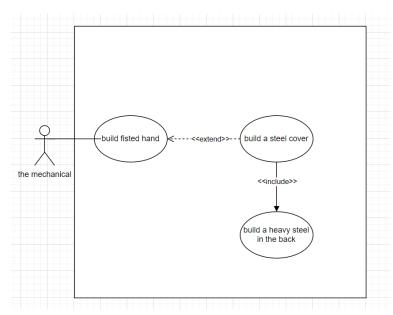
### **Mechanical:-**

#### **Functional:**

- The robot must have slightly fisted hand so that it can fit the dallah's grip.
- The robot's arm must covered by a tough and heavy steel to be able to carry the dallah.
- The robot's back must include a heavy steel to keep the robot in balance.

# **Non-functional requirements:**

• The steel in the back of the robot, should weigh at least 80 pounds.



use case diagram

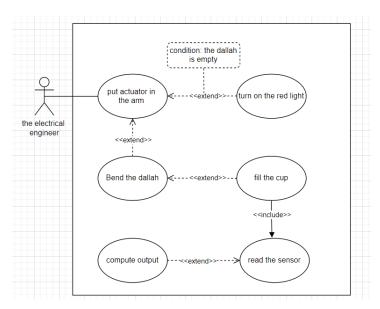
#### **Electronical:-**

#### **Functional:**

- When the coffee is almost over, a small red light will appear in the robot's arm to inform the operator about the emptiness of the coffee, by putting actuator in the robot's arm.
- The dallah will bend until the cup receive the coffee and then start filling it by reading the sensor and then compute the actuator output.
- All the cups will have the same amount of coffee based on a predefined value.

### **Non-functional requirement:-**

The coffee should be filled until the top of the cup.



use case diagram

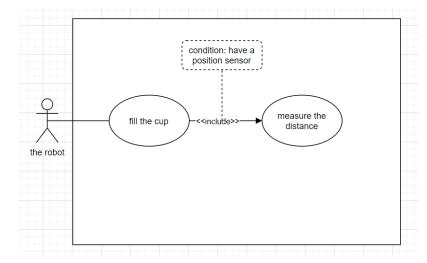
### **Artificial Intelligence:-**

#### **Functional:**

 After the robot fills the cup of coffee; it must measure the distance between itself and the object in front of it by having a position sensor, in order to avoid any collision or spilling of coffee.

#### **Non-functional:**

- The position sensor should keep 2 meters distance away from any object in front of it.
- Temperature sensor must be included inside the 'Dallah' to inform the operator whenever the temperature is less than 100 degrees fahrenheit.
- The robot shouldn't ask a child if they want a coffee, by measuring their height.



use case diagram

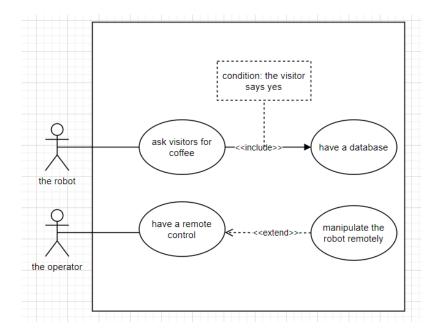
### **Internet of things:-**

### **Functional requirements:**

- The robot must ask the visitors if they would like to drink a coffee before pour for them by feed it of a database with many related words.
- The operator will have a remote control that allow him to manipulate the robot remotely in any cases would happen in the environment.

## **Non-functional requirements:**

• The robot should pour the coffee after 2 second of their replying of 'yes'.



use case diagram