

# Computational Soft Matter and Biophysics

We start at 10:00

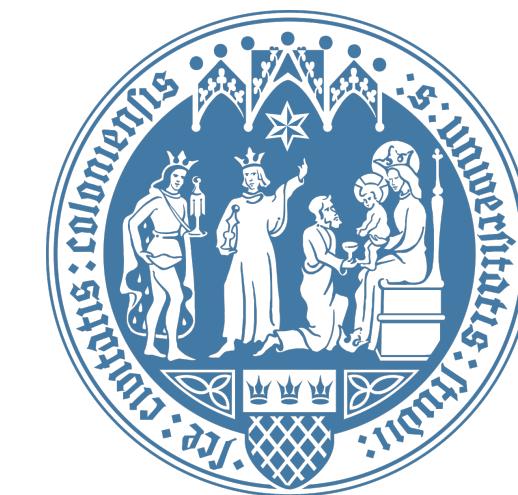
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Forschungszentrum Jülich

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Gerhard Gompper, 4<sup>th</sup> July 2023





## 4. Mesoscale Simulation Techniques for Hydrodynamics

### 4.1.) Introduction

Describe behavior of fluids on length scales around  $10 \text{ nm}$  to  $10 \mu\text{m}$

Idea: Coarse grain microscopic



description but respect  
conservation laws:

- mass
- momentum
- energy

Hydrodyn. (Navier - Stokes)  
at large length scales



Several methods developed in  
last 20 years:

- Lattice Boltzmann (LB)
- Dissipative Particle Dynamics (DPD)
- Multiparticle Collision Dynamics (MPC)



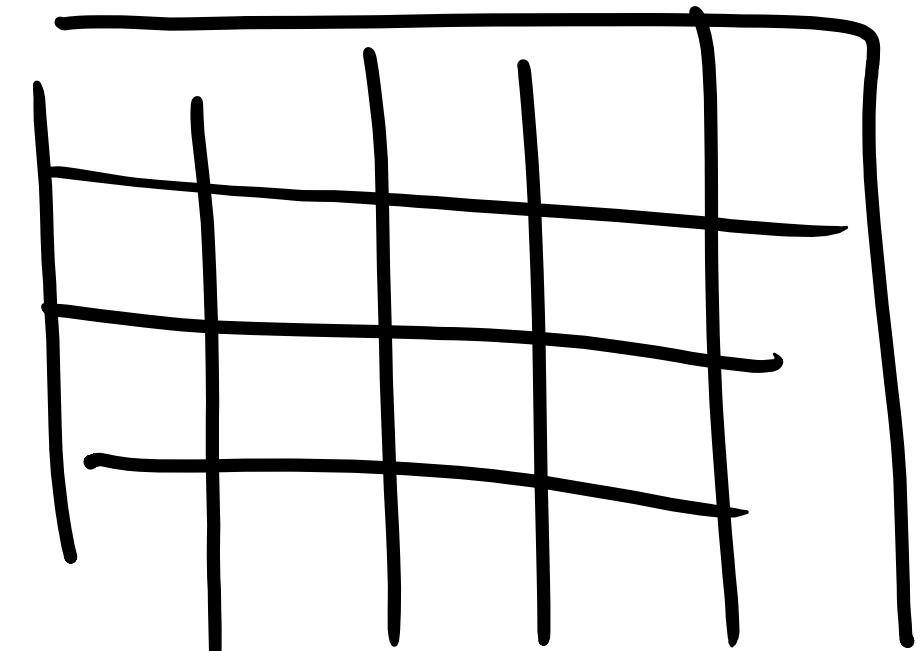
DPD: Mol. Dyn. ⊕ Friction (velocity-dep. force) ⊕ Random noise with fluctuation-dissipation theorem

MPC: Point particles: streaming (no interact.)

⊕ collisions: - sorting into boxes

- all particles in a box  
"collide"

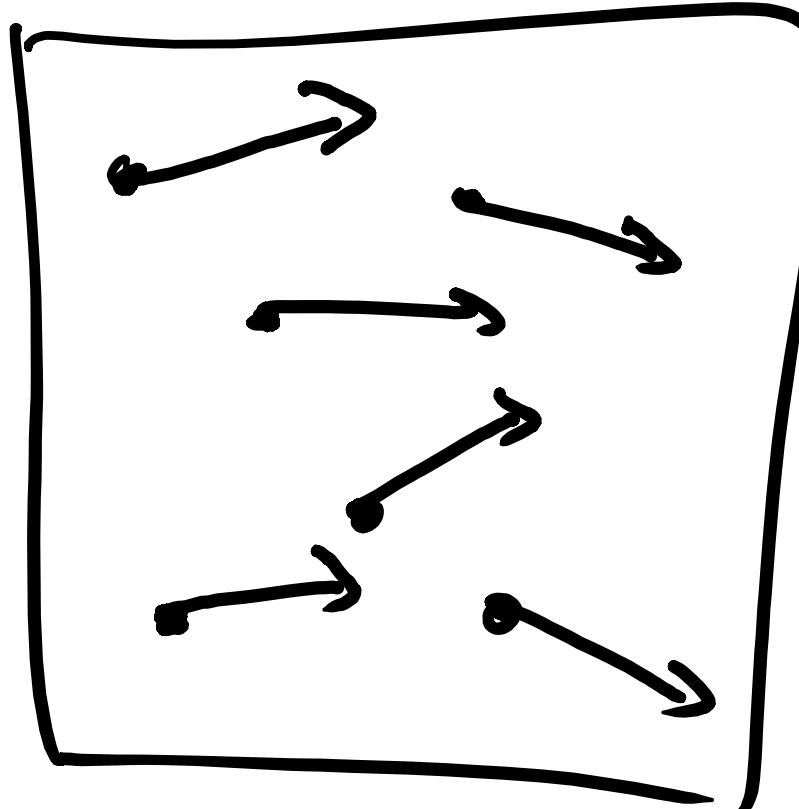
free step Δ



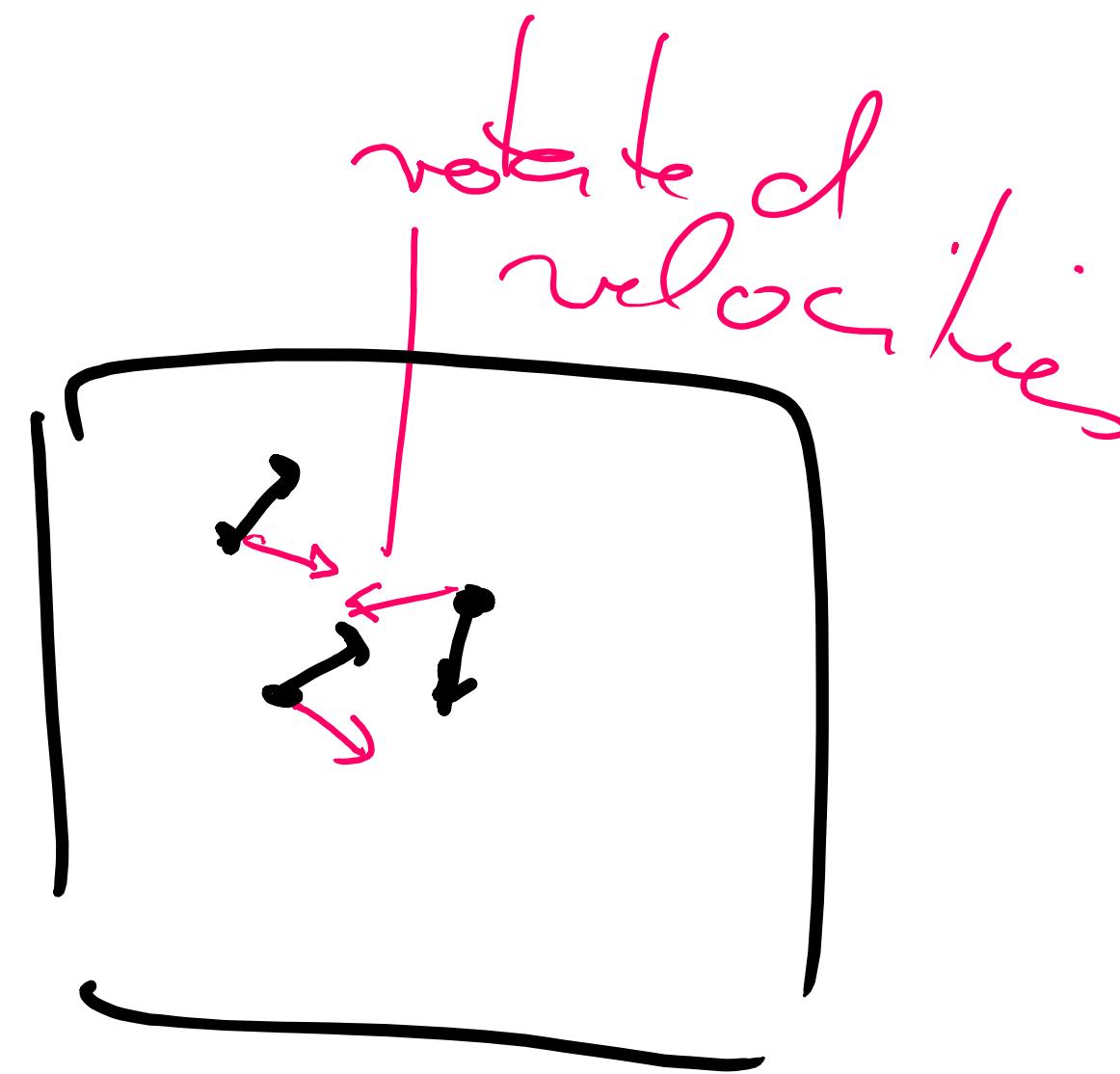


## MPC-collisions:

(i) subtract Center-of-mass velocity



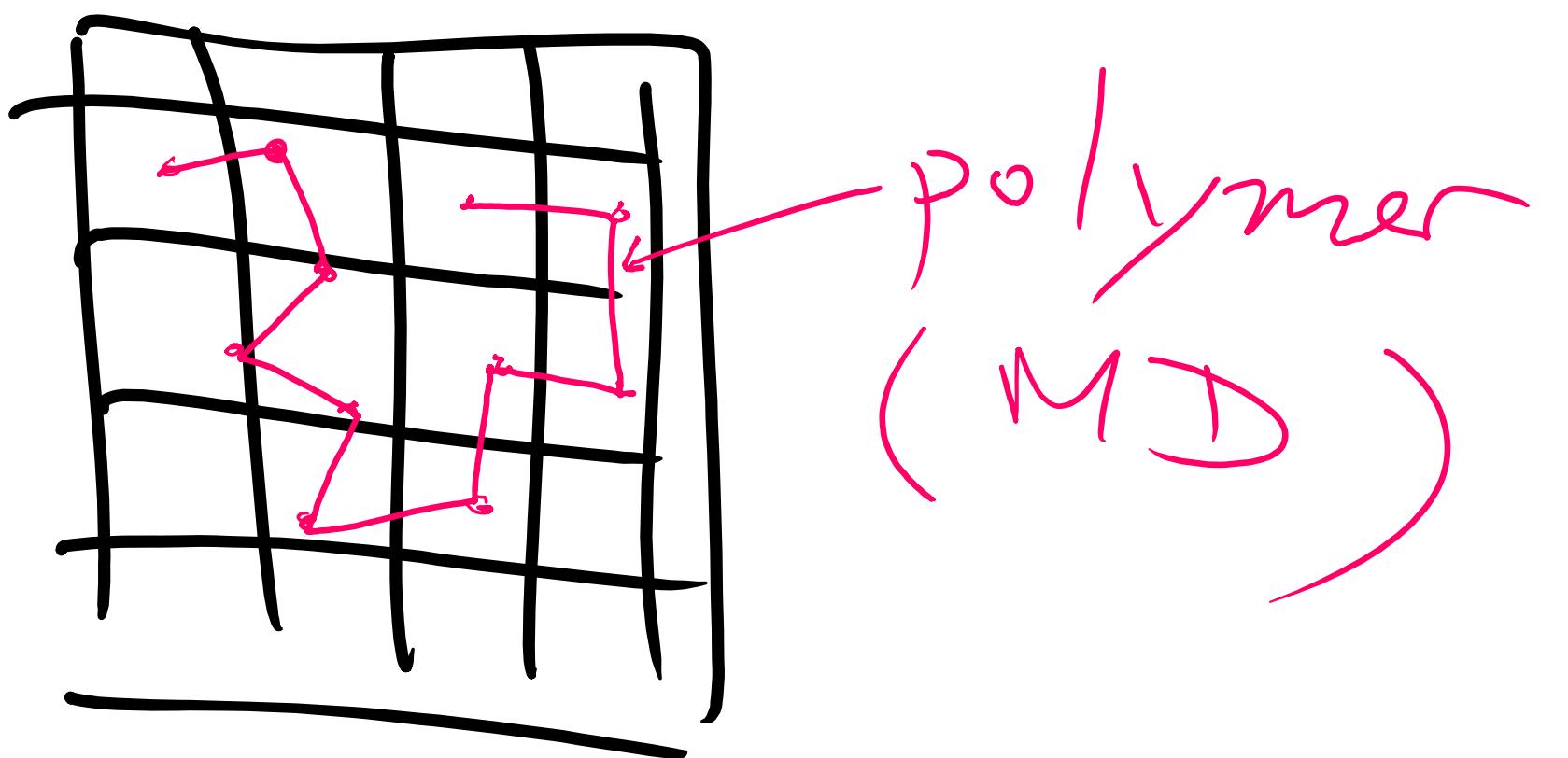
(ii) rotate all relative velocities by same angle  $\alpha$



(iii) add again previous CM velocity  
→ guarantees momentum conservation

Straightforward to include particles in fluid

Example: Polymer  
just include monomers  
in collision step



## 4.2. Lattice Boltzmann Method

### 4.2.1) Boltzmann Equation

Basic variable in BE is distribution function

$$f(\underline{r}, \underline{v}, t) d^3r d^3v$$

which is number of molecules in  $d^3r$  and  $d^3v$   
with position  $\underline{r}$  and velocity  $\underline{v}$



Without collisions, particles move  
ballistically

$$f(\underline{r} + \underline{v} \delta t, \underline{v} + \frac{\underline{F}}{m} \delta t, t + \delta t) d^3 r d^3 v =$$
$$f(\underline{r}, \underline{v}, t) d^3 r d^3 v + \left( \frac{\partial f}{\partial t} \right)_{\text{coll}} \delta t d^3 r d^3 v$$

With collisions



Expand both sides to leading order in  $\delta t$

$$\left( \frac{\partial}{\partial t} + \underline{v} \cdot \nabla_{\underline{r}} + \frac{\underline{\tau}}{m} \nabla_{\underline{v}} \right) f(\underline{r}, \underline{v}, t) = \left( \frac{\partial f}{\partial t} \right)_{\text{coll}}$$

Boltzmann equation

Only makes sense with explicit definition  
of collision term.



Conservation laws:

Consider observable  $X(\underline{r}, \underline{v})$ , for which under collision  $\{\underline{v}_1, \underline{v}_2\} \rightarrow \{\underline{v}'_1, \underline{v}'_2\}$  satisfies

$$X_1 + X_2 = X'_1 + X'_2 \quad (\text{i.e. conserved})$$

This implies:

$$\boxed{\int d^3v X(\underline{r}, \underline{v}) \cdot \left( \frac{\partial f}{\partial t} \right)_{\text{coll}} = 0}$$



This implies for BE:

$$\int d^3v X(T, v) \left( \frac{\partial}{\partial t} + \underline{v} \cdot \underline{\nabla}_r + \frac{1}{m} \underline{T} \cdot \underline{\nabla}_v \right) f = 0$$

Partial integration

$$\begin{aligned} & \frac{\partial}{\partial t} \int d^3v X f + \frac{\partial}{\partial r_\alpha} \int d^3v X v_\alpha f - \int d^3v \frac{\partial X}{\partial r_\alpha} v_\alpha f \\ & + \frac{1}{m} \int d^3v \frac{\partial}{\partial v_\alpha} (X T_\alpha f) - \frac{1}{m} \int d^3v \frac{\partial X}{\partial v_\alpha} T_\alpha f \end{aligned}$$

$\circlearrowleft$



$$-\frac{1}{m} \int d^3 \mathbf{r} \times \frac{\partial \mathbf{F}_\alpha}{\partial v_\alpha} f = 0$$

0 (for velocity-  
indep. forces)

Define average

$$\langle A \rangle = \frac{\int d^3 r A f}{\int d^3 r f} = \frac{1}{n} \int d^3 r A \rho$$

particle density

# Resul.1: conservation law



$$\left[ \frac{\partial}{\partial t} \bar{m} \langle X \rangle + \frac{\partial}{\partial r_\alpha} \left( \bar{m} \langle v_\alpha X \rangle \right) - \bar{m} \left\langle v_\alpha \frac{\partial X}{\partial r_\alpha} \right\rangle \right. \\ \left. - \frac{\bar{m}}{\bar{m}} \left\langle F_\alpha \frac{\partial X}{\partial v_\alpha} \right\rangle \right] = 0$$

(1)  $X_m : \text{mass conservation}$

$$\frac{\partial}{\partial t} (m \cdot n) + \frac{\partial}{\partial r_\alpha} (m \cdot n \langle v_\alpha \rangle) = 0$$

$$\rightsquigarrow \frac{\partial}{\partial t} s + \nabla \cdot (s \underline{u}) = 0$$

with mass density  $s = m \cdot n$

and velocity  $\underline{u} = \langle \underline{v} \rangle$



(ii)  $X = m v_\alpha$  momentum conservation

$$\frac{\partial}{\partial t} S(v_\alpha) + \frac{\partial}{\partial r_\beta} S(v_\alpha v_\beta) - \frac{1}{m} g F_\alpha = 0$$

Use

$$\langle v_\alpha v_\beta \rangle = \langle (v_\alpha - u_\alpha)(v_\beta - u_\beta) \rangle + u_\alpha u_\beta$$

Proseuse tensor:

$$P_{\alpha\beta} = g \langle (v_\alpha - u_\alpha)(v_\beta - u_\beta) \rangle$$

gives

$$\left( \frac{\partial}{\partial t} + u_p \frac{\partial}{\partial r_p} \right) u_\alpha = \frac{1}{m} F_\alpha - \frac{1}{S} \frac{\partial}{\partial r_p} P_{\alpha\beta}$$

"Navier-Stokes-equation"

$$(-\gamma P^2 u_\alpha)$$

## 4.2.2.) Boltzmann - equation on a lattice

Discretize time

$$t \in \{0, \delta t, 2\delta t, \dots\}$$

and space

$$\underline{\Delta} = \sum_i n_i \underline{e}_i; \quad \text{with lattice vectors } \underline{e}_i;$$

and relaxes:

$$\Sigma \cdot \delta t \in \{0, \underline{e}_i, -\underline{e}_i\} \equiv \{\underline{e}_i\}$$

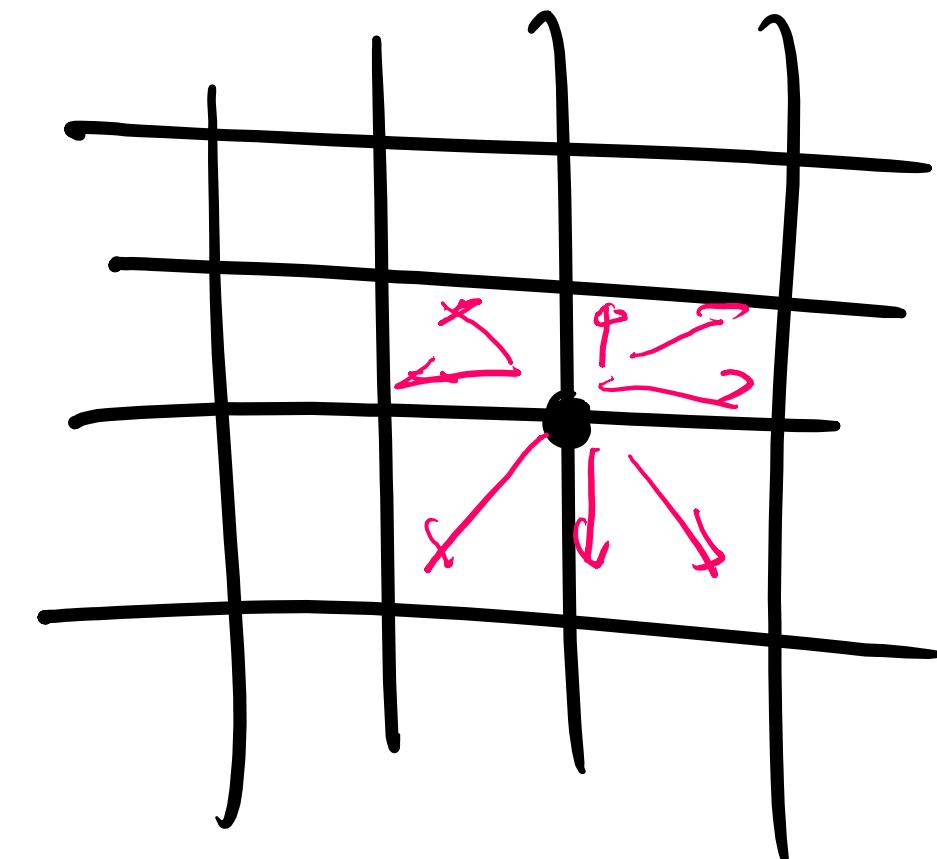


in 2dim: ideal triangular lattice,  
(isotropy.)

can also use square lattice

also diagonal vectors  
required

( $\rightarrow$  3dim  $\rightarrow$  D19 lattice)



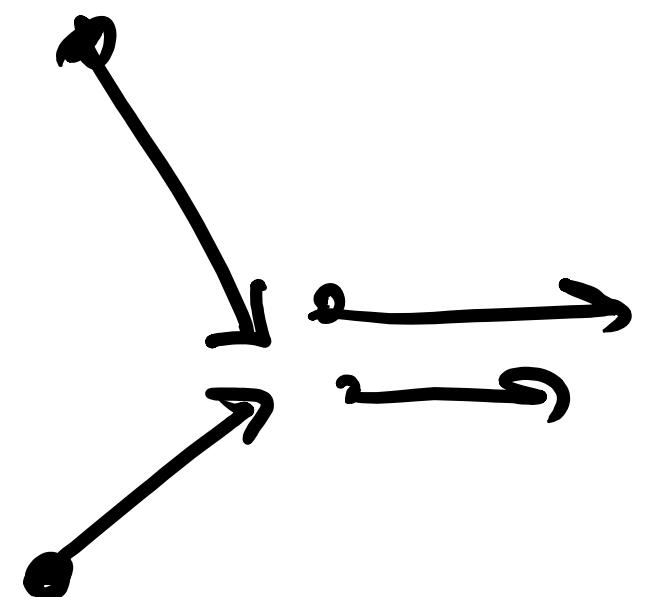
velocities.

Implies:  $A(x, y, t) \rightarrow A_i(\underline{r}_n, t)$   
 $i = 1, \dots, 9$

Discretized Boltzmann equation:

$$f_i(\varepsilon_n + e_i, t + \delta t) - f_i(\varepsilon_n, t) = \left( \frac{\partial}{\partial t} \right)_{\text{coll}} f_i \delta t$$

For dilute gases: Calculation of collision term from 2-particle collisions



For fluids: microscopic calculation  
not possible



Relaxation ansatz:

$$\left(\frac{\partial f}{\partial t}\right)_{\text{coll}} \delta t \doteq -\frac{1}{2} (f_i - f_i^{\text{eq}})$$

so hat

$$f_i(r + e_i, t + \delta t) - f_i(r, t) = -\frac{1}{2} [f_i(r, t) - f_i^{\text{eq}}(r, t)]$$

still needs to  
be determined

For conserved observables, collision integral has to vanish

$$\sum_i \chi_i(\underline{r}) [f_i(\underline{r}, t) - f_i^{eq}(\underline{r}, t)] \equiv 0$$

Thus

$$g = \sum_i f_i^{eq}$$

$$g_{\underline{U}} = \sum_i e_i f_i^{eq}$$

$$\begin{aligned} g u_\alpha u_\beta + p_\alpha p_\beta &= \\ &= \sum_i e_{i\alpha} e_{i\beta} f_i^{eq} \end{aligned}$$

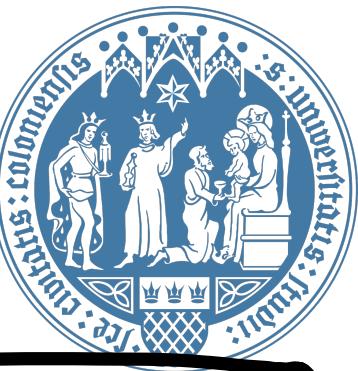
Additional requirement: rotational invariance

plus: expansion for small velocities  $\underline{u}$  to  
2<sup>nd</sup> order

$$f_0^{eq} = A^{(0)} + C^{(0)} \underline{u}^2$$

$$f_i^{eq} = A^{(1)}_{\alpha\beta} e_{i\alpha} e_{i\beta} + B^{(1)} e_i \cdot \underline{u} + C^{(1)} \underline{u}^2 + D^{(1)} (e_i \cdot \underline{u})^2$$

Set of eq. can be solved generally



$$f_0^{eq} = g - \frac{3}{4}(P_{xx} + P_{yy}) - \frac{2}{3}gu^2$$

$$f_i^{eq} = A_{\alpha\beta}^{(1)} e_{i\alpha} e_{i\beta} + \frac{1}{3}g e_i u - \frac{1}{6}gu^2 + \frac{1}{2}g(e_i u)^2$$

$$\text{for } |e_i| = 1$$

$$\text{with } A_{\alpha\beta}^{(1)} = \frac{1}{2}P_{\alpha\beta} - \frac{1}{8}(P_{xx} + P_{yy})S_{\alpha\beta}$$



Finally: Pressure tensor from thermodyn.  
of given system  
(properties of fluid enter here)

viscosity, compressibility, ...

$$\partial_\beta P_{\alpha\beta} = g \frac{\partial}{\partial x} \left( \frac{g F}{Sg} \right) = g \partial_\alpha \mu$$

free energy

chemical potential



# Boundaries and boundary conditions:

