On Convergence of Bregman Proximal Point Subgradient Method

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1 Preliminaries

1.1 Bregman divergence

Definition 1 (Legendre function) [1] A function $h : \mathbb{R}^n \to \mathbb{R} \cup \{\infty\}$ is called a Legendre function if h is proper, lsc, strictly convex and essentially smooth.

Definition 2 (Bregman divergence) The Bregman divergence $D_h(x, y)$ induced by Legendre function h is defined as

$$D_h(x,y) := h(x) - h(y) - \langle \nabla h(y), x - y \rangle$$

for all $x \in \text{dom } h$ and $y \in \text{dom } \nabla h$.

Here we define the non-differentiable version of relatively smoothness.

Definition 3 (Relatively smooth) [2] Let h be a Legendre function and f (possibly non-differentiable) be a function with dom $f \subseteq \text{dom } h$. Function f is said to be L-smooth relative to h if

$$Lh - f$$
 is convex on dom f ,

or equivalently,

$$f(y) \le f(x) + \langle f'(x), y - x \rangle + LD_h(y, x)$$

for all $x \in \text{dom } f$, $f'(x) \in \partial f(x)$ and $y \in \text{dom } f$.

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1.2 Problem setup

We consider the optimization problem(P)

$$\min_{x \in \mathbb{R}^d} f(x) \tag{P}$$

which satisfies following assumptions.

Assumption 1

- -h is a Legendre function on \mathbb{R}^d ,
- $-f: \mathbb{R}^d \to \mathbb{R} \cup \{\infty\}$ is a convex, proper, lsc function (possibly not differentiable) and is L-smooth relative to h,
- For any $\lambda > 0$, $u, v \in \mathbb{R}^d$ and $x \in \text{int dom } h$, the problem

$$\min_{u \in \mathbb{R}^d} f(u) + \frac{1}{\lambda} D_h(u, x)$$

has a unique minimizer in dom ∇h ,

- The problem (P) has nonempty solution.

We denote $\mathcal{F}_L(\mathbb{R}^d)$ as the class of function tuples satisfying above assumptions, namely

$$\mathcal{F}_L(\mathbb{R}^d) := \{(f, h) \mid f, h \text{ satisfy Assumption } 1\}.$$

1.3 Method

We use the following fixed step Bregman Proximal Point Subgradient method to solve (P).

Algorithm 1: Bregman Proximal Point Subgradient (BPPSG)

Input: f and h satisfying Assumption 1, $x_0 \in \text{int dom } h$, step size $\lambda \in (0, 1/L]$. **Output:** x_N

for k = 0, 1, ..., N - 1 do

$$y_k = \operatorname*{arg\,min}_{u \in \mathbb{R}^d} f(u) + \frac{1}{\lambda} D_h(u, x_k) \tag{1}$$

$$x_{k+1} = \nabla h^* \left(\nabla h(y_k) - \lambda f'(y_k) \right), \quad f'(y_k) \in \partial(y_k)$$
 (2)

From the optimality condition of (1) we obtain

$$0 \in \partial f(y_k) + \frac{1}{\lambda} \left(\nabla h(y_k) - \nabla h(x_k) \right). \tag{3}$$

Let $f'(y_k) = -\frac{1}{\lambda} (\nabla h(y_k) - \nabla h(x_k))$ and plug this into (2) we have

$$\nabla h(x_{k+1}) = \nabla h(y_k) + (\nabla h(y_k) - \nabla h(x_k)). \tag{4}$$

With (3) we get

$$\begin{cases}
\nabla h(y_0) = \nabla h(x_0) - f'(y_0), \\
\nabla h(y_{k+1}) = \nabla h(y_k) - \lambda \left(f'(y_k) + f'(y_{k+1}) \right) & k = 0, 1, 2, \dots
\end{cases}$$
(5)

2 Convergence rate through PEP

We analyze first the convergence of sequence $\{y_k\}$, then move on to $\{x_k\}$. We shall see that they converge at about the same speed.

2.1 PEP formulation

We construct the relaxed version of PEP, that is, we require h to be convex, not necessarily strictly convex.

Firstly, notice that (5) relates to x_0 and $\{y_k\}_{k=0}^N$ only. We rename these variables with the minimizer of (P) as $\{u_i\}_{i\in I}$, where $I=\{*,0,1,\ldots,N+1\}$,

$$\begin{cases} u_* = \arg\min_u f(u), \\ u_0 = x_0, \\ u_i = y_{i-1}, \quad i = 1, \dots, N+1. \end{cases}$$

We define variables $\{(f_i, g_i, h_i, s_i)\}_{i \in I} \subseteq (\mathbb{R} \times \mathbb{R}^d \times \mathbb{R} \times \mathbb{R}^d)^{|I|}$ such that

$$\begin{cases} f_i = f(u_i), & g_i = f'(u_i), \\ h_i = h(u_i), & s_i = \nabla h(u_i). \end{cases}$$

With the interpolation conditions introduced in [3], we obtain the relaxed PEP formulation after dropping some of the inequalities:

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where R > 0 is a predetermined constant and $\lambda \in (0, 1/L]$. Here we make use of the fact that $\frac{1}{\lambda}Lh - f$ is convex as long as $\frac{1}{\lambda} \geq L$. This comes from the additive conservation of convexity, and the fact that h is convex.

Above (r-PEP-P) problem can be formulated as a semidefinite programming and be solved. The resulting dual solution gives a proof of upper bound on BPPSG method.

2.2 Upper bound through duality

We derive the upper bound for sequence $\{y_k\}_{k\geq 0}$. With the notation defined in the last section, $y_N=u_{N+1}$.

Theorem 1 (BPPSG convergence rate) Let L > 0, (f, h, ϕ) are a tuple of function satisfying Assumption 1. Then the sequence $\{y_k\}_{k\geq 0}$ generated by Algorithm 1 with constant step size $\lambda \in (0, 1/L]$ satisfies for all N > 0,

$$f(y_N) - f(x_*) \le \frac{D_h(x_*, x_0)}{\lambda(2N+1)}.$$
 (6)

Proof We make use of the convexity inequalities in (r-PEP-P) and perform weighted sum of these inequalities, where weights are given by the corresponding dual solutions of (r-PEP-P).

The proof itself is purely arithmetic. We use the notations defined in the last section. The nonzero dual solution and corresponding constraint inequalities involved in the proof:

$$-c_{N,i}^{(1)} = \frac{2}{2N+1}, (i=1,\ldots,N+1)$$
 for convexity of f between u_* and u_i :

$$f_i - f_* + \langle q_i, u_* - u_i \rangle < 0,$$

$$-c_{N,i}^{(2)} = \frac{2i-1}{2N+1}, (i=1,\ldots,N)$$
 for convexity of f between u_i and u_{i+1} :

$$f_{i+1} - f_i + \langle q_{i+1}, u_i - u_{i+1} \rangle < 0,$$

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$$c_{N,N}^{(3)} = \frac{1}{2N+1}$$
 for convexity of f between u_1 and u_0

$$f_0 - f_1 + \langle g_0, u_1 - u_0 \rangle \le 0,$$

$$-c_{N,i}^{(4)}=\frac{2i-1}{4N+2}, (i=2,\ldots,N+1)$$
 for convexity of $\frac{1}{\lambda}h-f$ between u_i and u_{i-1} :

$$\frac{1}{\lambda}h_{i-1} - f_{i-1} - \left(\frac{1}{\lambda}h_i - f_i\right) + \left\langle \frac{1}{\lambda}s_{i-1} - g_{i-1}, u_i - u_{i-1} \right\rangle \le 0,$$

$$-c_{N,i}^{(5)} = \frac{2i-1}{4N+2}, (i=1,\ldots,N)$$
 for convexity of $\frac{1}{\lambda}h - f$ between u_i and u_{i+1} :

$$\frac{1}{\lambda}h_{i+1} - f_{i+1} - (\frac{1}{\lambda}h_i - f_i) + \left\langle \frac{1}{\lambda}s_{i+1} - g_{i+1}, u_i - u_{i+1} \right\rangle \le 0,$$

$$-c_{N,N}^{(6)} = \frac{1}{2N+1} \text{ for convexity of } \frac{1}{\lambda}h - f \text{ between } u_1 \text{ and } u_0:$$

$$\frac{1}{\lambda}h_0 - f_0 - (\frac{1}{\lambda}h_1 - f_1) + \left\langle \frac{1}{\lambda}s_0 - g_0, u_1 - u_0 \right\rangle \leq 0,$$

$$-c_{N,N}^{(7)} = \frac{1}{2N+1} \text{ for convexity of } \frac{1}{\lambda}h - f \text{ between } u_* \text{ and } u_{N+1}:$$

$$\frac{1}{\lambda}h_{N+1} - f_{N+1} - (\frac{1}{\lambda}h_* - f_*) + \left\langle \frac{1}{\lambda}s_{N+1} - g_{N+1}, u_* - u_{N+1} \right\rangle \leq 0.$$

The weighted sum is

$$\sum_{i=1}^{N+1} \frac{2}{2N+1} (f_i - f_* + \langle g_i, u_* - u_i \rangle)$$

$$+ \sum_{i=1}^{N} \frac{2i-1}{2N+1} (f_{i+1} - f_i + \langle g_{i+1}, u_i - u_{i+1} \rangle)$$

$$+ \frac{1}{2N+1} (f_0 - f_1 + \langle g_0, u_1 - u_0 \rangle)$$

$$+ \sum_{i=2}^{N+1} \frac{2i-1}{4N+2} \left(\frac{1}{\lambda} h_{i-1} - f_{i-1} - (\frac{1}{\lambda} h_i - f_i) + \left\langle \frac{1}{\lambda} s_{i-1} - g_{i-1}, u_i - u_{i-1} \right\rangle \right)$$

$$+ \sum_{i=2}^{N} \frac{2i-1}{4N+2} \left(\frac{1}{\lambda} h_{i+1} - f_{i+1} - (\frac{1}{\lambda} h_i - f_i) + \left\langle \frac{1}{\lambda} s_{i+1} - g_{i+1}, u_i - u_{i+1} \right\rangle \right)$$

$$+ \frac{1}{2N+1} \left(\frac{1}{\lambda} h_0 - f_0 - (\frac{1}{\lambda} h_1 - f_1) + \left\langle \frac{1}{\lambda} s_0 - g_0, u_1 - u_0 \right\rangle \right)$$

$$+ \frac{1}{2N+1} \left(\frac{1}{\lambda} h_{N+1} - f_{N+1} - (\frac{1}{\lambda} h_* - f_*) + \left\langle \frac{1}{\lambda} s_{N+1} - g_{N+1}, u_* - u_{N+1} \right\rangle \right)$$

$$= f_{N+1} - f_* - \frac{1}{\lambda(2N+1)} (h_* - h_0) + \frac{1}{2N+1} \left\langle \frac{1}{\lambda} s_0, -u_0 \right\rangle$$

$$+ \left\langle \sum_{i=1}^{N+1} \frac{2}{2N+1} g_i + \frac{1}{2N+1} \left(\frac{1}{\lambda} s_{N+1} - g_{N+1} \right), u_* \right\rangle$$

$$+ \sum_{i=2}^{N} \frac{2i-1}{4N+2} \left\langle \frac{1}{\lambda} s_{i-1} - g_{i-1} + \frac{1}{\lambda} s_{i+1} + g_{i+1} - \frac{2}{\lambda} s_i, u_i \right\rangle$$

$$+ \frac{1}{4N+2} \left\langle \frac{1}{\lambda} s_2 + g_2 - \frac{3}{\lambda} s_1 - g_1 + \frac{2}{\lambda} s_0, u_1 \right\rangle$$

$$+ \frac{1}{2} \left\langle \frac{1}{\lambda} s_N - g_N - \frac{1}{\lambda} s_{N+1} - g_{N+1}, u_{N+1} \right\rangle$$
:= $E \le 0$.

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By equation (5), written with new notations as

$$\begin{cases} s_1 = s_0 - g_1, \\ s_{k+1} = s_k - \lambda (g_k + g_{k+1}) & k = 1, \dots, N, \end{cases}$$

we have

$$\frac{1}{\lambda}s_{i-1} - g_{i-1} + \frac{1}{\lambda}s_{i+1} + g_{i+1} - \frac{2}{\lambda}s_i = 0, \quad \forall 2 \le i \le N,$$
 (7)

$$s_{N+1} + \lambda g_{N+1} + 2\lambda \sum_{i=1}^{N} g_i = s_0.$$
 (8)

Thus II = 0 and

$$I = \frac{1}{\lambda(2N+1)} \left\langle s_0, u_* \right\rangle.$$

The weighted sum of inequalities becomes

$$\begin{split} E = & f_{N+1} - f_* - \frac{1}{\lambda(2N+1)} (h_* - h_0) \\ & + \frac{1}{\lambda(2N+1)} \left\langle s_0, u_* - u_0 \right\rangle \\ & + \frac{1}{4N+2} \left\langle -\frac{2}{\lambda} s_1 - 2g_1 + \frac{2}{\lambda} s_0, u_1 \right\rangle \\ & + \frac{1}{2} \left\langle \frac{1}{\lambda} s_N - g_N - \frac{1}{\lambda} s_{N+1} - g_{N+1}, u_{N+1} \right\rangle \\ = & f_{N+1} - f_* - \frac{1}{\lambda(2N+1)} D_h(u_*, u_0) \le 0. \end{split}$$

Replace the symbol back and we obtain the convergence result

$$f(y_N) - f(x_*) \le \frac{1}{\lambda(2N+1)} D_h(x_*, x_0).$$
 (9)

Analogously, we can perform PEP on the sequence $\{x_i\}$ and obtain its convergence rate. The result is similar.

Proposition 1 (BPPSG convergence rate (take II)) Let L > 0, (f, h, ϕ) are a tuple of function satisfying Assumption 1. Then the sequence $\{x_k\}_{k\geq 0}$ generated by Algorithm 1 with constant step size $\lambda \in (0, 1/L]$ satisfies for all N > 0,

$$f(x_N) - f(x_*) \le \frac{D_h(x_*, x_0)}{2\lambda N}.$$
 (10)

References

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