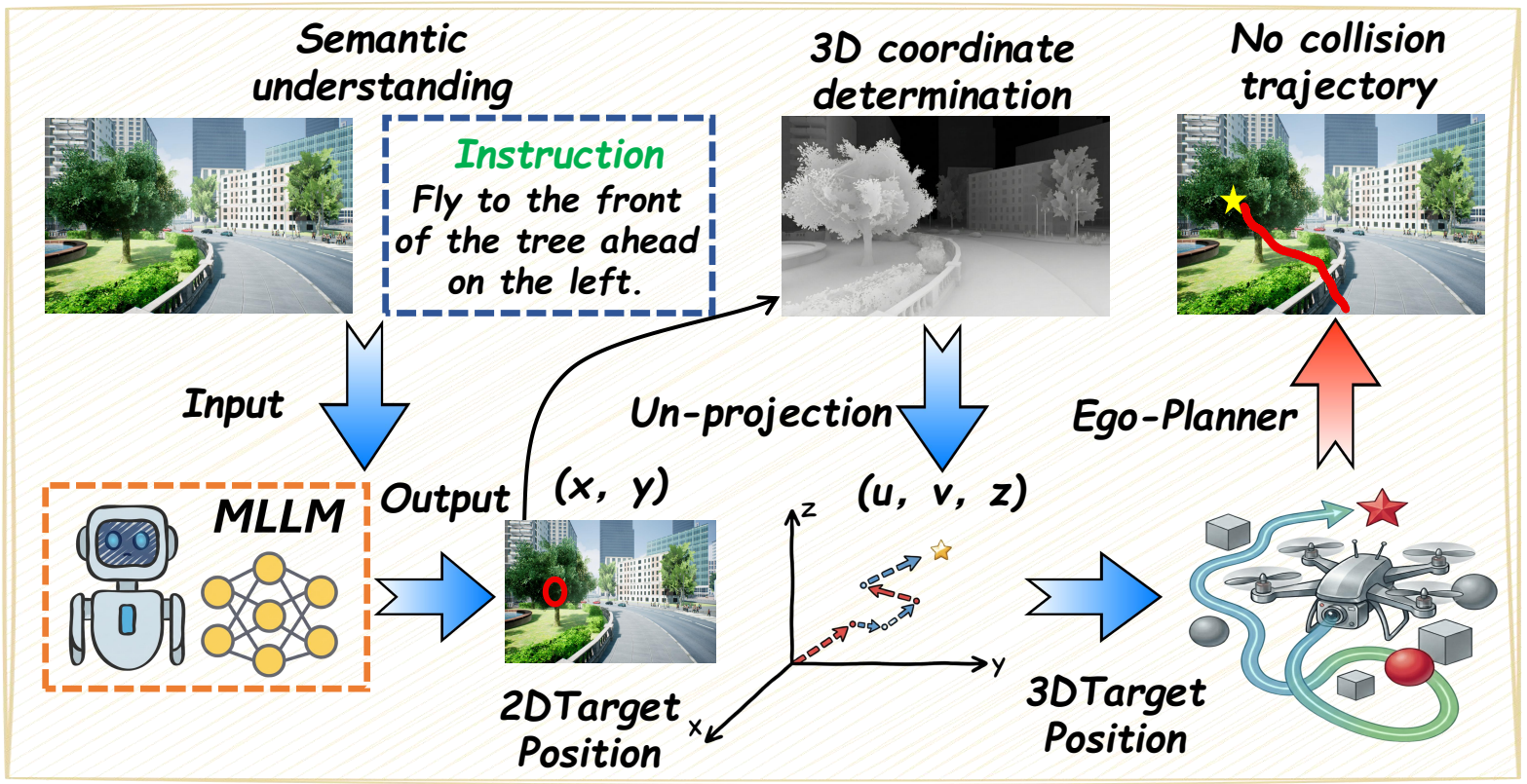
Semantic understanding
3D coordinate determination
No collision trajectory
Instruction
Fly to the front of the tree ahead on the left.
Input
Un-projection
Ego-Planner
MLLM
Output
(x, y)
(u, v, z)
z
y
x
2DTarget Position
3DTarget Position