

# 60006 - Tutorial 3

## Interest Point Detection

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### Question 1

**Question 1.1:** Please derive the eigenvalues for this matrix.

$$\det \left( \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix} - \lambda \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \right) : \lambda^2 - 6\lambda + 8$$
$$\lambda = 4 \quad \lambda = 2$$

**Question 1.2:** Please compute the Harris detector response.

$$\begin{aligned} R &= \lambda_1 \lambda_2 - k(\lambda_1 + \lambda_2)^2 \\ &= 4 * 2 - 0.05(4 + 2)^2 \\ &= 6.2 \end{aligned}$$

**Question 1.3:** Please derive the eigenvalues for this matrix and the corresponding Harris detector response.

$$M = \begin{bmatrix} 12 & 4 \\ 4 & 12 \end{bmatrix}$$
$$\lambda_1 = 16 \quad \lambda_2 = 8$$
$$R = 16 * 8 - 0.05(16 + 8)^2 = 99.2$$

**Question 1.4:** Directly calculate the scale-adapted Harris detector using trace and determinant instead of eigen decomposition.

$$\begin{aligned} \det(M) &= 128 \\ \text{tr}(M) &= 24 \\ R &= \det(M) - k(\text{tr}(M))^2 = 128 - 0.05(24)^2 = 99.2 \end{aligned}$$

### Question 2

**Question 2.1:** Please prove the following equation holds (also known as the heat diffusion equation).

$$G(x, y, \sigma) = \frac{1}{2\pi\sigma^2} e^{-\frac{x^2+y^2}{2\sigma^2}}$$

$$\begin{aligned}\frac{\partial G}{\partial \sigma} &= \frac{(y^2 + x^2) e^{-\frac{y^2+x^2}{2\sigma^2}}}{2\pi\sigma^5} - \frac{e^{-\frac{y^2+x^2}{2\sigma^2}}}{\pi\sigma^3} \\ &= -\frac{(2\sigma^2 - y^2 - x^2)}{2\pi\sigma^5} e^{-\frac{y^2+x^2}{2\sigma^2}}\end{aligned}$$

$$\begin{aligned}\frac{\partial^2 G}{\partial x^2} &= \frac{(x^2 - \sigma^2) e^{-\frac{x^2+y^2}{2\sigma^2}}}{2\pi\sigma^6} \\ \frac{\partial^2 G}{\partial y^2} &= \frac{(y^2 - \sigma^2) e^{-\frac{y^2+x^2}{2\sigma^2}}}{2\pi\sigma^6}\end{aligned}$$

**Question 2.2:**

$$\begin{aligned}\frac{\partial G}{\partial \sigma} &\approx \sigma \nabla^2 G \quad \text{and} \quad \frac{\partial G}{\partial \sigma} \approx \frac{G(k\sigma - G(\sigma))}{k\sigma - \sigma} \\ DoG(x, y, \sigma) &= G(k\sigma) - G(\sigma) \approx (k - 1)\sigma^2 \nabla^2 G\end{aligned}$$