Imperial College London

DEPARTMENT OF ELECTRICAL AND ELECTRONIC ENGINEERING

ELEC50008: Engineering Design Project

Group 18: Mars Rover Project Report

Authors

Aixin Zhang CID: 01738988 az419@ic.ac.uk

Ebby Samson CID: 01737449 es1219@ic.ac.uk

Igor Dmytrovich Silin CID: 01756268 ids19@ic.ac.uk

> Kaling Ng CID: 01737644 kln19@ic.ac.uk

Nur Izzah Mohd Zafer CID: 01738670 nim19@ic.ac.uk

> Xin Wang CID: 01735253 xw2519@ic.ac.uk

Contents

1	\mathbf{Pro}	oject Management	
	1.1	Conception and Initiation	
	1.2	Definition and Planning	
	1.3	Implementation	
	1.4	Performance and Control	
	1.5	Project conclusion	
2	Str	uctural design	
3	Rover Submodules		
	3.1	Command	
	3.2	Control	
	3.3	Vision	
	3.4	Drive	
	3.5	Energy	
	3.6	Integration	
4	\mathbf{Pro}	oject Issues	
5	Ref	rences	

1 Project Management

The project team utilised the Project Management Institute's 5 Phases of Project Management ¹ as a guide to ensure all aspects of project planning and management are captured in the team's project management approach.

The approach is split into 5 stages which combines to form a robust project management system.

1.1 Conception and Initiation

Project definition: Design and build a rover system that has autonomous capabilities to detect, avoid and transmit the locations of the obstacles i.e. coloured balls to a server that users can interact with.

Project requirement: The rover system is split into 5 modules, each with its own requirements:

- Command:
 - Establish and maintain bilateral communication with Control module
 - Display rover sensor data
 - Enable users to nagivate the rover
 - Plot a map of the locations of the obstacles encountered by the rover
- Control:
- Drive:
- Energy:
- Vision:
- 1.2 Definition and Planning
- 1.3 Implementation
- 1.4 Performance and Control
- 1.5 Project conclusion

¹PMI: https://www.smartsheet.com/blog/demystifying-5-phases-project-management

2 Structural design

3 Rover Submodules

- 3.1 Command
- 3.2 Control
- 3.3 Vision
- 3.4 Drive
- 3.5 Energy
- 3.6 Integration

4 Project Issues

5 References