

1 Events and Probability

A *probability space* is a *measure space* $(\Omega, \mathcal{F}, \mathbb{P})$ consisting of:

- the *sample space* Ω — a set of outcomes called *sample*;
- the *σ -algebra* \mathcal{F} — a family of subsets of Ω , called *events*, such that $\Omega \in \mathcal{F}$ and \mathcal{F} is closed under complements (i.e. $\forall A \in \mathcal{F}, \Omega \setminus A \in \mathcal{F}$) and countable unions (i.e. $\forall A_i \in \mathcal{F}, \bigcup_{i=1}^{\infty} A_i \in \mathcal{F}$);
- the *probability function* $\mathbb{P} : \mathcal{F} \rightarrow [0, 1]$ such that $\mathbb{P}(\Omega) = 1$ and \mathbb{P} is *σ -additive* (i.e. $\mathbb{P}(\bigcup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} \mathbb{P}(A_i)$).

The motivation behind this complicated definition is that some sets are *non-measurable*, thus mathematicians developed the theory of *measure*. For instance, *Borel set* on real line forms a σ -algebra which is *generated by* open intervals. *Stieltjes measures* is a *Borel measure* and builds the measure foundation of *continuous probability distribution*.

Lemma 1.1 (Inclusion-exclusion principle) *Let E_1, \dots, E_n be any n events. Then*

$$\mathbb{P}\left(\bigcup_{i=1}^n E_i\right) = \sum_{\ell=1}^n (-1)^{\ell+1} \sum_{i_1 < i_2 < \dots < i_\ell} \mathbb{P}\left(\bigcap_{r=1}^{\ell} E_{i_r}\right).$$

Events E_1, E_2, \dots, E_n are *mutually independent* (simply called *independent* when $k = 2$) if and only if, for any subset $I \subseteq \{1, 2, \dots, k\}$, $\mathbb{P}(\bigcap_{i \in I} E_i) = \prod_{i \in I} \mathbb{P}(E_i)$. Note that events X, Y, Z, \dots are unnecessarily mutually independent when they are pairwise independent.

The *conditional probability* that event E occurs given that event F occurs is $\mathbb{P}(E | F) = \mathbb{P}(E \cap F) / \mathbb{P}(F)$ ($\mathbb{P}(F) > 0$).

Theorem 1.2 (Law of total probability) *Let events $\bigcup_{i=1}^n E_i = \Omega$. Then we have $\mathbb{P}(B) = \sum_{i=1}^n \mathbb{P}(B | E_i) \cdot \mathbb{P}(E_i)$.*

Theorem 1.3 (Bayes's law) *Let events E_1, E_2, \dots, E_n satisfy $\bigcup_{i=1}^n E_i = \Omega$. Then we have*

$$\mathbb{P}(E_k | B) = \frac{\mathbb{P}(E_k \cap B)}{\mathbb{P}(B)} = \frac{\mathbb{P}(B | E_k) \cdot \mathbb{P}(E_k)}{\sum_{i=1}^n \mathbb{P}(B | E_i) \cdot \mathbb{P}(E_i)}.$$

In the *Bayesian approach* one starts with a *prior* model, giving some initial value to the model parameters. This model is then modified, by incorporating new observations, to obtain a *posterior* model that captures the new information.

Exercise 1.6 Using mathematical induction, we have $p_{i,j} = \frac{i-1}{i+j-1} \cdot p_{i-1,j} + \frac{j-1}{i+j-1} \cdot p_{i,j-1} = \frac{i+j-2}{i+j-1} \cdot \frac{1}{i+j-2} = \frac{1}{i+j-1}$.

Exercise 1.7.b Let $F_{b_1 b_2 \dots b_n}$ be the intersection of events E_i ($b_i = 1$) or $\Omega \setminus E_i$ ($b_i = 0$), and P_k be the sum of $\mathbb{P}(F_b)$ where b consists of k one and $n - k$ zero. Then for every $k \geq 1$, we have $\sum_{i=1}^l (-1)^{i+1} \binom{k}{i} = 1 + (-1)^{l+1} \binom{k-1}{l} \geq 1$. Multiply both sides by P_k and sum them up. We eventually reach the desired inequality.

Exercise 1.11.b $p_3 = p_1 \cdot (1 - p_2) + (1 - p_1) \cdot p_2 \Rightarrow q_3 = 1 - 2p_3 = (1 - 2p_1)(1 - 2p_2) = q_1 q_2$. Is there any underlying motivation?

Exercise 1.24 (Karger's algorithm) Let K be the minimum r -way cut-set. Considering all r -way cut-sets consisting of $r - 1$ single vertex, the total size is $m \cdot \binom{n-2}{r-1}$ with an upper bound $(m - |K|) \cdot \binom{n}{r-1}$. It follows that

$$m \cdot \binom{n-2}{r-1} \leq (m - |K|) \cdot \binom{n}{r-1} \Rightarrow 1 - \frac{|K|}{m} \geq \binom{n-2}{r-1} \binom{n}{r-1}^{-1} = \frac{(n-r+1)(n-r)}{n(n-1)}.$$

The probability that K survives all the $n - r$ iterations is at least

$$\prod_{i=0}^{n-r-1} \frac{(n-i+1-r)(n-i-r)}{(n-i)(n-i-1)} = r \cdot \binom{n}{r-1}^{-1} \binom{n-1}{r-1}^{-1}$$

and its reciprocal is the maximum possible number of minimum cardinality of r -way cut-sets.