

L2. SC-SC: GDA, by monotone field

• monotone field $F: \mathbb{R}^d \rightarrow \mathbb{R}^d$ $\cancel{\text{convex in } \mathbb{R}^d}$

def $F(x)$ is called monotone on \mathbb{R}^d if

$$\langle F(\tilde{x}) - F(x), \tilde{x} - x \rangle \geq 0, \forall x, \tilde{x} \in \mathbb{R}^d$$

F is α -strongly monotone if

$$\langle F(\tilde{x}) - F(x), \tilde{x} - x \rangle \geq \alpha \|\tilde{x} - x\|^2, \forall \tilde{x}, x \in \mathbb{R}^d.$$

- follow monotone field imply convergence

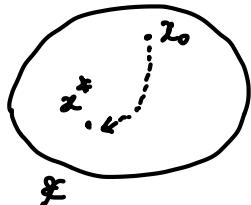
lemma If F is α -strongly monotone, then zero pt of F is unique.

pf. $F(x_1) = f(x_2) = 0$, then

$$\cancel{\langle F(x_1) - F(x_2), x_1 - x_2 \rangle \geq \alpha \|x_1 - x_2\|^2 \Rightarrow x_1 = x_2}$$

rk. F is cont, \mathcal{E} is compact convex, then $\exists! x^*$.

- how to converge to x^* ?



$$x_{k+1} = x_k - s F(x_k)$$

$$F(x^*) = 0$$

$$\|x_{k+1} - x^*\|^2 = \|x_k - x^* - s F(x_k)\|^2 \leq ?$$

$$= \|x_k - x^*\|^2 - 2s \underbrace{\langle F(x_k), x_k - x^* \rangle}_{\|F(x_k) - f(x^*)\|} + s^2 \|F(x_k)\|^2$$

$$\langle F(x_k) - f(x^*), x_k - x^* \rangle \geq \alpha \|x_k - x^*\|^2$$

$$\|F(x_k) - f(x^*)\| \leq \beta \|x_k - x^*\| \quad \text{if } F \text{ is } \underline{\beta\text{-Lipstiz}}$$

$\beta > \alpha > 0$

then

$$\begin{aligned}\|x_{k+1} - x^*\|^2 &\leq \|x_k - x^*\|^2 - 2s\alpha \|x_k - x^*\|^2 + s^2\beta^2 \|x_k - x^*\|^2 \\ &= \underbrace{(1 - 2s\alpha + s^2\beta^2)}_{<1 \text{ if } 0 < s < \frac{2\alpha}{\beta^2} (\leq \frac{\alpha}{\beta})} \|x_k - x^*\|^2\end{aligned}$$

this gives $\|x_k - x^*\| \leq \rho^k \|x_0 - x^*\|$, $\rho < 1$.

"exponential convergence" i.e.
(linear)

$\|x_k - x^*\| \leq \varepsilon$ in $O(\log \frac{1}{\varepsilon})$ steps.

kr. Follow a strongly monotone field converges to its unique vanishing pt exponentially fast.

Eg. $\min_x f(x)$, f α -strongly convex
 $\Rightarrow \nabla f$ α -monotone

GD (Gradient Descent)

$$x_{k+1} = x_k - s \nabla f(x_k)$$

\Rightarrow For strongly convex minimization, GD converges exponentially fast (need $s < \frac{2}{\beta}$)

- difference btw convex v.s. convex-concave

consider $f: \mathbb{R}^2 \rightarrow \mathbb{R}$, f is C^2 , $\alpha \geq 0$.

$$f(xy) = f(z), \quad z = \begin{bmatrix} x \\ y \end{bmatrix}$$

1. (jointly) convex f

fact ∇f is α -monotone $\Leftrightarrow \nabla^2 f(z) \succeq \alpha I$, $\forall z \in \mathbb{R}^2$

$$\nabla^2 f = \begin{bmatrix} \partial_{xx}^2 f & \partial_{xy}^2 f \\ \partial_{yx}^2 f & \partial_{yy}^2 f \end{bmatrix} \text{ the matrix matter.}$$

Pf. " \Leftarrow " $\forall z, \tilde{z} = z + sh, \forall h, \|h\|=1, s>0,$

$$\langle \nabla f(z+sh) - \nabla f(z), sh \rangle \stackrel{?}{\geq} \alpha \|sh\|^2$$

$$\phi(s) := \langle \nabla f(z+sh), h \rangle,$$

$$\phi(1) - \phi(0) \stackrel{?}{\geq} \alpha s \|h\|^2$$

$$\text{By BVT, } \phi(s) - \phi(0) = s\phi'(s)$$

$$= s \underbrace{\langle \nabla^2 f(z+sh) h, h \rangle}_{\geq \alpha \|h\|^2} \checkmark$$

" \Rightarrow " $\forall z, \text{wt } \nabla^2 f(z) \succeq \alpha I.$

$$\text{if } \forall h, \|h\|=1, \langle \nabla^2 f(z) h, h \rangle \stackrel{?}{\geq} \alpha \|h\|^2$$

define $\phi(s)$ as above, by F is α -monotone,

$$\phi(s) - \phi(0) \geq \alpha s \|h\|^2, \forall h, \|h\|=1, \forall s > 0.$$

$$\Rightarrow \phi'(0) \geq \alpha \|h\|^2. \quad \phi'(0) = \langle \nabla^2 f(z) h, h \rangle \#$$

2. convex-concave f

Lemma If $\partial_{xx}^2 f(z), -\partial_{yy}^2 f(z) \geq \alpha$, then

$$\partial f(z) := \begin{bmatrix} \partial_x f(z) \\ -\partial_y f(z) \end{bmatrix} \text{ is } \alpha\text{-monotone on } \mathbb{R}^2.$$

$$\nabla^2 f = \begin{bmatrix} \underline{\partial_{xx}^2 f} & \underline{\partial_{xy}^2 f} \\ \underline{\partial_{yx}^2 f} & \underline{\partial_{yy}^2 f} \end{bmatrix} \text{ only } \partial_{xx}, \partial_{yy} \text{ matter!}$$

Cor. $f(x, y) : \mathbb{R}^m \times \mathbb{R}^n \rightarrow \mathbb{R}$,

$$[\partial_{xx}^2 f]_{mn} \succeq \alpha I, \quad [\partial_{yy}^2 f]_{mn} \succeq \alpha I_n,$$

then $\partial f(z)$ is α -monotone on \mathbb{R}^{m+n} .

Pf. $f(x, y) \stackrel{\text{convex}}{\geq} f(x, y) + \partial_x f(x, y)(\tilde{x} - x) + \frac{\alpha}{2} (\tilde{x} - x)^2$

$$f(x, y) \stackrel{\text{concave}}{\leq} f(\tilde{x}, \tilde{y}) + \partial_y f(\tilde{x}, \tilde{y})(y - \tilde{y}) - \frac{\alpha}{2} (\tilde{y} - y)^2$$

$$\Rightarrow f(\tilde{x}, \tilde{y}) - f(x, y) \geq \partial_x f(x, y)(\tilde{x} - x) + \partial_y f(\tilde{x}, \tilde{y})(y - \tilde{y})$$

$$+\frac{\alpha}{2} \|y - \tilde{y}\|^2 + \frac{\alpha}{2} \|x - \tilde{x}\|^2 \quad \dots (1)$$

by symmetry, $(x, y) \leftrightarrow (\tilde{x}, \tilde{y})$

$$\begin{aligned} f(x, y) - f(\tilde{x}, \tilde{y}) &\geq \partial_x f(\tilde{x}, \tilde{y})(x - \tilde{x}) + \partial_y f(x, y)(y - \tilde{y}) \\ &+ \frac{\alpha}{2} (y - \tilde{y})^2 + \frac{\alpha}{2} (x - \tilde{x})^2 \end{aligned} \quad \dots (2)$$

(1), (2) \Rightarrow

$$\partial_x f(\tilde{x}, \tilde{y})(x - \tilde{x}) + \partial_y f(x, y)(y - \tilde{y}) - \frac{\alpha}{2} (y - \tilde{y})^2 - \frac{\alpha}{2} (x - \tilde{x})^2$$

$$\geq \partial_x f(x, y)(\tilde{x} - x) + \partial_y f(\tilde{x}, \tilde{y})(\tilde{y} - y) + \frac{\alpha}{2} (y - \tilde{y})^2 + \frac{\alpha}{2} (x - \tilde{x})^2$$

i.e.

$$\left\langle \begin{bmatrix} \partial_x f(\tilde{x}, \tilde{y}) - \partial_x f(x, y) \\ (-\partial_y f(\tilde{x}, \tilde{y})) - (-\partial_y f(x, y)) \end{bmatrix}, \begin{bmatrix} \tilde{x} - x \\ \tilde{y} - y \end{bmatrix} \right\rangle \geq \alpha \left\| \begin{bmatrix} \tilde{x} - x \\ \tilde{y} - y \end{bmatrix} \right\|^2$$

i.e. $\langle \partial f(\tilde{x}) - \partial f(x), \tilde{x} - x \rangle \geq \alpha \|\tilde{x} - x\|^2 \neq$

• exponential convergence for SC-SC objective

$$\min_x \max_y L(x, y), \quad L: \mathbb{R}^n \times \mathbb{R}^m \rightarrow \mathbb{R}, \quad C^2$$

a) μ -strongly convex - strongly concave : $\mu > 0$.

$$\nabla_{xx}^2 L(x, y) \succeq \mu I_n, -\nabla_{yy}^2 L(x, y) \succeq \mu I_m, \forall x, y$$

b) ℓ -smooth
 $\nabla_x L, \nabla_y L$ is ℓ -Lipschitz $\ell \geq \mu > 0$

GDA (Gradient Descent Ascent) $s > 0$

$$\begin{cases} x_{k+1} = x_k - s \nabla_x L(x_k, y_k) \end{cases}$$

$$\begin{cases} y_{k+1} = y_k + s \nabla_y L(x_k, y_k) \end{cases}$$

$$z_k = \begin{bmatrix} \partial_x L(z) \\ \partial_y L(z) \end{bmatrix}, \quad \partial L(z) := \begin{bmatrix} \nabla_x L(z) \\ -\nabla_y L(z) \end{bmatrix}$$

$$\beta_{k+1} = \beta_k - \gamma \partial L(\beta_k),$$

a) $\Rightarrow \partial L$ is μ -monotone } \Rightarrow exp. convergence to
 b) $\Rightarrow \partial L$ is L -Lip } $\frac{\text{the}}{\text{a}}$ stationary pt
 $\partial L(\beta^*) = 0$

Q. existence of β^* ? M.S.C.-S.C. implies that.

ref lemma B.1 of [GLWM 2023] on PPM

[GLWM 2023] Grimmer, Lu, Worah, Mirrokni (2023). The landscape of the proximal point method for nonconvex–nonconcave minimax optimization. *Mathematical Programming*, 201(1), 373–407.

$$\text{Eq } L(x,y) = f(x) - g(y) + \alpha xy \quad (\text{bilinear interaction})$$

effect of α small or large?

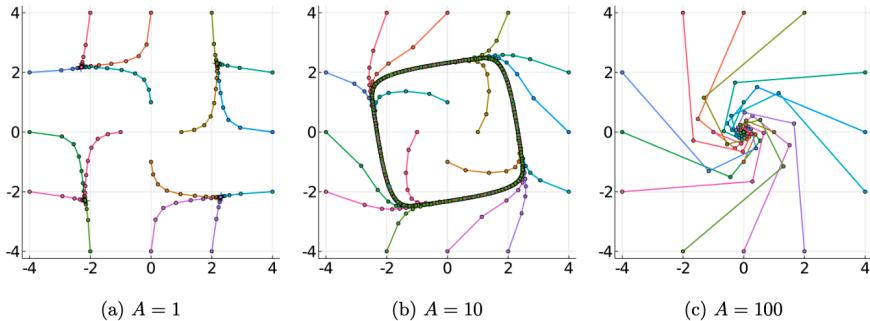
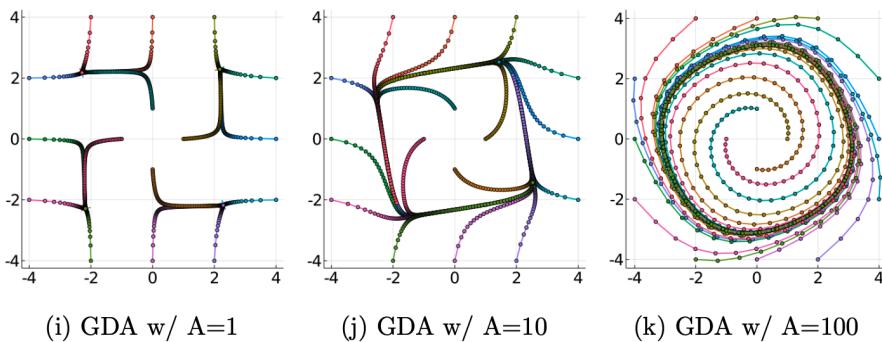


Figure 1: Sample paths of PPM from different initial solutions applied to (3) with $f(x) = (x + 3)(x + 1)(x - 1)(x - 3)$ and $g(y) = (y + 3)(y + 1)(y - 1)(y - 3)$ and different scalars A . As $A \geq 0$ increases, the solution path transitions from having four locally attractive stationary points, to a globally attractive cycle, and finally to a globally attractive stationary point.



This minimax problem is NC-NC type, GDA cycles in a case ($A=100$, strong interaction) when PPM converges better. See L3.