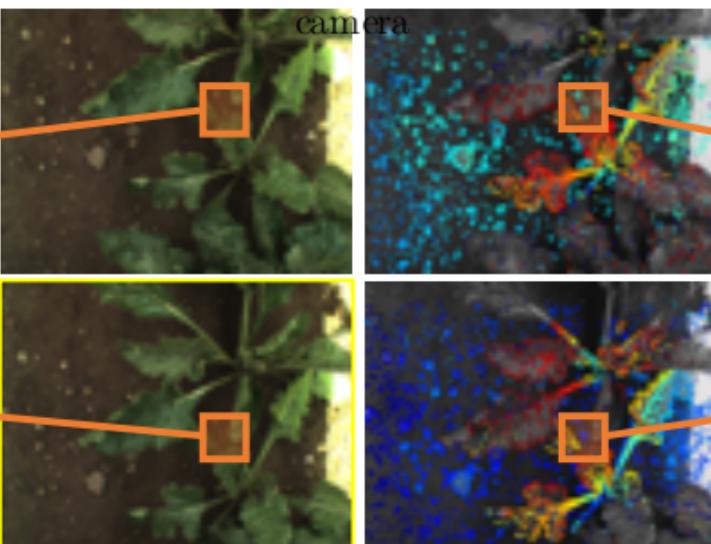


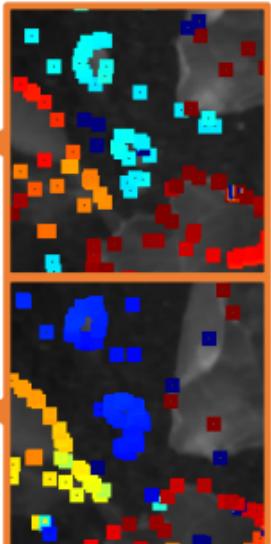
2D template



Image and depth map from detection



3D template



2D-2D match



Image from tracking camera



3D-2D match