Partial Label Clustering -Appendix-

A Evaluation Metrics

We use Average Clustering Accuracy (ACC) and Normalized Mutual Information (NMI) metrics, both of which are widely used criteria in the field of clustering. ACC discovers the one-to-one relationship between clusters and classes. Denote c_i as the clustering result of sample x_i and g_i as the ground-truth label of sample x_i , ACC is defined as

$$ACC = \frac{1}{n} \sum_{i=1}^{n} \delta(c_i, map(g_i)),$$
 (S1)

where $\delta(p,q)=1$, if p=q and $\delta(p,q)=0$ otherwise. n is the total number of examples and $map(g_i)$ is the mapping function that permutes the clusters to match the ground-truth labels. NMI measures the mutual information entropy between the clusters and the ground-truth labels. Given the ground-truth labels \mathbf{Y} and the clustering results \mathbf{C} , NMI is defined as

$$NMI = \frac{\sum_{y \in \mathbf{Y}, c \in \mathbf{C}} p(y, c) log(\frac{p(y, c)}{p(y)p(c)})}{\sqrt{\sum_{y \in \mathbf{Y}} p(y) \log p(y) \sum_{c \in \mathbf{C}} p(c) \log p(c)}}, \quad (S2)$$

where p(y) and p(c) represent the marginal probability distribution functions of **Y** and **C** respectively, and p(y,c) is the joint distribution.

B Proof of Theorem 1

We first give a lemma as follows.

Lemma 1.

$$\operatorname{Tr}(\boldsymbol{A}\boldsymbol{B}) \le ||\boldsymbol{A}||_F ||\boldsymbol{B}||_F. \tag{S3}$$

Proof. By Cauchy-Schwarz, we have

$$\operatorname{Tr}(\mathbf{AB}) = \sum_{i,j} a_{ij} b_{ji}$$

$$\leq \sum_{i} (\sum_{j} |a_{ij}|^{2})^{1/2} (\sum_{j} |b_{ji}|^{2})^{1/2}$$

$$\leq (\sum_{i,j} |a_{ij}|^{2})^{1/2} (\sum_{i,j} |b_{ji}|^{2})^{1/2}$$

$$= ||\mathbf{A}||_{F} ||\mathbf{B}||_{F}.$$
(S4)

This concludes the proof.

Now we begin the proof of Theorem 1.

Proof. Denote $\mathbf{F} \in [0,1]^{n \times q}$ and $\mathbf{W} \in [0,1]^{n \times n}$ the label confidence matrix and the weight matrix to be optimized. For the convenience of explanation, the terms related to \mathbf{F} in the objective function Eq. (2) can be rewritten as

$$\min_{\mathbf{W}} ||\mathbf{F} - \mathbf{W}\mathbf{F}||_{F}^{2}$$
s.t. $w_{ij} = 0$ if $(\mathbf{x}_{i}, \mathbf{x}_{j}) \notin \mathcal{E}$, (S5)
$$\mathbf{W}^{\mathsf{T}} \mathbf{1}_{n} = \mathbf{1}_{n}, \mathbf{0}_{n \times n} < \mathbf{W} < \mathbf{N}.$$

Let \mathbf{F}_G and \mathbf{W}_G be the ground-truth label matrix and the optimal weight matrix under the ground-truth labels. We assume that \mathbf{W}_G is constructed on the premise that the ground-truth labels of neighboring examples are the same, which can improve clustering performance. Due to the constraint of $\mathbf{W}_G^{\top}\mathbf{1}_n = \mathbf{1}_n$, we have $||\mathbf{F}_G - \mathbf{W}_G\mathbf{F}_G||_F^2 = 0$. Denote $\Delta_{\mathbf{W}} = \mathbf{W}_G - \mathbf{W}$, the following inequality holds

$$||\mathbf{F}_G - (\Delta_{\mathbf{W}} + \mathbf{W})\mathbf{F}_G||_F^2 \le ||\mathbf{F} - \mathbf{W}\mathbf{F}||_F^2.$$
 (S6)

Expand Eq. (S6), we have

$$||\Delta_{\mathbf{W}}\mathbf{F}_{G}||_{F}^{2}$$

$$\leq ||\mathbf{F}||_{F}^{2} + \operatorname{Tr}(\mathbf{W}^{\top}\mathbf{W}(\mathbf{F}^{\top}\mathbf{F} - \mathbf{F}_{G}^{\top}\mathbf{F}_{G}))$$

$$+ \operatorname{Tr}((\mathbf{W} + \mathbf{W}^{\top})(\mathbf{F}_{G}^{\top}\mathbf{F}_{G} - \mathbf{F}^{\top}\mathbf{F})) - ||\mathbf{F}_{G}||_{F}^{2}$$

$$+ \operatorname{Tr}(\mathbf{F}_{G}^{\top}\mathbf{F}_{G}((\mathbf{I} - \mathbf{W})^{\top}\Delta_{\mathbf{W}} + (\mathbf{I} - \mathbf{W})\Delta_{\mathbf{W}}^{\top})).$$
(S7)

According to Lemma 1 and the fact that the Frobenius norm is submultiplicative, we have

$$\begin{aligned} &||\Delta_{\mathbf{W}}\mathbf{F}_{G}||_{F}^{2} \\ &\leq ||\mathbf{F}||_{F}^{2} - ||\mathbf{F}_{G}||_{F}^{2} + 2||\mathbf{F}_{G}||_{F}^{2}||\mathbf{I} - \mathbf{W}||_{F}||\Delta_{\mathbf{W}}||_{F} \\ &(||\mathbf{W}||_{F}^{2} + 2||\mathbf{W}||_{F})||\mathbf{F}^{\top}\mathbf{F} - \mathbf{F}_{G}^{\top}\mathbf{F}_{G}||_{F}. \end{aligned}$$
(S8)

Since **W** is upper bounded by the number of samples n, we have $||\mathbf{W}||_F^2 \leq n^2$ and $||\mathbf{I} - \mathbf{W}||_F^2 \leq n^2$. Due to \mathbf{F}_G is the ground-truth label matrix, we have $||\mathbf{F}_G||_F^2 = n$. Furthermore, **F** is upper bounded by the number of samples n and the number of classes q, i.e., $||\mathbf{F}||_F^2 \leq nq$. Assume that $||\Delta_{\mathbf{W}}||_F \geq 1$, which is a reasonable assumption when n is large enough. We have

$$||\Delta_{\mathbf{W}}\mathbf{F}_{G}||_{F}^{2} \leq (n^{2} + 2n)||\mathbf{F}^{\top}\mathbf{F} - \mathbf{F}_{G}^{\top}\mathbf{F}_{G}||_{F}||\Delta_{\mathbf{W}}||_{F} + (2n^{2} + nq - n)||\Delta_{\mathbf{W}}||_{F}.$$
(S9)

| Controlled UCI Datasets | | | | | | | | |
|-------------------------|------------|------------|----------------|-----------------------------|--|--|--|--|
| Dataset | # Examples | # Features | # Class Labels | # False Positive Labels (r) | | | | |
| Ecoli | 336 | 7 | 8 | r = 1, 2, 3 | | | | |
| Vehicle | 846 | 18 | 4 | r = 1, 2 | | | | |
| Coil20 | 1440 | 1024 | 20 | r = 1, 2, 3 | | | | |

| Real-World Datasets | | | | | | | | | |
|---------------------|--------------------|------|----------------|-----------|--------------------------|--|--|--|--|
| Dataset | Dataset # Examples | | # Class Labels | Avg.# CLs | Task Domain | | | | |
| Lost | 1122 | 108 | 16 | 2.23 | automatic face naming | | | | |
| MSRCv2 | 1758 | 48 | 23 | 3.16 | object classification | | | | |
| Mirflickr | 2780 | 1536 | 14 | 2.76 | web image classification | | | | |
| BirdSong | 4998 | 38 | 13 | 2.18 | bird song classification | | | | |
| LYN10 | 16526 | 163 | 10 | 1.84 | automatic face naming | | | | |

Table S1: Characteristics of controlled UCI datasets and real-world datasets.

| Compared | LYN10 | | | |
|------------|--------------------------------|------------------------------|--|--|
| Method | $\rho = 0.01$ | $\rho = 0.02$ | | |
| PLC (Ours) | $\boldsymbol{0.525 \pm 0.024}$ | 0.556 ± 0.010 | | |
| DPCLS | 0.485 ± 0.016 | 0.523 ± 0.020 | | |
| AGGD | 0.493 ± 0.016 | 0.538 ± 0.019 | | |
| IPAL | 0.468 ± 0.015 | 0.522 ± 0.013 | | |
| PL-kNN | 0.394 ± 0.025 | 0.426 ± 0.016 | | |
| PL-SVM | 0.485 ± 0.038 | 0.542 ± 0.016 | | |
| PARM | 0.497 ± 0.010 | 0.550 ± 0.018 | | |
| SSPL | $\overline{0.445 \pm 0.041}$ | $\overline{0.482 \pm 0.021}$ | | |

Table S2: ACCs when compared with PLL and semi-supervised PLL methods on large-scale dataset, where bold and underlined indicate the best and second best results respectively.

Note that $\mathbf{F}_G^{\top}\mathbf{F}_G$ is a positive semidefinite matrix, thus its eigenvalues are non-negative. Taking λ as the smallest eigenvalue of $\mathbf{F}_G^{\top}\mathbf{F}_G$, we have $\lambda||\Delta_{\mathbf{W}}||_F^2 \leq ||\Delta_{\mathbf{W}}\mathbf{F}_G||_F^2$. Thus, Eq. (S9) can be further relaxed as

$$\lambda ||\Delta_{\mathbf{W}}||_F^2 \le (n^2 + 2n)||\mathbf{F}^{\top}\mathbf{F} - \mathbf{F}_G^{\top}\mathbf{F}_G||_F ||\Delta_{\mathbf{W}}||_F + (2n^2 + nq - n)||\Delta_{\mathbf{W}}||_F.$$
 (S10)

Let $||\overline{\Delta}_{\mathbf{W}}||_F$ be the average distance of each corresponding position between \mathbf{W}_G and \mathbf{W} , i.e., $||\overline{\Delta}_{\mathbf{W}}||_F = \frac{1}{n^2}||\mathbf{W}_G - \mathbf{W}||_F$. Dividing n^2 on both sides of Eq. (S10), we finally have

$$||\overline{\Delta}_{\mathbf{W}}||_F \le \frac{n+2}{\lambda n} ||\mathbf{F}^{\mathsf{T}}\mathbf{F} - \mathbf{F}_G^{\mathsf{T}}\mathbf{F}_G||_F + \frac{2n+q-1}{\lambda n}.$$
 (S11)

This concludes the proof of Theorem 1. \Box

C Complexity Analysis

The computational complexity of our algorithm is dominated by steps 7-11. Before alternative optimization, we use the KD-Tree method to find the k nearest neighbors for each sample in the dataset with the complexity of $\mathcal{O}(kn\log n)$. In steps 7-9, we use interior point method [Ye and Tse, 1989] to solve a series of QP problems with the complexity of $\mathcal{O}(nk^3)$. Similarly, step 10 solves a QP problem with the

complexity of $\mathcal{O}(n^3q^3)$. When dealing with large datasets, we can transform the original problem into a series of subproblems as Eq. (9) with the complexity of $\mathcal{O}(nq^3)$. Step 11 solves the problem by KKT conditions with the complexity of $\mathcal{O}(n^3)$. In summary, the overall complexity of our algorithm in each iteration is $\mathcal{O}(kn\log n + nk^3 + n^3q^3 + n^3)$ and $\mathcal{O}(kn\log n + nk^3 + nq^3 + n^3)$ for large datasets.

D Details of Compared Datasets

Table S1 summarizes the characteristics of controlled UCI datasets and real-world datasets. Following the widely-used partial label data generation protocol [Cour *et al.*, 2011], we generate artificial partial label datasets under the parameter r which controls the number of false-positive labels¹.

The real-world datasets are collected from various domains including Lost [Cour *et al.*, 2009] for automatic face naming, MSRCv2 [Liu and Dietterich, 2014] for object classification, Mirflickr [Huiskes and Lew, 2008] for web image classification and BirdSong [Raich, 2012] for bird song classification.

E Supplementary Experimental Results

E.1 More Comparison to Constrained Clustering

Fig. S1 illustrates the ACCs and NMIs of our PLC method compared to the constrained clustering methods on the datasets Ecoli r=3 and Coil20 r=3. Our PLC method ranks first in 87.5% (21/24) cases which further proves the effectiveness of our PLC method.

E.2 More Comparison to PLL & Semi-supervised PLL

Fig. S2 illustrates the ACCs of our PLC method compared to the PLL and semi-supervised PLL methods on synthetic UCI datasets. Our PLC method achieves superior or competitive performance against the comparing methods with a lower proportion of partial labeled samples. According to Fig. S2, PLC method achieves superior performance against PL-KNN and PL-SVM in 100% (32/32) cases, against IPAL, DP-CLS, PARM and SSPL in 96.88% (31/32) cases, and against

 $^{^{1}}$ For Vehicle, the setting r=3 is not considered as there are only four class labels in the label space

| Compared | LYN10 | | | | | | | |
|------------|-------------------|--------------------------------|-------------------|-------------------|-------------------|-------------------|--|--|
| Method | $\rho = 0.05$ | $\rho = 0.10$ | $\rho = 0.15$ | $\rho = 0.20$ | $\rho = 0.30$ | $\rho = 0.40$ | | |
| PLC (Ours) | 0.595 ± 0.007 | $\boldsymbol{0.624 \pm 0.008}$ | 0.643 ± 0.011 | 0.659 ± 0.007 | 0.670 ± 0.010 | 0.675 ± 0.009 | | |
| K-means | 0.372 ± 0.033 | 0.366 ± 0.022 | 0.366 ± 0.023 | 0.371 ± 0.019 | 0.366 ± 0.031 | 0.361 ± 0.018 | | |
| SC | 0.301 ± 0.005 | 0.299 ± 0.007 | 0.304 ± 0.008 | 0.297 ± 0.006 | 0.307 ± 0.008 | 0.302 ± 0.010 | | |
| SSC-TLRR | 0.379 ± 0.007 | 0.415 ± 0.010 | 0.467 ± 0.006 | 0.392 ± 0.024 | 0.382 ± 0.012 | 0.423 ± 0.008 | | |
| DP-GLPCA | 0.278 ± 0.011 | 0.284 ± 0.009 | 0.287 ± 0.009 | 0.287 ± 0.008 | 0.292 ± 0.013 | 0.299 ± 0.012 | | |
| SSSC | 0.340 ± 0.011 | 0.346 ± 0.009 | 0.362 ± 0.010 | 0.358 ± 0.011 | 0.351 ± 0.019 | 0.332 ± 0.011 | | |

Table S3: Experimental results on ACCs when compared with constrained clustering methods on large-scale datasets, where bold and underlined indicate the best and second best results respectively.

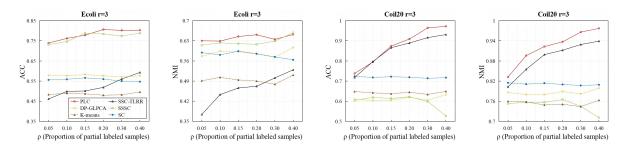


Figure S1: ACCs and NMIs when compared with constrained clustering methods under different proportions of partial label training samples on the datasets Ecoli r=3 and Coil20 r=3.

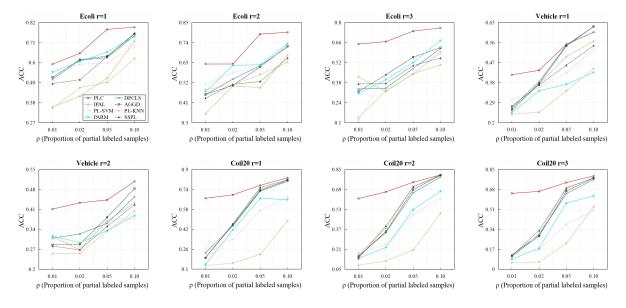


Figure S2: ACCs when compared with PLL and semi-supervised PLL methods under different proportions of partial label training samples on synthetic UCI datasets.

| | DPCLS | AGGD | IPAL | PL-SVM | PL-KNN | SSPL | PARM | SSC-TLRR | DP-GLPCA | SSSC |
|-------|---------|---------|--------|--------|--------|--------|--------|----------|----------|---------|
| (i) | 11/6/1 | 11/7/1 | 14/4/0 | 17/1/0 | 18/0/0 | 16/2/0 | 17/1/0 | 30/0/0 | 30/0/0 | 30/0/0 |
| (ii) | 28/4/0 | 25/6/1 | 29/3/0 | 32/0/0 | 32/0/0 | 27/5/0 | 32/0/0 | 31/17/0 | 48/0/0 | 35/13/0 |
| Total | 39/10/1 | 36/13/1 | 43/7/0 | 49/1/0 | 50/0/0 | 43/7/0 | 49/1/0 | 61/17/0 | 78/0/0 | 65/13/0 |

Table S4: Win/tie/loss counts on the classification performance of PLC against the PLL, semi-supervised PLL and constrained clustering methods on all datasets. (i), (ii) indicate the summaries on real-world datasets and synthetic UCI datasets. "Total" denotes the summary on all the datasets.

AGGD in 93.75% (30/32) cases. The experimental results further prove that our PLC method performs well in the case of fewer partial label training samples.

E.3 Experiment on Large-scale Dataset

LYN10 is a large-scale dataset for automatic face naming, consisting of samples from the top 10 classes of the Yahoo!News [Guillaumin *et al.*, 2010] dataset. The characteristics of LYN10 are shown in Table S2. Table S2 reports the ACCs of our PLC method compared to PLL and semi-supervised PLL methods on the large-scale dataset. Table S3 reports the ACCs of our PLC method compared to constrained clustering methods on the large-scale dataset. Our PLC method performs well on the large-scale dataset and ranks first in all experimental settings.

E.4 Significance Analysis

Table S4 reports win/tie/loss counts between our PLC methods and ten comparing methods on the real-world datasets and synthetic UCI datasets according to the pairwise ttest at the significance level of 0.05. We can find that our PLC method statistically outperforms the PLL and semi-supervised PLL methods (the first seven columns) in 88.3% (309/350) cases and statistically outperforms the constrained clustering methods (the last three columns) in 87.2% (204/234) cases.

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