

AI2619 Digital Signal and Image Processing

Written Assignment 4

Xiangyuan Xue (521030910387)

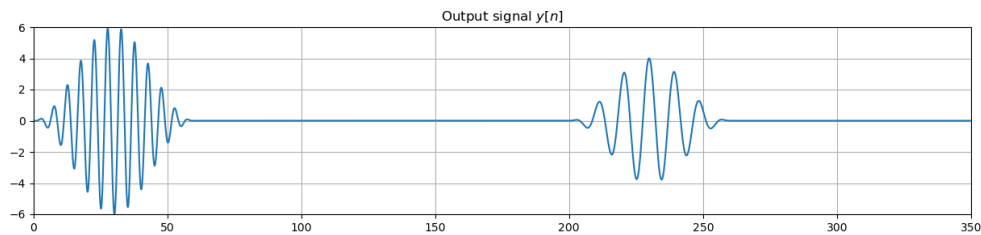
1. Divide $x[n]$ into 3 wave packets

$$x_1[n] = x[n] \cdot (u[n] - u[n - 60])$$

$$x_2[n] = x[n] \cdot (u[n - 60] - u[n - 120])$$

$$x_3[n] = x[n] \cdot (u[n - 120] - u[n - 180])$$

which corresponds to 3 frequencies in $|X(e^{j\omega})|$. According to the magnitude response $|H(e^{j\omega})|$, the wave packets are approximately scaled by 4, 6 and 0 respectively. According to the phase response $\angle[H(e^{j\omega})]$, the sinoids are approximately biased by -50° , -100° and -100° respectively. According to the group delay response $\text{grd}[H(e^{j\omega})]$, the wave packets are approximately shifted by 140, 0 and 0 respectively.



Output signal $y[n]$ is roughly sketched in the figure above, where the parameters are estimated.

2. (a) By definition of impulse response

$$H(z) = \frac{Y(z)}{X(z)} = \frac{1 - z^{-1}}{1 - \frac{5}{4}z^{-1} - \frac{3}{2}z^{-2}}$$

which yields

$$Y(z) - \frac{5}{4}z^{-1}Y(z) - \frac{3}{2}z^{-2}Y(z) = X(z) - z^{-1}X(z)$$

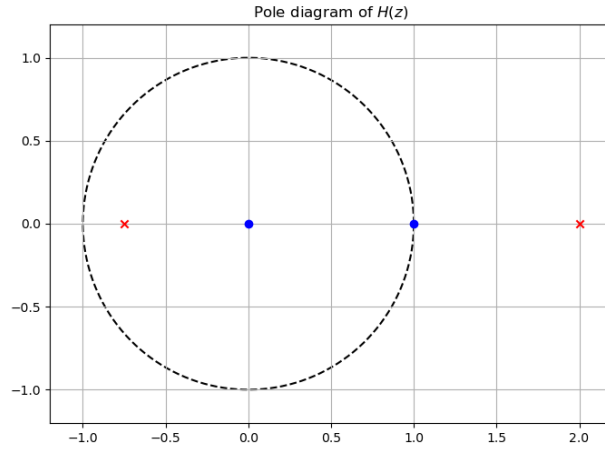
Therefore, the difference equation is

$$y[n] - \frac{5}{4}y[n-1] - \frac{3}{2}y[n-2] = x[n] - x[n-1]$$

- (b) Reformulate the function as

$$H(z) = \frac{z(z-1)}{(z-2)(z+\frac{3}{4})}$$

The poles and zeros are shown in the figure below.



Since $\omega = \frac{\pi}{2}$, we have

$$H(e^{j\omega}) = H(z) \big|_{z=e^{j\frac{\pi}{2}}} = \frac{j(j-1)}{(j-2)(j+\frac{3}{4})} = \frac{12}{25} + j\frac{4}{25}$$

which yields

$$\begin{aligned} |H(e^{j\omega})| &= \frac{4\sqrt{10}}{25} \\ \angle [H(e^{j\omega})] &= \arctan \frac{1}{3} \end{aligned}$$

Hence, the output is $y[n] = A \cos(\omega n + \phi)$, where $A = \frac{4\sqrt{10}}{25}$ and $\phi = \arctan \frac{1}{3}$.

3. (a) The phase response is

$$\angle [H_a(e^{j\omega})] = -\arctan \frac{b \sin \omega}{a + b \cos \omega}$$

The group delay is

$$\text{grd} [H_a(e^{j\omega})] = -\frac{d}{d\omega} \{ \angle [H_a(e^{j\omega})] \} = \frac{b(a \cos \omega + b)}{a^2 + b^2 + 2ab \cos \omega}$$

(b) The phase response is

$$\angle [H_b(e^{j\omega})] = \arctan \frac{c \sin \omega}{1 + c \cos \omega}$$

The group delay is

$$\text{grd} [H_b(e^{j\omega})] = -\frac{d}{d\omega} \{ \angle [H_b(e^{j\omega})] \} = -\frac{c(\cos \omega + c)}{1 + c^2 + 2c \cos \omega}$$

(c) The phase response is

$$\angle [H_c(e^{j\omega})] = -\arctan \frac{b \sin \omega}{a + b \cos \omega} + \arctan \frac{c \sin \omega}{1 + c \cos \omega}$$

The group delay is

$$\text{grd} [H_c(e^{j\omega})] = -\frac{d}{d\omega} \{ \angle [H_c(e^{j\omega})] \} = \frac{b(a \cos \omega + b)}{a^2 + b^2 + 2ab \cos \omega} - \frac{c(\cos \omega + c)}{1 + c^2 + 2c \cos \omega}$$

(d) The phase response is

$$\angle [H_d(e^{j\omega})] = \arctan \frac{c \sin \omega}{1 + c \cos \omega} + \arctan \frac{d \sin \omega}{1 + d \cos \omega}$$

The group delay is

$$\text{grd} [H_d(e^{j\omega})] = -\frac{d}{d\omega} \{ \angle [H_d(e^{j\omega})] \} = -\frac{c(\cos \omega + c)}{1 + c^2 + 2c \cos \omega} - \frac{d(\cos \omega + d)}{1 + d^2 + 2d \cos \omega}$$

4. According to the pole diagram of $H(z)$, we have

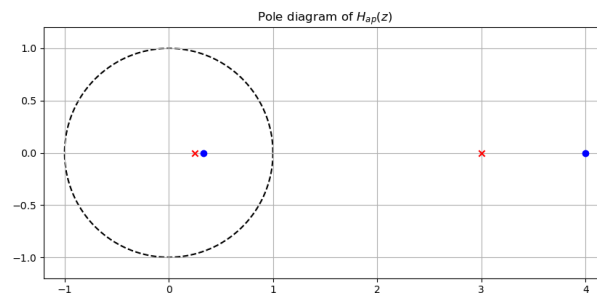
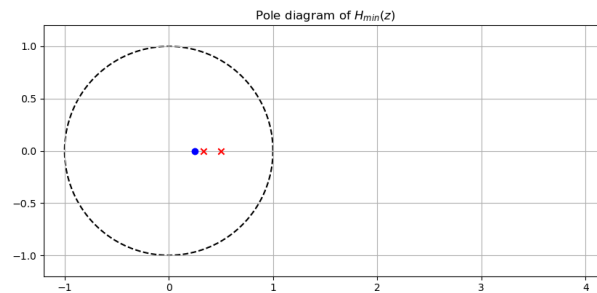
$$H(z) = \frac{z - 4}{(z - \frac{1}{2})(z - 3)} = \frac{(z - \frac{1}{3})(z - 4)}{(z - \frac{1}{4})(z - 3)} \cdot \frac{z - \frac{1}{4}}{(z - \frac{1}{3})(z - \frac{1}{2})}$$

which yields

$$H_{\min}(z) = \alpha \cdot \frac{z - \frac{1}{4}}{(z - \frac{1}{3})(z - \frac{1}{2})}$$

$$H_{\text{ap}}(z) = \beta \cdot \frac{(z - \frac{1}{3})(z - 4)}{(z - \frac{1}{4})(z - 3)}$$

Their pole diagrams are shown in the figures below.



We can see that all the poles and zeros have been included in $H_{\text{ap}}(z)$, and additional poles and zeros cannot be cancelled out by $H_{\min}(z)$. Therefore, the decomposition is unique up to a scale factor.

5. Assume $D(\cos \theta, \sin \theta)$ where $\theta \in [0, 2\pi)$ and $P(p, 0)$, $Z(q, 0)$, we have

$$|DP| = \sqrt{(\cos \theta - p)^2 + \sin^2 \theta} = \sqrt{1 + p^2 - 2p \cos \theta}$$

$$|DZ| = \sqrt{(\cos \theta - q)^2 + \sin^2 \theta} = \sqrt{1 + q^2 - 2q \cos \theta}$$

Since $\frac{|DZ|}{|DP|} = \frac{1}{\alpha}$, we have

$$\frac{1 + q^2 - 2q \cos \theta}{1 + p^2 - 2p \cos \theta} = \frac{1}{\alpha^2}$$

which is equivalent to

$$2 \cos \theta (p - q\alpha^2) = (1 + p^2) - \alpha^2 (1 + q^2)$$

The equation holds for any $\theta \in [0, 2\pi)$, which yields

$$\begin{cases} p = q\alpha^2 \\ 1 + p^2 = \alpha^2 (1 + q^2) \end{cases}$$

Eliminate α and we have

$$(p - q)(pq - 1) = 0$$

Since $p \neq q$, we have $pq = 1$, namely

$$|OZ| \cdot |OP| = 1$$