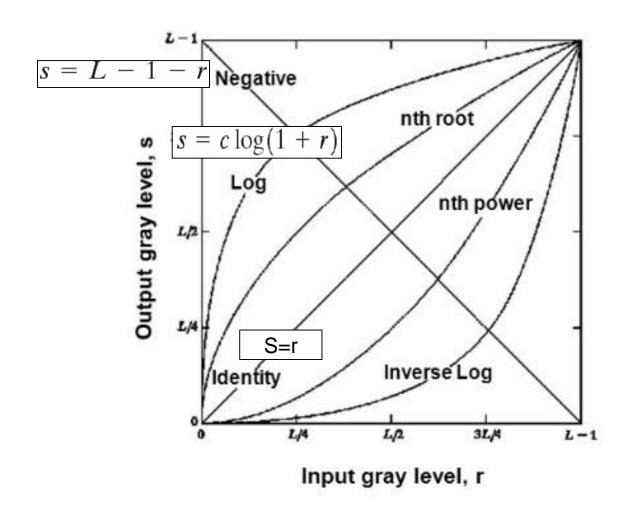
## 電腦視覺原理及應用簡介

Lab2 Enhancement

# Point Processing: Gray-level transformation function



#### Negative transformation

• S = L - 1 - r

```
import cv2
import numpy as np
image = cv2.imread('detention_1.jpg', cv2.IMREAD_GRAYSCALE)
transfer img = 255 - image
                                                               137 141 138 ... 32 32 31]
148 146 139 ... 32 32 32]
155 147 138 ... 32 33 33]
transfer img = transfer img.astype(np.uint8)
cv2.imshow("Image", image)
cv2.imshow("Output", transfer img)
cv2.waitKey(0)
                                                                           Numpy array
cv2.destroyAllWindows()
```

### Demo





### Log transformation

- $S = c \log(1+r)$
- c is a constant. For r varying between 0 and 255, output results in 0 and 2.41 where c=1. So, the range [0, 2.41] should be mapped to [0, L-1] for getting a meaningful image.





#### Assignment

- 將彩色圖片變灰階後分一半,一邊負片轉換,一邊 Log轉換,把轉換結果寫出
- 完成請繳交程式碼與圖片,以學號命名壓縮檔

#### Hint:

- 1. 對每個pixel做轉換
- 2. Log transformation (S = c log(1+r) ),調整好c的值

#### Demo

