Machine Learning

Topic: Active Learning

Concept Learning

- Much of learning involves acquiring general concepts from specific training examples
- Concept: subset of objects from some space
- Concept learning: Defining a function that specifies which elements are in the concept set.

Some terms

- X is the set of all possible instances
- C is the set of all possible concepts c where $c: X \rightarrow \{0,1\}$
- H is the set of hypotheses considered by a learner, $H \subseteq C$
- L is the learner
- D is a probability distribution over X that generates observed instances

Concept Learning Task

GIVEN:

- Instances X
- Target function $c \rightarrow \{0,1\}$
- Hypothesis space H
- Training examples D = $\{\langle x_1, c(x_1) \rangle, ..., \langle x_n, c(x_n) \rangle\}$

FIND:

• A hypothesis h in H such that h(x)=c(x) for all x in D.

Labeling examples

• Example 1: Netflix Challenge

Too time consuming

Concept: movies Bob would like

Instances: 10,000 movies on netflix

Labeling: Bob watches a movie and reports

Example 2: Labeling phonemes

Concept: words labeled with phonetic alphabet

Instances: 1000 hours of talk radio recordings

Labeling: Hire linguist to annotate each syllable

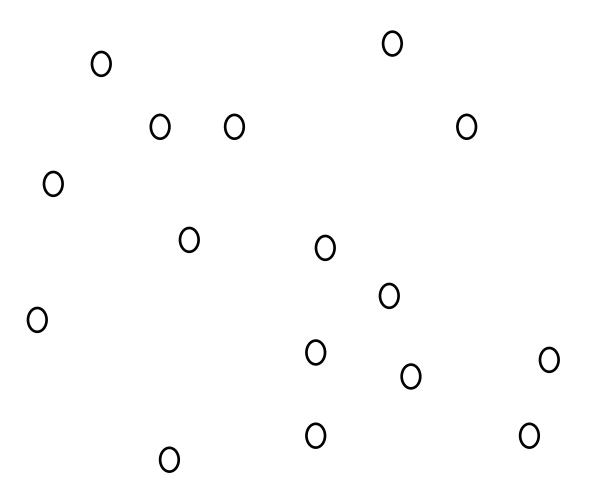
The BIG IDEA

 If we just pick the RIGHT examples to label, we can learn the concept from only a few labeled examples (it's like 20 questions)

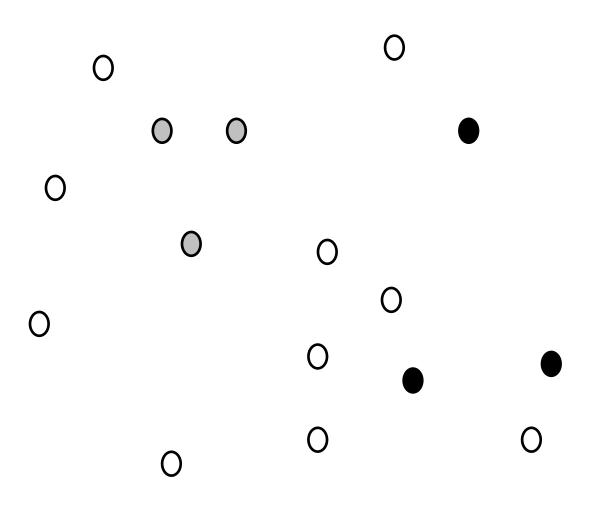
Active Learning Heuristic

- Start with a pool of unlabeled data
- Pick a few points at random and get their labels
- Repeat the following
 - 1. Fit a classifier to the labels seen so far
 - 2. Pick the BEST unlabeled point to get a label for (closest to the boundary?)
 (most uncertain?)
 (most likely to decrease overall uncertainty?)

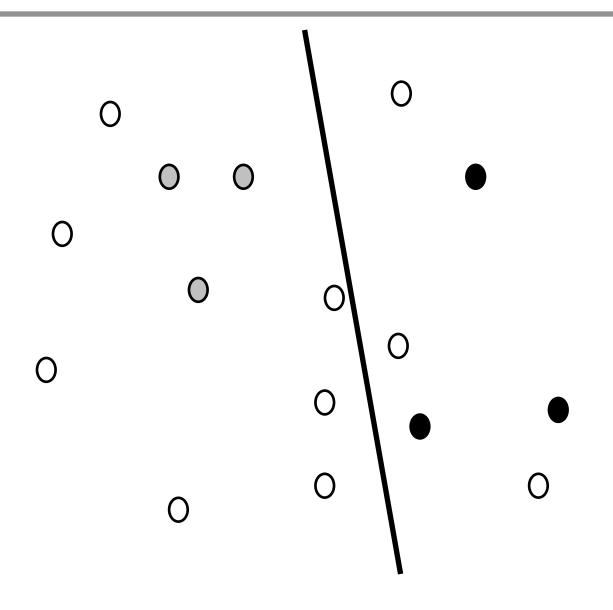
Start: Unlabeled Data



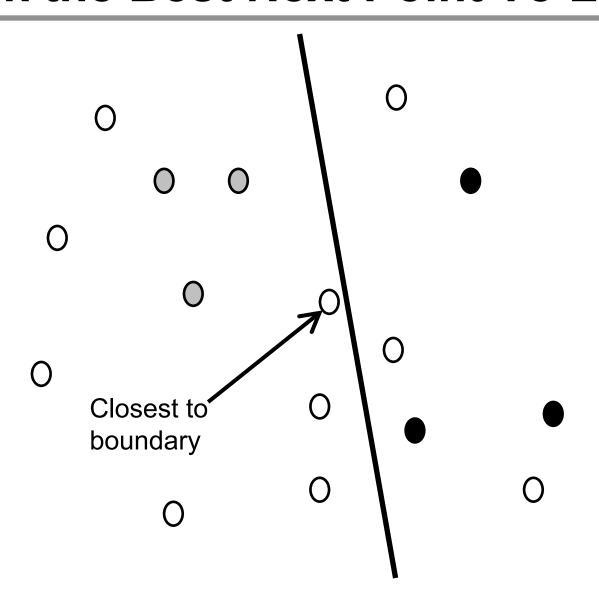
Label a Random Subset



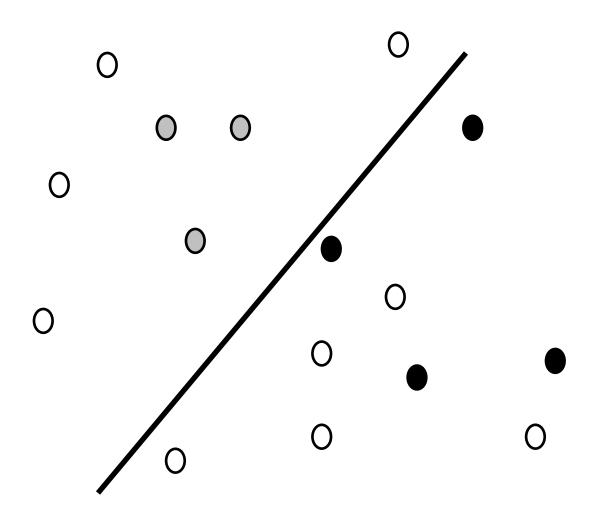
Fit a Classifier to Labeled Data



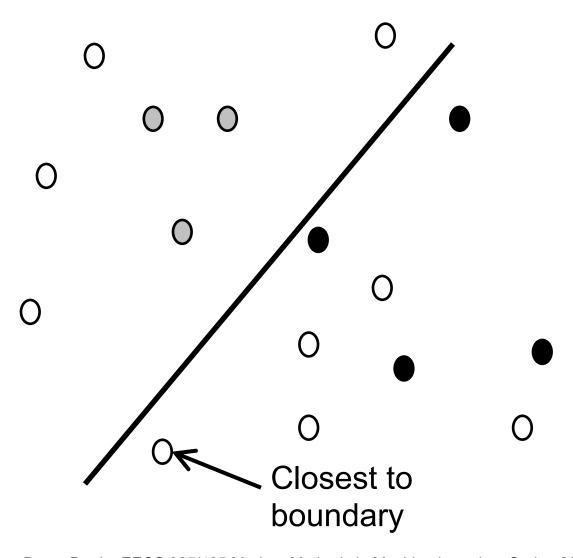
Pick the Best Next Point To Label



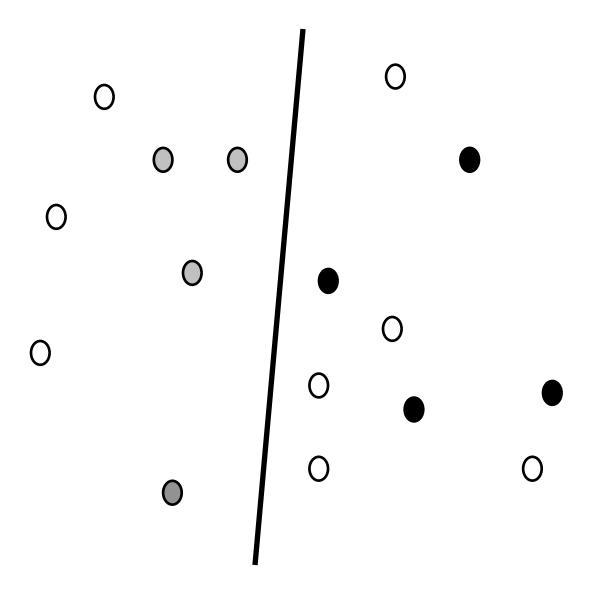
Fit a Classifier to Labeled Data



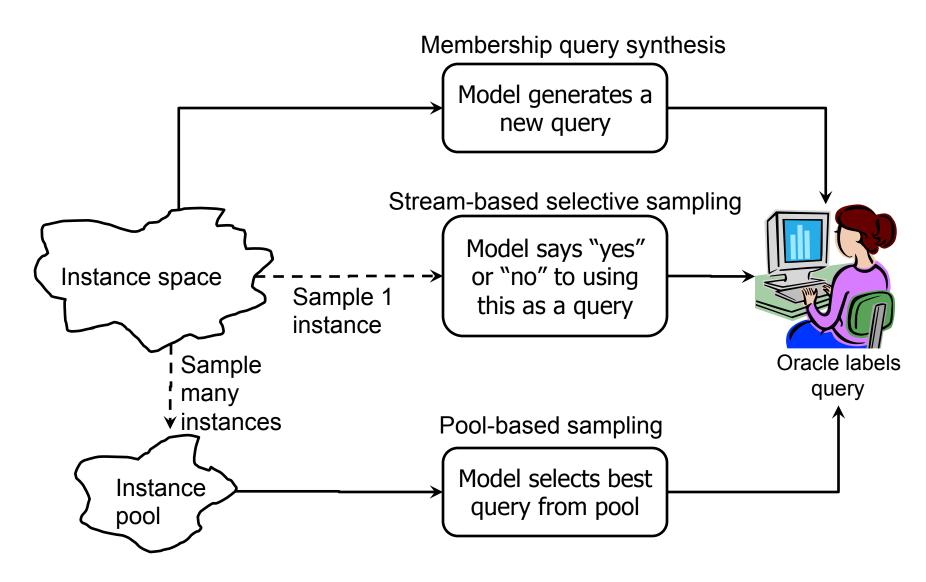
Pick the Best Next Point To Label



Fit a Classifier to Labeled Data

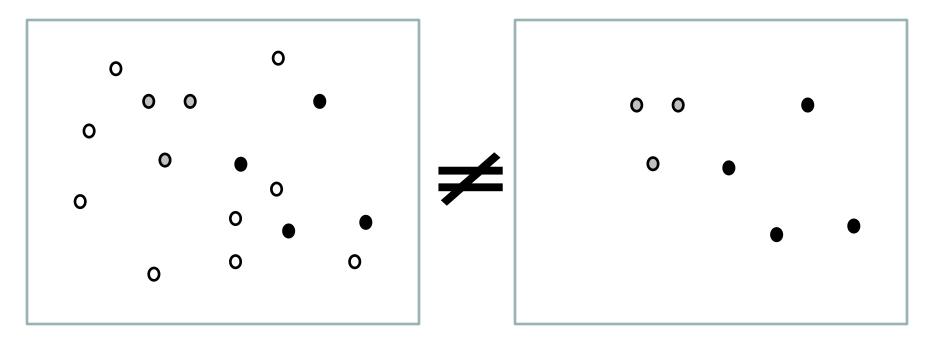


3 Approaches to Querying



Biased Sampling

- The labeled points may not be representative of the underlying distribution
- This can increase error in the limit (as number of labeled examples goes to infinity) (Schutze et al 03)



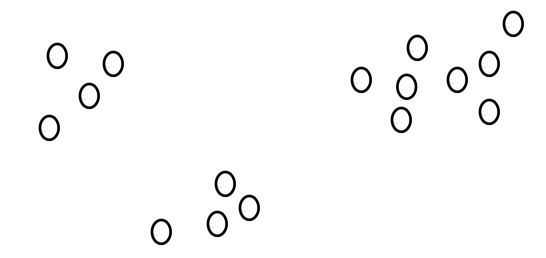
Two Rationales for Active Learning

Rationale 1: We can exploit cluster structure in data

Rationale 2: We can efficiently search through the hypothesis space

Exploiting structure in data

If the data looked like this...



...then we might just need 3 labeled points

Issues:

Structure may not be so clearly defined Structure exists at many levels of granularity Clusters may not be all one label

Efficient Hypothesis Search

If each query cuts the version space in 2, we may need only log(|H|) to get a perfect hypothesis.

Which example should we label?

```
S: {<Sunny,Warm,?,Strong,?,?>}

<Sunny,?,?,Strong,?,?> <Sunny,Warm,?,?,?> <?,Warm,?,Strong,?,?>

G: {<Sunny,?,?,?,?>, <?,Warm,?,?,?>, }
```

```
x_5 = <Sunny Warm Normal Strong Cool Change> + 6/0

x_6 = <Rainy Cold Normal Light Warm Same> - 0/6

x_7 = <Sunny Warm Normal Light Warm Same> ? 3/3

x_8 = <Sunny Cold Normal Strong Warm Same> ? 2/4
```

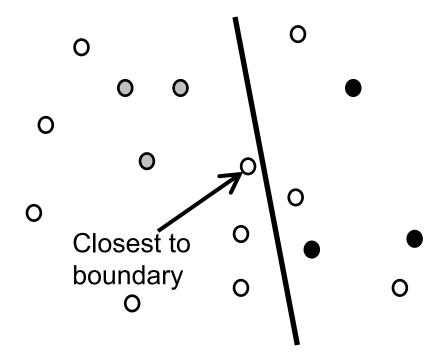
Questions

 Do there always exist queries that will cut off a good portion of the version space?

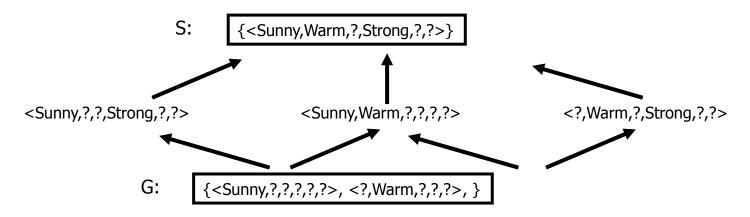
If so, how can these queries be found?

What happens in the nonseparable case?

- Uncertainty Sampling
 - A single model
 - Query the instances we are least certain how to label (e.g. closet to the decision boundary)

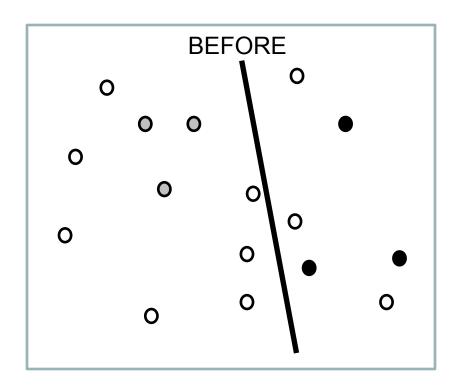


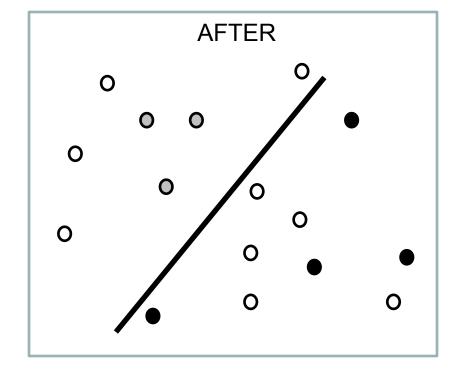
- Query by Committee (QBC)
 - Maintain a version space of hypotheses
 - Pick the instances generating the most disagreement among hypotheses



$x_5 = $ <sunny change="" cool="" normal="" strong="" warm=""></sunny>	+ 6/0
$x_6 = $ < Rainy Cold Normal Light Warm Same >	- 0/6
$x_7 = \langle Sunny Warm Normal Light Warm Same \rangle$	-, -
$x_8 = \langle Sunny Cold Normal Strong Warm Same \rangle$? 3/3
3	? 2/4

- Expected Model Change
 - A single model
 - Pick the unlabeled instance that would cause the greatest change to the model, if we knew its label





- Expected Error Reduction
 - A single probabilistic model
 - Query the instances that would most reduce error.
 - most computationally expensive query framework
 - we have to estimate given all possible labelings for each new instance

Density Weighting Selections

Pick instances that are both "informative" and "representative"

"informative" = score highly on one of the query evaluation measures discussed earlier

"representative" = inhabit dense regions of the input space

Example Density Weighting

