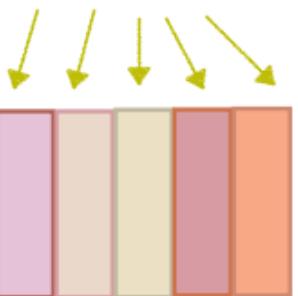


Random noise



Shape Diffusion

$$\hat{\sigma}_s^0 \hat{\sigma}_s^1 \dots \hat{\sigma}_s^L \hat{s}_i$$



Shape Dictionary

Condition



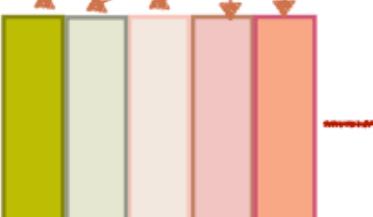
Initial shape

Random noise



Motion Diffusion

$$\hat{m}^t \hat{\sigma}_m^0 \hat{\sigma}_m^1 \dots \hat{\sigma}_m^L$$



Motion Dictionary

t



4D deforming shapes over time