# MathDNN Homework 1

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# Problem 1

(a) Let 
$$X_i = \begin{bmatrix} x_{i1} \\ \vdots \\ x_{ip} \end{bmatrix}$$
 and  $\theta = \begin{bmatrix} \theta_1 \\ \vdots \\ \theta_p \end{bmatrix}$ , then for  $j = 1, \dots, p$ ,
$$\frac{\partial}{\partial \theta_j} l_i(\theta) = \frac{\partial}{\partial \theta_j} \left[ \frac{1}{2} (X_i^{\mathsf{T}} \theta - Y_i)^2 \right]$$

$$= \frac{\partial}{\partial \theta_j} \left[ \frac{1}{2} (x_{i1} \theta_1 + \dots + x_{ip} \theta_p - Y_i)^2 \right]$$

$$= (x_{i1} \theta_1 + \dots + x_{ip} \theta_p - Y_i) x_{ij}$$

$$= (X_i^{\mathsf{T}} \theta - Y_i) x_{ij}.$$

Therefore

$$\nabla_{\theta} l_{i}(\theta) = \begin{bmatrix} \frac{\partial}{\partial \theta_{1}} l_{i}(\theta) \\ \vdots \\ \frac{\partial}{\partial \theta_{p}} l_{i}(\theta) \end{bmatrix}$$

$$= \begin{bmatrix} (X_{i}^{\mathsf{T}} \theta - Y_{i}) x_{i1} \\ \vdots \\ (X_{i}^{\mathsf{T}} \theta - Y_{i}) x_{ip} \end{bmatrix} = (X_{i}^{\mathsf{T}} \theta - Y_{i}) \begin{bmatrix} x_{i1} \\ \vdots \\ x_{ip} \end{bmatrix}$$

$$= (X_{i}^{\mathsf{T}} \theta - Y_{i}) X_{i}.$$

(b) Let 
$$X_{i} = \begin{bmatrix} x_{i1} \\ \vdots \\ x_{ip} \end{bmatrix}$$
 and  $\theta = \begin{bmatrix} \theta_{1} \\ \vdots \\ \theta_{p} \end{bmatrix}$ , then for  $j = 1, \dots, p$ ,
$$\frac{\partial}{\partial \theta_{j}} \mathcal{L}(\theta) = \frac{\partial}{\partial \theta_{j}} \left[ \frac{1}{2} \| X\theta - Y \|^{2} \right]$$

$$= \frac{\partial}{\partial \theta_{j}} \left[ \frac{1}{2} \left\| \begin{matrix} X_{1}^{\mathsf{T}}\theta - Y_{1} \\ \vdots \\ X_{N}^{\mathsf{T}}\theta - Y_{N} \end{matrix} \right\|^{2} \right] = \frac{\partial}{\partial \theta_{j}} \left[ \sum_{i=1}^{N} \frac{1}{2} (X_{i}^{\mathsf{T}}\theta - Y_{i})^{2} \right] = \frac{\partial}{\partial \theta_{j}} \left[ \sum_{i=1}^{N} l_{i}(\theta) \right]$$

$$= \sum_{i=1}^{N} \frac{\partial}{\partial \theta_{i}} l_{i}(\theta) = \sum_{i=1}^{N} (X_{i}^{\mathsf{T}}\theta - Y_{i}) x_{ij}.$$

Therefore

$$\nabla_{\theta} \mathcal{L}(\theta) = \begin{bmatrix} \sum_{i=1}^{N} (X_{i}^{\mathsf{T}} \theta - Y_{i}) x_{i1} \\ \vdots \\ \sum_{i=1}^{N} (X_{i}^{\mathsf{T}} \theta - Y_{i}) x_{ip} \end{bmatrix}$$

$$= \begin{bmatrix} (X_{1}^{\mathsf{T}} \theta - Y_{1}) x_{11} + (X_{2}^{\mathsf{T}} \theta - Y_{2}) x_{21} + \dots + (X_{N}^{\mathsf{T}} \theta - Y_{N}) x_{N1} \\ \vdots \\ (X_{1}^{\mathsf{T}} \theta - Y_{1}) x_{1p} + (X_{2}^{\mathsf{T}} \theta - Y_{2}) x_{2p} + \dots + (X_{N}^{\mathsf{T}} \theta - Y_{N}) x_{Np} \end{bmatrix}$$

$$= \sum_{i=1}^{N} X_{i} (X_{i}^{\mathsf{T}} \theta - Y_{i}) = \sum_{i=1}^{N} (X^{\mathsf{T}})_{:,i} (X \theta - Y)_{i}$$

$$= X^{\mathsf{T}} (X \theta - Y).$$

#### Problem 2

Since  $f(\theta) = \theta^2/2$ , we can get  $f'(\theta) = \theta$  and the iteration equation can be written as

$$\theta^{k+1} = (1 - \alpha)\theta^k.$$

Thus the nth iteration gives

$$\theta^n = (1 - \alpha)\theta^{n-1} = \dots = (1 - \alpha)^n \theta^0.$$

Therefore if  $\alpha > 2$  and  $\theta^0 \neq 0$ ,  $\theta^n$  diverges since it is a geometric sequence where its ratio is less than -1.

#### Problem 3

Since  $f(\theta) = \frac{1}{2} \|X\theta - Y\|^2$ , we can get  $\nabla f(\theta) = X^{\intercal}(X\theta - Y)$  and the iteration equation can be written as

$$\theta^{k+1} = \theta^k - \alpha X^{\mathsf{T}} (X \theta^k - Y).$$

Assume  $X^\intercal X$  is invertible and let  $\theta^* = (X^\intercal X)^{-1} X^\intercal Y$ , then

$$\begin{split} \theta^{k+1} - \theta^* &= \theta^k - \alpha X^\intercal \big( X \theta^k - Y \big) - (X^\intercal X)^{-1} X^\intercal Y \\ &= \theta^k - \alpha X^\intercal X \theta^k + \alpha X^\intercal Y - (X^\intercal X)^{-1} X^\intercal Y \\ &= (I - \alpha X^\intercal X) \theta^k + (\alpha X^\intercal X - I) (X^\intercal X)^{-1} X^\intercal Y = (I - \alpha X^\intercal X) \theta^k + (\alpha X^\intercal X - I) \theta^* \\ &= (I - \alpha X^\intercal X) (\theta^k - \theta^*) \end{split}$$

where  $I \in \mathbb{R}^{p \times p}$  is an identity matrix. Thus the *n*th iteration gives

$$\theta^n - \theta^* = (I - \alpha X^{\mathsf{T}} X) (\theta^{n-1} - \theta^*) = \dots = (I - \alpha X^{\mathsf{T}} X)^n (\theta^0 - \theta^*).$$

Since  $X^{\intercal}X$  is a symmetric matrix and a positive matrix, it has p real positive eigenvalues and is diagonalizable by them. Let  $\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_p \geq 0$  the eigenvalues and M the matrix with the eigenvectors as its columns, then

$$M^{-1}X^{\mathsf{T}}XM = \operatorname{diag}(\lambda_1, \cdots, \lambda_p), \ X^{\mathsf{T}}X \sim \operatorname{diag}(\lambda_1, \cdots, \lambda_p)$$

and gradually

$$\begin{split} I - \alpha X^\intercal X &= I - \alpha M \mathrm{diag}(\lambda_1, \cdots, \lambda_p) M^{-1} \\ &= M I M^{-1} - M (\alpha \, \mathrm{diag}(\lambda_1, \cdots, \lambda_p)) M^{-1} \\ &= M (I - \alpha \, \mathrm{diag}(\lambda_1, \cdots, \lambda_p)) M^1 = M \mathrm{diag}(1 - \alpha \lambda_1, \cdots, 1 - \alpha \lambda_p) M^{-1} \end{split}$$

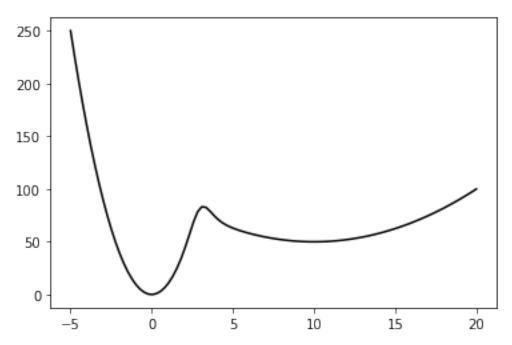
so  $I - \alpha X^{\intercal}X \sim \text{diag}(1 - \alpha \lambda_1, \dots, 1 - \alpha \lambda_p)$ . Therefore

$$(I - \alpha X^{\mathsf{T}} X)^n = M \operatorname{diag}(1 - \alpha \lambda_1, \cdots, 1 - \alpha \lambda_p)^n M^{-1}$$
$$= M \operatorname{diag}((1 - \alpha \lambda_1)^n, \cdots, (1 - \alpha \lambda_p)^n) M^{-1}.$$

If  $\alpha > 2/\rho(X^{\mathsf{T}}X)$ , we can obtain  $1 - \alpha\lambda_1 < -1$  since  $\rho(X^TX) = \lambda_1 \ge 0$ . Therefore  $(1 - \alpha\lambda_1)^n$  diverges, and consequently  $(I - \alpha X^{\mathsf{T}}X)^n$ ,  $\theta^n - \theta^*$ , and  $\theta^n$  also diverge.

# Problem 4

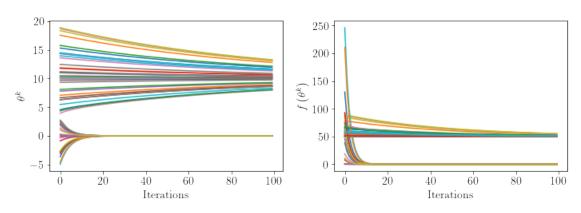
```
[1]: import numpy as np
     import matplotlib.pyplot as plt
     import random as rd
     %matplotlib inline
     np.seterr(invalid='ignore', over='ignore') # suppress warning caused by division by_
[1]: {'divide': 'warn', 'over': 'warn', 'under': 'ignore', 'invalid': 'warn'}
[2]: def f(x):
         return 1/(1 + np.exp(3*(x-3))) * 10 * x**2 + 1 / (1 + np.exp(-3*(x-3))) * (0.
      5*(x-10)**2 + 50
     def fprime(x):
         return 1 / (1 + np.exp((-3)*(x-3))) * (x-10) + 1/(1 + np.exp(3*(x-3))) * 20 * x +__
      \rightarrow (3* np.exp(9))/(np.exp(9-1.5*x) + np.exp(1.5*x))**2 * ((0.5*(x-10)**2 + 50) - 10 *_
      <u>→</u>x**2)
[3]: x = np.linspace(-5,20,100)
     plt.plot(x,f(x), 'k')
     plt.show()
```



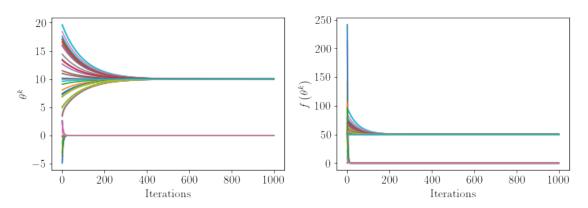
```
[4]: def GD(alpha, start_x, iteration_count):
         x = [start_x]
         y = [f(start_x)]
         for _ in range(iteration_count - 1):
             x.append(x[-1] - alpha * fprime(x[-1]))
             y.append(f(x[-1]))
         return x, y
     def GD_plot_alpha(alpha, sample_count, iteration_count):
         plt.rc('text', usetex=True)
         plt.rc('font', family='serif')
         plt.rc('font', size = 14)
         plt.rcParams["figure.figsize"] = [10, 4]
         plt.rcParams["figure.autolayout"] = True
         fig, axs = plt.subplots(1, 2)
         fig.suptitle('Learning Rate = {alpha}'.format(alpha=alpha))
         for _ in range(sample_count):
             x, y = GD(alpha, rd.uniform(-5, 20), iteration_count)
             axs[0].plot(list(range(iteration_count)), x)
             axs[0].set(xlabel='Iterations', ylabel=r'$\theta^k$')
             axs[1].plot(list(range(iteration_count)), y)
             axs[1].set(xlabel='Iterations', ylabel=r'$f\left(\theta^k\right)$')
         plt.show()
```

In the case of  $\alpha = 0.01$ , starting points that are relatively large converge to the wide minimum, and others converge to the sharp minimum.

Learning Rate = 0.01

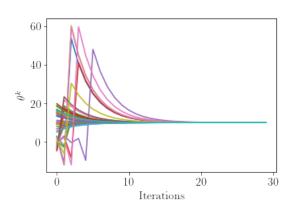


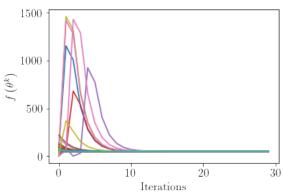
# Learning Rate = 0.01



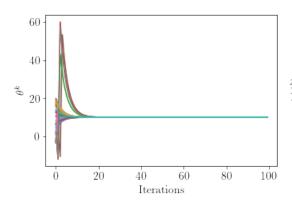
In the case of  $\alpha=0.3$ , all cases converge to the wide minimum.

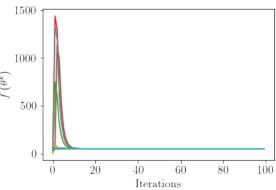
#### Learning Rate = 0.3





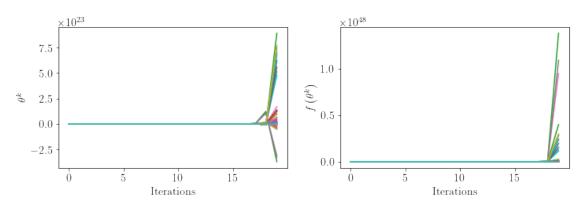
### Learning Rate = 0.3



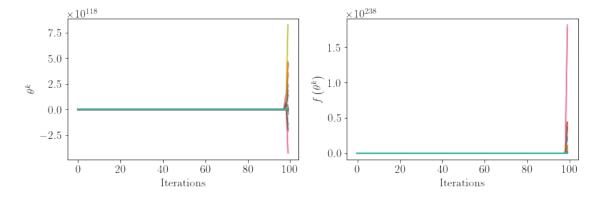


In the case of  $\alpha = 4$ , most cases do not converge.

#### Learning Rate = 4



#### Learning Rate = 4



#### Problem 5

```
[8]: import numpy as np
 [9]: class Convolution1d:
          def __init__(self, filt) :
              self.__filt = filt
              self.__r = filt.size
              self.T = TransposedConvolution1d(self.__filt)
          def __matmul__(self, vector) :
              r, n = self.__r, vector.size
              return np.asarray([sum([self.__filt[v] * vector[h + v] for v in range(r)]) for_
       \rightarrowh in range(n - r + 1)])
      class TransposedConvolution1d :
          Transpose of 1-dimensional convolution operator used for the
          transpose-convolution operation A.T@(...)
          def __init__(self, filt) :
              self.__filt = filt
              self.__r = filt.size
          def __matmul__(self, vector) :
              r = self.__r
              n = vector.size + r - 1
              return np.asarray([sum([self.__filt[v] * vector[h - v] for v in range(max(0, h_
       \rightarrow n + r), min(r, h + 1))]) for h in range(n)])
[10]: def huber_loss(x) :
          return np.sum( (1/2)*(x**2)*(np.abs(x)<=1) + (np.sign(x)*x-1/2)*(np.abs(x)>1) )
      def huber_grad(x) :
          return x*(np.abs(x) \le 1) + np.sign(x)*(np.abs(x) > 1)
[11]: r, n, lam = 3, 20, 0.1
      np.random.seed(0)
      k = np.random.randn(r)
      b = np.random.randn(n-r+1)
      A = Convolution1d(k)
      x = np.zeros(n)
      alpha = 0.01
      for \underline{\quad} in range(100):
          x = x - alpha*(A.T@(huber_grad(A@x-b))+lam*x)
      print(huber_loss(A@x-b)+0.5*lam*np.linalg.norm(x)**2)
```