



# Tema 2: Planificación inteligente

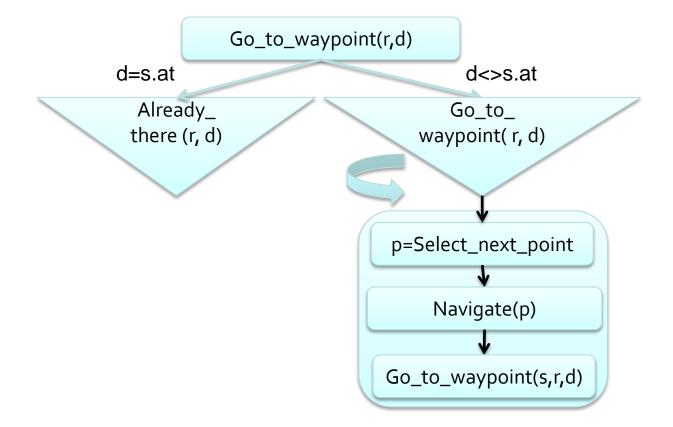
## Diseño del dominio rovers







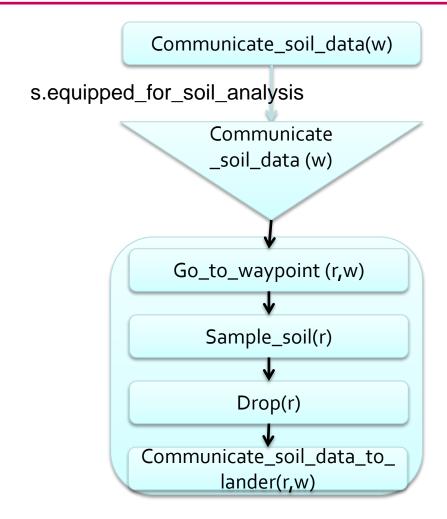
### Tarea go\_to\_waypoint







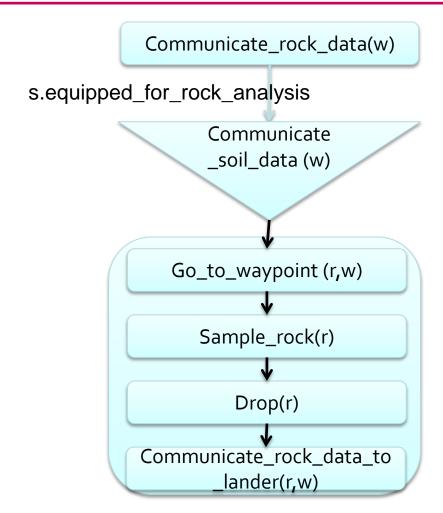
#### Tarea comunicate\_soil\_data







#### Tarea comunicate\_rock\_data







#### Tarea comunicate\_image\_data

