
Team Machina: OpenMANIPULATOR-X Coursework Report

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Contents

1	Task 1 - Modelling	2
1.1	Assigning Coordinate Frames	2
1.2	Simulation: Graphical simulation of coordinate frames	2
1.3	Inverse Kinematics	2
1.4	Simulation: Tracing a square on each cartesian plane	2

1 Task 1 - Modelling

1.1 Assigning Coordinate Frames

1.2 Simulation: Graphical simulation of coordinate frames

1.3 Inverse Kinematics

1.4 Simulation: Tracing a square on each cartesian plane