

L1. Minimization and saddle point problem

- Non-convex minimization

$$\min_{\mathbb{R}^d} f(x)$$

$O(\varepsilon^2)$ steps to find ε -stationary pt

Assump. on f : "nothing but C^1 "

Reference: Section 1.2.3
 [N2018] Nesterov. *Introductory lectures on convex optimization*. Vol. 137. Berlin: Springer International Publishing, 2018.

(A1) f is C^1 on \mathbb{R}^d , l -smooth
 i.e. ∇f is l -Lipschitz

(A2) $\min_x f(x) = f^*$ finite, i.e. f is lower bounded
 below on \mathbb{R}^d .

GD (Gradient Descent)

$$x_{k+1} = x_k - \gamma \nabla f(x_k)$$

No other information, f may have local minima, and
 generally GD only finds a stationary pt.

Rmk. Without (A2), GD may diverge

$$\text{e.g. } f(x,y) = xy, \text{ along } [1]^\top, f \rightarrow -\infty.$$

$$\text{define } \Delta_f := f(x_0) - f^* \geq 0.$$

Then If $0 < \gamma < \frac{2}{l}$, then for $N = O(\frac{1}{\varepsilon^2})$, $\exists k \leq N$

$$\text{s.t. } \|\nabla f(x_k)\| \leq \varepsilon.$$

Pf. idea: make $f(x_k) \downarrow$, then bcz f has
 a lower bound, it can not always make progress.

$$f(x_k) - f^* \leq \frac{l}{2} \|x_k - x^*\|^2$$

$$T^{(x_{k+1})} \leq T^{(x_k)} + \langle \nabla f(x_k), x_{k+1} - x_k \rangle + \|x_{k+1} - x_k\|$$

by Taylor expansion and ℓ -smoothness of f

$$x_{k+1} - x_k = -s \nabla f(x_k)$$

$$\begin{aligned} f(x_{k+1}) - f(x_k) &\leq -s \|\nabla f(x_k)\|^2 + \frac{\ell}{2} s^2 \|\nabla f(x_k)\|_F^2 \\ &= -s \underbrace{\left(1 - \frac{\ell s}{2}\right)}_{> 0 \text{ if } \frac{\ell s}{2} < 1} \|\nabla f(x_k)\|^2 \end{aligned}$$

Suppose $s = \frac{2}{\ell} \alpha$, $0 < \alpha < 1$, then

$$f(x_{k+1}) - f(x_k) \leq \frac{2\alpha((1-\alpha))}{\ell} \|\nabla f(x_k)\|^2$$

telescopic sum $k=0, \dots, N$

$$\frac{2\alpha((1-\alpha))}{\ell} \sum_{k=0}^N \|\nabla f(x_k)\|^2 \leq f(x_0) - f(x_{N+1}) \leq \Delta f$$

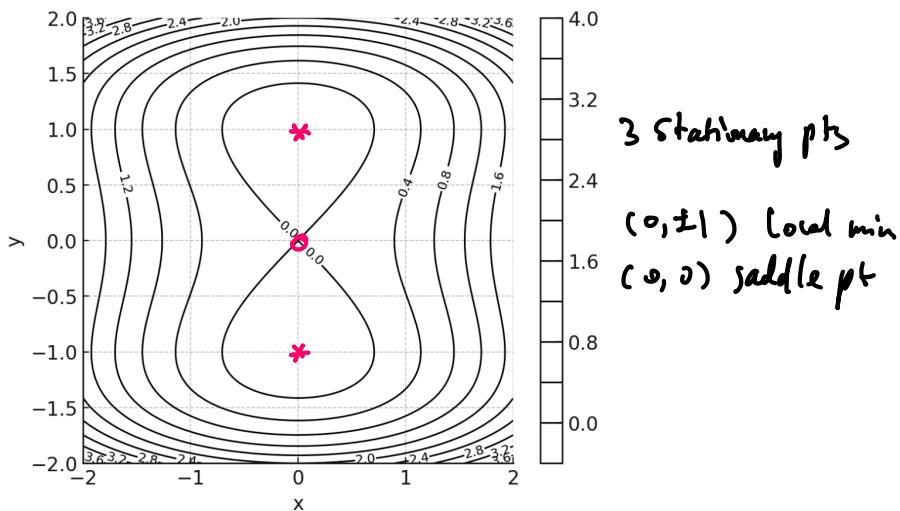
$\Rightarrow \exists k \leq N$ s.t.

$$\|\nabla f(x_k)\|^2 \leq \frac{\Delta f}{2\alpha((1-\alpha))} \cdot \frac{1}{N+1} \sim \frac{1}{N}$$

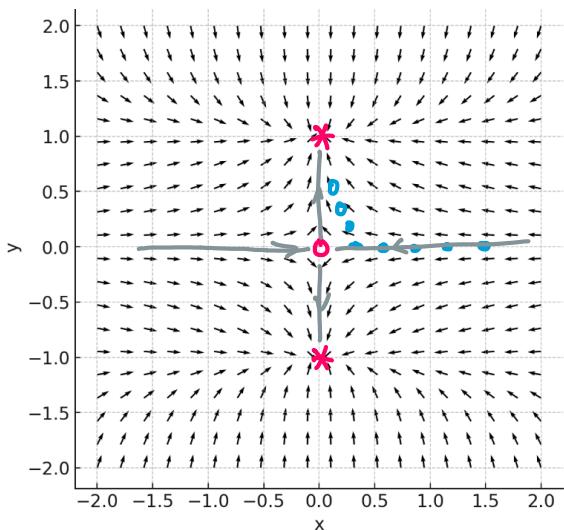
RK. The $O(\tilde{\epsilon}^2)$ iteration complexity is tight, to find $\tilde{\epsilon}$ -stationary pt is $\Omega(\tilde{\epsilon}^2)$ grad evaluations.

[CDHS2017] Carmon, Duchi, Hinder, Sidford. Lower bounds for finding stationary points. arXiv:1710.11606, 2017.

Eg. $f(x, y) = \frac{1}{2}x^2 + \frac{1}{4}y^4 - \frac{1}{2}y^2$



Gradient Descent Directions for $f(x, y)$



starting GD from

$$x_0 = (1, 0)$$

in theory $x_k \rightarrow (0, 0)$

RE. finding saddle
it is not easy in
practical computation

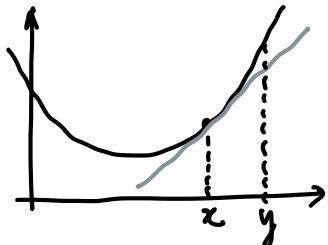
- Convex minimization

$$\min_x f(x) \quad f \text{ is } C^1 \text{ on } \mathbb{R}^d$$

$f(x)$ is convex on \mathbb{R}^d

fact If f is C^1 and convex, then

$$f(y) \geq f(x) + \langle \nabla f(x), y - x \rangle, \forall x, y \in \mathbb{R}^d.$$



'above the tangent line'

lemma If f is C^1 and convex, $\nabla f(x^*) = 0$, then

$$f(x^*) = \min_x f(x),$$

i.e. x^* is a global minimum. (may not unique)

pf. $\forall x, f(x) \geq f(x^*) + \langle \nabla f(x^*), x - x^* \rangle$

prop f is C^1 , then f is convex iff.

$$\langle \nabla f(x) - \nabla f(y), x - y \rangle \geq 0, \forall x, y.$$

Res. The field $F(x) = \nabla f(x)$ is called monotone.

Pf. " \Rightarrow " $f(x) - f(y) \geq \langle \nabla f(y), x-y \rangle$ } $\quad \quad \quad$
 $f(y) - f(x) \geq \langle \nabla f(x), y-x \rangle$ } \rightarrow adding the two.

" \Leftarrow " 

$$F(t) := f(x + t(y-x)), \quad f(0) = f(x), \quad F'(0) = f(x)$$

$$\begin{aligned} f(y) - f(x) &= \int_0^1 F'(t) dt \\ &= \int_0^1 \underbrace{\langle \nabla f(x+t(y-x)), y-x \rangle}_{\nabla f(x) + \nabla f(x+t(y-x)) - \nabla f(x)} dt \\ &= \langle \nabla f(x), y-x \rangle \\ &\quad + \underbrace{\int_0^1 \langle \nabla f(x+t(y-x)) - \nabla f(x), \frac{x(t)-x(0)}{t} \rangle dt}_{\geq 0} \quad \# \end{aligned}$$

Prop. f is C^2 on \mathbb{R}^d , f is convex iff $\nabla^2 f \succeq 0$.

Pf (Ex)

$$\text{i.e. } \nabla^2 f(x) \succeq 0, \forall x.$$

• strongly convexity

If f is C^1 on \mathbb{R}^d , f is μ -strongly convex if $\mu > 0$ M.S.C.

$$f(y) \geq f(x) + \langle \nabla f(x), y-x \rangle + \frac{\mu}{2} \|y-x\|^2, \quad \forall x, y.$$

Prop. f is C^1 and μ -S.C., then

$$\langle \nabla f(x) - \nabla f(y), x-y \rangle \geq \mu \|x-y\|^2, \quad \forall x, y.$$

Res. $F(x) = \nabla f(x)$ is μ -strongly monotone.

Prop f is C^2 on \mathbb{R}^d , f is μ -S.C. iff $\nabla^2 f \succeq \mu \text{Id}$.

Lemma f is C^1 and μ -S.C. on \mathbb{R}^d , then $\min_x f(x) :$

$\dots \cdot 0 \cdot \dots \quad \dots \cdot 1 \cdot 1 \cdot \dots$

occurred at a unique (global) minimizer.

pf. First use "quadratic growth" to show that

Q.G.
level set is compact, then $\min_x f(x)$ is attained within
a compact set.

$$\text{QG: } f(y) \geq f(x_0) + \langle \nabla f(x_0), y - x_0 \rangle + \frac{\mu}{2} \|y - x_0\|^2$$

$$\sim \|y - x_0\|^2 \text{ as } \|y\| \rightarrow \infty.$$

Then use μ -S.C. to prove uniqueness of x^* #

Thm If f is C^1 , ℓ -smooth, μ -S.C., then GD converges

(RK. $\ell \geq \mu$)

exponentially fast (or "linear convergence"), i.e

1) $f(x_k) \leq f^* + \varepsilon$ (function value convergence)

2) $\|\nabla f(x_k)\| \leq \varepsilon$ (first-order optimality)

3) $\|x_k - x^*\| \leq \varepsilon$ (variable convergence)

"identification of x^* parameters"

within $k = O(\log \frac{1}{\varepsilon})$ steps, assuming $\delta < \frac{2\mu}{\ell^2}$

$$\frac{1}{k} \frac{2}{\ell}$$

RK $\kappa := \frac{\ell}{\mu}$ is called condition number, $\kappa \geq 1$.

pf. $x^* \exists!$ by S.C.

3) \Rightarrow 2) : $\|\nabla f(x_k) - \nabla f(x^*)\| \leq \ell \|x_k - x^*\|$
 ~~$\nabla f(x^*)$~~ by ℓ -smoothness.

3) \Rightarrow 1) : $f(x^*) \geq f(x_k) + \underbrace{\langle \nabla f(x_k), x^* - x_k \rangle}_{f^{x^*}}$
 $\leq \underbrace{\|\nabla f(x_k)\|}_{\text{by 2)}} \|x_k - x^*\| \leq \varepsilon^2$

function value actually achieves $O(\varepsilon^2)$ approximation.

We thus only prove 3).

Recall that $x_{k+1} = x_k - s \nabla f(x_k)$.

$$x_{k+1} - x^* = x_k - x^* - s \nabla f(x_k)$$

$$\begin{aligned} \Rightarrow \|x_{k+1} - x^*\|^2 &= \|x_k - x^*\|^2 - 2s \underbrace{\langle \nabla f(x_k), x_k - x^* \rangle}_{\text{by monotonicity}} \\ &\quad + s^2 \underbrace{\|\nabla f(x_k)\|_2^2}_{\text{bdd.}} \\ &\quad \langle \nabla f(x_k) - \nabla f(x^*), x_k - x^* \rangle \geq \mu \|x_k - x^*\|^2 \\ &\quad \|\nabla f(x_k) - \nabla f(x^*)\|_2 \leq \ell \|x_k - x^*\| \\ &\leq \|x_k - x^*\|^2 - 2s\mu \|x_k - x^*\|^2 + s^2 \ell^2 \|x_k - x^*\|^2 \\ &= \underbrace{(1 - 2s\mu + s^2 \ell^2)}_{< 1 ? \text{ when } 0 < 2s\mu - s^2 \ell^2} \|x_k - x^*\|^2 \\ &\quad \Leftrightarrow s < \frac{2\mu}{\ell^2} \# \end{aligned}$$

RK. The proof only uses that $\nabla f(x)$ is strongly-monotone

(in addition to ℓ -smoothness of f). See L2.