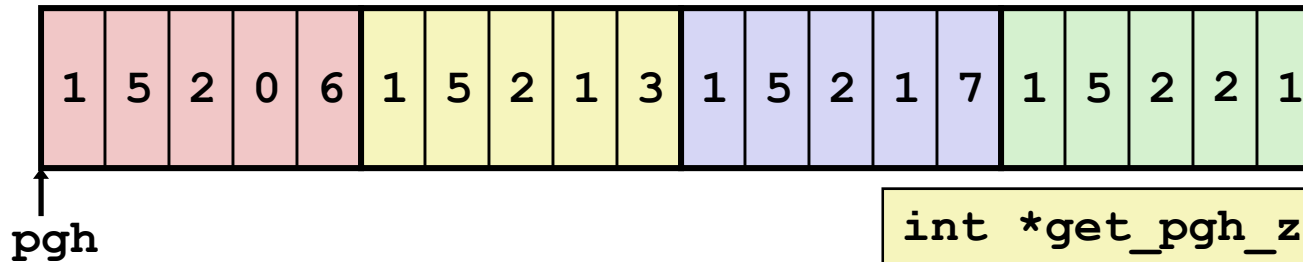
Row Vectors

- $A[i]$ is array of C elements
- Each element of type T requires K bytes
- Starting address $A + i * (C * K)$

```
int A[R][C];
```



Nested Array Row Access Code



```
int *get_pgh_zip(int index)
{
    return pgh[index];
}
```

```
# %rdi = index
leaq (%rdi,%rdi,4),%rax # 5 * index
leaq pgh(,%rax,4),%rax  # pgh + (20 * index)
```

Row Vector

- `pgh[index]` is array of 5 `int`'s
- Starting address `pgh+20*index`

Machine Code

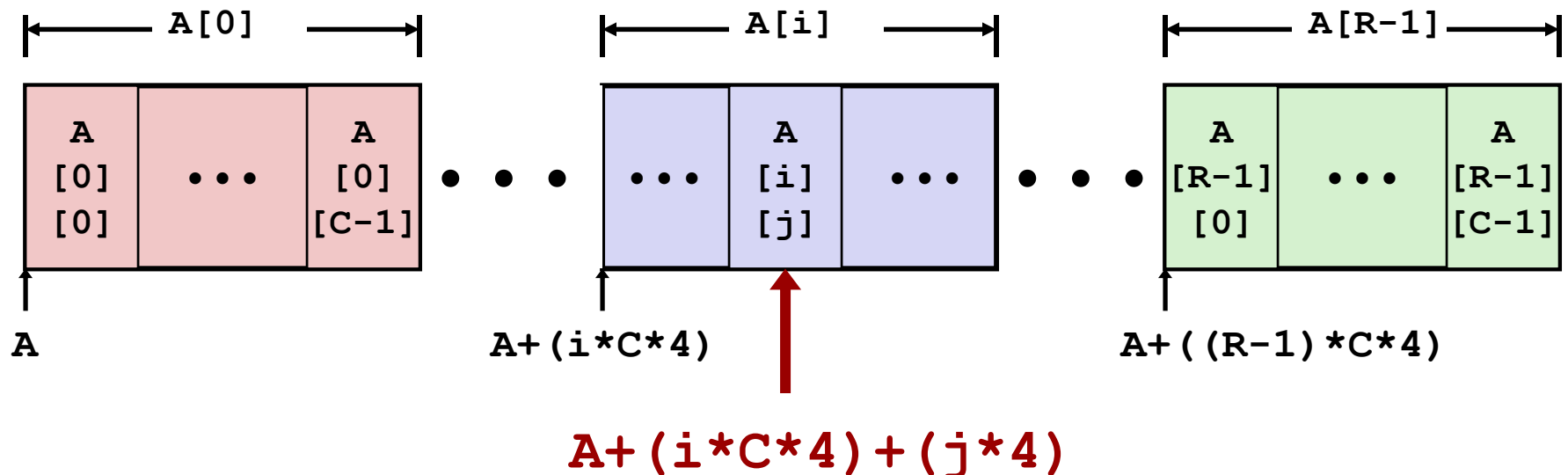
- Computes and returns address
- Compute as `pgh + 4*(index+4*index)`

Nested Array Element Access

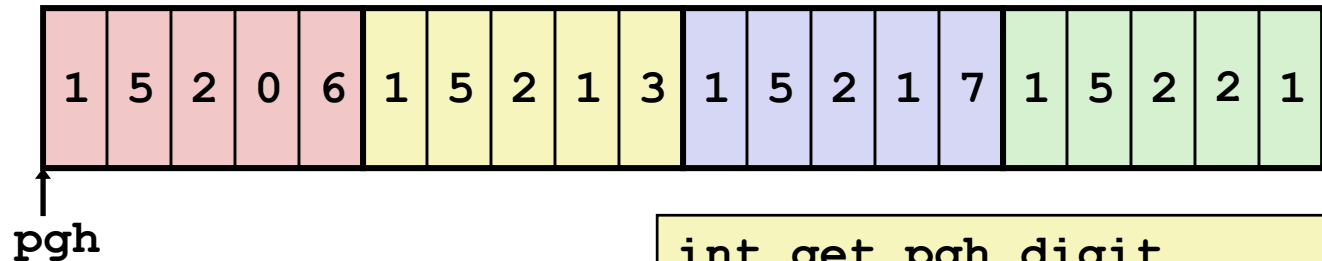
Array Elements

- $A[i][j]$ is element of type T , which requires K bytes
- Address $A + i * (C * K) + j * K = A + (i * C + j) * K$

```
int A[R][C];
```



Nested Array Element Access Code



```
int get_pgh_digit
(int index, int dig)
{
    return pgh[index][dig];
}
```

```
leaq    (%rdi,%rdi,4), %rax    # 5*index
addl    %rax, %rsi             # 5*index+dig
movl    pgh(,%rsi,4), %eax     # M[pgh + 4*(5*index+dig)]
```

🌀 Array Elements

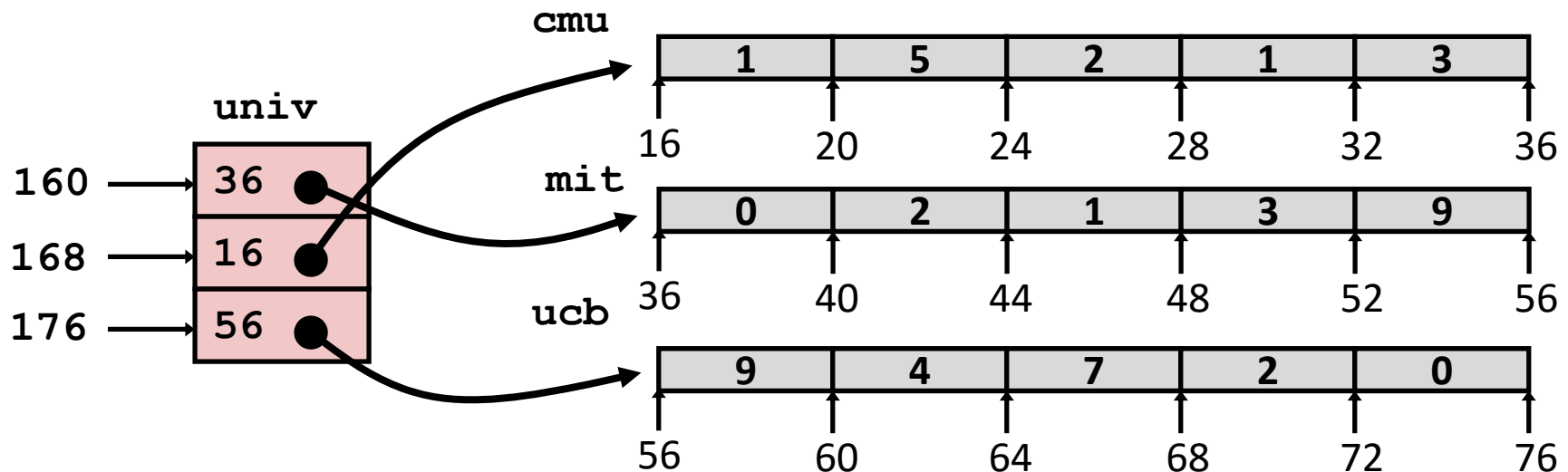
- 🌀 `pgh[index][dig]` is `int`
- 🌀 Address: `pgh + 20*index + 4*dig`
 - 🌀 `= pgh + 4*(5*index + dig)`

Multi-Level Array Example

```
zip_dig cmu = { 1, 5, 2, 1, 3 };  
zip_dig mit = { 0, 2, 1, 3, 9 };  
zip_dig ucb = { 9, 4, 7, 2, 0 };
```

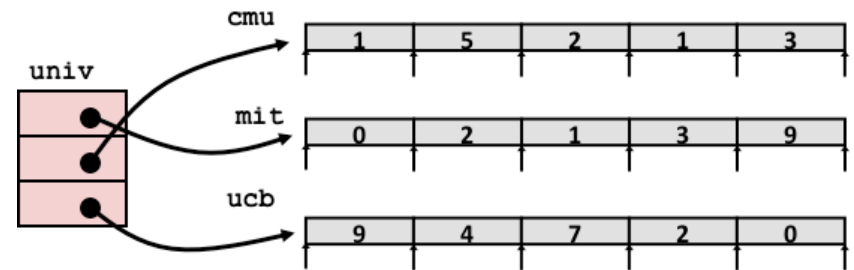
```
#define UCOUNT 3  
int *univ[UCOUNT] = {mit, cmu, ucb};
```

- Variable `univ` denotes array of 3 elements
- Each element is a pointer
 - 8 bytes
- Each pointer points to array of `int`'s



Element Access in Multi-Level Array

```
int get_univ_digit
(size_t index, size_t digit)
{
    return univ[index][digit];
}
```



```
salq    $2, %rsi           # 4*digit
addq    univ(,%rdi,8), %rsi # p = univ[index] + 4*digit
movl    (%rsi), %eax        # return *p
ret
```

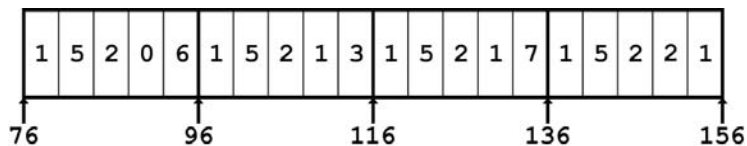
Computation

- Element access **Mem[Mem[univ+8*index]+4*digit]**
- Must do two memory reads
 - First get pointer to row array
 - Then access element within array

Array Element Accesses

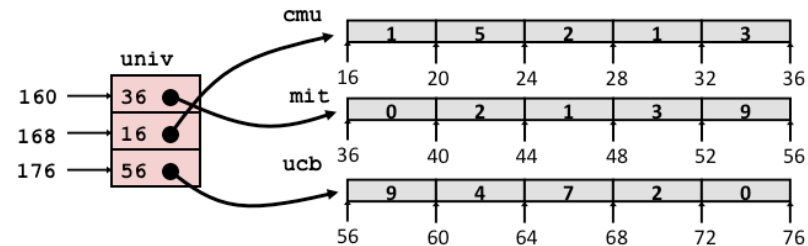
Nested array

```
int get_pgh_digit
(size_t index, size_t digit)
{
    return pgh[index][digit];
}
```



Multi-level array

```
int get_univ_digit
(size_t index, size_t digit)
{
    return univ[index][digit];
}
```



Accesses looks similar in C, but address computations very different:

$\text{Mem}[\text{pgh} + 20 * \text{index} + 4 * \text{digit}]$ $\text{Mem}[\text{Mem}[\text{univ} + 8 * \text{index}] + 4 * \text{digit}]$

N X N Matrix Code

Fixed dimensions

- Know value of N at compile time

```
#define N 16
typedef int fix_matrix[N][N];
/* Get element a[i][j] */
int fix_ele(fix_matrix a,
            size_t i, size_t j)
{
    return a[i][j];
}
```

Variable dimensions, explicit indexing

- Traditional way to implement dynamic arrays

```
#define IDX(n, i, j) ((i)*(n)+(j))
/* Get element a[i][j] */
int vec_ele(size_t n, int *a,
            size_t i, size_t j)
{
    return a[IDX(n,i,j)];
}
```

Variable dimensions, implicit indexing

- Now supported by gcc

```
/* Get element a[i][j] */
int var_ele(size_t n, int a[n][n],
            size_t i, size_t j) {
    return a[i][j];
}
```

16 X 16 Matrix Access

■ Array Elements

- Address $A + i * (C * K) + j * K$
- $C = 16, K = 4$

```
/* Get element a[i][j] */  
int fix_ele(fix_matrix a, size_t i, size_t j) {  
    return a[i][j];  
}
```

```
# a in %rdi, i in %rsi, j in %rdx  
salq    $6, %rsi          # 64*i  
addq    %rsi, %rdi         # a + 64*i  
movl    (%rdi,%rdx,4), %eax # M[a + 64*i + 4*j]  
ret
```

n X n Matrix Access

■ Array Elements




- Address $A + i * (C * K) + j * K$
- $C = n, K = 4$
- Must perform integer multiplication

```
/* Get element a[i][j] */  
int var_ele(size_t n, int a[n][n], size_t i, size_t j)  
{  
    return a[i][j];  
}
```




```
# n in %rdi, a in %rsi, i in %rdx, j in %rcx  
imulq    %rdx, %rdi          # n*i  
leaq     (%rsi,%rdi,4), %rax  # a + 4*n*i  
movl     (%rax,%rcx,4), %eax  # a + 4*n*i + 4*j  
ret
```

Today

Arrays

-  One-dimensional
-  Multi-dimensional (nested)
-  Multi-level

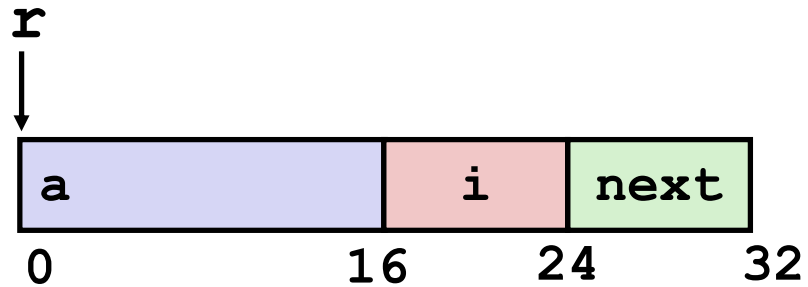
Structures

-  Allocation
-  Access
-  Alignment

Floating Point

Structure Representation

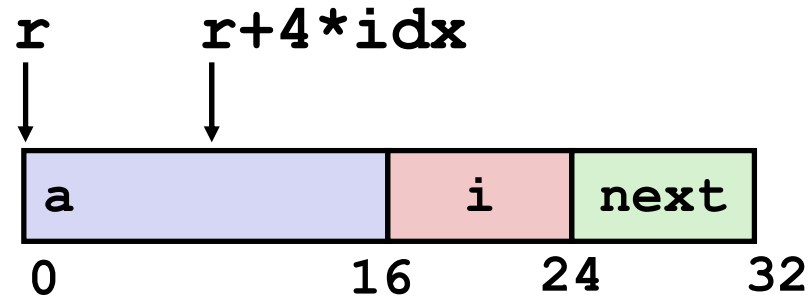
```
struct rec {  
    int a[4];  
    size_t i;  
    struct rec *next;  
};
```



- Structure represented as block of memory
 - Big enough to hold all of the fields
- Fields ordered according to declaration
 - Even if another ordering could yield a more compact representation
- Compiler determines overall size + positions of fields
 - Machine-level program has no understanding of the structures in the source code

Generating Pointer to Structure Member

```
struct rec {  
    int a[4];  
    size_t i;  
    struct rec *next;  
};
```



Generating Pointer to Array Element

- Offset of each structure member determined at compile time
- Compute as $r + 4 \cdot idx$

```
int *get_ap  
(struct rec *r, size_t idx)  
{  
    return &r->a[idx];  
}
```

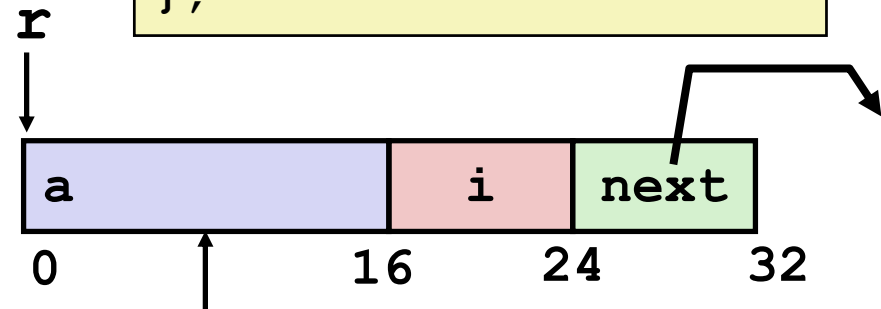
```
# r in %rdi, idx in %rsi  
leaq (%rdi,%rsi,4), %rax  
ret
```

Following Linked List

C Code

```
void set_val
(struct rec *r, int val)
{
    while (r) {
        int i = r->i;
        r->a[i] = val;
        r = r->next;
    }
}
```

```
struct rec {
    int a[4];
    int i;
    struct rec *next;
};
```



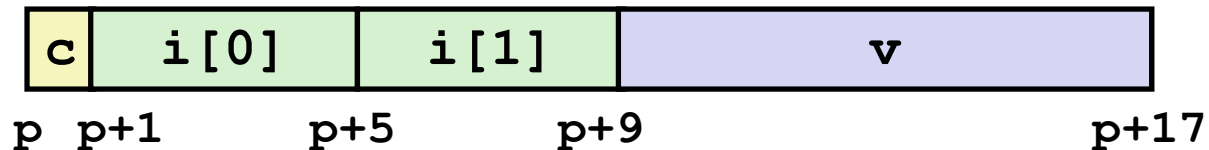
Element i

Register	Value
%rdi	r
%rsi	val

```
.L11:                                # loop:
    movslq    16(%rdi), %rax          # i = M[r+16]
    movl      %esi, (%rdi,%rax,4)    # M[r+4*i] = val
    movq      24(%rdi), %rdi         # r = M[r+24]
    testq     %rdi, %rdi             # Test r
    jne       .L11                  # if !=0 goto loop
```

Structures & Alignment

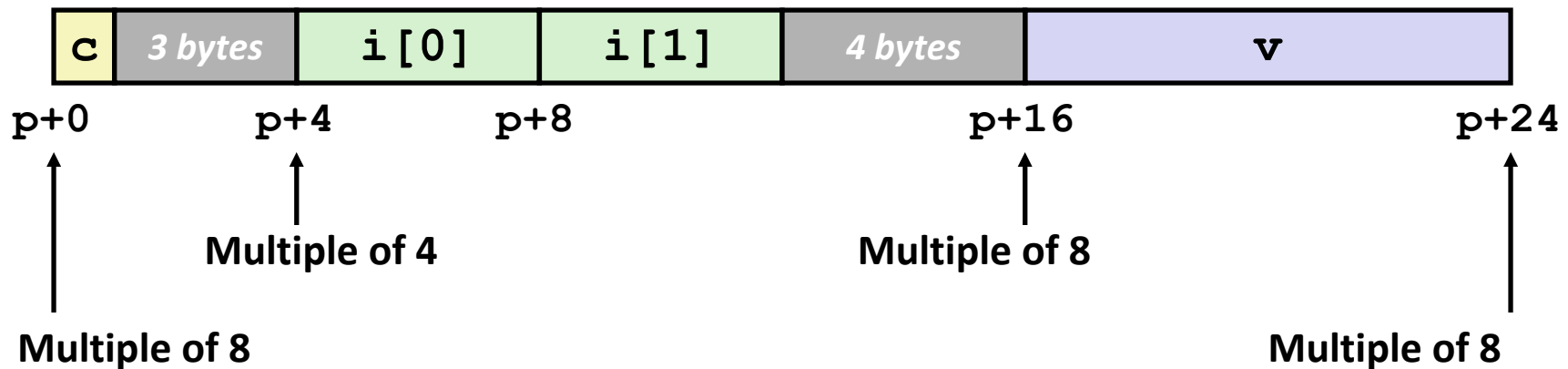
Unaligned Data



```
struct S1 {  
    char c;  
    int i[2];  
    double v;  
} *p;
```

Aligned Data

- Primitive data type requires K bytes
- Address must be multiple of K



Alignment Principles

🌀 Aligned Data

- 🌀 Primitive data type requires K bytes
- 🌀 Address must be multiple of K
- 🌀 Required on some machines; advised on x86-64

🌀 Motivation for Aligning Data

- 🌀 Memory accessed by (aligned) chunks of 4 or 8 bytes (system dependent)
 - 🌀 Inefficient to load or store datum that spans quad word boundaries
 - 🌀 Virtual memory trickier when datum spans 2 pages

🌀 Compiler

- 🌀 Inserts gaps in structure to ensure correct alignment of fields

Specific Cases of Alignment (x86-64)

- **1 byte: `char`, ...**

- no restrictions on address

- **2 bytes: `short`, ...**

- lowest 1 bit of address must be 0_2

- **4 bytes: `int`, `float`, ...**

- lowest 2 bits of address must be 00_2

- **8 bytes: `double`, `long`, `char *`, ...**

- lowest 3 bits of address must be 000_2

- **16 bytes: `long double` (GCC on Linux)**

- lowest 4 bits of address must be 0000_2

Satisfying Alignment with Structures

Within structure:

- Must satisfy each element's alignment requirement

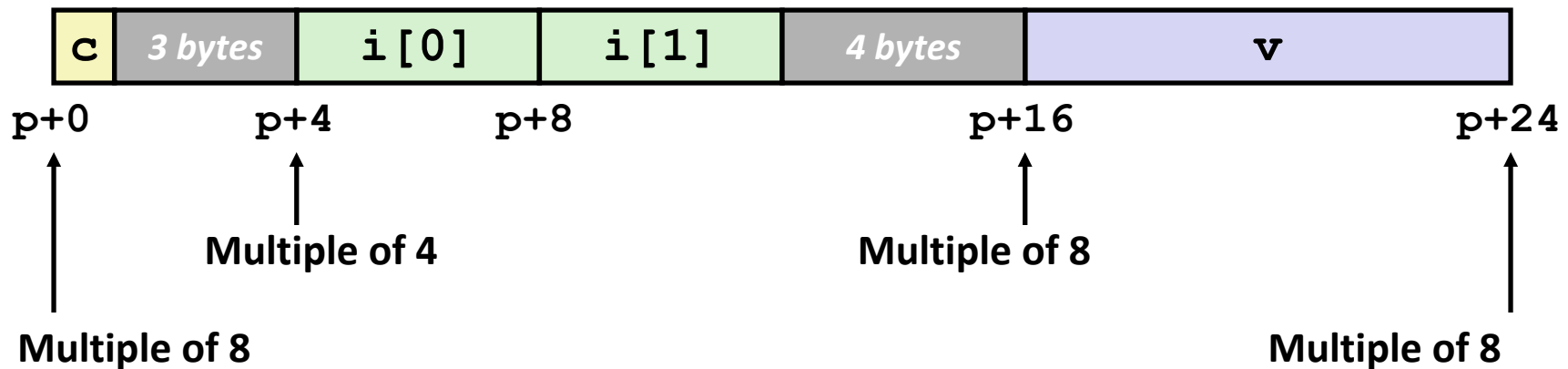
Overall structure placement

- Each structure has alignment requirement K
 - K = Largest alignment of any element
- Initial address & structure length must be multiples of K

```
struct S1 {  
    char c;  
    int i[2];  
    double v;  
} *p;
```

Example:

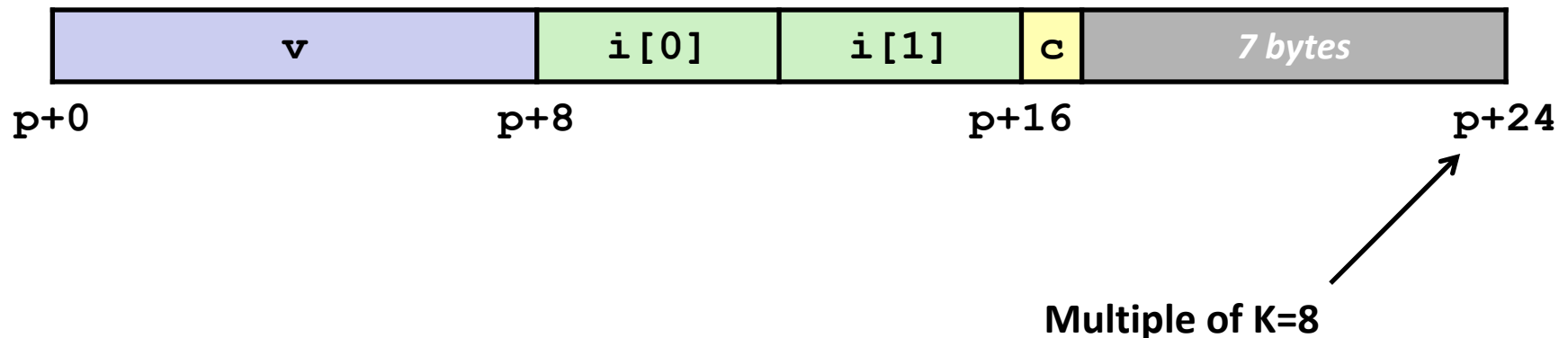
- $K = 8$, due to **double** element



Meeting Overall Alignment Requirement

- For largest alignment requirement K
- Overall structure must be multiple of K

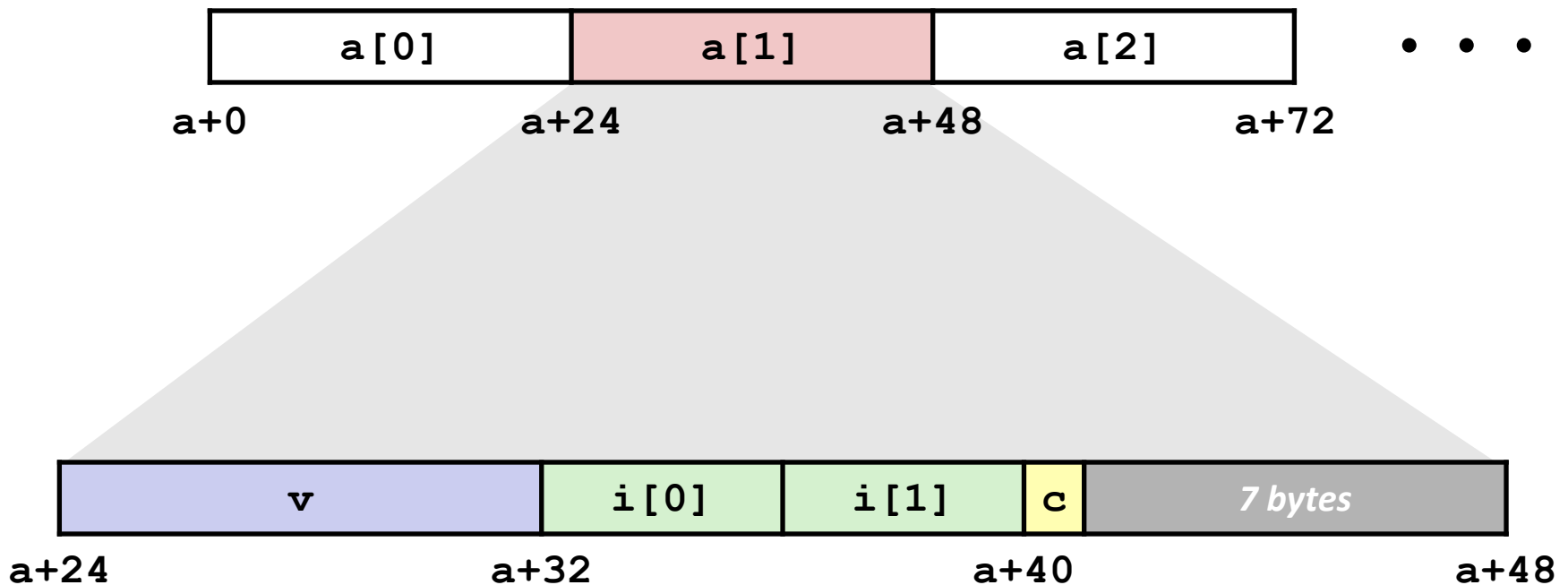
```
struct S2 {  
    double v;  
    int i[2];  
    char c;  
} *p;
```



Arrays of Structures

- Overall structure length multiple of K
- Satisfy alignment requirement for every element

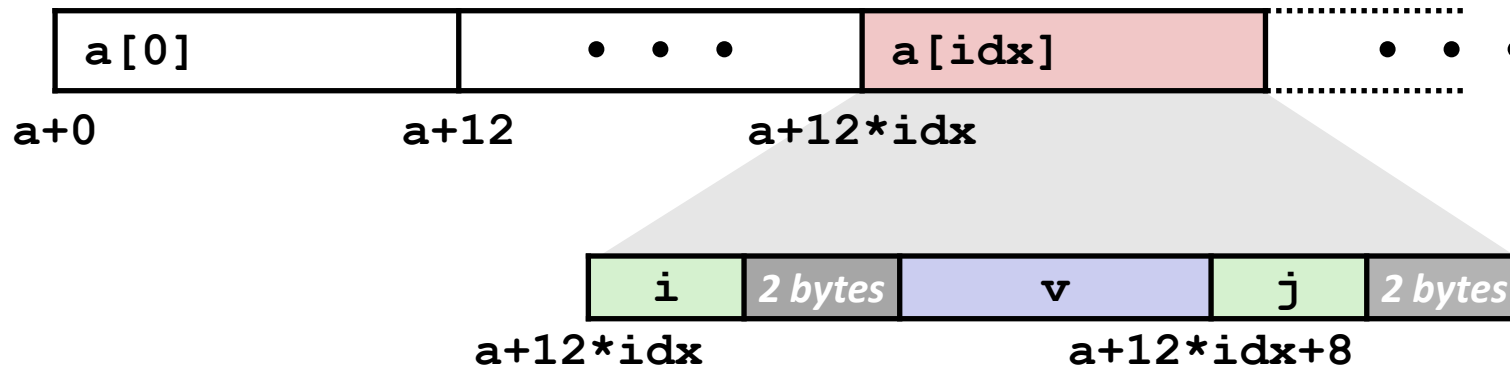
```
struct S2 {  
    double v;  
    int i[2];  
    char c;  
} a[10];
```



Accessing Array Elements

```
struct S3 {  
    short i;  
    float v;  
    short j;  
} a[10];
```

- Compute array offset $12 * \text{idx}$
 - `sizeof(S3)`, including alignment spacers
- Element `j` is at offset 8 within structure
- Assembler gives offset `a+8`
 - Resolved during linking



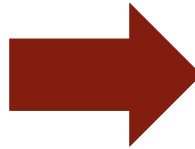
```
short get_j(int idx)  
{  
    return a[idx].j;  
}
```

```
# %rdi = idx  
leaq (%rdi,%rdi,2),%rax # 3*idx  
movzwl a+8(,%rax,4),%eax
```

Saving Space

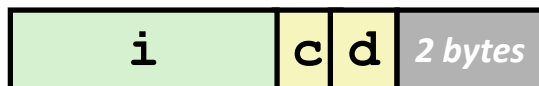
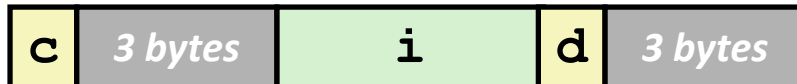
Put large data types first

```
struct S4 {  
    char c;  
    int i;  
    char d;  
} *p;
```






```
struct S5 {  
    int i;  
    char c;  
    char d;  
} *p;
```

Effect (K=4)






Today

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-  One-dimensional
-  Multi-dimensional (nested)
-  Multi-level

Structures

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Floating Point



Background

History




x87 FP

-  Legacy, very ugly

SSE FP

-  Supported by Shark machines
-  Special case use of vector instructions

AVX FP

-  Newest version
-  Similar to SSE
-  Documented in book

Programming with SSE3

XMM Registers

- 16 total, each 16 bytes

- 16 single-byte integers



- 8 16-bit integers



- 4 32-bit integers



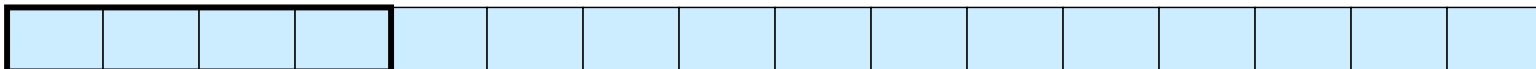
- 4 single-precision floats



- 2 double-precision floats



- 1 single-precision float



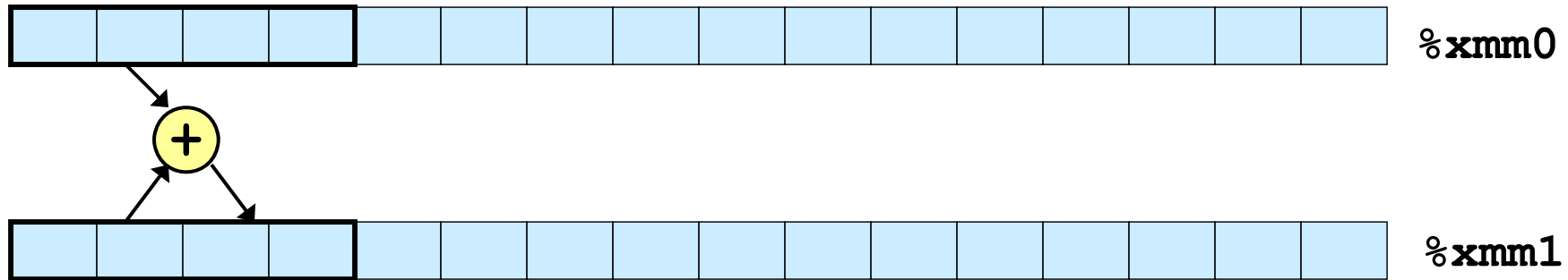
- 1 double-precision float



Scalar & SIMD Operations

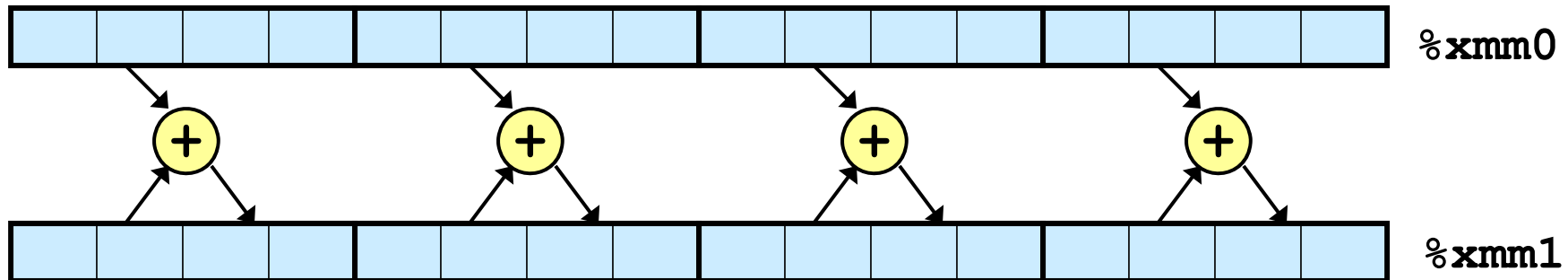
Scalar Operations: Single Precision

addss %xmm0, %xmm1



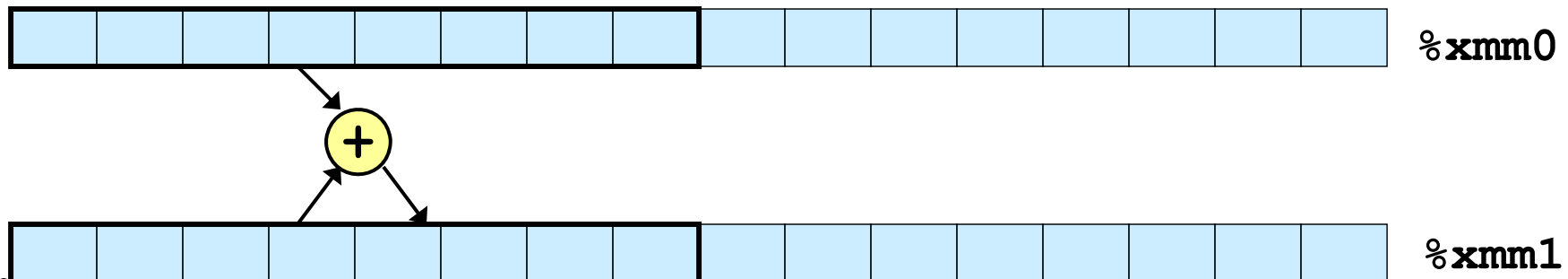
SIMD Operations: Single Precision

addps %xmm0, %xmm1



Scalar Operations: Double Precision

addsd %xmm0, %xmm1



FP Basics

- Arguments passed in `%xmm0`, `%xmm1`, ...
- Result returned in `%xmm0`
- All XMM registers caller-saved

```
float fadd(float x, float y)
{
    return x + y;
}
```

```
double dadd(double x, double y)
{
    return x + y;
}
```

```
# x in %xmm0, y in %xmm1
addss    %xmm1, %xmm0
ret
```

```
# x in %xmm0, y in %xmm1
addsd    %xmm1, %xmm0
ret
```

FP Memory Referencing

- Integer (and pointer) arguments passed in regular registers
- FP values passed in XMM registers
- Different mov instructions to move between XMM registers, and between memory and XMM registers

```
double dincr(double *p, double v)
{
    double x = *p;
    *p = x + v;
    return x;
}
```

```
# p in %rdi, v in %xmm0
movapd  %xmm0, %xmm1    # Copy v
movsd   (%rdi), %xmm0    # x = *p
addsd   %xmm0, %xmm1    # t = x + v
movsd   %xmm1, (%rdi)    # *p = t
ret
```

Other Aspects of FP Code

🌀 *Lots of instructions*

- 🌀 Different operations, different formats, ...

🌀 **Floating-point comparisons**



- 🌀 Instructions **ucomiss** and **ucomisd**
- 🌀 Set condition codes CF, ZF, and PF

🌀 **Using constant values**




- 🌀 Set XMM0 register to 0 with instruction **xorpd %xmm0, %xmm0**
- 🌀 Others loaded from memory

Summary

Arrays

-  Elements packed into contiguous region of memory
-  Use index arithmetic to locate individual elements

Structures

-  Elements packed into single region of memory
-  Access using offsets determined by compiler
-  Possible require internal and external padding to ensure alignment

Combinations

-  Can nest structure and array code arbitrarily

Floating Point

-  Data held and operated on in XMM registers

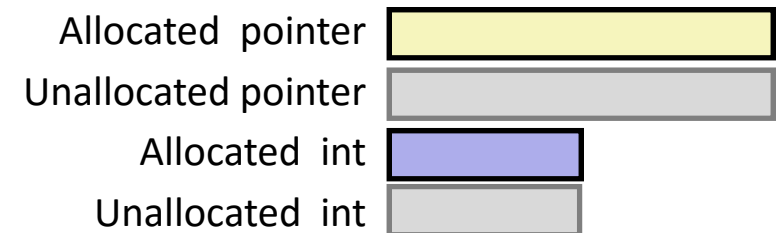
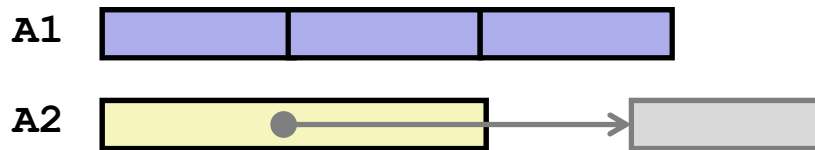
Understanding Pointers & Arrays #1

Decl	<i>An</i>			<i>*An</i>		
	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3]</code>						
<code>int *A2</code>						

- 🌀 **Cmp: Compiles (Y/N)**
- 🌀 **Bad: Possible bad pointer reference (Y/N)**
- 🌀 **Size: Value returned by `sizeof`**

Understanding Pointers & Arrays #1

Decl	An			*An		
	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3]</code>	Y	N	12	Y	N	4
<code>int *A2</code>	Y	N	8	Y	Y	4



- 🌀 **Cmp: Compiles (Y/N)**
- 🌀 **Bad: Possible bad pointer reference (Y/N)**
- 🌀 **Size: Value returned by `sizeof`**

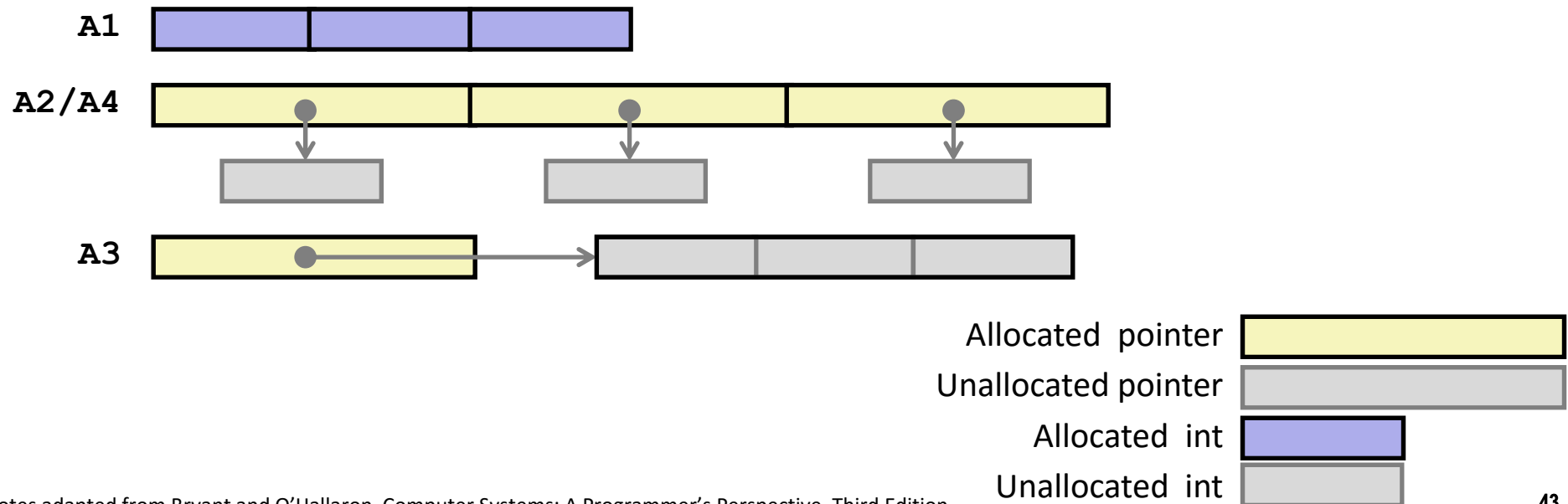
Understanding Pointers & Arrays #2

Decl	<i>A_n</i>			<i>*A_n</i>			<i>**A_n</i>		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3]</code>									
<code>int *A2[3]</code>									
<code>int (*A3)[3]</code>									
<code>int (*A4[3])</code>									

- 🌀 **Cmp: Compiles (Y/N)**
- 🌀 **Bad: Possible bad pointer reference (Y/N)**
- 🌀 **Size: Value returned by `sizeof`**

Understanding Pointers & Arrays #2

Decl	An			*An			**An		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
int A1[3]	Y	N	12	Y	N	4	N	-	-
int *A2[3]	Y	N	24	Y	N	8	Y	Y	4
int (*A3)[3]	Y	N	8	Y	Y	12	Y	Y	4
int (*A4[3])	Y	N	24	Y	N	8	Y	Y	4

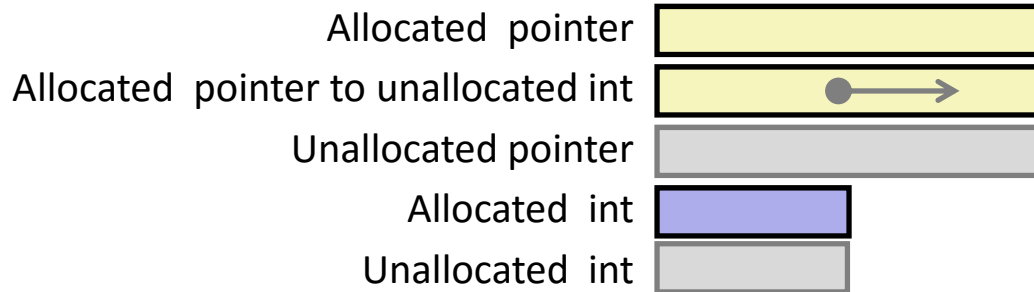


Understanding Pointers & Arrays #3

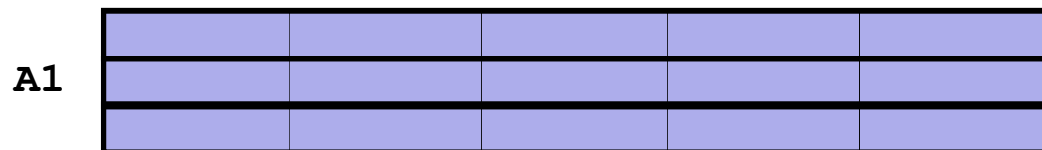
Decl	<i>A_n</i>			<i>*A_n</i>			<i>**A_n</i>		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3][5]</code>									
<code>int *A2[3][5]</code>									
<code>int (*A3)[3][5]</code>									
<code>int *(A4[3][5])</code>									
<code>int (*A5[3])[5]</code>									

- 🌀 **Cmp: Compiles (Y/N)**
- 🌀 **Bad: Possible bad pointer reference (Y/N)**
- 🌀 **Size: Value returned by `sizeof`**

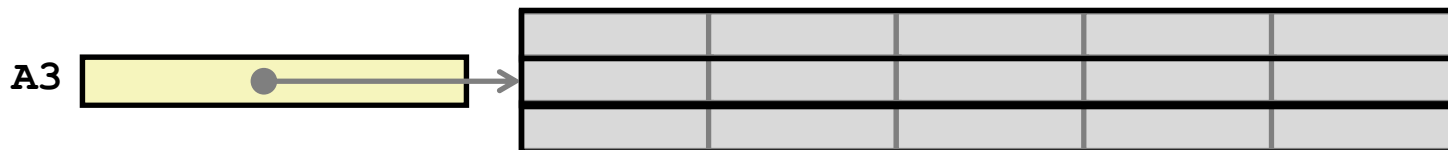
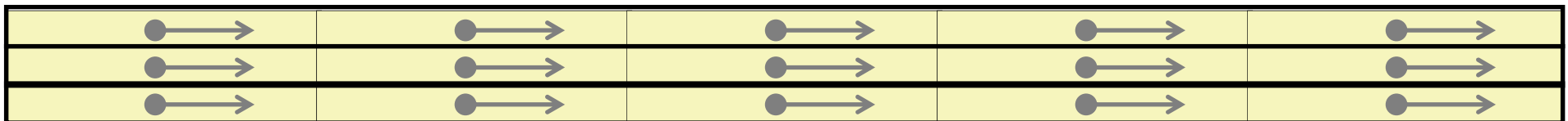
Decl	<i>***A_n</i>		
	Cmp	Bad	Size
<code>int A1[3][5]</code>			
<code>int *A2[3][5]</code>			
<code>int (*A3)[3][5]</code>			
<code>int *(A4[3][5])</code>			
<code>int (*A5[3])[5]</code>			



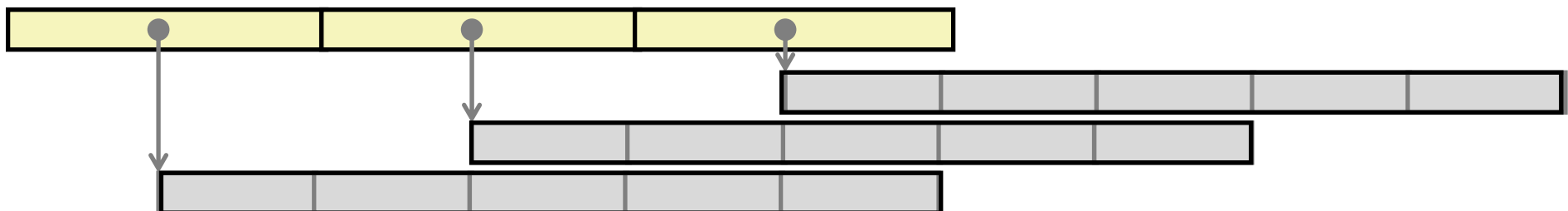
Declaration
<code>int A1[3][5]</code>
<code>int *A2[3][5]</code>
<code>int (*A3)[3][5]</code>
<code>int *(A4[3][5])</code>
<code>int (*A5[3])[5]</code>



A2/A4



A5



Understanding Pointers & Arrays #3

Decl	An			*An			**An		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
int A1[3][5]	Y	N	60	Y	N	20	Y	N	4
int *A2[3][5]	Y	N	120	Y	N	40	Y	N	8
int (*A3)[3][5]	Y	N	8	Y	Y	60	Y	Y	20
int *(A4[3][5])	Y	N	120	Y	N	40	Y	N	8
int (*A5[3])[5]	Y	N	24	Y	N	8	Y	Y	20

- 🌀 **Cmp: Compiles (Y/N)**
- 🌀 **Bad: Possible bad pointer reference (Y/N)**
- 🌀 **Size: Value returned by sizeof**

Decl	***An		
	Cmp	Bad	Size
int A1[3][5]	N	-	-
int *A2[3][5]	Y	Y	4
int (*A3)[3][5]	Y	Y	4
int *(A4[3][5])	Y	Y	4
int (*A5[3])[5]	Y	Y	4