Willmore type inequalities in geodesic balls of hyperbolic space

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Outline

Mean curvature

Mean curvature type flow

Free boundary surface

First result: Convergence of the flow

Second result: Monotonicity of a Willmore type quantity

Proof: Monotonicity of a Willmore type quantity

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► The above formula is also known as the first variation of area

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- ▶ The second fundamental form is defined to be $\nabla \nu$, in components, $h_{ij} = \langle \bar{\nabla}_{e_i} \nu, e_j \rangle$
- ▶ The mean curvature is just the trace of h: $H = \sum_i \langle \nabla_{e_i} \nu, e_i \rangle$

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3. Stahl 96 mean curvature flow with free boundary

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- 2. Huisken-Ilmanen 01 Inverse mean curvature flow to prove a Penrose inequality; most importantly the Hawking mass

$$m_H(\Sigma) = |\Sigma|^{1/2} \left(1 - \frac{1}{16\pi} \int_{\Sigma} H^2\right)$$

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3. Neves 07, Wang-Hung 14 starting from convex hypersurface the IMCF does not converge. Converges in stronger conditions: principal curvatures $\kappa_i > 1$. The Penrose inequality asymptotically hyperbolic is still open; locally hyperbolic case is settled by Lee-Neves 13.

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- ▶ If the mean curvature of Σ is zero, we say that Σ is a free boundary minimal surface

Example: Critical catenoid

Put a large sphere centered at the center of the neck of a standard catenoid in R³;

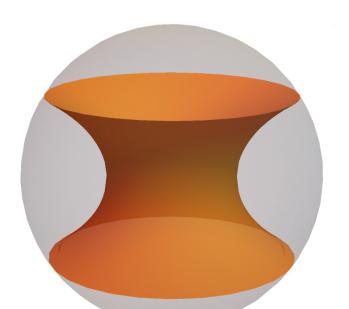
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- ► The piece inside the sphere is called critical catenoid.

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 Scheuer-Wang-Xia 22 Alexandrov-Fenchel type inequality which involves higher order mean curvature; Wang-Weng-Xia 22 capillary.

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- ► M be a free boundary convex surface inside B
- ▶ We are going to generalize Lambert-Scheuer 16, 17 result to M

Theorem: Convergence of the flow

Theorem Let M be a strictly convex, free boundary hypersurface in the ball B, then the inverse mean curvature flow M_t converges to a totally geodesic disk in finite time.

Monotonicity of a Willmore type quantity: Theorem

► Theorem (C. 22) Suppose that M is strictly convex, then $m_H(M)$ given by

$$m_H(M) = |M|^{\frac{2-n}{n}} \int_M (H^2 - n^2) + \Lambda |\partial M|$$

is monotone under IMCF with free boundary (assume for now strict convexity is preserved and that $|M_t| \leq \lambda$).

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- \triangleright λ volume of *n*-dimensional hyperbolic geodesic ball of radius ρ_0 (note dimension n here!) $\Lambda = 2 \coth \rho_0 \lambda^{(2-n)/n}$

Lower bound of the Willmore type quantity

► Theorem (C. 22) Assuming that the flow preserves strict convexity, and converges to a totally geodesic disk, then

$$|M|^{\frac{2-n}{n}}\int_M (H^2-n^2)+\Lambda|\partial M|\geqslant -n^2\lambda^{\frac{2}{n}}+\Lambda\omega_{n-1}\sinh^{n-1}\rho_0.$$

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- Maximal existence time: T^* largest time such that M_t is mean convex for all $0 < t < T^*$

Key lemma from convex geometry in spheres

(Makowski-Scheuer 15) If ∂M_T is weakly convex in \mathbb{S}^n , then it lies in an open hemisphere or it is the equator.

Idea

• ($\underline{\text{easy}}$) If ∂M_T is some equator, then using mean convexity of M_T , free boundary condition, maximum principle, M_T has to be a totally geodesic disk. (T being \bar{T} or T^* is OK)

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 - 1. Lower bound of the mean curvature H before \bar{T} (flow loses convexity)
 - 2. $\bar{T} = T^*$
 - 3. If the ∂M_t is not an equator, then the flow can be continued.
 - 4. Which means at maximal existence time, the flow M_t converges to a totally geodesic disk.

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4.
$$\partial_t h_{ij} = -\bar{R}(\partial_i, \nu, \nu, \partial_j) \frac{1}{H} + \frac{h_i^k h_{jk}}{H} - \nabla_i \nabla_j \frac{1}{H}$$

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5.
$$\partial_t H = -\Delta \frac{1}{H} - (\text{Ric}(\nu) + |A|^2) \frac{1}{H}$$

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- ► By Hessian decomposition

$$\Delta z^{\alpha} = nz^{\alpha} - H\nu^{\alpha}$$



$$\nabla_{\eta} \frac{1}{H} = \langle \nabla_{\eta} (\frac{1}{H} \nu), \nu \rangle \tag{1}$$

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- **•** Boundary derivative of z^0 : $\nabla_{\eta} \log z^0 = \tanh \rho_0$
- ▶ Boundary derivative of z^i : $\nabla_{\eta}z^i = \coth \rho_0 z^i$

Curvature estimates

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Boundary derivtives and then by maximum principle.

Height estimate

Theorem Let M be a strictly convex hypersurface, then $z^1 \geqslant \delta > 0$ for all M where the constant δ depends only on $\sup_M |A|$ and the distance of ∂M to some equator of $\mathbb{S}^n(\rho_0)$.

Comments The proof is long; and uses hyperbolic trignogeometry and convex geometry.

Lower bound of the mean curvature

Proposition Let M_t be the solution to the mean curvature flow with free boundary, if $\partial M_{\bar{T}}$ is positive distance from the equator, then

$$\sup_{M_t, t \in [0, \bar{T})} \frac{1}{H} \le c$$

where c depends only on M_0 and the distance of $\partial M_{\bar{T}}$ to the equator.

1.
$$f(q) = -\log(\Lambda - q)$$
, $q = \lambda z^1 + z^0$, $F(z) = -\log(\Lambda - (\lambda z^1 + z^0))$ with $0 < \Lambda < \frac{1}{\cosh \rho_0}$ and $\lambda < -1 - \frac{\cosh \rho_0}{\delta}$ where δ is the number in the heigth estimate.

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- \blacktriangleright the equality implies an bound on 1/H

Maximal existence time is also maximal convexity time

Theorem The strict convexity is preserved up to T^* . Observation If $\bar{T} < T^*$, then the smallest principal curvature κ_1 reaches zero when the flow M_t accross the time \bar{T}

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However, this cannot always be true; just pick a big α .

Proof

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▶ Then for large α , the supremum of ϕ would be decreasing which implies a bound on \tilde{H} contradicting the definition of $\bar{\mathcal{T}}$

Monotonicity of a Willmore type quantity: Theorem

Theorem (C. 22) Suppose that M is strictly convex, then $m_H(M)$ given by

$$m_H(M) = |M|^{\frac{2-n}{n}} \int_M (H^2 - n^2) + \Lambda |\partial M|$$

is monotone under IMCF with free boundary (assume for now strict convexity is preserved and that $|M_t| \leq \lambda$).

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▶ A comment: The definition of $m_H(M)$ depends the supporting hypersurface of the boundary. If ∂M lies on the horosphere, or an equidistant hypersurface, then m_H is different.

► Use the evolution equation

$$\begin{split} &\partial_t \int_{M_t} (H^2 - n^2) \sqrt{g} \\ &= \int_{M_t} (H^2 - n^2) \sqrt{g} + 2 \int_{M_t} H(-\Delta \frac{1}{H} - (-n + |A|^2) \frac{1}{H}) \sqrt{g}. \end{split}$$

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Integration on the Laplacian term

$$\begin{split} &-\int_{M_{t}} H\Delta \frac{1}{H} \\ &= -2\int_{\partial M_{t}} H\langle \nabla \frac{1}{H}, \eta \rangle + 2\int_{M_{t}} \langle \nabla H, \nabla \frac{1}{H} \rangle \\ &\leqslant -2\int_{\partial M_{t}} H\langle \nabla \frac{1}{H}, \eta \rangle \end{split}$$

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$$\begin{split} &\partial_t \int_{M_t} (H^2 - n^2) \sqrt{g} \\ &= \int_{M_t} (H^2 - n^2) \sqrt{g} + 2 \int_{M_t} H(-\Delta \frac{1}{H} - (-n + |A|^2) \frac{1}{H}) \sqrt{g}. \end{split}$$

Integration on the Laplacian term

$$\begin{split} &-\int_{M_{t}} H \Delta \frac{1}{H} \\ &= -2 \int_{\partial M_{t}} H \langle \nabla \frac{1}{H}, \eta \rangle + 2 \int_{M_{t}} \langle \nabla H, \nabla \frac{1}{H} \rangle \\ &\leqslant -2 \int_{\partial M_{t}} H \langle \nabla \frac{1}{H}, \eta \rangle \end{split}$$

 $\langle \nabla \frac{1}{H}, \eta \rangle = \coth \rho_0 / H$



► Use the evolution equation

$$\begin{split} &\partial_t \int_{M_t} (H^2 - n^2) \sqrt{g} \\ &= \int_{M_t} (H^2 - n^2) \sqrt{g} + 2 \int_{M_t} H(-\Delta \frac{1}{H} - (-n + |A|^2) \frac{1}{H}) \sqrt{g}. \end{split}$$

Integration on the Laplacian term

$$-\int_{M_{t}} H\Delta \frac{1}{H}$$

$$= -2\int_{\partial M_{t}} H\langle \nabla \frac{1}{H}, \eta \rangle + 2\int_{M_{t}} \langle \nabla H, \nabla \frac{1}{H} \rangle$$

$$\leq -2\int_{\partial M_{t}} H\langle \nabla \frac{1}{H}, \eta \rangle$$

$$|A|^2 \ge \frac{H^2}{R}$$
 (by diagonalize A)



Proof of monotonicity: adding a correction term

► So

$$\partial_t \int_{M_t} (H^2 - n^2) \leqslant rac{n-2}{n} \int_{M_t} (H^2 - n^2) - 2 \coth
ho_0 |\partial M_t|$$

Proof of monotonicity: adding a correction term

► So

$$\partial_t \int_{M_t} (H^2 - n^2) \leqslant \frac{n-2}{n} \int_{M_t} (H^2 - n^2) - 2 \coth
ho_0 |\partial M_t|$$

► Let
$$q(t) = |M_t|^{\frac{2-n}{n}} \int_{M_t} (H^2 - n^2) + \Lambda |\partial M_t|$$

$$q'(t) \le \Lambda \partial_t |\partial M_t| - 2 \coth
ho_0 |M|^{(2-n)/n} |\partial M_t|$$

$$q'(t) \le \Lambda \partial_t |\partial M_t| - 2 \coth \rho_0 |M|^{(2-n)/n} |\partial M_t|$$

▶
$$\partial_t |\partial M_t| = \int_{\partial M_t} \frac{H_{\partial M,\partial B}}{H} \le |\partial M_t|$$

$$q'(t) \le \Lambda \partial_t |\partial M_t| - 2 \coth \rho_0 |M|^{(2-n)/n} |\partial M_t|$$

▶
$$\partial_t |\partial M_t| = \int_{\partial M_t} \frac{H_{\partial M, \partial B}}{H} \le |\partial M_t|$$

$$\blacktriangleright H_{M,B} = H_{\partial M,\partial B} + A_M(\eta,\eta)$$

$$q'(t) \le \Lambda \partial_t |\partial M_t| - 2 \cosh \rho_0 |M|^{(2-n)/n} |\partial M_t|$$

▶
$$\partial_t |\partial M_t| = \int_{\partial M_t} \frac{H_{\partial M, \partial B}}{H} \le |\partial M_t|$$

$$\blacktriangleright H_{M,B} = H_{\partial M,\partial B} + A_M(\eta,\eta)$$

$$ightharpoonup |M| \le \lambda$$

$$q'(t) \le \Lambda \partial_t |\partial M_t| - 2 \coth \rho_0 |M|^{(2-n)/n} |\partial M_t|$$

$$lacksquare$$
 $\partial_t |\partial M_t| = \int_{\partial M_t} rac{H_{\partial M,\partial B}}{H} \leq |\partial M_t|$

$$\qquad \qquad H_{M,B} = H_{\partial M,\partial B} + A_M(\eta,\eta)$$

$$|M| \le \lambda$$

▶ So
$$q' \leq 0$$

Thank you

Thank you!