# Part Two: Decoding: The Viterbi Algorithm

Zihao Zhu, Gangze Li, Yufeng Xie

Tsinghua University

November 5, 2019

## Decoding

Decoding: Given as input an HMM  $\lambda = (A, B)$  and a sequence of observations  $O = o_1, o_2, \dots, o_T$ , find the most probable sequence of states  $Q = q_1 q_2 q_3 \dots q_T$ .

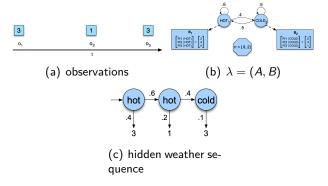


Figure: In the ice-cream domain, given a sequence of ice-cream observations 3 1 3 and an HMM, the task of the decoder is to find the best hidden weather sequence (H H H).

2/23

#### Problem

- One possibility
  - For each hidden state sequence Q
    - ► HHH, HHC, HCH, etc.
  - ightharpoonup Compute P(O|Q)
  - ► Pick the highest one
- ▶  $\stackrel{!}{\square}$  likelihood:  $N^T$  a set of N states, a sequence of T observations
- Instead
  - Viterbi algorithm

#### **Problem**

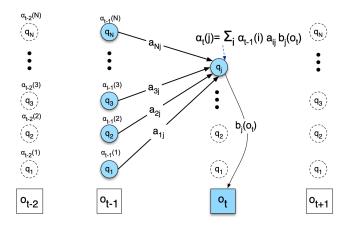


Figure: exponentially large number of state sequences! 1

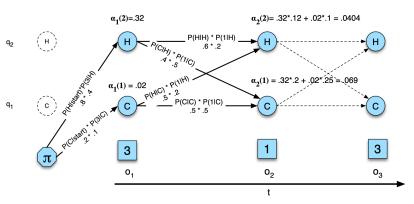
<sup>&</sup>lt;sup>1</sup>example from [JM19]

#### Viterbi algorithm

- ► The Viterbi algorithm is a dynamic programming algorithm for finding the most likely sequence of hidden states.
- ▶ We want to compute the joint probability of the observation sequence together with the best state sequence.
  - $v_t(j) = P(q_0, q_1, \ldots, q_{t-1}, o_1, o_2, \ldots, o_t, q_t = j | \lambda)$

#### The forward trellis

compute the total observation likelihood for the ice-cream events  $3\ 1\ 3$ 

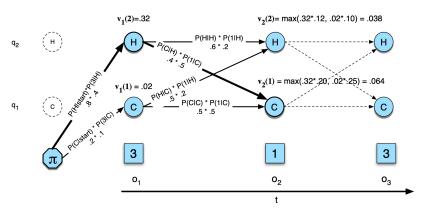


$$\alpha_t(j) = P(o_1, o_2 \dots o_t, q_t = j|\lambda)$$



## Viterbi algorithm

the computation of  $v_t(j)$  for two states at two time steps



$$v_t(j) = P(q_0, q_1, \ldots, q_{t-1}, o_1, o_2, \ldots, o_t, q_t = j | \lambda)$$

#### Viterbi algorithm

- The computation in each cell follows  $v_t(j) = \max_{1 \le i \le N-1} v_{t-1}(i)a_{ij}b_i(o_t)$
- ► The resulting probability expressed in each cell is  $v_t(j) = P(q_0, q_1, \dots, q_{t-1}, o_1, o_2, \dots, o_t, q_t = j | \lambda)$

#### the Viterbi backtrace

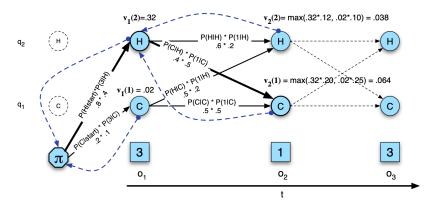


Figure: The Viterbi trellis for computing the best path through the hidden state space for the ice-cream eating events 3 1 3.

#### Viterbi recursion

Initialization

$$v_1(j) = \pi_j b_j(o_1)$$
  $1 \le j \le N$   
 $bt_1(j) = 0$   $1 \le j \le N$ 

Recursion

$$egin{aligned} v_t(j) &= \max_{i=1}^N v_{t-1}(i) a_{ij} b_j\left(o_t
ight); & 1 \leq j \leq N, 1 < t \leq T \ bt_t(j) &= \operatorname{argmax}_{i=1}^N v_{t-1}(i) a_{ij} b_j\left(o_t
ight); & 1 \leq j \leq N, 1 < t \leq T \end{aligned}$$

Termination

The best score: 
$$P* = \max_{i=1}^{N} v_T(i)$$
  
The start of backtrace:  $q_{T^*} = \operatorname{argmax}_{i=1}^{N} v_T(i)$ 

#### Pseudocode

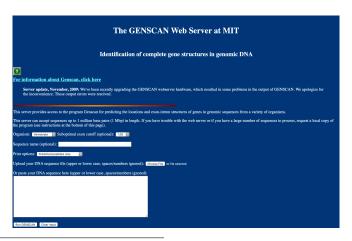
```
function VITERBI(observations of len T, state-graph of len N) returns best-path, path-prob
create a path probability matrix viterbi[N,T]
for each state s from 1 to N do
                                                                 ; initialization step
       viterbi[s,1] \leftarrow \pi_s * b_s(o_1)
       backpointer[s,1] \leftarrow 0
for each time step t from 2 to T do
                                                               : recursion step
   for each state s from 1 to N do
      \begin{aligned} \textit{viterbi}[s,t] \leftarrow & \underset{i'=1}{\overset{N}{\max}} \;\; \textit{viterbi}[s',t-1] \; * \; a_{s',s} \; * \; b_s(o_t) \\ \textit{backpointer}[s,t] \leftarrow & \underset{s}{\underset{m}{\max}} \;\; \textit{viterbi}[s',t-1] \; * \; a_{s',s} \; * \; b_s(o_t) \end{aligned}
\textit{bestpathprob} \leftarrow \max_{s=1}^{N} \ \textit{viterbi}[s,T] \hspace{1cm} ; \text{termination step}
bestpathpointer \leftarrow \underset{}{\operatorname{argmax}} viterbi[s, T]; termination step
return bestpath, bestpathprob
```

# Three fundamental problems [Rab89]

- ▶ **Problem 1 (Likelihood)** Given an HMM = (A, B) and an observation sequence O, determine the likelihood  $P(O|\lambda)$ .
- **Problem 2 (Decoding)** Given an observation sequence O and an HMM = (A, B), discover the best hidden state sequence Q.
- ▶ **Problem 3 (Learning)** Given an observation sequence *O* and the set of states in the HMM, learn the HMM parameters *A* and *B*.

# Application<sup>2</sup>





<sup>&</sup>lt;sup>2</sup>from the link

#### **GENSCAN**

GENSCAN was developed by Chris Burge in the research group of Samuel Karlin, Department of Mathematics, Stanford University [BK97, SSK98].

Burge and Karlin in their gene finding computer program GENSCAN used a three-periodic (inhomogeneous) fifth order Markov chain to model coding regions of DNA sequences [BE06].

# CpG island<sup>3</sup>

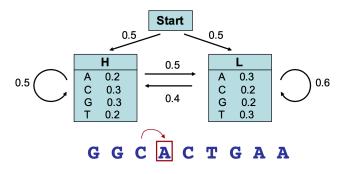
CATTCCGCCTTCTCTCCC \*GAGGTGG TGGGA GGTTCCGCTCCCAC GACAATGATTC CACTCTCGG CCTCCCATGTTGATCCCAGCTCCT GTCAGGACCCCTGGGCCC CTCCACTCAGTCAATCTTTTGTCCC GATTATCGGGGTGGCTGGGGG AATGCCCTTGGGGGTCACC GGAGGGAACTC GGCTCCGGCTTTGGCCAGCC AGGGCCACCAGGGGG ATGTTCCTGCAGCCCCC CAGCAGCCCCACTCC GCTCACCCTACGATTGGCTGGC CTCTGTGCTGTGATTGGTCACAGCC TGTC GGG GTGTCC AGGGC GGGCAGTGTGA GCAG GTCCTGGGAGG GAGCAGCTCCC CC CCCCTG GCTGAGGTAAGG GGGCTGGC GT GGGTTGGGGAGGG GGCCGCTTC GGGAGGAGCGGCCGGGCCGG GGTCCGGGCGGGGTCTGAGGGGA

CTCTTAGTTTTGGGTGCATTTGTCTGGTCTTCCAAA CTAGATTGAAAGCTCTGAAAAAAAAAAACTATCTTGT GTTTCTATCTGTTGAGCTCATAGTAGGTATCCAGGA AGTAGTAGGGTTGACTGCATTGATTTGGGACTACAC TGGGAGTTTTCTTCGCCATCTCCCTTTAGTTTTCCT TCTTGCTCAGTCCCCCAGGCTGGA GTGCAGTGGTGC( ATCTTGGCTCACTGTAGCCTCC ACCTCCCAGGTTCAAGCAATTCTACTGCCTTAGCCT CCCGAGTAGCTGGGATTACAAGCACCC TCCTGGCTAATTTTTTTTTTTTTTTTTTTAGTTGAGA CAGGGTTTCACCATGTTGGTGATGCTGGTCTCAGA CTCCTGGGGCCTAGCGATCCCCCTGCCTCAGCCT CCCAGAGTGTTAGGATTACAGGCATGAGCCACTGT CGCCTCTCTCCAGTTTCCAGTTGGAATCCAA GGGAAGTAAGTTTAAGATAAAGTTA CTTTGGATTCAGAAGAATTTGTCACCTTTAACACCT AGAGTTGAACGTTCATACCTGGAGAGCCTTAACAT AAGCCCTAGCCAGCCTCCAGCAAGTGGACATTGGT CAGGTTTGGCAGGATTCGTCCCCTGAAGTGGAC GAGAGCCACACCCTGGCCTGTCACCATACCCATCC CCTATCCTTAGTGAAGCAAAACTCCTTTGTTCCCT CTCCTTCTCCTAGTGACAGGAAATATTGTGATCCTA AAGAATGAAAATAGCTTGTCACCT GCCTCTTGACTTCAGG GTTCTGTTTAATCAAGT GACATCTTCC AGGCTCCCTGAATGTGGCAGATG AAAGAGACTAGTTCAACCCTGACCTGAGGGGAAAG CCTTTGTGAAGGGTCAGGAG

**Left**: CpG sites at 1/10 nucleotides, constituting a CpG island. The sample is of a gene-promoter, the highlighted ATG consitutes the start codon.

**Right**: CpG sites present at every 1/100 nucleotides, consituting a more normal example of the genome, or a region of the genome that is commonly methylated.

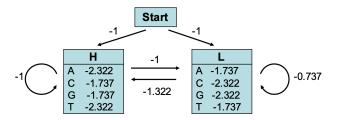
<sup>&</sup>lt;sup>3</sup>from the link



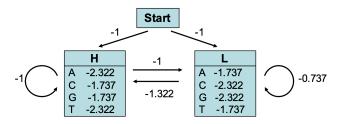
This model is composed of 2 states, H (high GC content) and L (low GC content). We can for example consider that state H characterizes coding DNA while L characterizes non-coding DNA.

$$p_H(A,4) = e_H(A) \max(p_L(C,3)p_{LH}, p_H(C,3)p_{HH})$$

<sup>&</sup>lt;sup>4</sup>example from the link



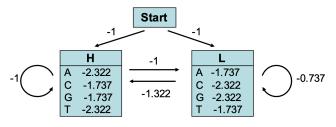
We used here log2(p), and compute sums instead of products.



#### **GGCACTGAA**

- Probability (in  $log_2$ ) that G at the first position was emitted by state H,  $p_H(G,1) = -1 1.737 = -2.737$
- ▶ Probability (in  $log_2$ ) that G at the first position was emitted by state L,  $p_L(G, 1) = -1 2.322 = -3.322$





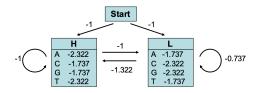
#### **GGCACTGAA**

- Probability (in  $log_2$ ) that G at the 2nd position was emitted by state H,  $p_H(G,2) = -1.737 + \max(p_H(G,1) + p_{HH}, p_L(G,1) + p_{LH})$ =  $-1.737 + \max(-2.737 - 1, -3.322 - 1.322)$ = -5.474 (obtained from  $p_H(G,1)$ )
- Probability (in  $log_2$ ) that G at the 2nd position was emitted by state L,  $p_L(G,2) = -2.322 + \max(p_H(G,1) + p_{HL}, p_L(G,1) + p_{LL})$

$$= -2.322 + \max(-2.737 - 1.322, -3.322 - 0.737)$$

 $=-6.059\,($  obtained from  $p_{H}(\mathrm{G},1))$ 

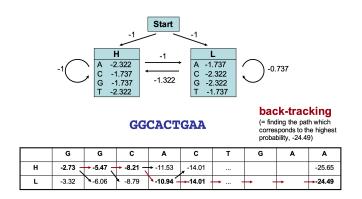




#### GGCACTGAA

	G	G	С	Α	С	Т	G	Α	Α
Н	-2.73	→-5.47	→ -8.21 —	<b>→</b> -11.53	-14.01				-25.65
L	-3.32	-6.06	-8.79	-10.94	<b>→</b> -14.01 -	<b>→</b>	<b>→</b> -	<b>→</b> -	<b>→</b> -24.49

We then compute iteratively the probabilities  $p_H(i,x)$  and  $p_L(i,x)$  that nucleotide i at position x was emitted by state H or L, respectively. The highest probability obtained for the nucleotide at the last position is the probability of the most probable path. This path can be retrieved by back-tracking.



The most probable path is: HHHLLLLLL

#### References I

- Mark Borodovsky and Svetlana Ekisheva, *Problems and solutions in biological sequence analysis*, Cambridge University Press, 2006.
- Chris Burge and Samuel Karlin, *Prediction of complete gene structures in human genomic dna*, Journal of molecular biology **268** (1997), no. 1, 78–94.
- Dan Jurafsky and James H. Martin, Speech and language processing (3rd ed. draft), 2019.
- Lawrence R Rabiner, A tutorial on hidden markov models and selected applications in speech recognition, Proceedings of the IEEE 77 (1989), no. 2, 257–286.
- SL Salzberg, DB Searls, and S Kasif, *Modeling dependencies* in pre-mrna splicing signals, Computational methods in molecular biology **32** (1998), 129.

#### References II