## 1 Simulation Graph

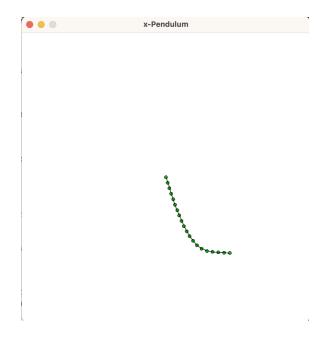


Figure 1: Simulation graph of x-Pendulum (x=20)

## 2 Graphs

All required graphs are shown on the next page in Fig 2.

## 3 Trend Observation

In Fig.2(a), simulation substep=1, the relaxation steps=100 and 10 show more stability in energy converse and relaxation step=100 is slightly higher in value, by conserving half of the energy after 30s.

In Fig.2(b), simulation substep=10, they all show some stability in energy converse and almost have the same performance, conserve about 700J after 30s.

In Fig.2(c), simulation substep=100, they all show some stability in energy converse and relaxation step=1 is slightly higher in value, it could conserve 100J more than relaxation step=100. The best result could converse about 800J after 30s.

In Fig.2(d), relaxation step=10, the simulation substeps=100 and 10 show more stability in energy converse and reaction step=100 is slightly higher in value.

From those graphs, we can tell that **simulation substep** is really important, when more substeps are used, the result is largely improved. As for the relaxation step, there is not a large difference when the substep is in a rational value.

In Fig.2(e), compared with the length error with simulation substeps=1, the relaxation steps=100 and 10 show less error in the changing of the length of the rope. Relaxation step=100 is slightly lower in value.

In the simulation, it is easy to observe that the relaxation step=1 always strength the rope for a longer distance between the base node and the first node.

## 4 Best results

By plotting all the results in Fig.3(b), I discovered that the **purple** line has the highest energy conservation value and remains stable. At the same time, the length error is small. The best result is **Relaxation\_steps=1**, **Simulation\_substeps=100**.

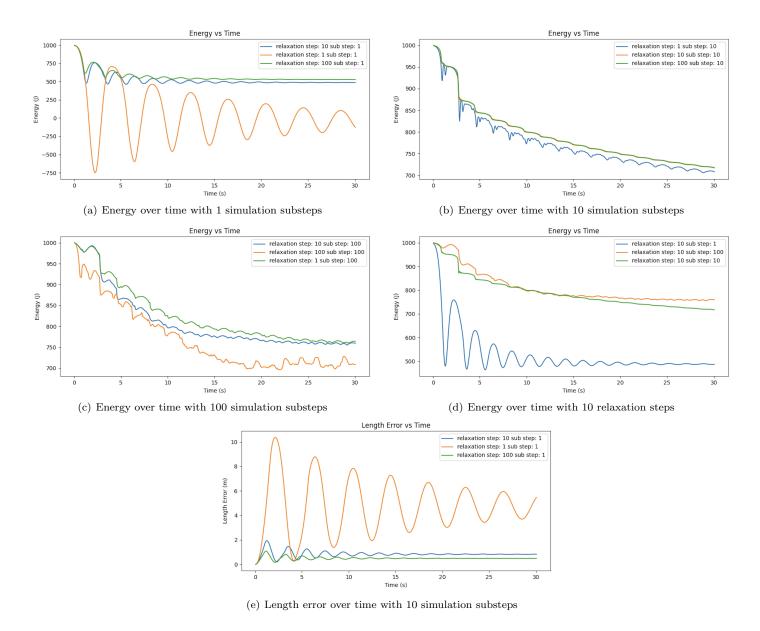


Figure 2: Comparison Graph of Energy / Length Error Over Time

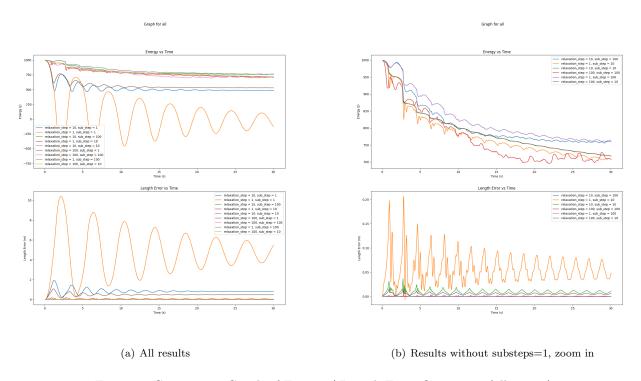


Figure 3: Comparison Graph of Energy / Length Error Over Time (all in one)