

A Multi-stage Cascaded Encoder-decoder Framework for CT-to-PET Image Conversion in Lung Imaging

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Keywords:

Tracking; Estimation; Information fusion; Resource management; Using point size 9

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TABLE 1. Encoder-decoder Setting Table

Block Name	input	output	trans	dropout
Encoder 1	3	16	-	-
Encoder 2	16	24	-	-
Encoder 3	24	42	-	-
Encoder 4	42	81	-	-
Encoder 5	81	114	-	-
Encoder 6	114	162	-	-
Encoder 7	162	162	-	-
Encoder 8	162	960	-	-
Decoder 1	960	960	162	0.5
Decoder 2	1122	162	162	0.5
Decoder 3	324	114	114	0.5
Decoder 4	228	81	81	-
Decoder 5	162	42	42	-
Decoder 6	84	24	24	-
Decoder 7	48	16	16	-
Visual Block	32	3	-	-

TABLE 2. Parameters of Neural Networks.

Architectures	Parameters
U-Net[?]	54.41
Cas-UNet[?]	108.82
DualStageGGAN[?]	92.54
Stage01	22.13
Stage02	44.26
Stage03	66.39
Stage04	88.52
Stage05	110.65
Stage06	132.77
Stage07	154.90
Stage08	177.03
Stage09	199.16
Stage10	221.29

The table depicts the Parameters of different generators. The quantity of parameters is expressed in millions.

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Mathematical formulas should be roughly centered and have to be numbered as formula (1).

$$y = f(x) \quad (1)$$

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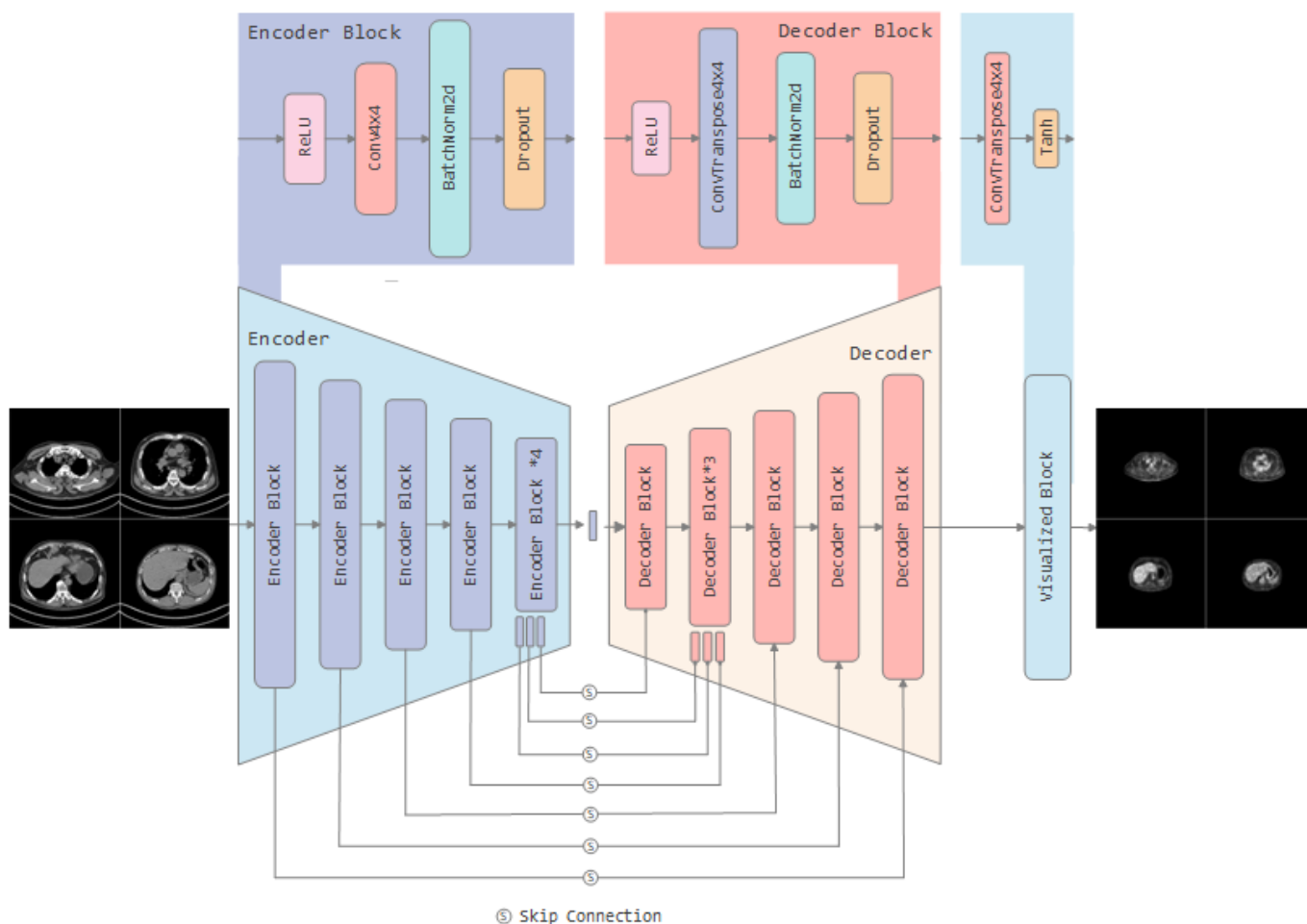


FIGURE 1. Schematic Diagram of Data Flow Within the Model. The PET image is shown on the left, and the CT image on the right. The blue modules correspond to the encoder architecture, while the orange modules represent the decoder architecture. The upper portion of the figure illustrates the fundamental structures of the encoder blocks, decoder blocks, and visualization blocks. The connections in the lower portion indicate the skip connections.

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3. Conclusions

In this sample paper, we have presented the formatting instructions for ICMLC and ICWAPR.

Acknowledgements

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