左偏树/左倾堆

Leftist Heaps

and Skew Heaps

斜堆

heap 最小堆 最大堆
查询最大和最小元素

插入元素：放在最末尾 自顶向上

删除元素：删除根节点后
将末尾元素放在根节点处
自顶向下调整

Leftist Heaps

merge 合并
选出根 并为左右子树 再调整
O(N), N为总结点数

Target : **Speed up merging in O(*N*).**

Heap: **Structure Property + Order Property**

> **Discussion 5:** **How fast can we merge two heaps if we simply use the original heap structure?**

Leftist Heap:

顺序性质相同：小的在上
结构性质不同：高度不平衡

Order Property – the same

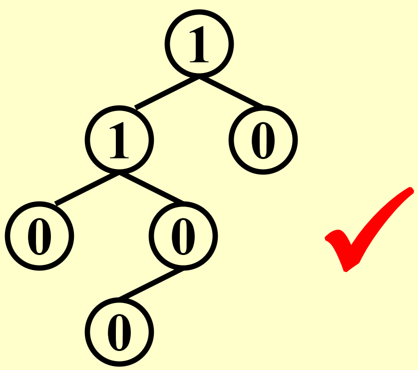
Structure Property – binary tree, but *unbalanced*

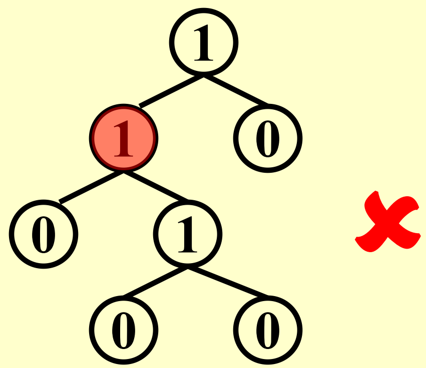
【Definition】The null path length, Npl(X), of any node X is the length of the shortest path from X to a node without two children. Define Npl(NULL) = –1.

Note:

Npl(X) = min { Npl(C) + 1 for all C as children of X }

【Definition】The leftist heap property is that for every node X in the heap, the null path length of the left child is at least as large as that of the right child.





The tree is biased to get deep toward the *left*.

【Theorem】A leftist tree with r nodes on the right path must have at least $2^r - 1$ nodes.

Proof: By induction on p. 162.

Discussion 6: How long is the right path of a leftist tree of *N* nodes? What does this conclusion mean to us?

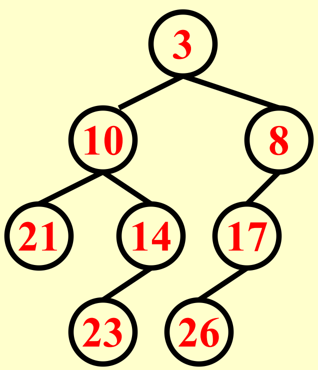
Trouble makers: Insert and Merge

Note: Insertion is merely a special case of merging.

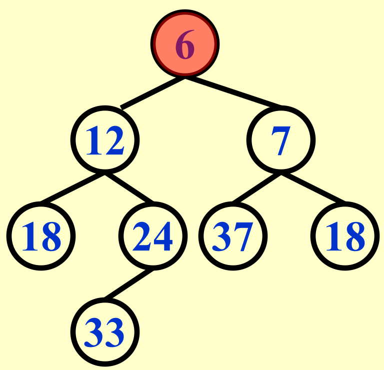
☞ Declaration:

```
struct TreeNode
{
    ElementType       Element;
    PriorityQueue     Left;
    PriorityQueue     Right;
    int               Npl;
} ;
```

☞ Merge (recursive version):

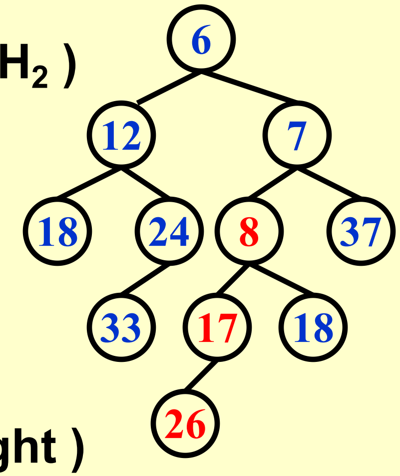


H_1

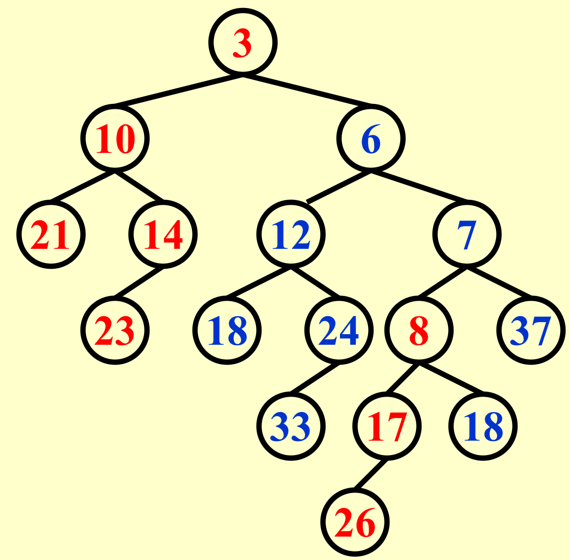


H_2

Step 1:
Merge(H_1->Right, H_2)



Step 2:
Attach(H_2, H_1->Right)



Step 3:
Swap(H_1->Right, H_1->Left)
if necessary

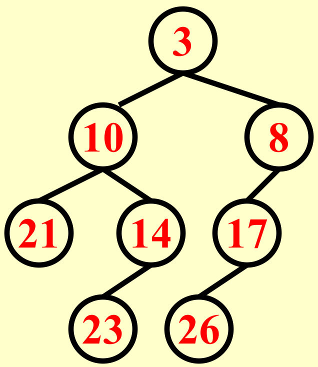
```
PriorityQueue  Merge ( PriorityQueue H1, PriorityQueue H2 )
{
    if ( H1 == NULL )   return H2;
    if ( H2 == NULL )   return H1;
    if ( H1->Element < H2->Element )  return Merge1( H1, H2 );
    else return Merge1( H2, H1 );
}
```

```
static PriorityQueue
Merge1( PriorityQueue H1, PriorityQueue H2 )
{
    if ( H1->Left == NULL )     /* single node */
            H1->Left = H2;      /* H1->Right is already NULL
                                   and H1->Npl is already 0 */
    else {
            H1->Right = Merge( H1->Right, H2 );     /* Step 1 & 2 */
            if ( H1->Left->Npl < H1->Right->Npl )
                        SwapChildren( H1 );         /* Step 3 */
            H1->Npl = H1->Right->Npl + 1;
    } /* end else */
    return H1;
}
```

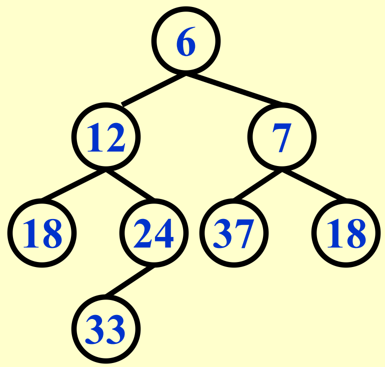
$T_p = O(\log N)$

What if *Npl* is NOT updated?

☞ **Merge (iterative version):**

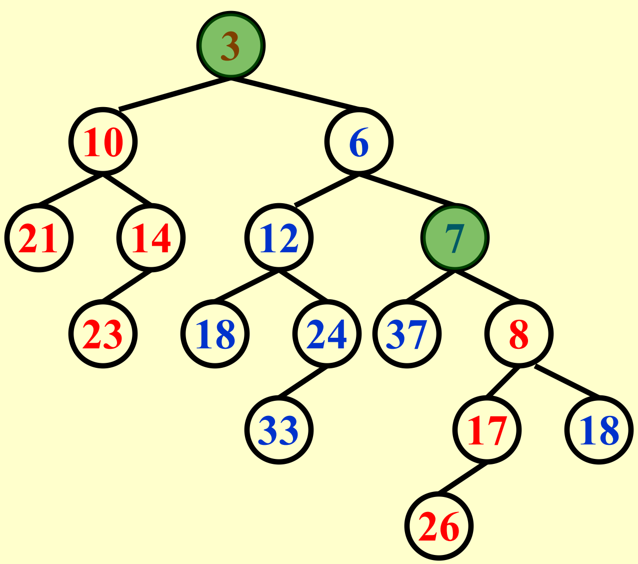


H_1

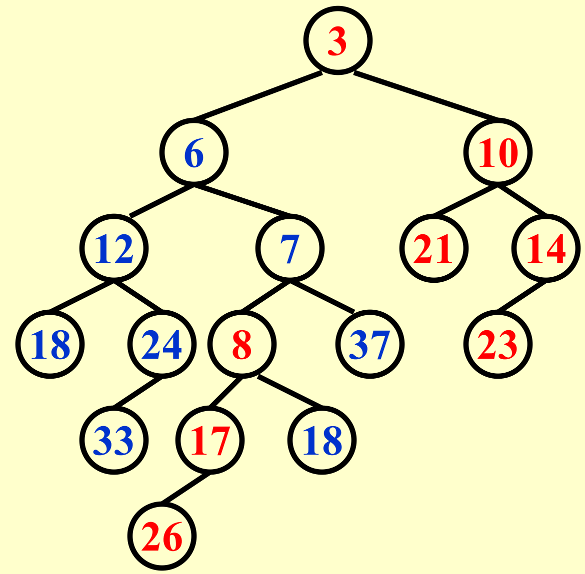


H_2

Step 1: **Sort the right paths without changing their left children**



Step 2: **Swap children if necessary**



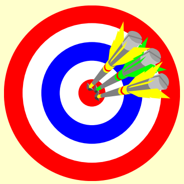
☞ **DeleteMin:**

Step 1: **Delete the root**

Step 2: **Merge the two subtrees**

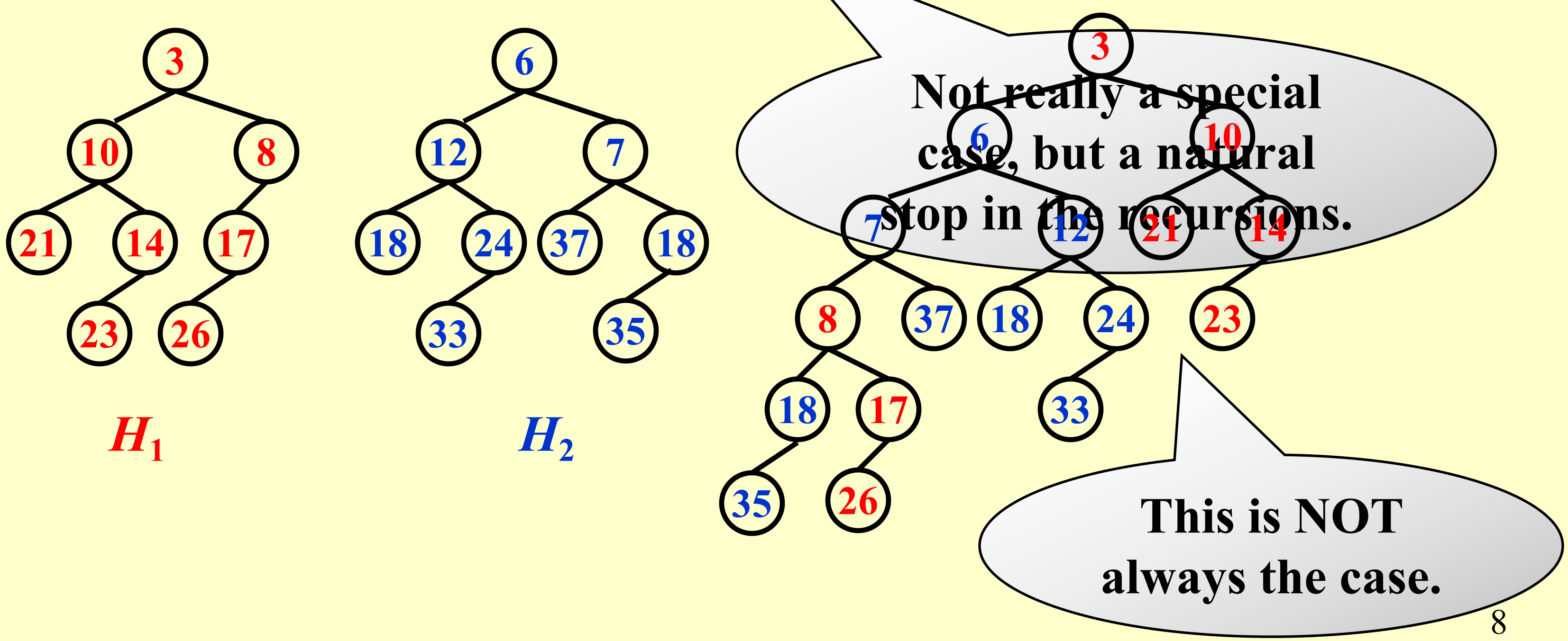
$T_p = O(\log N)$

Skew Heaps -- a simple version of the leftist heaps

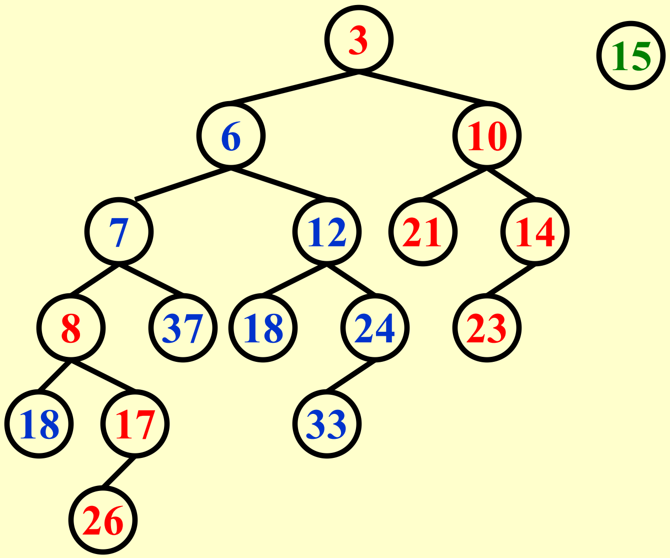


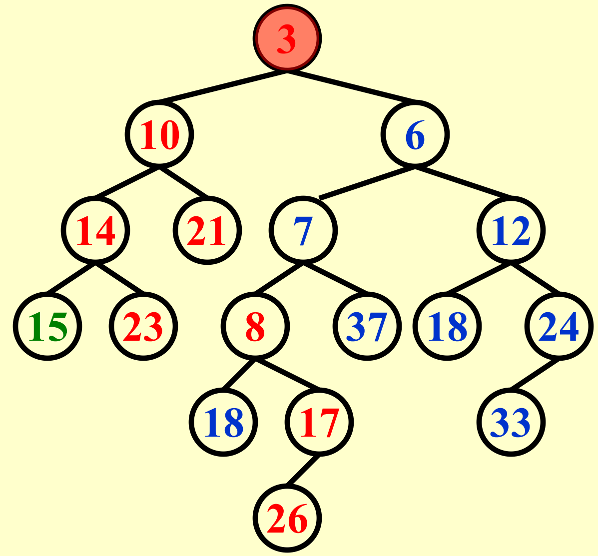
Target : Any M consecutive operations take at most $O(M \log N)$ time.

☞ **Merge:** **Always** swap the left and right children except that the **largest** of all the nodes on the right paths does not have its children swapped. **No Npl.**

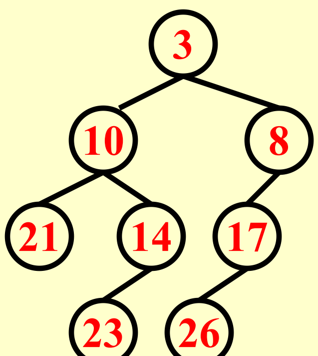


【Example】Insert 15

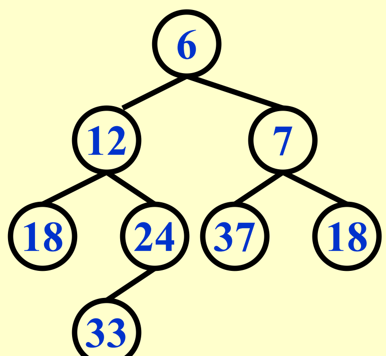




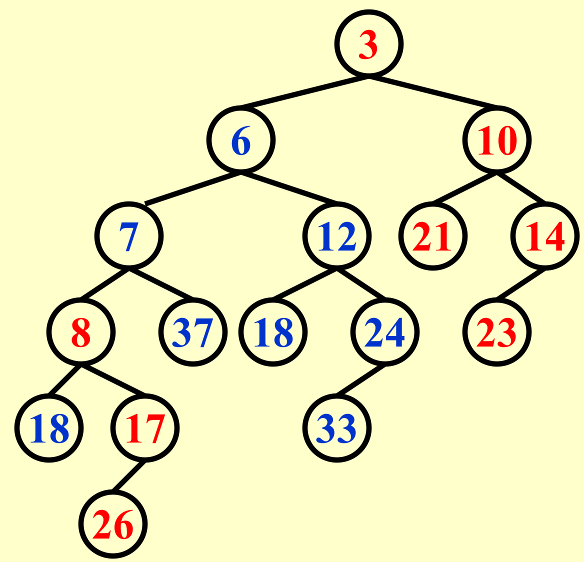
☞ **Merge (iterative version):**



H_1



H_2



Note:

☞ Skew heaps have the advantage that no extra space is required to maintain path lengths and no tests are required to determine when to swap children.

☞ It is an open problem to determine precisely the expected right path length of both leftist and skew heaps.

Amortized Analysis for Skew Heaps

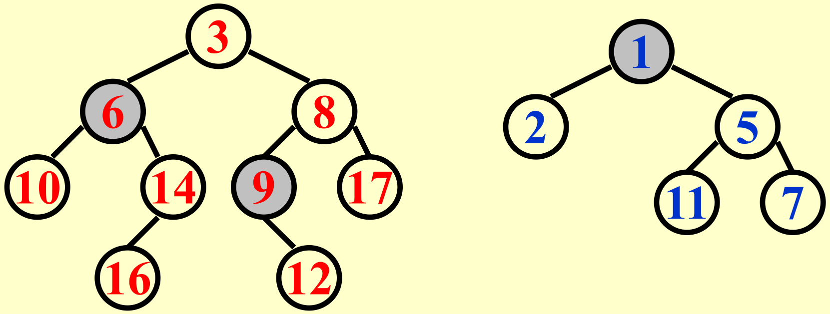
Insert & Delete are just Merge

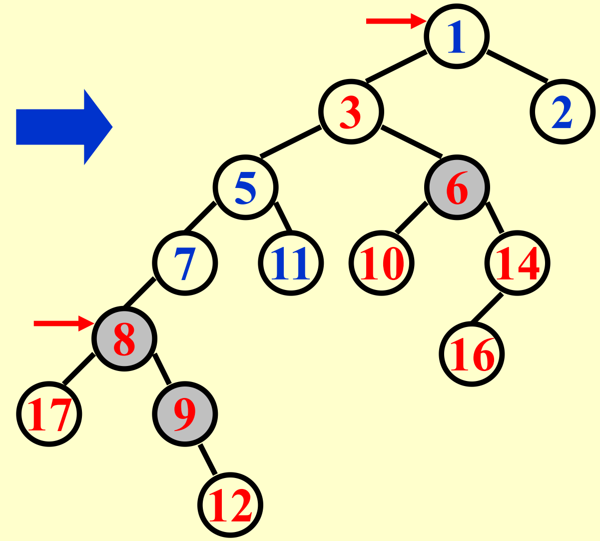
$T_{amortized} = O(\log N)$?

$D_i =$ **the root of the resulting tree**

$\Phi(D_i) =$ **number of *heavy* nodes**

【Definition】A node *p* is *heavy* if the number of descendants of *p*'s right subtree is at least half of the number of descendants of *p*, and *light* otherwise. Note that the number of descendants of a node includes the node itself.





The only nodes whose heavy/light status can change are nodes that are **initially on the right path**.

$H_i : l_i + h_i \ (i = 1, 2)$ ➡ $T_{worst} = l_1 + h_1 + l_2 + h_2$

Along the right path

Before merge: $\Phi_0 = h_1 + h_2 + h$ $\quad T_{amortized} = T_{worst} + \Phi_N - \Phi_0$

After merge: $\Phi_N \leq l_1 + l_2 + h$ $\quad \leq 2\,(l_1 + l_2)$

$l = O(\log N)$ ➡ $T_{amortized} = O(\log N)$

Reference:

Data Structure and Algorithm Analysis in C **(2nd Edition)：** **Ch.5，p.161-169； Ch.11，p.435-437；*M.A.Weiss著、陈越改编，人民邮件出版社，2005***