

Advanced Quantitative Research Methodology, Lecture Notes: Theories of Inference¹

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The Problem of Inference

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3. A more reasonable, limited goal. Let $M = \{M^*, \theta\}$, where M^* is assumed & θ is to be estimated:

$$P(\theta|y, M^*) \equiv P(\theta|y)$$

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8. The two differ on the rest

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6. $L(\theta|y)$ is a function: for y fixed at the observed values, it gives the “likelihood” of any value of θ .

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10. The **likelihood principle**: the data only affect inferences through the likelihood function

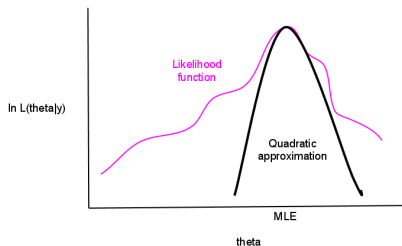
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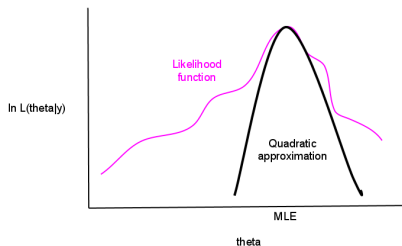
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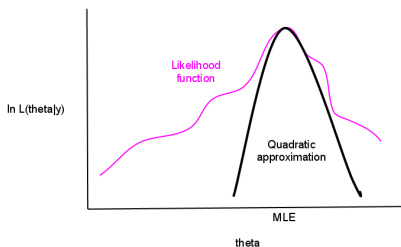
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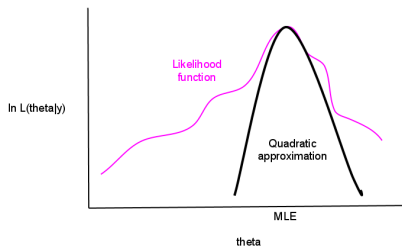
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- Uncertainty of point estimate: **curvature at the maximum**

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- $P(\theta)$, the prior density — the way Bayes differs from likelihood

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2. An **opportunity**: a way of getting other information outside the data set into the model
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4. A **philosophical assumption** that nonsample information should matter (as it always does) *and* be formalized and included in all inferences.

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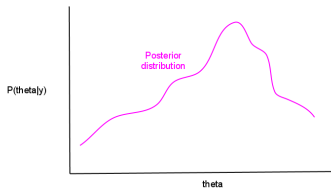
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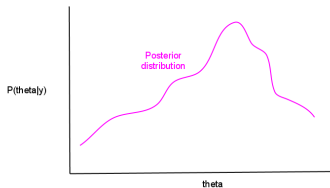
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4. If variables A and B are both unknown, then the distribution of A alone is $P(A) = \int P(A, B)dB = \int P(A|B)P(B)dB$.

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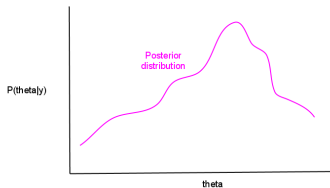


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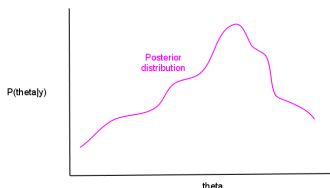
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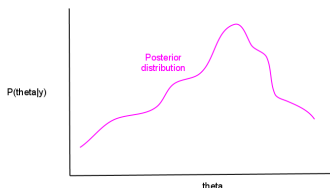
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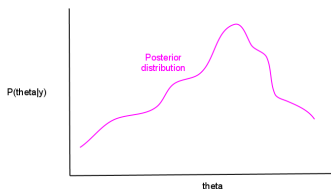
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- **Bayesian inference** obeys the **likelihood principle**: the data set only affects inferences through the likelihood function
- If $P(\theta) = 1$, i.e., is uniform in the relevant region, then $L(\theta|y) = P(\theta|y)$.

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- Few fights now between Bayesians and likelihoodists

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- Then $b|(\beta = 0) \sim N(0, \sigma_b^2)$

A 3rd Theory: Neyman-Pearson Hypothesis Testing

- ① Huge fights between these folks and the {Bayesians, Likelihoodists}
- ② Strict but arbitrary distinction: null H_0 vs alternative H_1 hypotheses
- ③ All tests are “under” (i.e., assuming) H_0

For example, is $\beta = 0$ in $E(Y) = \beta_0 + \beta X$?

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- or

$$(TS)_\beta | (\beta = 0) \equiv \frac{b - \beta}{\hat{\sigma}_b} \equiv \frac{b}{\hat{\sigma}_b} \sim N(0, 1).$$

Neyman-Pearson Hypothesis Testing

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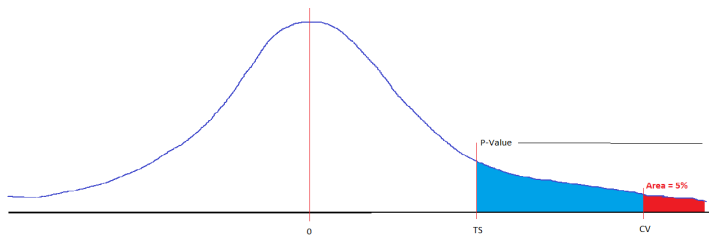
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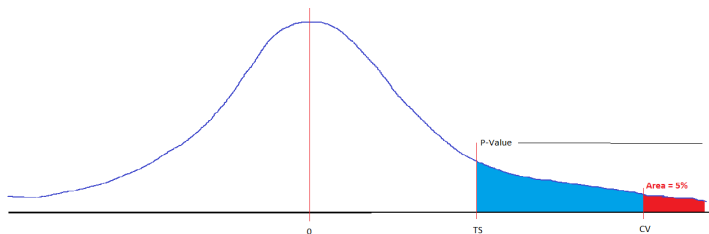
And then first collect your data. You may not revise your hypothesis or your theory.

Neyman-Pearson Hypothesis Testing

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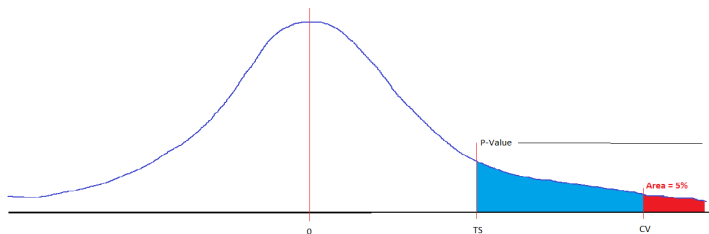


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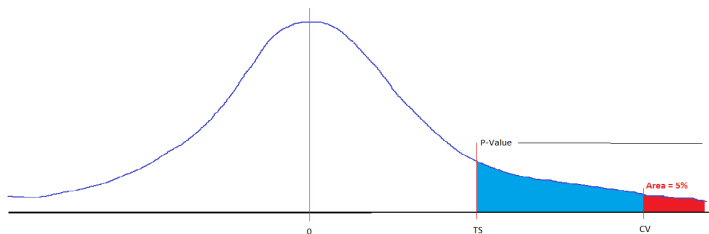
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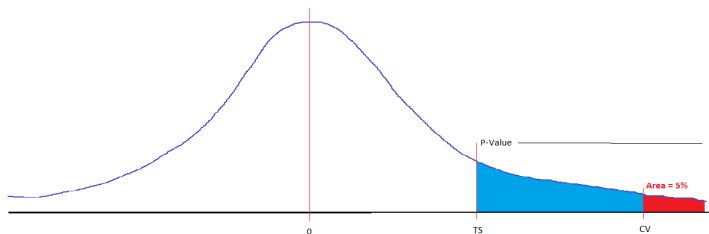
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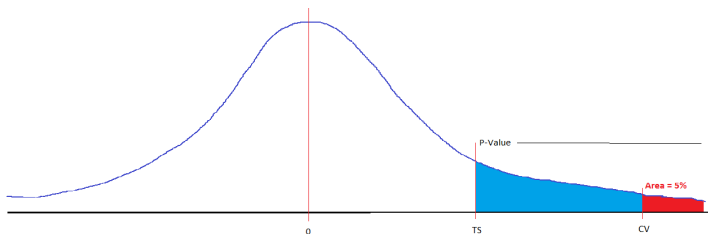
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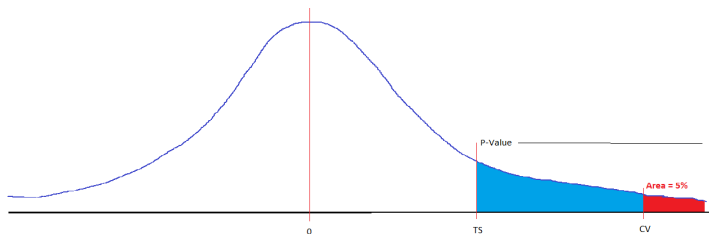
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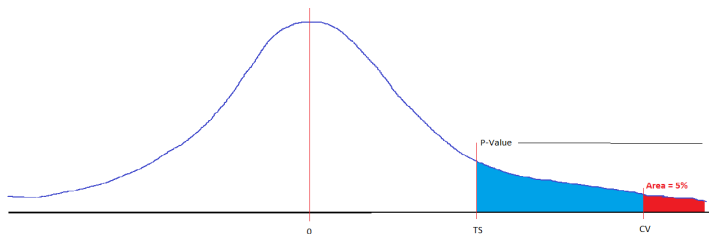
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4. Methods for applied researchers: either useful or irrelevant

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- The key: No assumptions can be trusted; all theories of inference condition on assumptions and so data analysts always struggle trying to understand and get around them

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- What can you do with this probability density?

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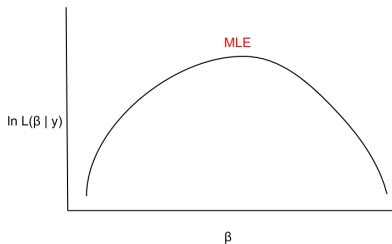
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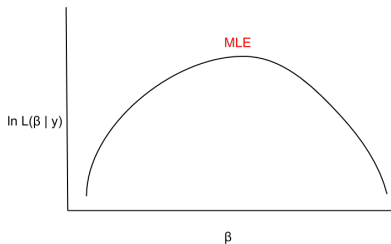
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Log-likelihood interpretation

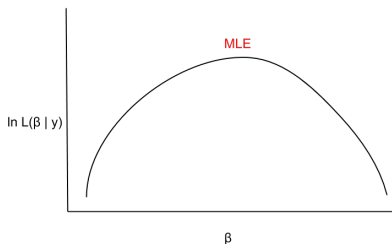


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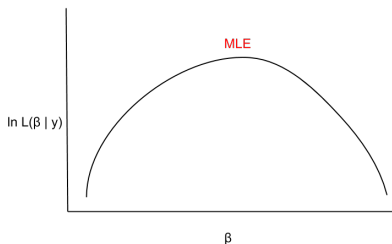
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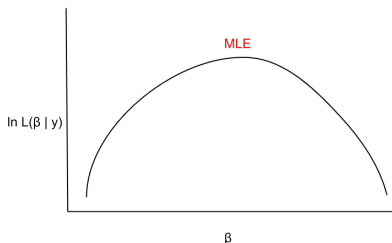
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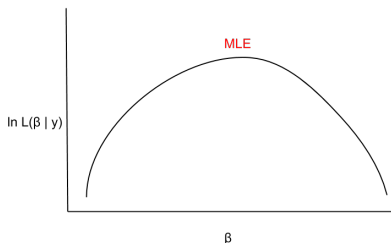
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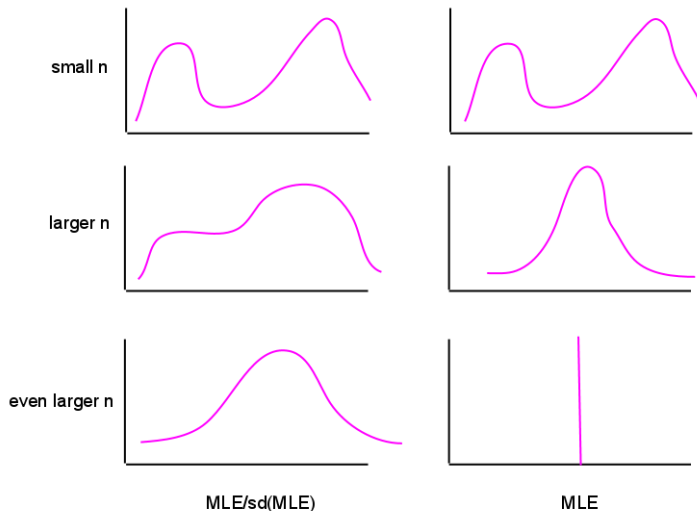
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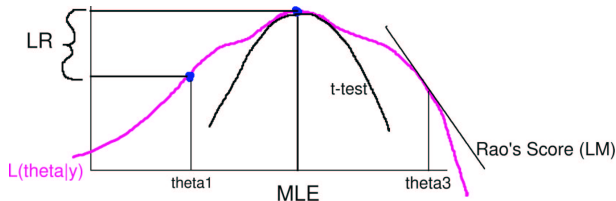
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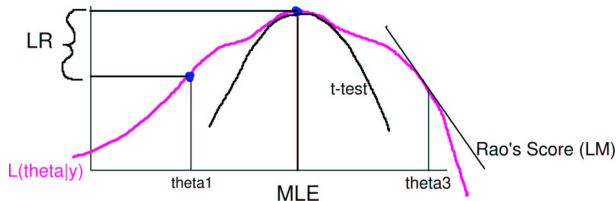
Sampling distributions of the MLE: CLT vs LLN



Uncertainty: Likelihood Ratios for nested models

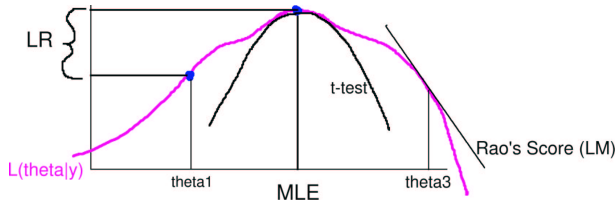


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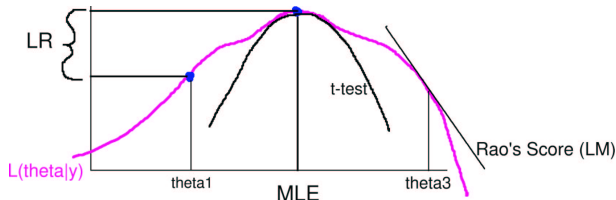
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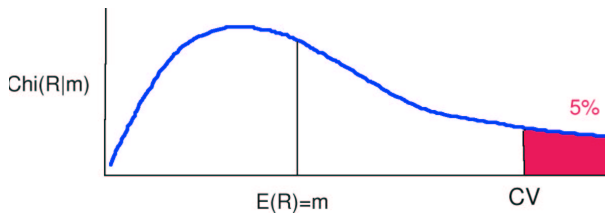
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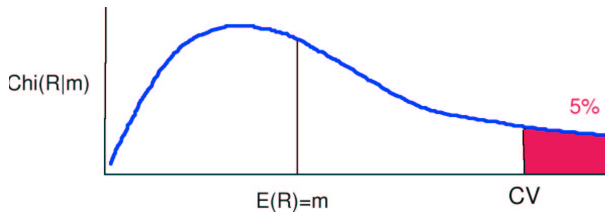
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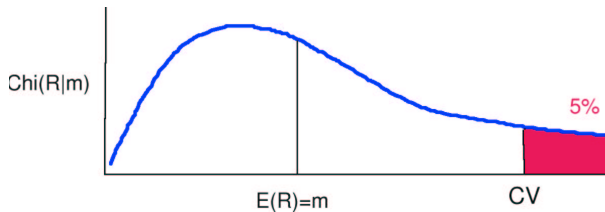


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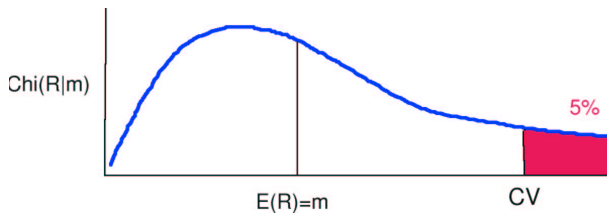
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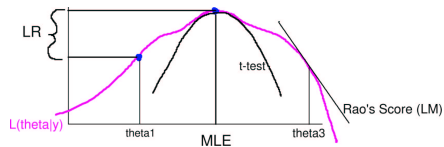
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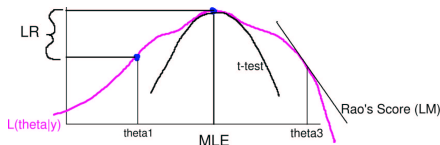
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- Disadvantage: Too many likelihood ratio tests may be required to test all points of interest

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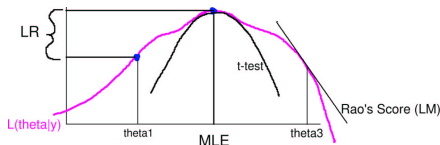


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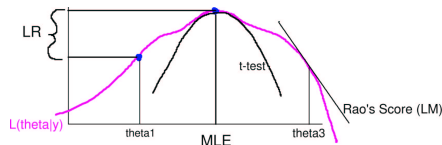
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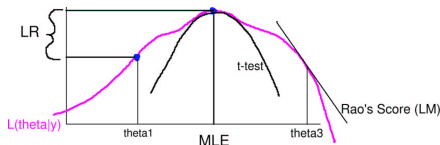
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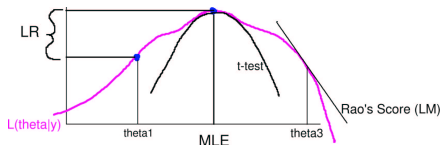
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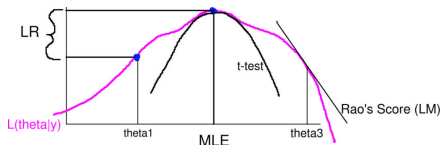
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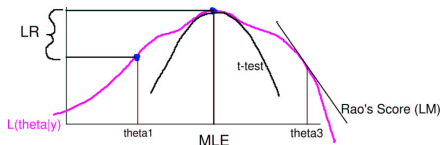
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$$\hat{V}(\hat{\theta}) = \left[-\frac{\partial^2 \ln L(\theta|y)}{\partial \theta \partial \theta'} \right]_{\theta=\hat{\theta}}^{-1} = \begin{pmatrix} \hat{\sigma}_1^2 & \hat{\sigma}_{12} & \dots \\ \hat{\sigma}_{21} & \hat{\sigma}_2^2 & \dots \\ \vdots & \vdots & \ddots \end{pmatrix}$$

- Statistical interpretation: variance and covariance across repeated samples
 - Works in general for a k -dimensional θ vector
 - Can be computed numerically
 - Known as the variance matrix, or variance-covariance matrix, or covariance matrix
9. This is an **estimate** of a **quadratic approximation** to the log-likelihood.

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Forecasting Presidential Elections.

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E_i	The number of electoral college votes for each state in 2016

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$$\begin{aligned} L(\mu_{it}, \sigma | y_{it}) &\propto N(y_{it} | \mu_{it}, \sigma^2) \\ &= (2\pi\sigma^2)^{-1/2} e^{-\frac{(y_{it} - \mu_{it})^2}{2\sigma^2}} \end{aligned}$$

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Estimation

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- Compute and save $\hat{V}(\hat{\theta})$, which is $k + 2 \times k + 2$

R Code for the Log-Likelihood

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- Mathematical Form:

$$\ln L(\beta, \sigma^2 | y) = \sum_{i=1}^n \sum_{t=1}^T -\frac{1}{2} \left[\ln \sigma^2 + \frac{(y_{it} - X_{it}\beta)^2}{\sigma^2} \right]$$

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- An R function:

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ll.normal <- function(par, X, Y) {  
  X <- as.matrix(cbind(1, X))  
  beta <- par[1:ncol(X)]  
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- Calling it:

```
ll.normal(c(2,1,2,1,33,4,3.2),x,y)  
ll.normal(c(2,1,2,1,33,4,3.7),x,y)  
ll.normal(c(2,1,2,1,33,4,3.5),x,y)
```

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- Repeat Steps 1–3 $M = 1,000$ times, and plot a histogram of the results.

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4. Add fundamental uncertainty: draw $\tilde{y}_{i,2016} \sim N(\tilde{\mu}_{i,2016}, \tilde{\sigma}^2)$

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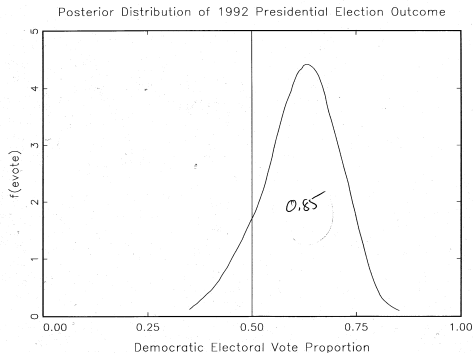
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 - Or, in our preferred notation, draw $\tilde{y}_{i,2016}$ from $N(X_{i,2016}\tilde{\beta}, \tilde{\sigma}^2)$

Actual Results (calculated before the election) for 1992

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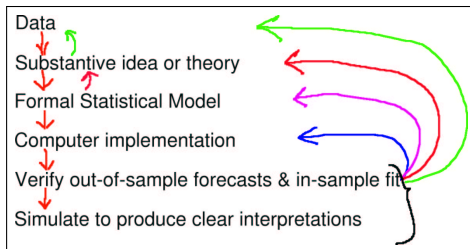
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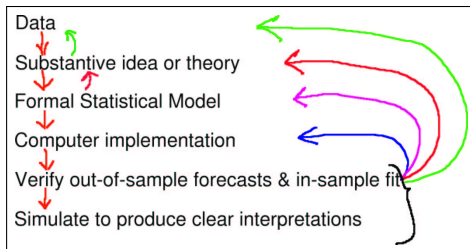
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- For what applications would this model be informative?

An Outline of the Research Process

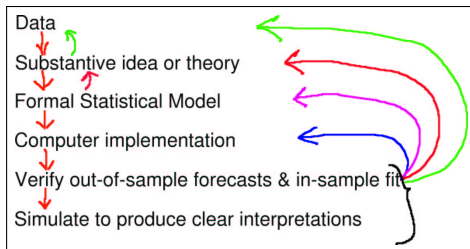


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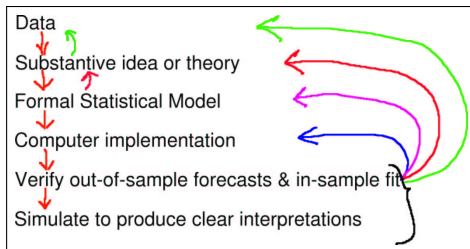
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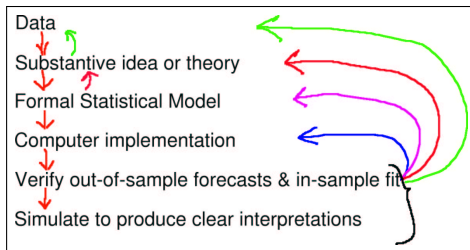
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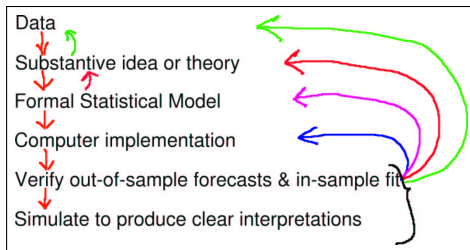
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5. Don't miss any parts.