## **Course Operating Systems**

# Complementary Notes: Locks, condition variables and use in synchronization problems

EDA093, DIT 401 Study Period 1

Ack: pseudocode sections are adaptations of examples in Leture Notes by John Ousterhout, Stanford Un: https://web.stanford.edu/~ouster/cgi-bin/cs140-spring14/lecture.php?topic=locks

### Locks

- Lock: an object that can only be "owned" by a single thread at any given time. Basic operations:
  - acquire: mark the lock as owned by the current thread; if some other thread already owns the lock then first wait (spinning or @queue) until the lock is free.
  - release: mark the lock as free (it must currently be owned by the calling thread).

# Bounded producer-consumer buffer: solve it using locks

#### Remember the requirements:

- Producer inserts items; must wait if buffer full
- Consumer removes items; must wait if buffer empty
- Accessing the buffer is a critical section

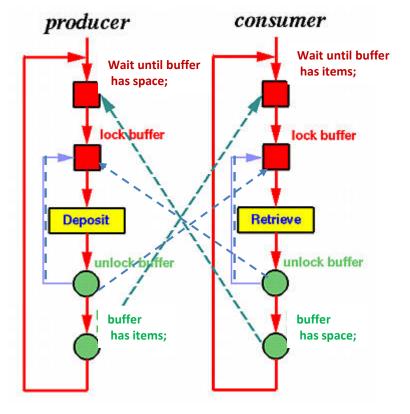
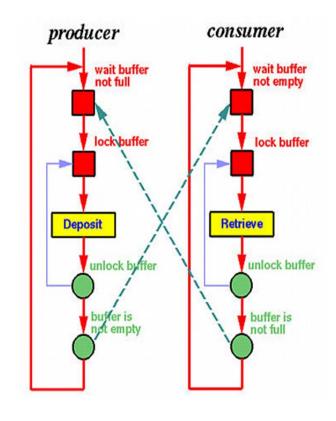


fig C.K. Shene http://www.cs.mtu.edu/~shene/NSF-3/e-Book/

#### **Bounded buffer using locks**

(PintOS-like API)

```
<some type> buffer[SIZE];
           int count = 0;
           struct lock 1; // synchronization object
           lock init(&1);
producer
                                      consumer
 do {
                                      do {
                                        lock acquire(&1);
    produce item
                                        while (count == 0) {
                                          lock release(&1);
                                          lock acquire(&1);
  lock acquire(&1);
  while (count == SIZE) {
    lock release(&1); ▼
    lock acquire(&1);
                                      // remove item from buffer
 // add item to buffer
                                      count--;
                                      lock release(&1);
count++;
lock release(&1);
                                     // use the item
                                      } while (True);
} while (True);
```



Homework: compare it with the semaphore-based solution studied in class

#### **Condition Variables**

Condition variable: an object to wait for a particular condition to become true. Associated with a *lock* 

#### API: (PintOS-like (\*)):

- cond\_wait(condition, lock): release lock, put thread to sleep until condition is signaled;
   when thread wakes up again, re-acquire lock before returning.
- cond\_signal(condition, lock): if any threads are waiting on condition, wake up one of them. Caller must hold lock, which must be the same as the lock used in the wait call.
- cond broadcast (condition, lock): same as signal, except wake up all waiting threads.

Check also Ptreads API eg here https://pages.cs.wisc.edu/~remzi/OSTEP/threads-cv.pdf for perspective

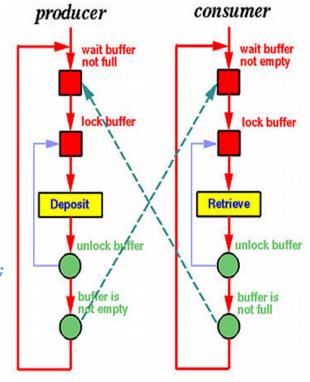


<sup>(\*)</sup> Note: after signal, signaling thread keeps lock, waking thread goes on the queue waiting for the lock.

## **Bounded buffer using condition variables**

(PintOS-like API)

```
<some type> buffer[SIZE];
                   int count = 0;
                   struct lock 1; // synchronization object
                   struct condition dataAvailable; // synchronization object
                   struct condition spaceAvailable; // synchronization object
                   lock init(&1);
                   cond init(&dataAvailable);
                   cond init(&spaceAvailable);
producer
                                                  consumer
 do {
                                                  do {
                                                    lock acquire(&1);
    produce item
                                                    while (count == 0) {
                                                      cond wait(&dataAvailable, &1);
  lock acquire(&1);
  while (count == SIZE) {
    cond wait(&spaceAvailable, &1);
                                                  // remove item from buffer
                                                  count--;
 // add item to buffer
                                                  cond signal(&spaceAvailable, &1);
                                                  lock release(&1);
count++;
cond signal(&dataAvailable, &1);
                                                  // use the item
lock release(&1);
                                                  } while (True);
} while (True);
```



Homework: compare it with the lock-based and the semaphore-based solutions we studied

#### **Observe**

- Condition Variables: higher-level synchronization mechanism that provide
  - Mutual exclusion: easy to create critical sections
  - Scheduling-related functionality: block thread until some desired event occurs
- When locks and condition variables are used together like this, the result is called a *monitor*:
  - A collection of procedures manipulating a shared data structure.

#### See also:

- Operating Systems: Three Easy Pieces Remzi H. Arpaci-Dusseau and Andrea C. Arpaci-Dusseau (University of Wisconsin-Madison) <a href="https://pages.cs.wisc.edu/~remzi/OSTEP/threads-cv.pdf">https://pages.cs.wisc.edu/~remzi/OSTEP/threads-cv.pdf</a>