

Development of an optimal filtering method for Ultra-Light Dark Matter search with GW detectors

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Collaborator: Soichiro Morisaki, Jun'ya Kume

Contents

* Dark Matter search with Gravitational Wave detectors

- Ultra-Light Dark Matter and ULDM models
- A problem with data analysis

* Approach with an optimal filtering method

- Correlation of the ULDM signals
- Optimal filter for the signals
- Application to simulated data and comparison with a previous method

* Discussion

- DM model selection

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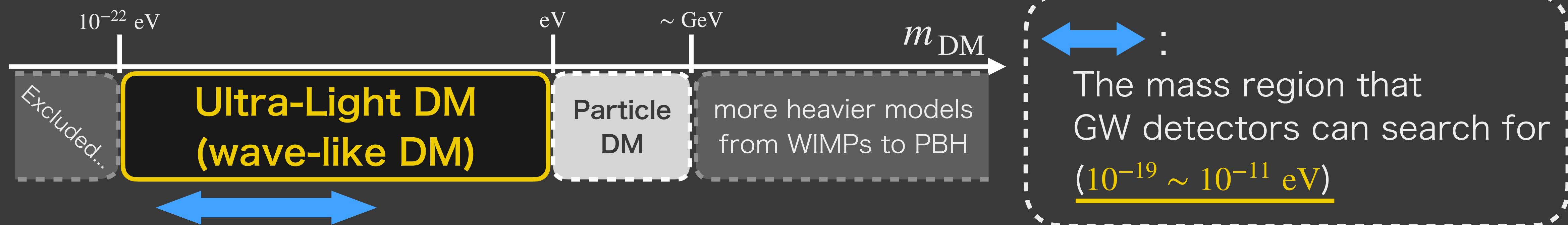
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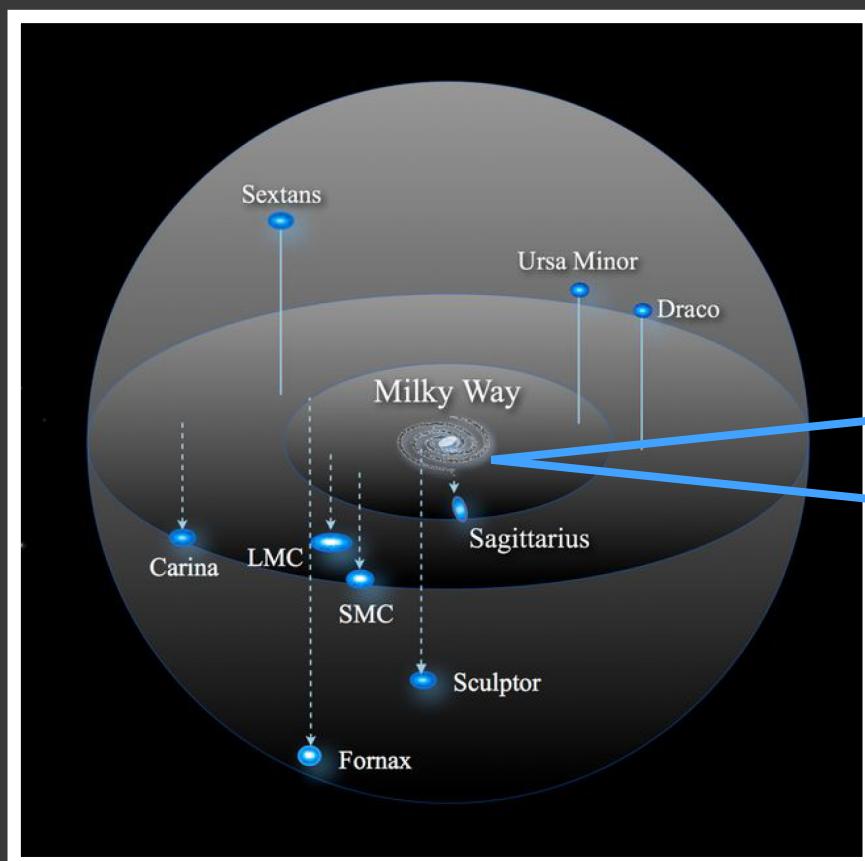
- DM model selection

DM search with GW detectors

* Huge discovery space: 90 orders of magnitude!



* Local DM distribution



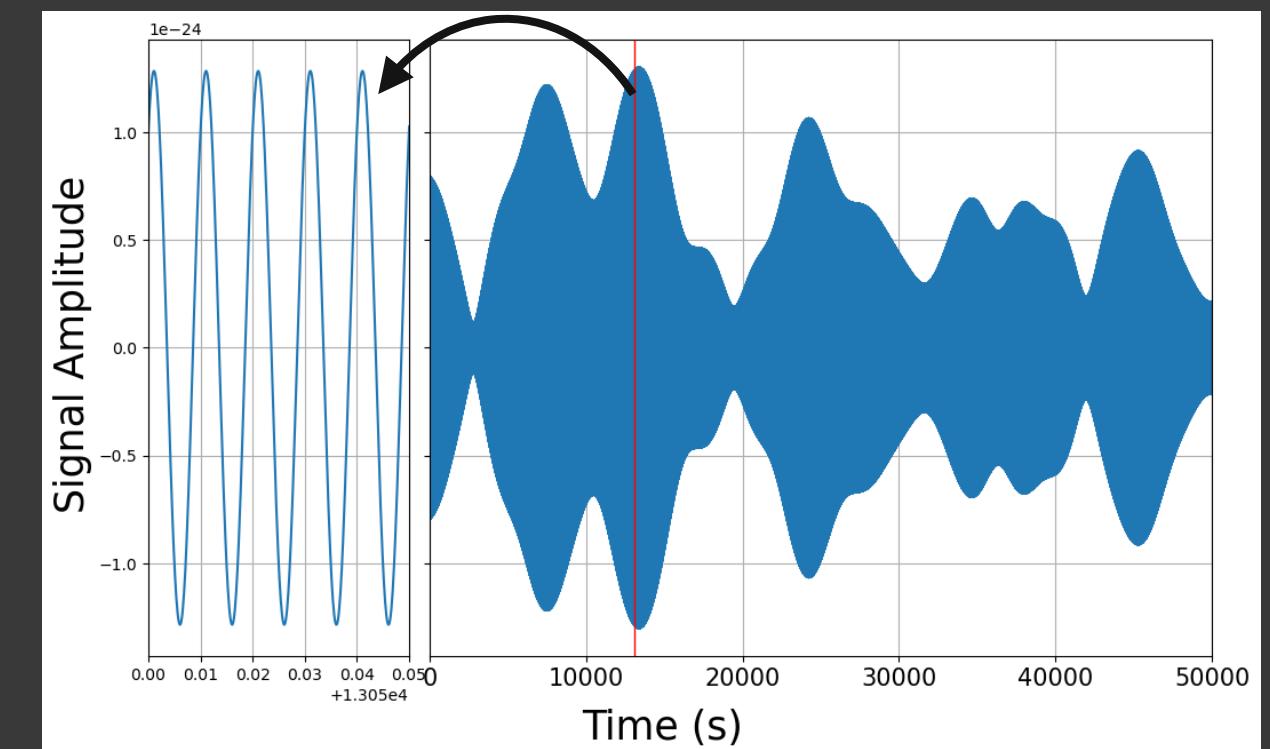
Local DM energy density
 $\rho_{\text{DM}} \sim 0.4 \text{ GeV/cm}^3$

cite: de Martino, I.+
Universe 2020, 6, 107.

When the halo is composed of ULDM

- number density $\gg 1$
- DM halo behaves as a classical wave field
- The amplitude fluctuates **stochastically**

$$f_{\text{DM}} \propto m_{\text{DM}}/2\pi$$



ULDM models

* According to the number density, $m_{\text{DM}} \leq 1 \text{ eV}$ is allowed for **bosons**

spin-0 candidate:

axion (or ALPs)

- coupling to photon

$$\mathcal{L} \supset \frac{g_{a\gamma}}{4} a F_{\mu\nu} F^{\mu\nu}$$

1. K. Nagano+, PRL **123**, 111301 (2019)
2. D. Martynov+, PRD **101**, 095034 (2020)
3. K. Nagano+, PRD **104**, 062008 (2021)

spin-1 candidate:

dark photon

- coupling to fermions

$$\mathcal{L} \supset e \epsilon_D J_D^\mu A_\mu$$

- ※ We especially focused on
the $D = B - L$ case
(so-called " $U(1)_{B-L}$ " gauge boson)
1. Y. Michimura+, PRD **102**, 102001 (2020)
 2. S. Morisaki+, PRD **103**, L051702 (2021)
 3. LVK Collab., PRD **110**, 042001 (2024)

spin-2 candidate:

spin-2 DM

- coupling to matter
field

$$\mathcal{L} \supset -\frac{\alpha}{2M_{\text{Pl}}} \Phi_{ij} T^{ij}$$

1. Y. Manita+, PRD **107**, 104007 (2023)
2. Y. Manita+, PRD **109**, 095012 (2024)

* Each model interacts with GW detectors and **produces similar signals**

Data analysis in the previous study

* Analysis method for ULDM



Cutting in chunks is to;

- consider **the directional change** of the detectors
- Ensure **the stationarity** of the detectors

→ **shorter chunk is better**

* Incoherent analysis

- detection statistic: $\rho(f_{\text{DM}})$

incoherently sum up ρ_i ,

$$\rho(f) = \sum_i^{N_{\text{ch}}} \rho_i(f), \quad \rho_i(f) = \frac{4|\tilde{d}(f; t_i)|^2}{T_{\text{ch}} S(f; t_i)}$$

then search for the DM with the threshold determined by the frequentist method

T_{ch} : duration of each chunk
 $S(f; t_i)$: one-sided noise power spectral density

A Problem of Incoherent Analysis

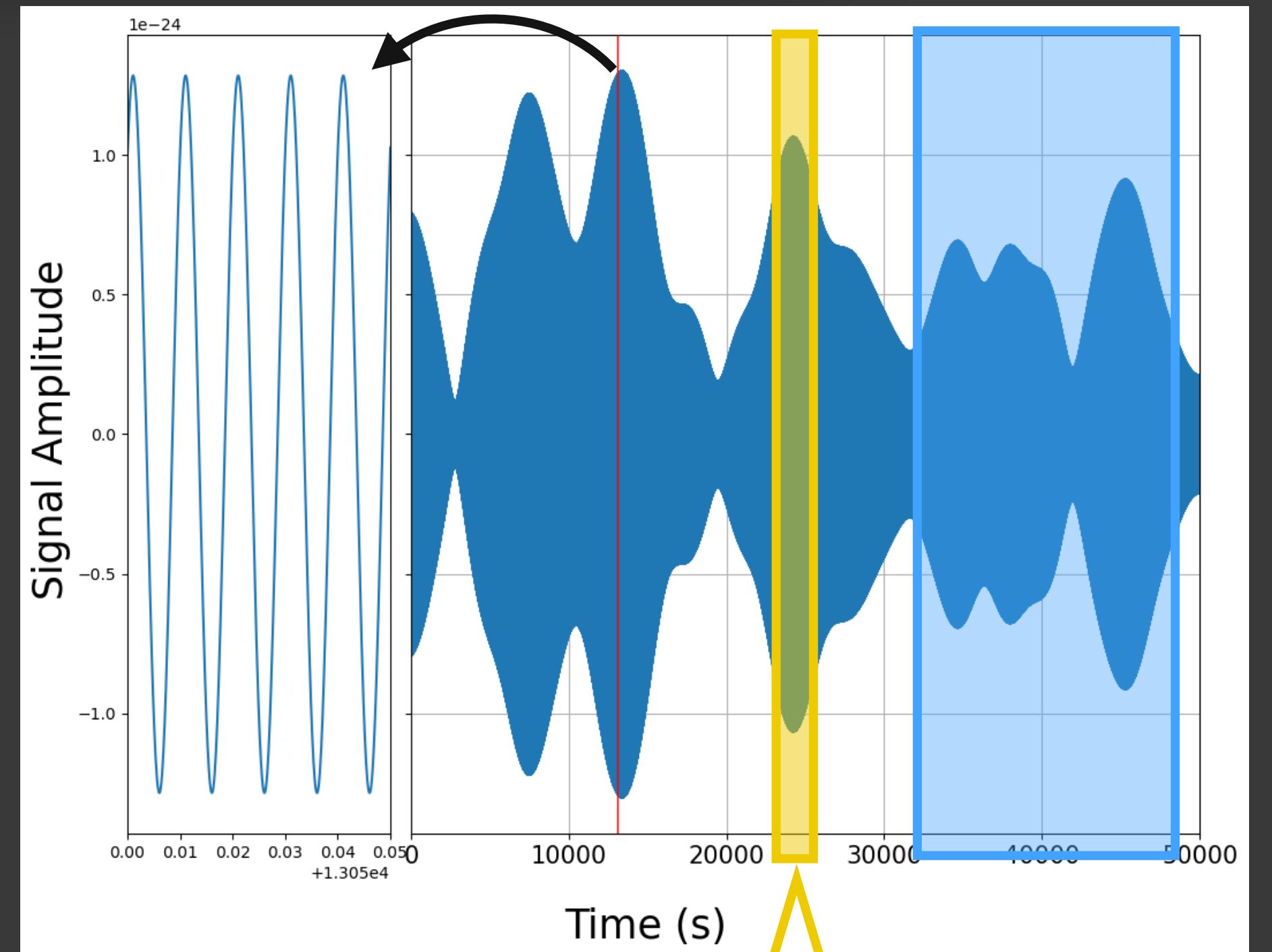
- * Criteria of the detection or upper bound estimation: **Signal-to-Noise Ratio(SNR)**

$$\text{SNR} \propto \begin{cases} (\underline{T_{\text{ch}} T_{\text{tot}}})^{1/4} & \text{for } T_{\text{ch}} < \tau \text{ (or low } m_{\text{DM}} \text{)} \\ (\underline{\tau} T_{\text{tot}})^{1/4} & \text{for } T_{\text{ch}} > \tau \text{ (or high } m_{\text{DM}} \text{)} \end{cases}$$

$$\tau \equiv 2\pi/m_{\text{DM}} \langle v^2 \rangle$$

Coherent time (typical timescale of variation of field amplitude)

- * Incoherent search loses phase information
 - * SNR improvement is limited by the duration of the chunk instead of the coherent time
- **Worse efficiency for search for lower mass ULDM**



Shorter chunks fail to **integrate over the coherence time**

A Problem of Incoherent Analysis

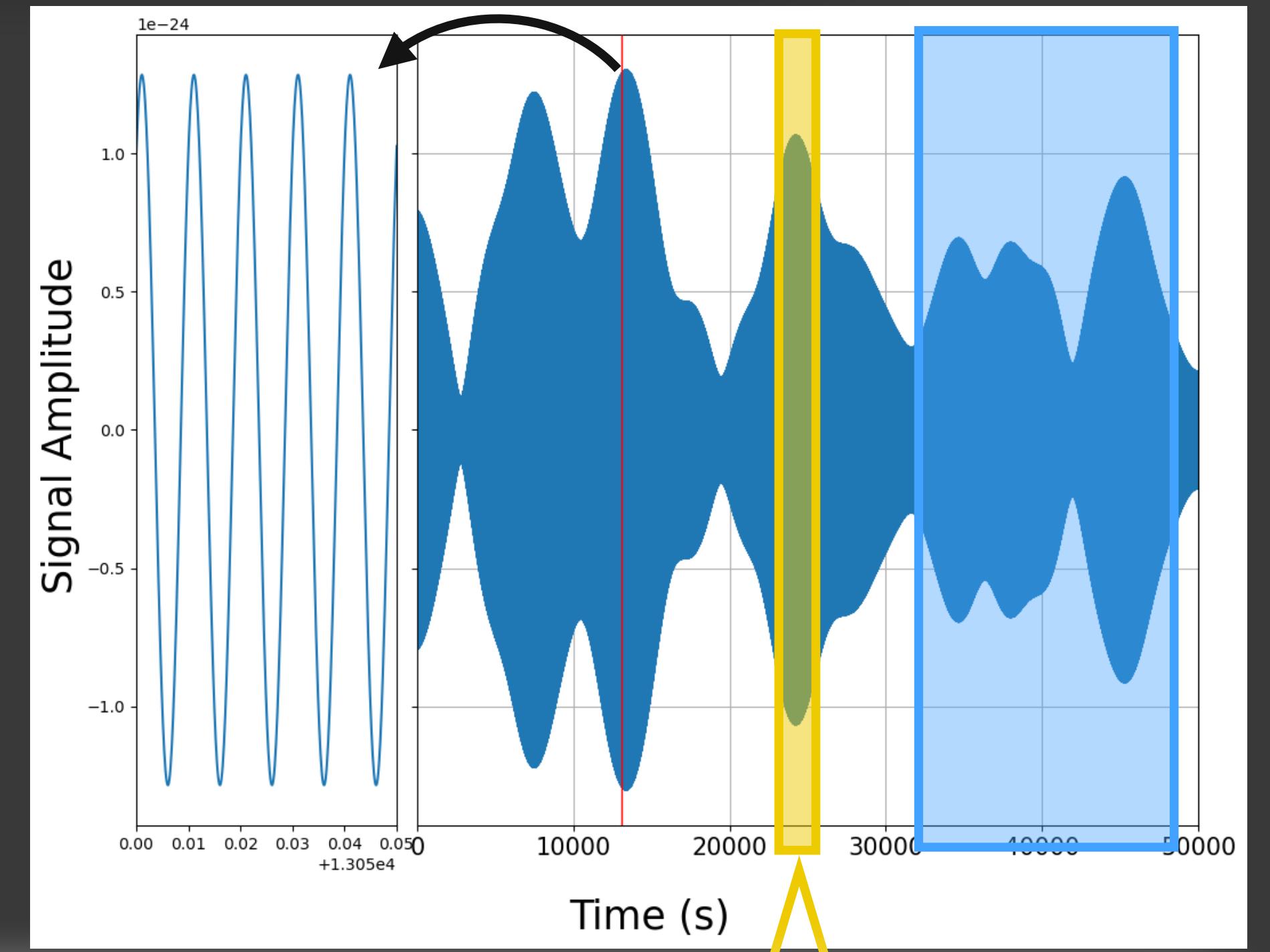
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A more effective analysis
method is needed!

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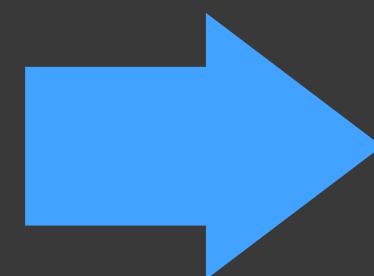
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Correlation between chunks

- * DM signal in each chunk has a correlation

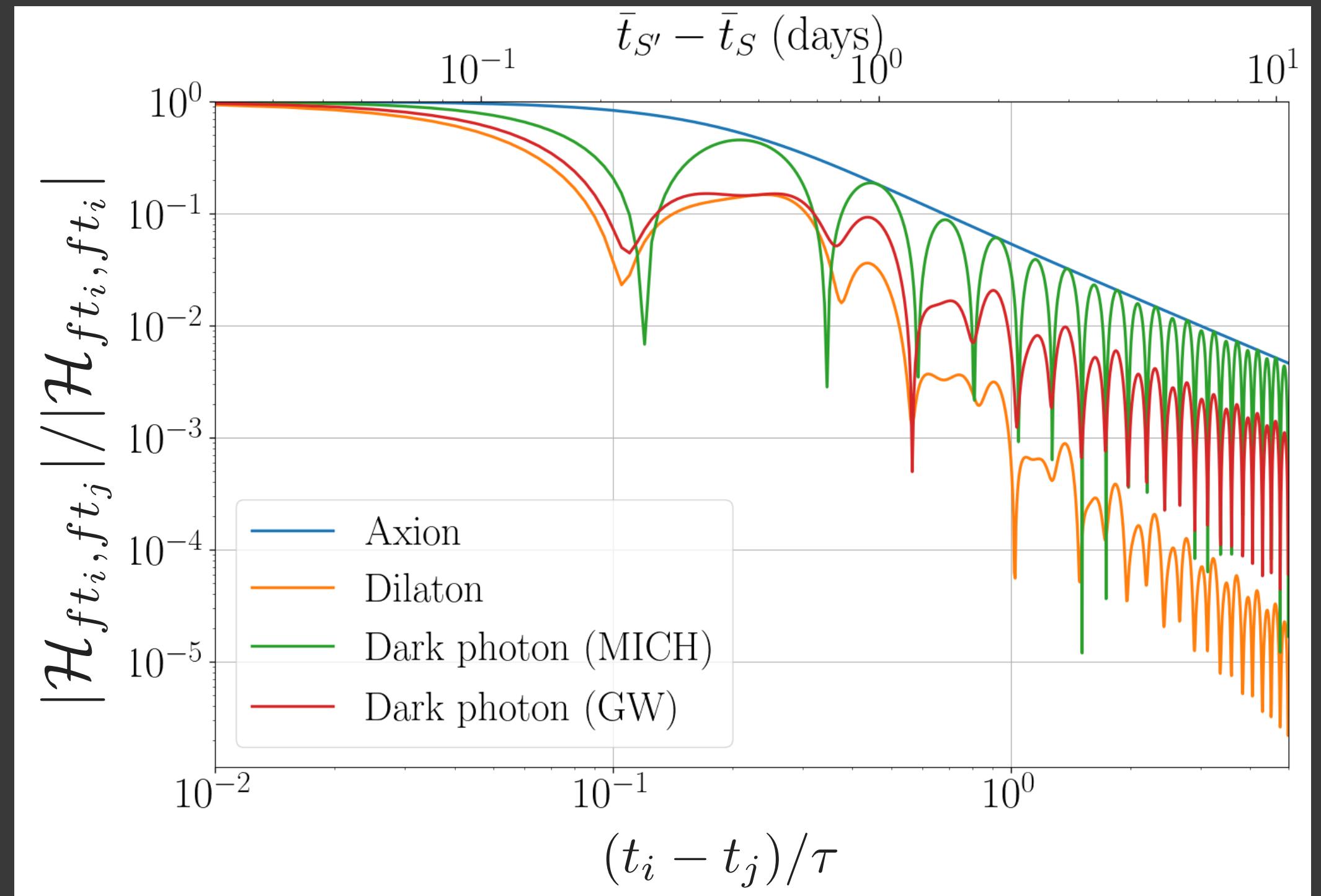
$$\tilde{d}(f; t_i) = \tilde{n}(f; t_i) + \epsilon \tilde{h}(f; t_i)$$



$$\begin{aligned}\mathcal{H}_{ft_i, f't_j} \\ \equiv \langle \tilde{h}(f; t_i), \tilde{h}(f'; t_j) \rangle\end{aligned}$$

- * Correlation functions are different for each DM models

- * The difference comes from the mechanism of the interaction with detectors



Effect of direction of relative velocity

* The case that the correlation depends on the relative motion

- Assuming the DM velocity distribution is isotropic
- Consider the relative velocity as $\vec{v} = \vec{v}_{\text{vir}} + \vec{v}_{\odot}$
(ignoring the velocity of the Earth's orbit and rotation)

\vec{v}_{vir} : virial velocity of DM

\vec{v}_{\odot} : velocity of the solar system
relative to the galactic center

* **dark photon** (spin-1 (vector) DM)

signal: $h(t) = h_1(t) + h_2(t)$

$$h_2(t) = \frac{\epsilon_D e}{m_{\text{DM}}} \frac{Q_D}{M} \sum_i A_i ((\vec{n} \cdot \vec{e}_i)(\vec{n} \cdot \underline{\vec{k}_i}) - (\vec{m} \cdot \vec{e}_i)(\vec{m} \cdot \underline{\vec{k}_i})) \cos(\omega_i(t - L) + \phi_i)$$

\vec{n}, \vec{m} : unit vector of the GW detector

\vec{e}_i, \vec{k}_i : unit polarization vector and wave number vector of i-th wave

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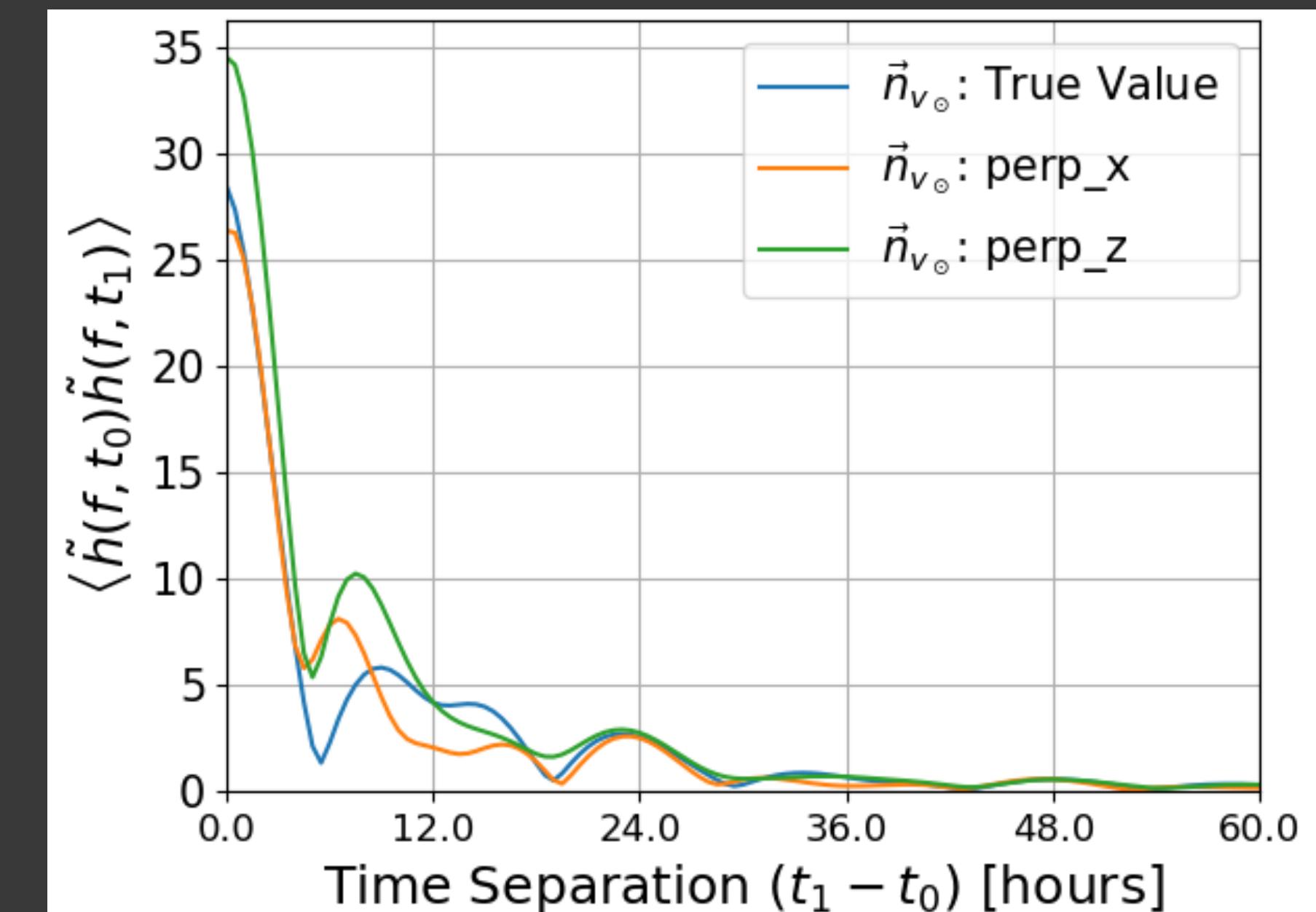
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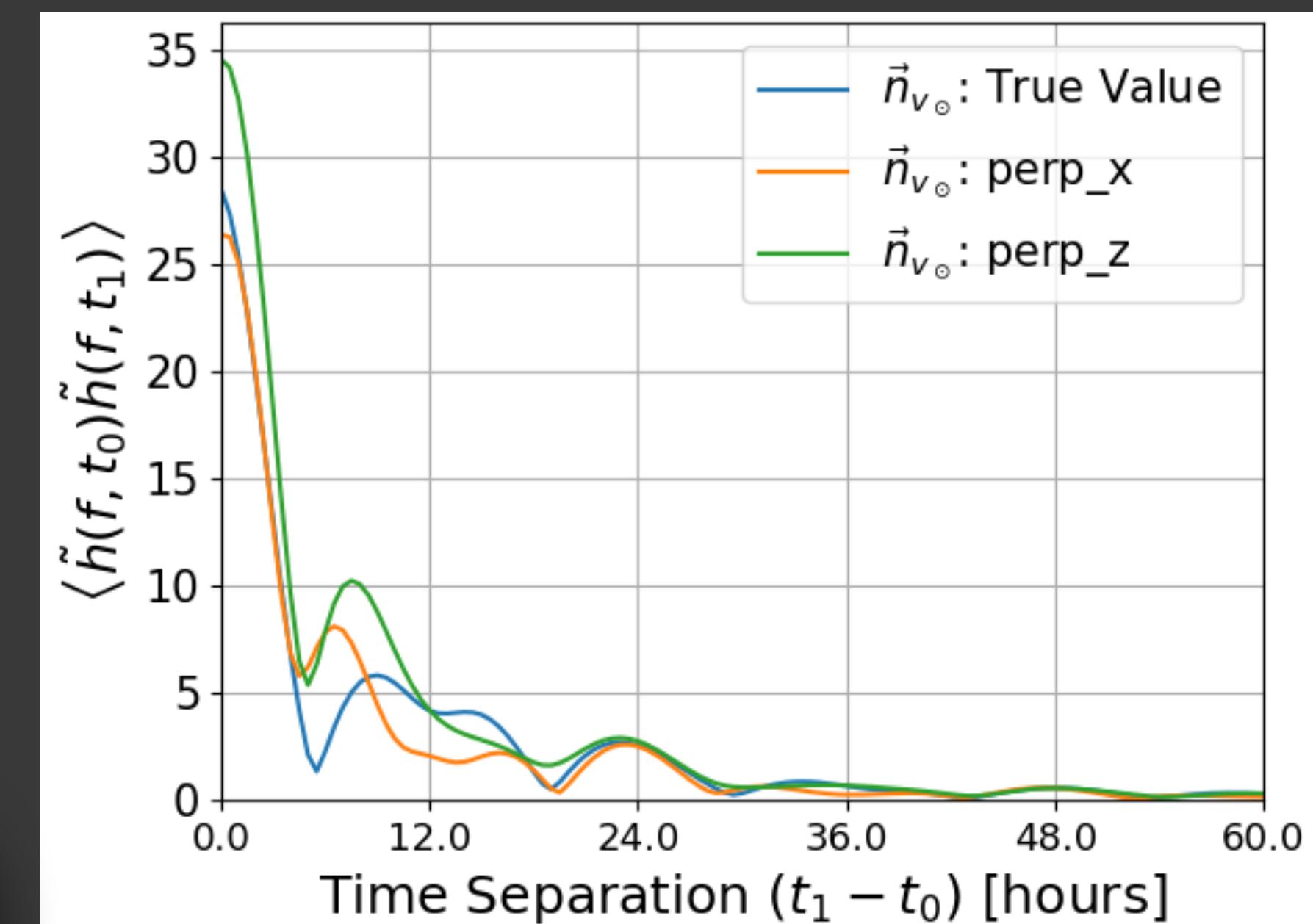
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Accurate \vec{v}_{\odot} must be taken into account!

\vec{v}_{vir} : virial velocity of DM
 \vec{v}_{\odot} : velocity of the solar system relative to the galactic center



Optimal Filtering Approach

* Construction of Detection Statistics

$$\rho = \vec{d}^\dagger \mathcal{N}^{-1} \mathcal{H} \mathcal{N}^{-1} \vec{d}$$

\vec{d} : Fourier components of data segments

\mathcal{N} : noise covariance \mathcal{H} : signal covariance

for maximizing SNR; $\text{SNR} \equiv \langle \rho \rangle / \sqrt{\text{Var}[\rho]}$

- Considering the correlation of each chunk in \mathcal{N} and \mathcal{H}
- The effect of the relative velocity is also included
- **This can be applied to any model and other ULDM searches**

Incoherent analysis

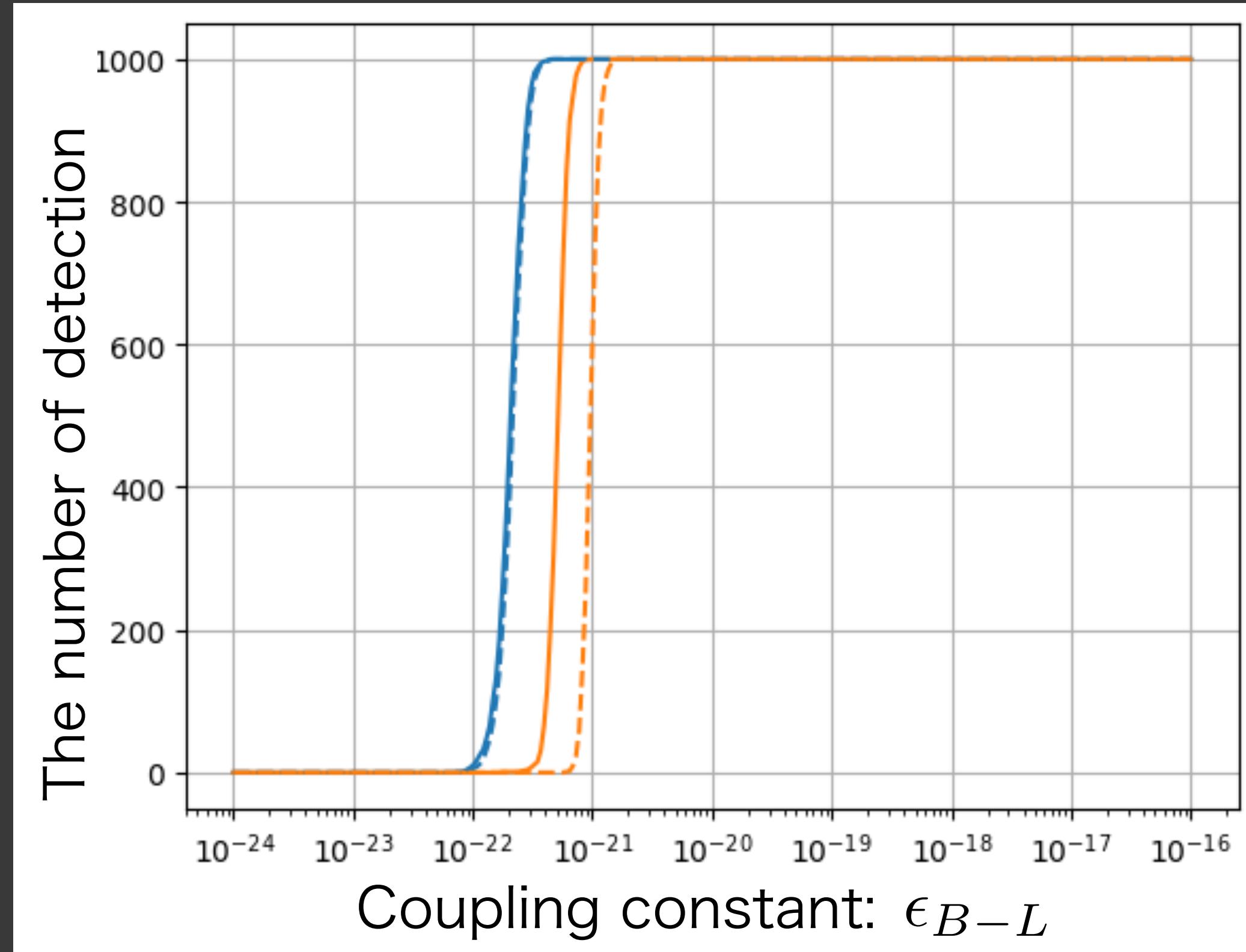
$$\rho(f) = \sum_i^{N_{\text{ch}}} \rho_i(f),$$

$$\rho_i(f) = \frac{4|\tilde{d}(f; t_i)|^2}{T_{\text{ch}} S(f; t_i)}$$

Application to the simulation data

- * Search for 1000 simulated data

Signal: $U(1)_{B-L}$ gauge boson (100 Hz)



$$\tau \sim \frac{2\pi}{m_{DM}\langle v^2 \rangle}$$
$$\sim 2.8 \text{ hours}$$

Characterizes the strength
of the interaction

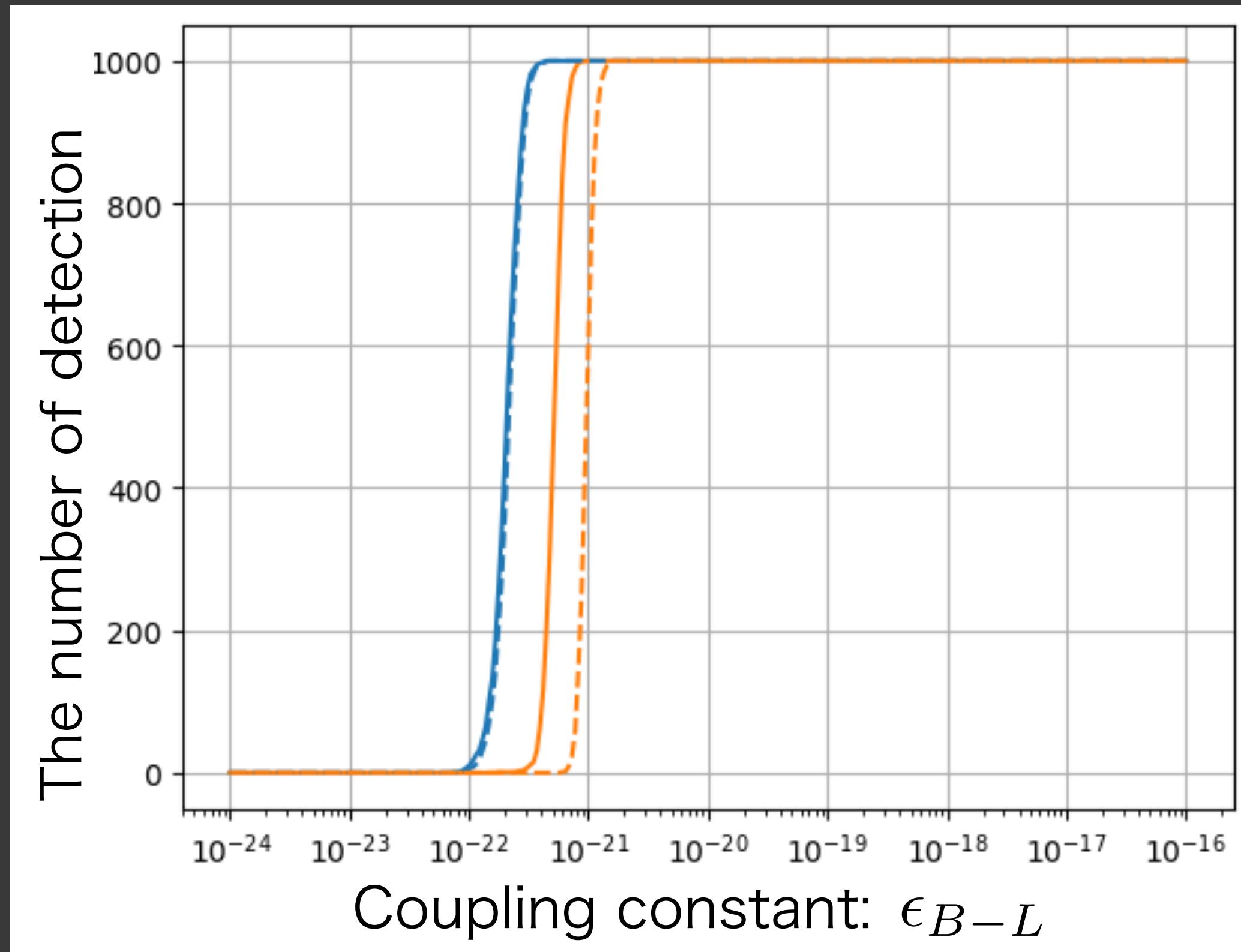
$$\tilde{d} = \tilde{n} + \epsilon_{B-L} \tilde{h}$$

- : OF, 100 sec. — : Incoherent search, 100 sec.
- - - : OF, 25 sec. - - - : Incoherent search, 25 sec.
- ※OF: Optimal Filtering

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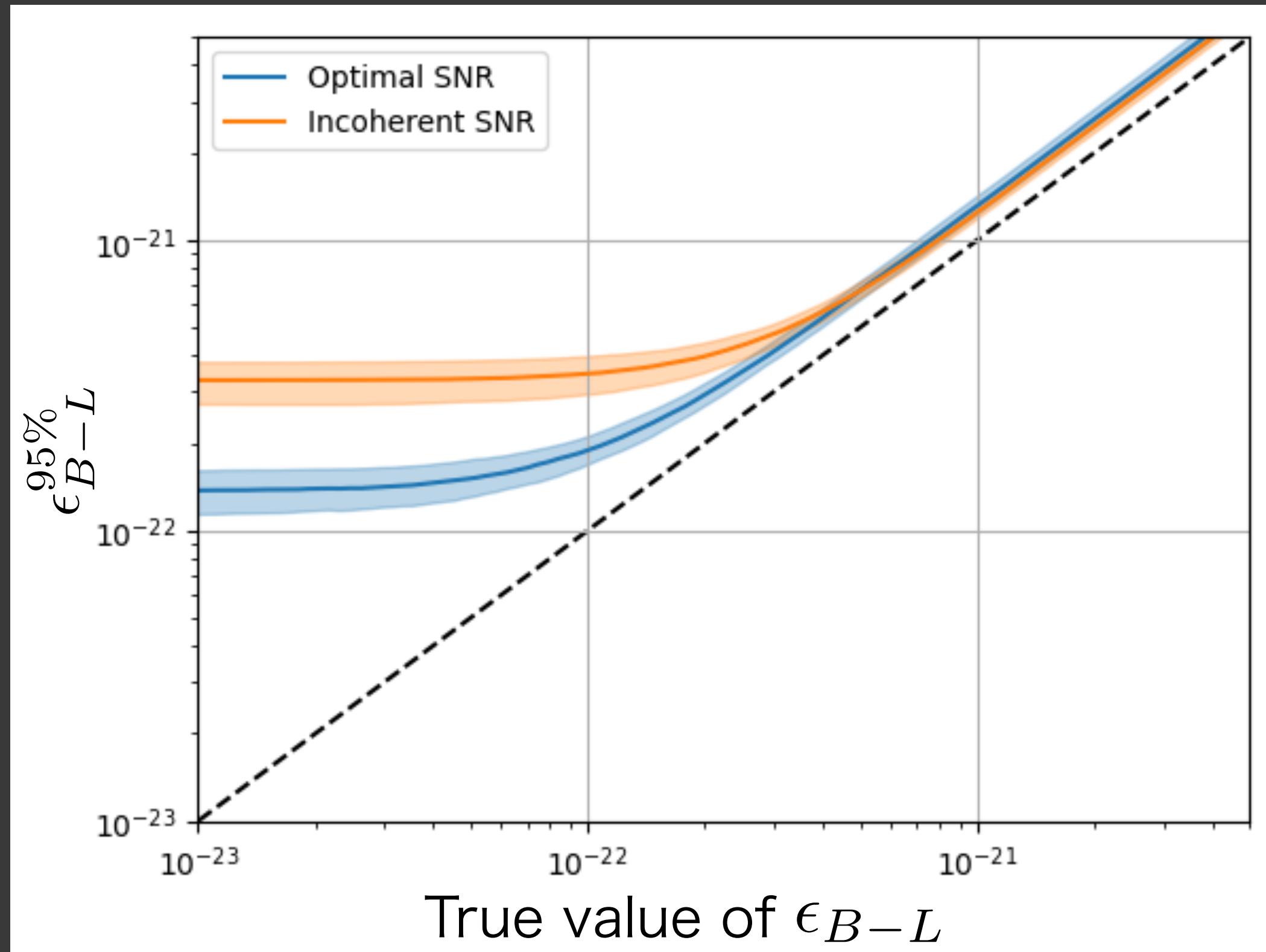
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- ※ OF: Optimal Filtering

The optimal filtering method;
✓ can **detect much smaller signal**
✓ is **independent of the duration
of the chunk**

Application to the simulation data

- * **Estimate the 95% upper bound** with 1000 data

Signal: $U(1)_{B-L}$ gauge boson (100 Hz)



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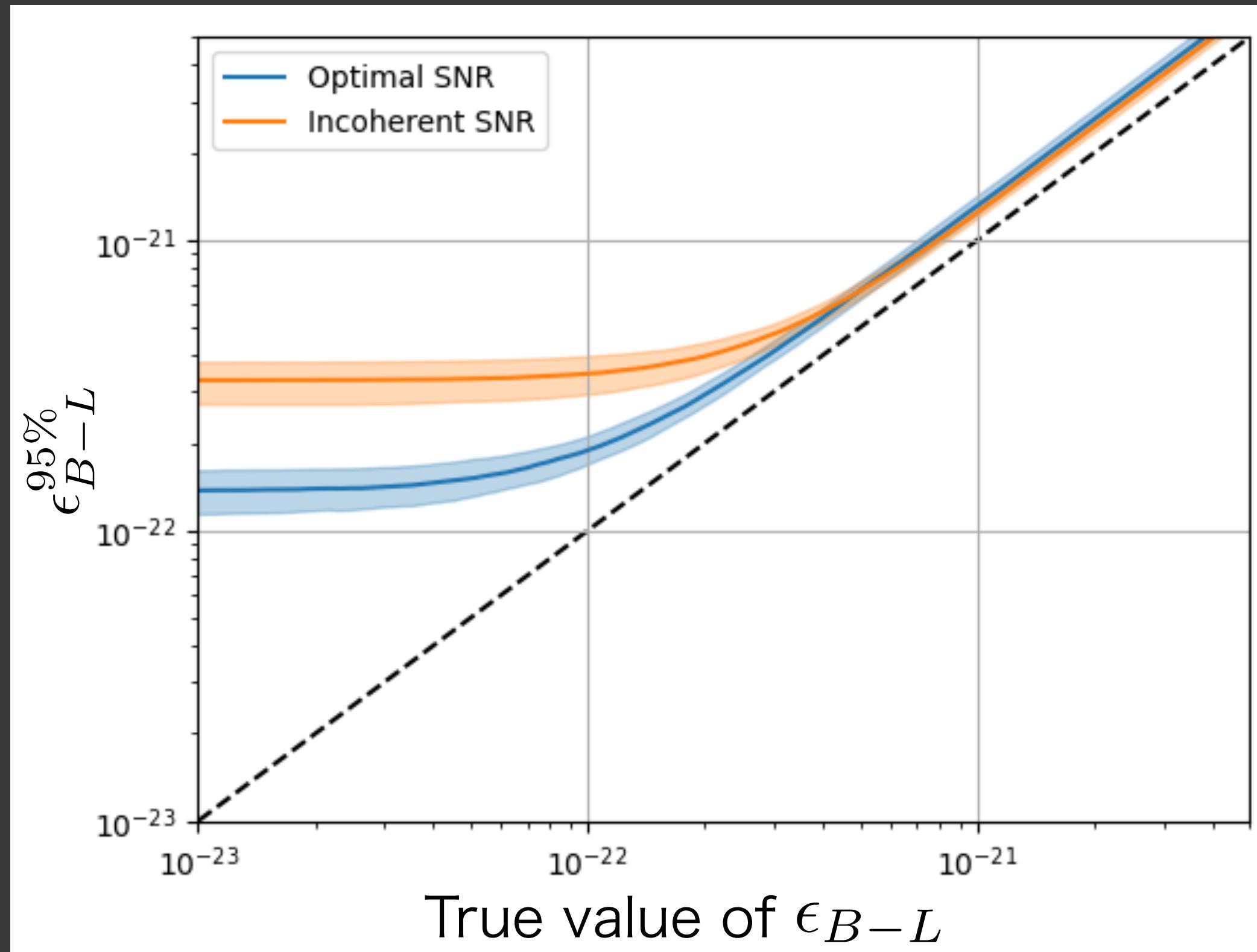
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※ Chunk duration: 100 sec.

Application to the simulation data

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Characterizes the strength
of the interaction

$$\tilde{d} = \tilde{n} + \epsilon_{B-L} \tilde{h}$$

— : OF — : Incoherent search
※ Chunk duration: 100 sec.

The optimal filtering (OF) method;
✓ can **set a much tighter bound**
when $T_{ch} < \tau$

Conclusion and Future Works

* Optimal Filtering(OF) method

- New data analysis method for ULDM search
- OF is constructed based on the general nature of the ULDM field
→ can be applied to any other ULDM searches
- **More detection numbers** and **Tighter bound on coupling constants** than those with the previous method

* Future Works

- Application for real data

* Discussion

- DM model selection

$$\rho = \vec{d}^\dagger \mathcal{N}^{-1} \mathcal{H} \mathcal{N}^{-1} \vec{d}$$

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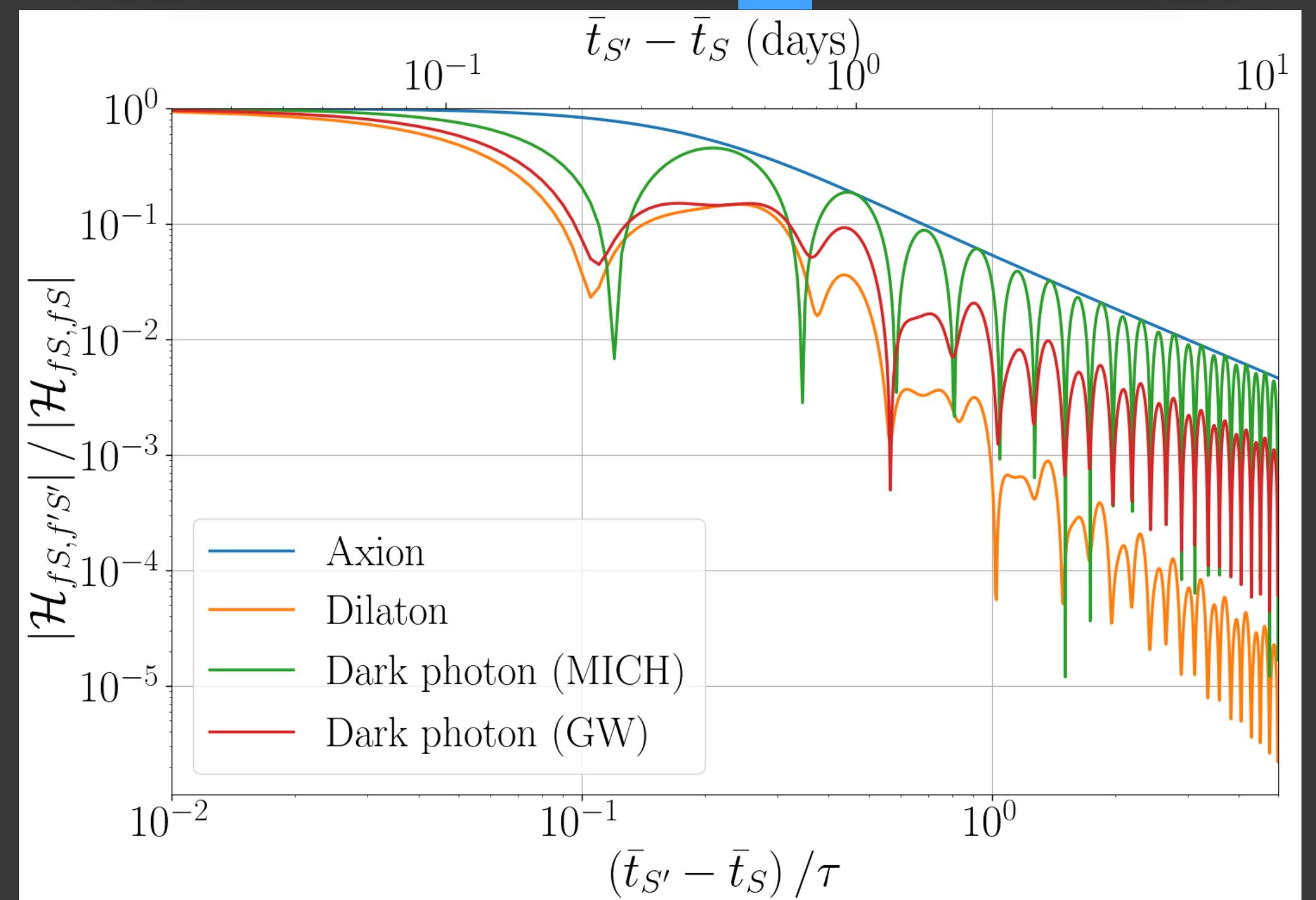
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DM Model Selection

- * The nature of the ULDM field (quasi-monoclonal classical wave field, stochastic amplitude fluctuation) is **common to all the models**
- * On the other hand, the correlation matrix \mathcal{H} changes with the interaction mechanism
- 🤔 We will be able to distinguish the origin of the DM signal by focusing on the statistical difference of ρ_s ???

$$\rho = \vec{d}^\dagger \mathcal{N}^{-1} \mathcal{H} \mathcal{N}^{-1} \vec{d}$$



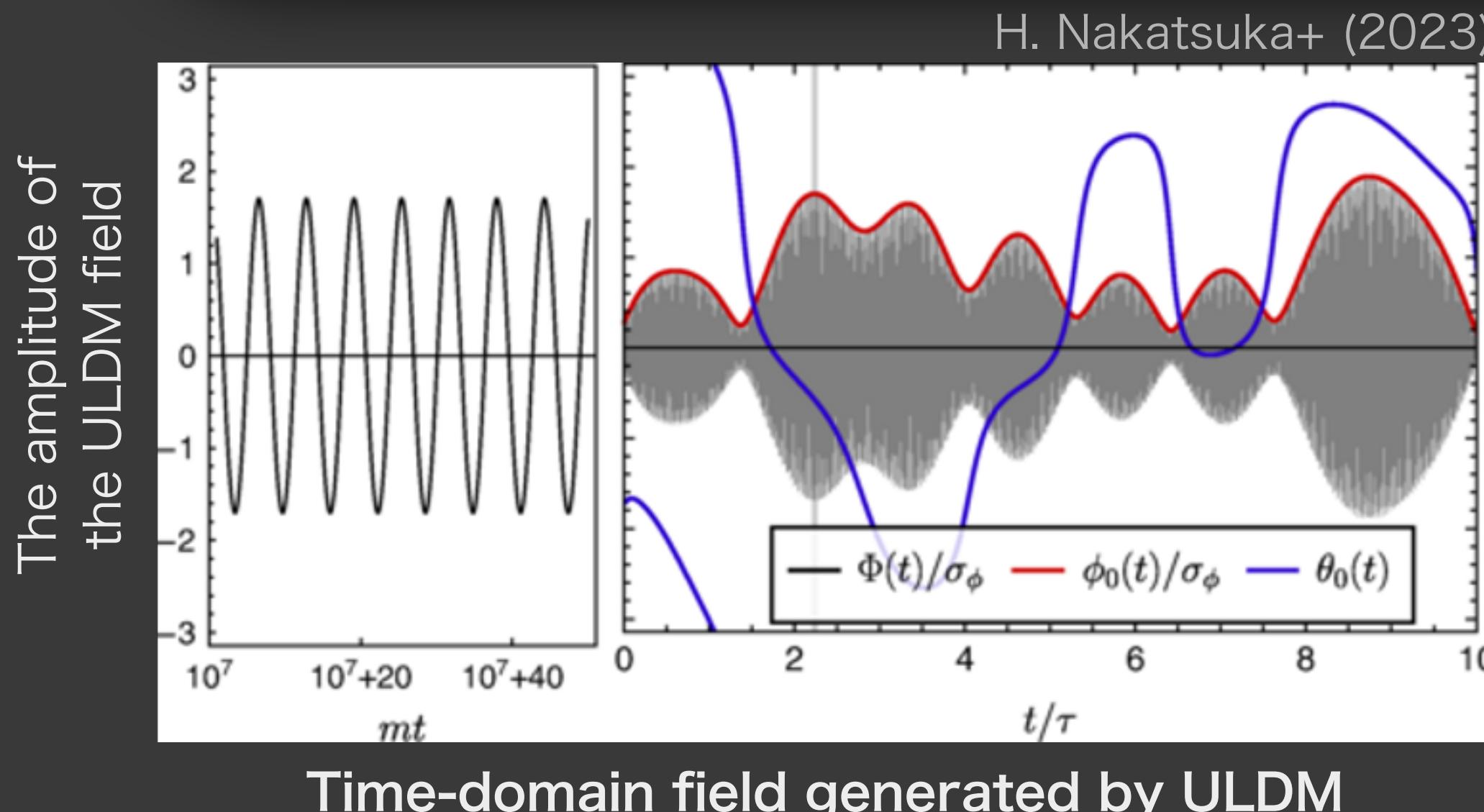
Appendix

DM search with GW detectors

* The description of the ULDM field

$$\vec{A}(t) = \frac{A}{\sqrt{N}} \sum_{n=1}^N \vec{e}_n \cos \left(m_{\text{DM}} \left(1 + \frac{v_n^2}{2} \right) t - m_{\text{DM}} \vec{v}_n \cdot \vec{x} + \theta_n \right)$$

N : number of partial waves
 \vec{v}_n : velocity of n -th wave
 $\vec{v} = \vec{v}_{\text{vir}} + \vec{v}_{\odot}$
 θ_n : random phase of n -th wave



$$\vec{v} \sim 10^{-3} \ll 1$$

Frequency: $f \sim \frac{m_{\text{DM}}}{2\pi}$

Frequency width: $\Delta f \sim \frac{m_{\text{DM}} \langle v^2 \rangle}{2\pi}$

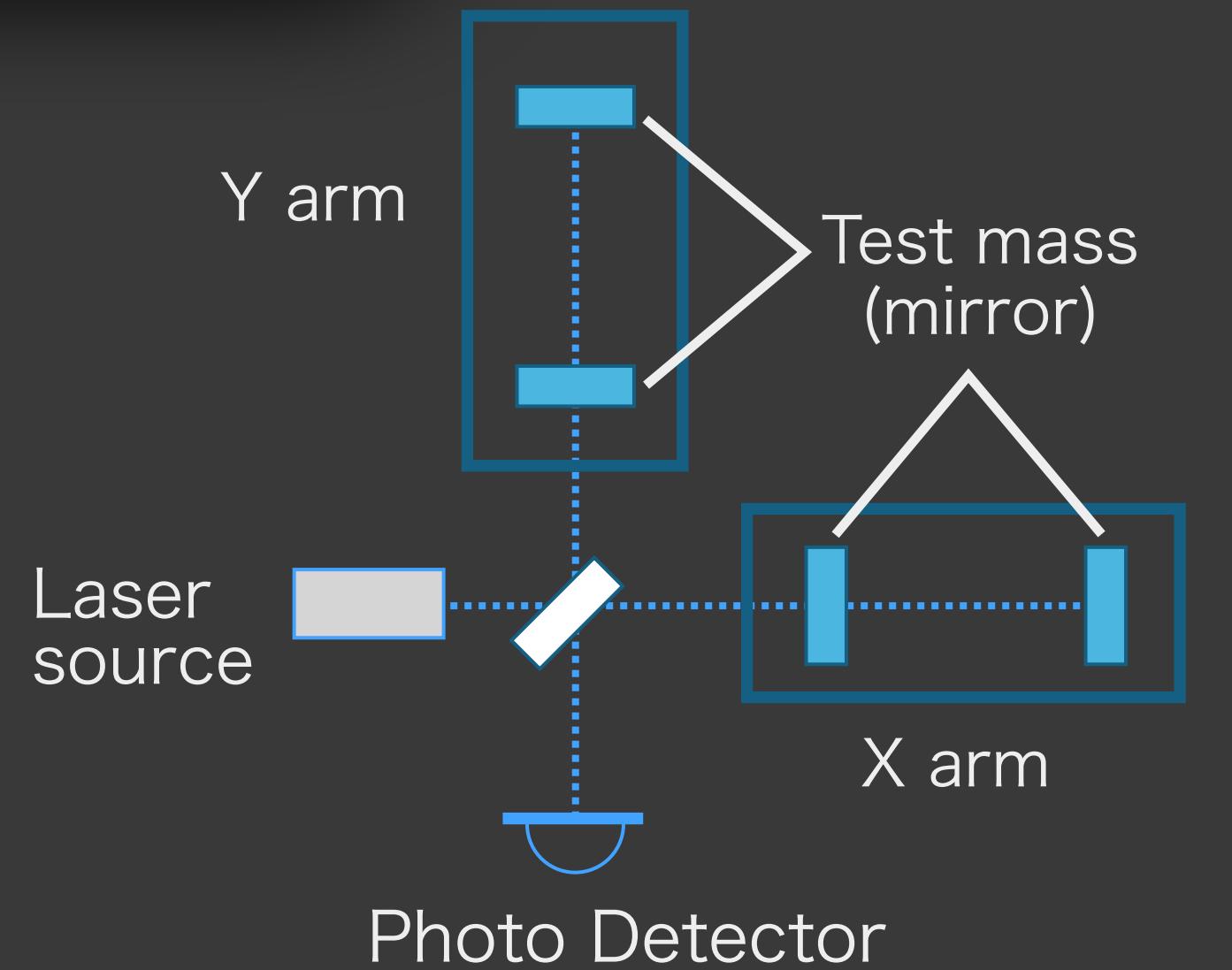
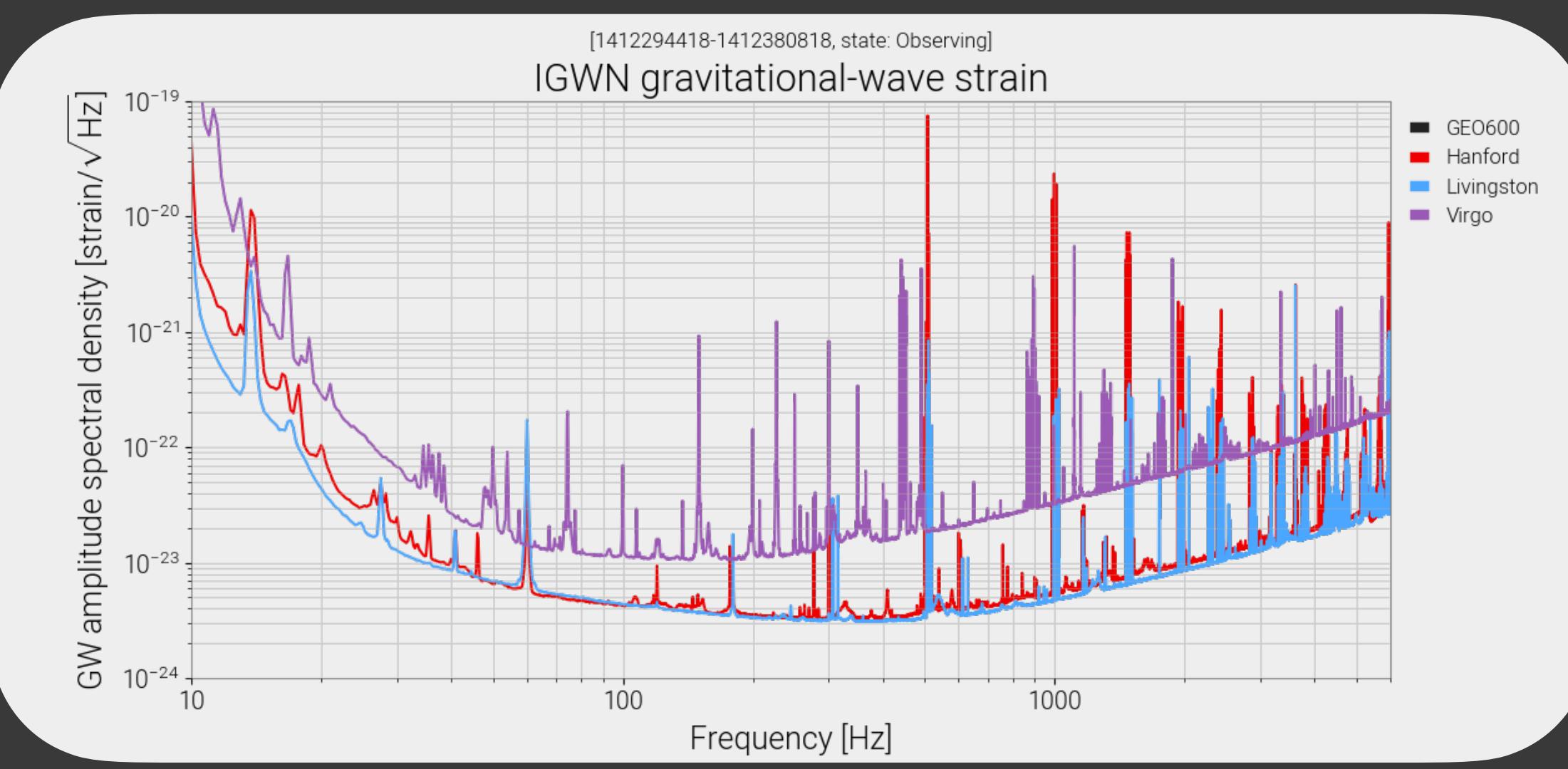
Coherent time: $\tau \sim \frac{2\pi}{m_{\text{DM}} \langle v^2 \rangle} \sim \frac{10^6}{f}$

Gravitational Wave Detector

- Laser Michelson interferometer
- Observe the change in the difference between the lengths of the two arms.

$$\frac{\Delta L}{L} \sim 10^{-23}$$

- Arm length: 4 km (LIGO, Virgo), 3 km(KAGRA)



Obtaining the threshold

* For obtaining the detection threshold

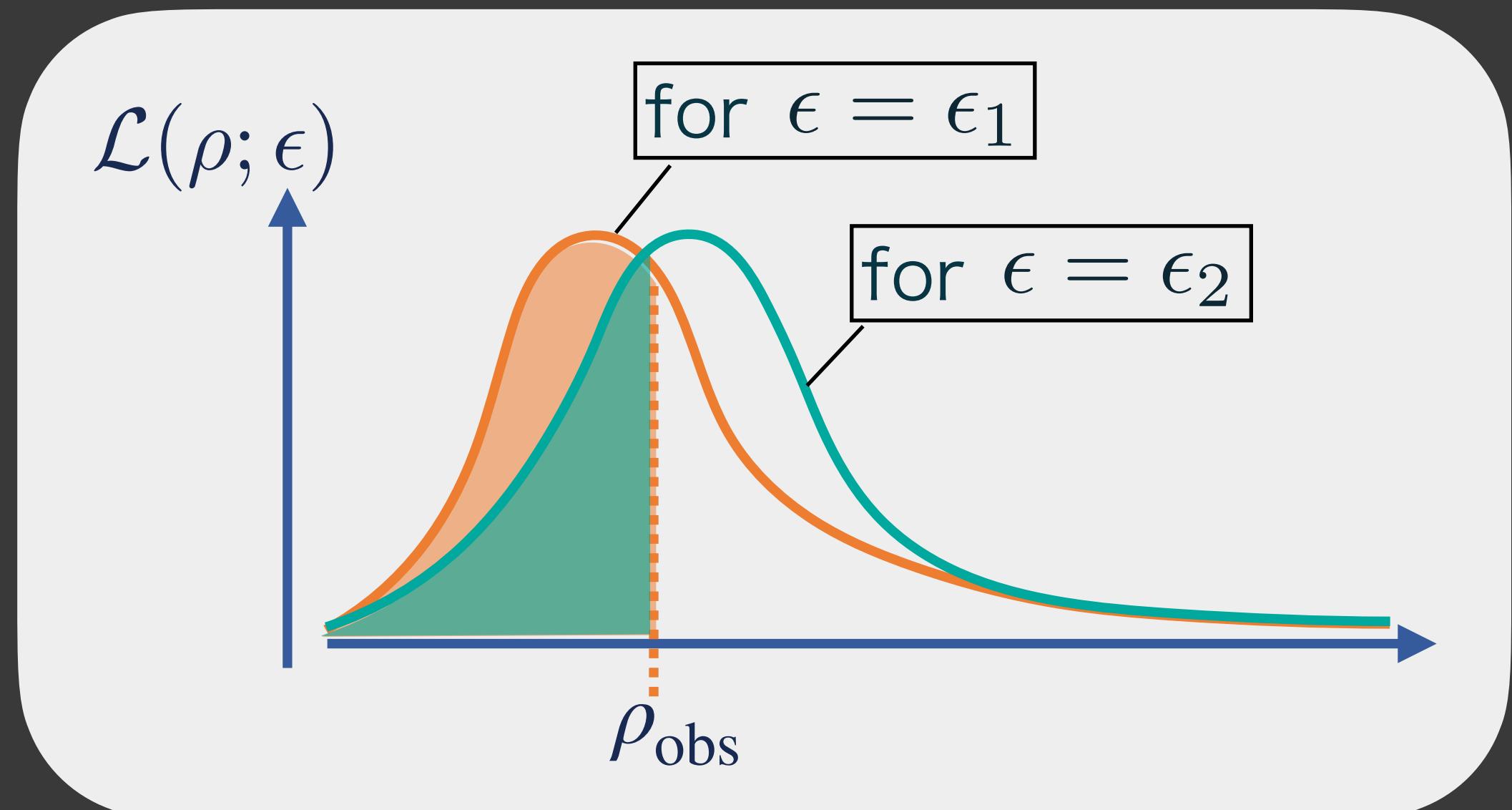
- α is the false alarm rate
(in this presentation $\alpha = 1 - 10^{-4}$)

$$\alpha = \int_0^{\rho_{\text{thr}}} \mathcal{L}(\rho(f) | \epsilon = 0) d\rho$$

* For setting the upper bound

- $\beta = 95$ is often used

$$1 - \frac{\beta}{100} = \int_0^{\rho_{\text{obs}}} \mathcal{L}(\rho(f) | \epsilon^{\beta\%}) d\rho$$

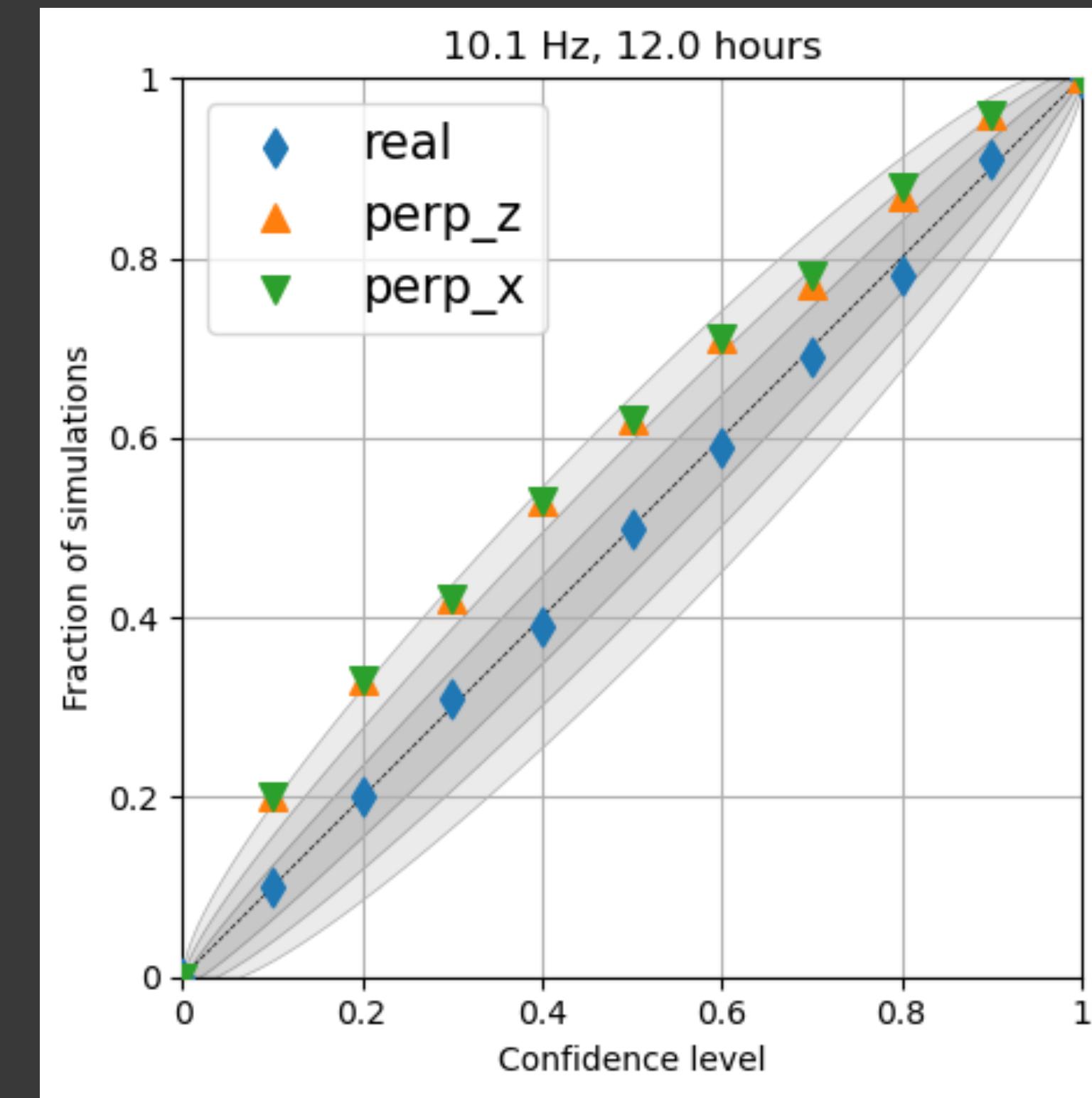
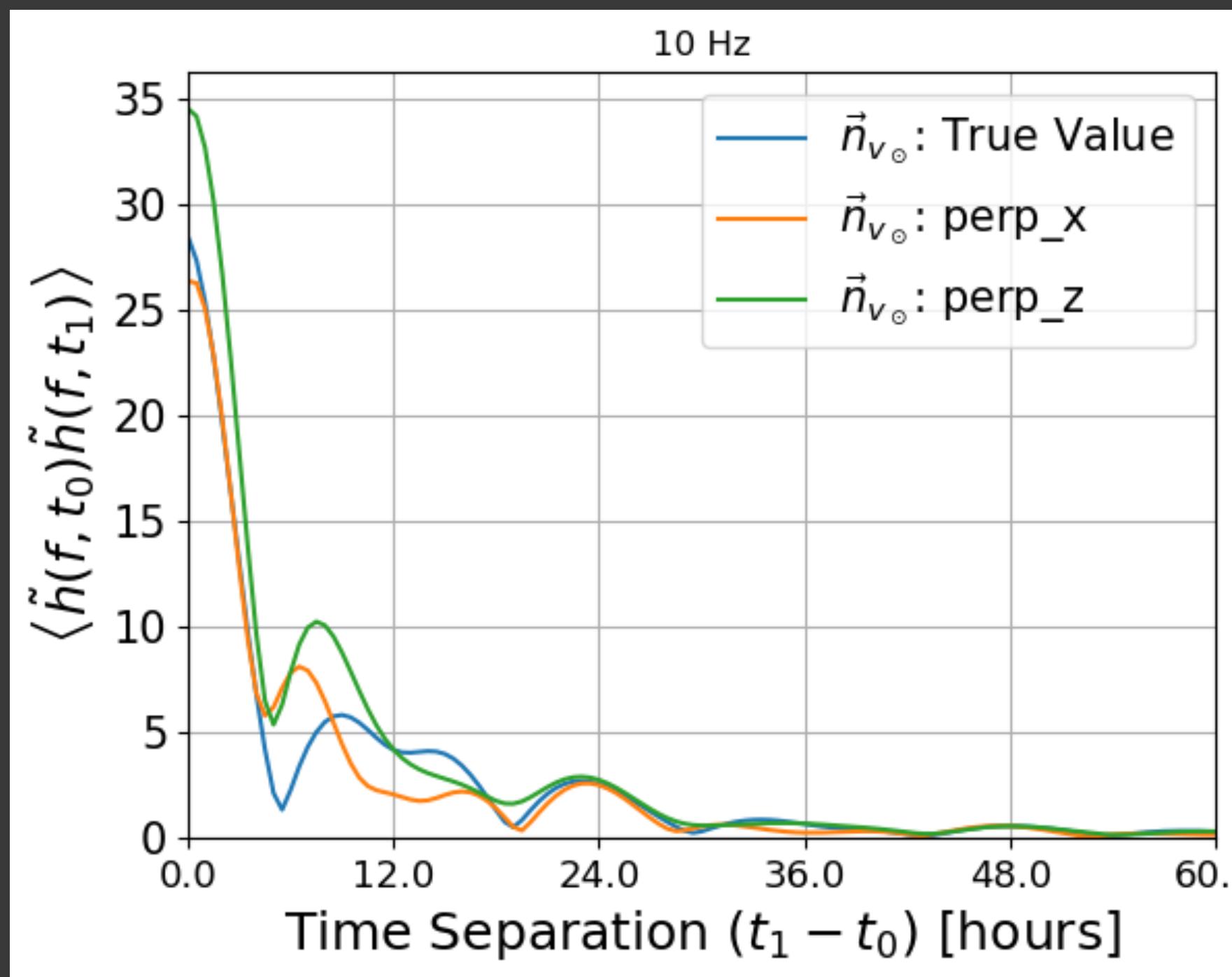


Effect of direction of relative velocity

* Analysis with incoherent method

- Coupling constant estimation for **dark photon** with simulated data

$$\mathcal{L} \supset e\epsilon_D J_D^\mu A_\mu$$



$$\vec{v} = \vec{v}_{\text{vir}} + \vec{v}_{\odot}$$