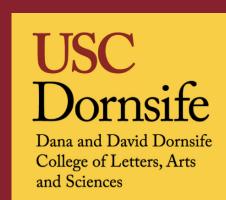
A Computational Model of Executive Function in a Food Preference Task Xiaoyuan Zhu, Jiaqi Fan, Xiao Liu, Xinpeng Diao, Stephen Read



TL;DR

We developed a computational model for executive function and cognitive inhibition, demonstrated by a food preference task in which the presence of a dieting goal biases food choice (\$\subsete\$ \$I\$ \$\mathref{p}\$\$). The model demonstrates:

- A computational personality model* as basis
- A higher-order goal in biasing decision-making
- A higher-order goal in biasing the reward value, and subsequent reinforcement learning

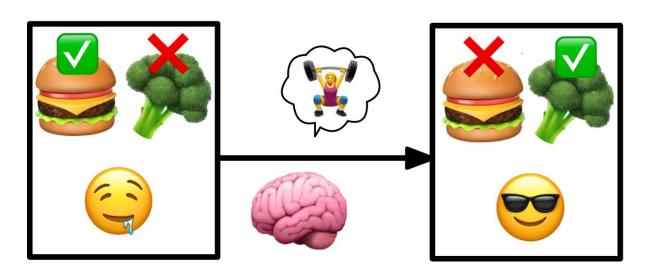


Fig 1. The food preference task: the food choice is biased by a higher-order goal (**)

MODEL DESIGN

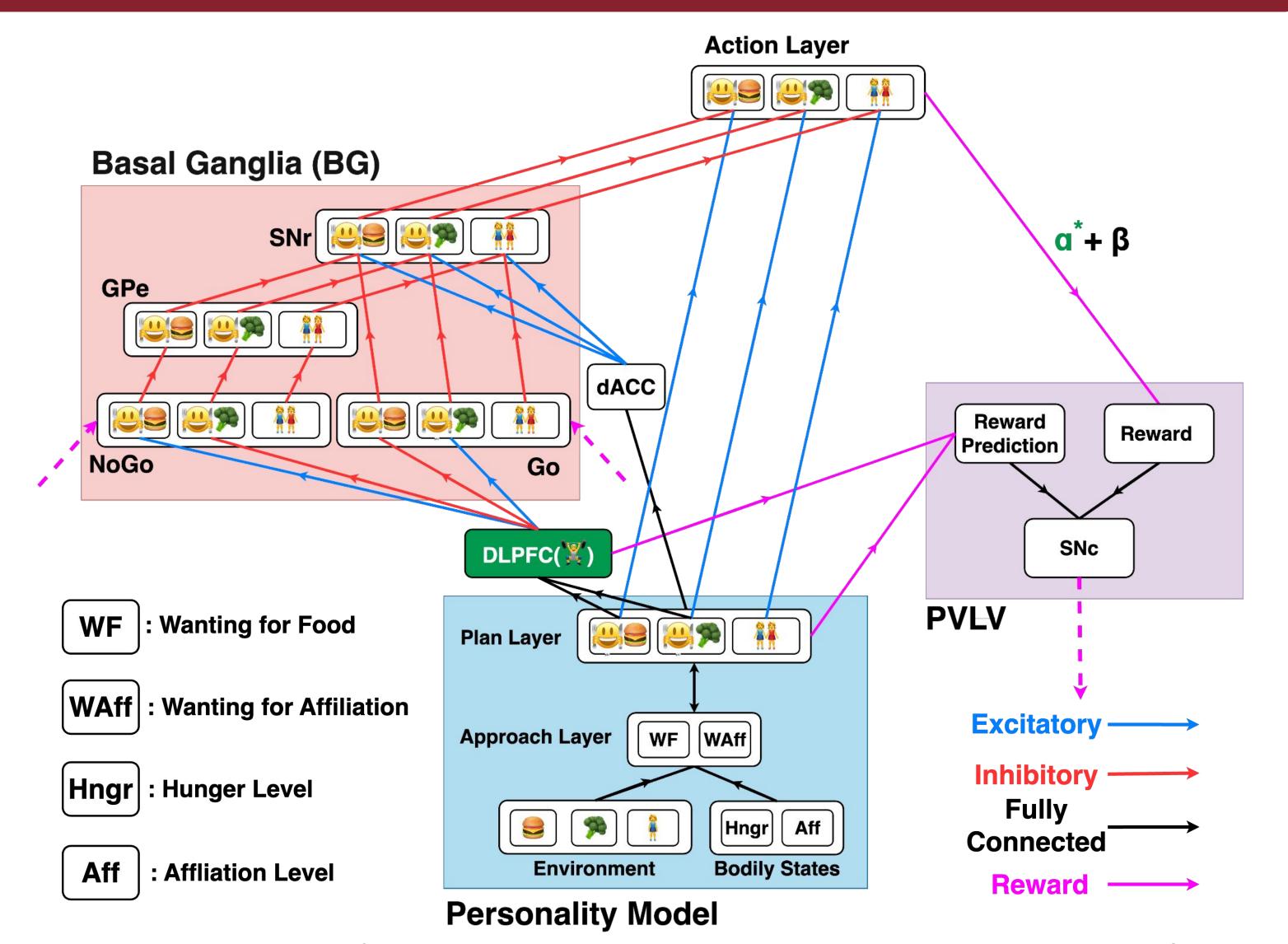


Fig 2. Visualization of the computational model with a higher-order goal biasing in DLPFC

MODEL DETAILS

- Personality model: proposes action plan
- BG: gates plans based on predicted reward
- DLPFC: maintains dieting goal that biases gating
- PVLV: learns from cognitive reward (α*) and sensory reward (β) from action, updates BG

RESULTS Environment | Bodily States | Approach | Plan | -1.0 | -0.5 | -0.5 | -0.0 | -0.5 | -0.0 | -0.5 | -0.0 | -0.5 | -0.0 | -0.5 | -0.0 | -0.5 | -0.0 | -0.5 | -0.0 | -0.5 | -0.0 | -0.5 | -0.0 | -0.5 | -0.0 | -0.5 | -0.0 | -0.5 | -0.0 | -0.5 | -0.0 | -0.5 | -0.0 | -0.5 | -0.0 | -0.5 | -0.0 | -0.5 | -0.0 | -0.5 | -0.5 | -0.0 | -0.5 | -0.5 | -0.0 | -0.5 | -0.5 | -0.0 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -0.5 | -

Fig 3. Neuron Activations for the Motivational Model

^{*} Read, Stephen J, and Lynn C Miller. "A Neural Network Model of Motivated Decision-Making in Everyday Social Behavior." Social-Behavioral Modeling for Complex Systems, by Paul K. Davis et al., 29 Mar. 2019.