

## L1. Minimization and saddle point problem

- Non-convex minimization

$$\min_{z \in \mathbb{R}^d} f(z)$$

$O(\varepsilon^{-2})$  steps to find  $\varepsilon$ -stationary pt

assump- on  $f$ : "nothing but  $C'$ "

Reference: Section 1.2.3

[N2018] Nesterov. *Introductory lectures on convex optimization*. Vol. 137. Berlin: Springer International Publishing, 2018.

(A1)  $f$  is  $C^1$  on  $\mathbb{R}^d$ ,  $L$ -smooth  
i.e.  $\nabla f$  is  $L$ -Lipschitz

(A2)  $\min_z f(z) = f^*$  finite, i.e.  $f$  is lower bounded  
below on  $\mathbb{R}^d$ .

GD (Gradient Descent)

$$x_{k+1} = x_k - s \nabla f(x_k)$$

No other information,  $f$  may have local minima, and  
generally GD only finds a stationary pt.

Rk. Without (A2), GD may diverge

eg.  $f(x,y) = xy$ , along  $\begin{bmatrix} 1 \\ -1 \end{bmatrix}$ ,  $f \rightarrow -\infty$ .

define  $\Delta f := f(x_0) - f^* \geq 0$ .

Thm If  $0 < s < \frac{2}{L}$ , then for  $N = O(\frac{1}{\varepsilon^2})$ ,  $\exists k \leq N$

$$\text{s.t. } \|\nabla f(x_k)\| \leq \varepsilon.$$

pf. idea: make  $f(x_k) \downarrow$ , then b.c.  $f$  has  
a lower bound, it can not always make progress.

$$\| \nabla f(x_k) \|^2 = \langle \nabla f(x_k), \nabla f(x_k) \rangle = \langle \nabla f(x_k), -\frac{1}{s} (x_k - x_{k+1}) \rangle = \frac{1}{s} (f(x_k) - f(x_{k+1}))$$

$$f(x_{k+1}) \leq f(x_k) + \langle \nabla f(x_k), x_{k+1} - x_k \rangle + \frac{L}{2} \|x_{k+1} - x_k\|^2$$

by Taylor expansion and  $L$ -smoothness of  $f$

$$x_{k+1} - x_k = -s \nabla f(x_k)$$

$$\begin{aligned} \Rightarrow f(x_{k+1}) - f(x_k) &\leq -s \|\nabla f(x_k)\|^2 + \frac{L}{2} s^2 \|\nabla f(x_k)\|^2 \\ &= -s \underbrace{\left(1 - \frac{Ls}{2}\right)}_{> 0 \text{ if } \frac{Ls}{2} < 1} \|\nabla f(x_k)\|^2 \end{aligned}$$

suppose  $s = \frac{2}{L} \alpha$ ,  $0 < \alpha < 1$ , then

$$f(x_{k+1}) - f(x_k) \leq -\frac{2\alpha(1-\alpha)}{L} \|\nabla f(x_k)\|^2$$

telescopic sum  $k=0, \dots, N$

$$\frac{2\alpha(1-\alpha)}{L} \sum_{k=0}^N \|\nabla f(x_k)\|^2 \leq f(x_0) - f(x_{N+1}) \leq \Delta f$$

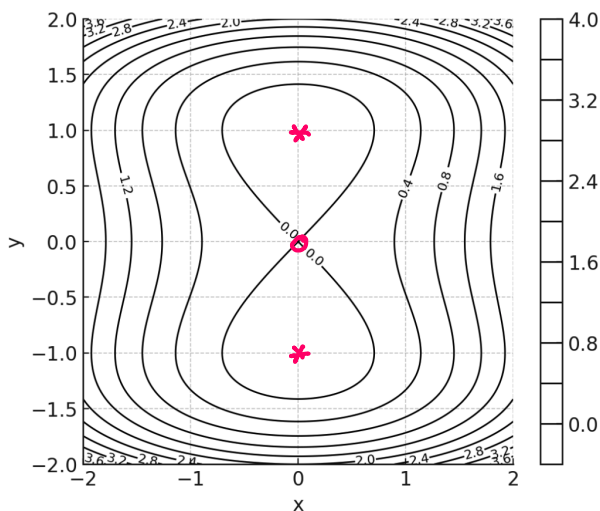
$\Rightarrow \exists k \leq N$  s.t.

$$\|\nabla f(x_k)\|^2 \leq \frac{\Delta f}{2\alpha(1-\alpha)} \cdot \frac{1}{N+1} \sim \frac{1}{N} \quad \#$$

rk. The  $O(\frac{1}{\epsilon^2})$  iteration complexity is tight, to find  $\epsilon$ -stationary pt is  $\Omega(\frac{1}{\epsilon^2})$  grad evaluations.

[CDHS2017] Carmon, Duchi, Hinder, Sidford. Lower bounds for finding stationary points. arXiv:1710.11606, 2017.

Ex.  $f(x, y) = \frac{1}{2} x^2 + \frac{1}{4} y^4 - \frac{1}{2} y^2$

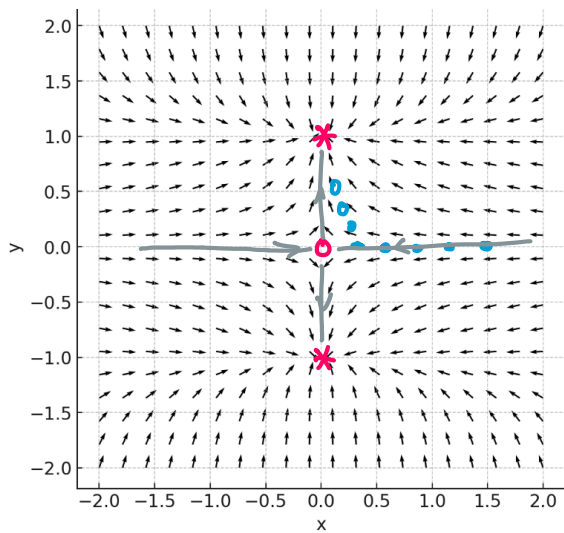


3 stationary pts

$(0, \pm 1)$  local min

$(0, 0)$  saddle pt

Gradient Descent Directions for  $f(x, y)$



starting GD from

$$x_0 = (1, 0)$$

in theory  $x_k \rightarrow (0, 0)$

Re. finding saddle  
pt is not easy in  
practical computation

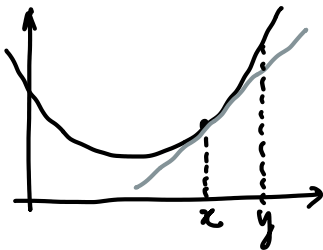
### • Convex minimization

$$\min_x f(x) \quad f \text{ is } C^1 \text{ on } \mathbb{R}^d$$

$f(x)$  is convex on  $\mathbb{R}^d$

fact If  $f$  is  $C^1$  and convex, then

$$f(y) \geq f(x) + \langle \nabla f(x), y - x \rangle, \forall x, y \in \mathbb{R}^d.$$



'above the tangent line'

lemma If  $f$  is  $C^1$  and convex,  $\nabla f(x^*) = 0$ , then

$$f(x^*) = \min_x f(x),$$

i.e.  $x^*$  is a global minimum. (may not be unique)

pf.  $\forall x, f(x) \geq f(x^*) + \langle \nabla f(x^*), x - x^* \rangle \quad \#.$

prop  $f$  is  $C^1$ , then  $f$  is convex iff.

$$\langle \nabla f(x) - \nabla f(y), x - y \rangle \geq 0, \forall x, y.$$

Def. The field  $F(x) = \nabla f(x)$  is called monotone.

pf.  $\Rightarrow \left. \begin{aligned} f(x) - f(y) &\geq \langle \nabla f(y), x - y \rangle \\ f(y) - f(x) &\geq \langle \nabla f(x), y - x \rangle \end{aligned} \right\} \rightarrow \text{adding the two.}$

" $\Leftarrow$ " ☺

$$F(t) := f(x + t(y-x)), \quad F(1) = f(y), \quad F(0) = f(x)$$

$$\begin{aligned} f(y) - f(x) &= \int_0^1 F'(t) dt \\ &= \int_0^1 \underbrace{\nabla f(x + t(y-x))}_{\substack{\parallel \\ \nabla f(x) + \nabla f(x(t)) - \nabla f(x)}} \cdot (y-x) dt \\ &= \langle \nabla f(x), y-x \rangle \\ &\quad + \int_0^1 \underbrace{\langle \nabla f(x(t)) - \nabla f(x), \frac{x(t)-x(0)}{t} \rangle}_{\geq 0} dt \quad \# \end{aligned}$$

Prop.  $f$  is  $C^2$  on  $\mathbb{R}^d$ ,  $f$  is convex iff  $\nabla^2 f \succeq 0$ .

pf (Ex)

$$\text{i.e. } \nabla^2 f(x) \succeq 0, \forall x.$$

• strongly convexity

Let  $f$  is  $C^1$  on  $\mathbb{R}^d$ ,  $f$  is  $\mu$ -strongly convex if  $\mu > 0$   $\mu$ -S.C.

$$f(y) \geq f(x) + \langle \nabla f(x), y-x \rangle + \frac{\mu}{2} \|y-x\|^2, \quad \forall x, y.$$

Prop.  $f$  is  $C^1$  and  $\mu$ -S.C., then

$$\langle \nabla f(x) - \nabla f(y), x-y \rangle \geq \mu \|x-y\|^2, \quad \forall x, y.$$

Def.  $F(x) = \nabla f(x)$  is  $\mu$ -strongly monotone.

Prop  $f$  is  $C^2$  on  $\mathbb{R}^d$ ,  $f$  is  $\mu$ -S.C. iff  $\nabla^2 f \succeq \mu I$ .

Lemma  $f$  is  $C^1$  and  $\mu$ -S.C. on  $\mathbb{R}^d$ , then  $\min_x f(x)$  is

assured at a unique (global) minimizer.

pf. First use "quadratic growth" to show that  
 Q.G. level set is compact, then  $\min_x f(x)$  is attained within a compact set.

$$\text{Q.G. } f(y) \geq f(x_0) + \langle \nabla f(x_0), y - x_0 \rangle + \frac{\mu}{2} \|y - x_0\|^2 \\ \sim \|y - x_0\|^2 \text{ as } \|y\| \rightarrow \infty.$$

Then use  $\mu$ -S.C. to prove uniqueness of  $x^*$  #

Thm If  $f$  is  $C^1$ ,  $L$ -smooth,  $\mu$ -S.C., then GD converges  
 exponentially fast (or "linear convergence" <sup>(K.K.  $L \geq \mu$ )</sup>), i.e.

$$1) \quad f(x_k) \leq f^* + \varepsilon \quad (\text{function value convergence})$$

$$2) \quad \|\nabla f(x_k)\| \leq \varepsilon \quad (\text{first-order optimality})$$

$$3) \quad \|x_k - x^*\| \leq \varepsilon \quad (\text{variable convergence})$$

"identification of  $x^*$  parameters"  
 within  $k = O(\log \frac{1}{\varepsilon})$  steps, assuming  $\delta < \frac{2\mu}{L^2}$   
 $\frac{1}{k \cdot 2}$

K.K.  $\kappa := \frac{L}{\mu}$  is called condition number,  $\kappa \geq 1$ .

pf.  $x^* \exists!$  by S.C.

$$3) \Rightarrow 2): \quad \|\nabla f(x_k) - \nabla f(x^*)\| \leq L \|x_k - x^*\| \\ \text{by } L\text{-smoothness.}$$

$$3) \Rightarrow 1): \quad \underbrace{f(x^*)}_{f^*} \geq f(x_k) + \underbrace{\langle \nabla f(x_k), x^* - x_k \rangle}_{\leq \|\nabla f(x_k)\| \|x_k - x^*\|} \leq \varepsilon^2 \\ \text{by 2) } \rightarrow \leq \varepsilon \quad \leq \varepsilon$$

function value actually achieves  $O(\varepsilon^2)$  approximation.

We thus only prove 3).

Recall that  $x_{k+1} = x_k - s \nabla f(x_k)$ .

$$x_{k+1} - x^* = x_k - x^* - s \nabla f(x_k)$$

$$\begin{aligned} \Rightarrow \|x_{k+1} - x^*\|^2 &= \|x_k - x^*\|^2 - 2s \underbrace{\langle \nabla f(x_k), x_k - x^* \rangle}_{\text{by monotonicity}} \\ &\quad + s^2 \underbrace{\|\nabla f(x_k)\|^2}_{\text{b.d.}} \\ &\quad \langle \nabla f(x_k) - \nabla f(x^*), x_k - x^* \rangle \geq \mu \|x_k - x^*\|^2 \\ &\quad \|\nabla f(x_k) - \nabla f(x^*)\| \leq L \|x_k - x^*\| \\ &\leq \|x_k - x^*\|^2 - 2s\mu \|x_k - x^*\|^2 + s^2 L^2 \|x_k - x^*\|^2 \\ &= \underbrace{(1 - 2s\mu + s^2 L^2)}_{< 1?} \|x_k - x^*\|^2 \\ &\quad \text{when } 0 < 2s\mu - s^2 L^2 \\ &\quad \Leftrightarrow s < \frac{2\mu}{L^2} \quad \# \end{aligned}$$

Rk. The proof only uses that  $\nabla f(x)$  is strongly-monotone (in addition to  $L$ -smoothness of  $f$ ). See L2.