#### Lecture Notes 3 Uniform Bounds

### 1 Introduction

Recall that, if  $X_1, \ldots, X_n \sim \text{Bernoulli}(p)$  and  $\widehat{p}_n = n^{-1} \sum_{i=1}^n X_i$  then, from Hoeffding's inequality,

$$\mathbb{P}(|\widehat{p}_n - p| > \epsilon) \le 2e^{-2n\epsilon^2}.$$

Sometimes we want to say more than this.

**Example 1** Suppose that  $X_1, \ldots, X_n$  have cdf F. Let

$$F_n(t) = \frac{1}{n} \sum_{i=1}^n I(X_i \le t).$$

We call  $F_n$  the **empirical cdf**. How close is  $F_n$  to F? From Hoeffding's inequality, we have for each t, that

$$\mathbb{P}(|F_n(t) - F(t)| > \epsilon) \le 2e^{-2n\epsilon^2}.$$

But how big is  $\sup_t |F_n(t) - F(t)|$ ? We would like a bound of the form

$$\mathbb{P}\left(\sup_{t} |F_n(t) - F(t)| > \epsilon\right) \le \text{ something small.}$$

**Example 2** Suppose that  $X_1, \ldots, X_n \sim P$ . Let

$$P_n(A) = \frac{1}{n} \sum_{i=1}^n I(X_i \in A).$$

How close is  $P_n(A)$  to P(A)? That is, how big is  $|P_n(A) - P(A)|$ ? From Hoeffding's inequality,

$$\mathbb{P}(|P_n(A) - P(A)| > \epsilon) \le 2e^{-2n\epsilon^2}.$$

But that is only for one set A. How big is  $\sup_{A \in \mathcal{A}} |P_n(A) - P(A)|$  for a class of sets A? We would like a bound of the form

$$\mathbb{P}\left(\sup_{A\in\mathcal{A}}|P_n(A)-P(A)|>\epsilon\right)\leq \text{ something small.}$$

**Example 3** (Classification.) Suppose we observe data  $(X_1, Y_1), \ldots, (X_n, Y_n)$  where  $Y_i \in \{0, 1\}$ . Let (X, Y) be a new pair. Suppose we observe X. Now we want to predict Y. A

classifier h is a function h(x) which takes values in  $\{0,1\}$ . When we observe X we predict Y with h(X). The classification error, or risk, is the probability of an error:

$$R(h) = \mathbb{P}(Y \neq h(X)).$$

The training error is the fraction of errors on the observed data  $(X_1, Y_1), \ldots, (X_n, Y_n)$ :

$$\widehat{R}(h) = \frac{1}{n} \sum_{i=1}^{n} I(Y_i \neq h(X_i)).$$

By Hoeffding's inequality,

$$\mathbb{P}(|\widehat{R}(h) - R(h)| > \epsilon) \le 2e^{-2n\epsilon^2}.$$

How do we choose a classifier? One way is to start with a set of classifiers  $\mathcal{H}$ . Then we define  $\widehat{h}$  to be the member of  $\mathcal{H}$  that minimizes the training error. Thus

$$\widehat{h} = \operatorname{argmin}_{h \in \mathcal{H}} \widehat{R}(h).$$

An example is the set of linear classifiers. Suppose that  $x \in \mathbb{R}^d$ . A linear classifier has the form h(x) = 1 of  $\beta^T x \geq 0$  and h(x) = 0 of  $\beta^T x < 0$  where  $\beta = (\beta_1, \dots, \beta_d)^T$  is a set of parameters.

Although  $\widehat{h}$  minimizes  $\widehat{R}(h)$ , it does not minimize R(h). Let  $h_*$  minimize the true error R(h). A fundamental question is: how close is  $R(\widehat{h})$  to  $R(h_*)$ ? We will see later than  $R(\widehat{h})$  is close to  $R(h_*)$  if  $\sup_h |\widehat{R}(h) - R(h)|$  is small. So we want

$$\mathbb{P}\left(\sup_{h}|\widehat{R}(h) - R(h)| > \epsilon\right) \leq \text{ something small.}$$

More generally, we can state out goal as follows. Let  $\mathcal{A}$  be a class of sets. We want a bound of the form

$$\mathbb{P}\left(\sup_{A\in\mathcal{A}}|P_n(A)-P(A)|>\epsilon\right)\leq c_1\kappa(\mathcal{A})e^{-c_2n\epsilon^2}$$

where  $P_n(A) = n^{-1} \sum_{i=1}^n I(X_i \in A)$ . Bounds like these are called *uniform bounds* since they hold uniformly over a class of functions or over a class of sets.

## 2 Finite Classes

Let  $\mathcal{A} = \{A_1, \ldots, A_N\}$ . We will make use of the *union bound*. Recall that

$$\mathbb{P}\left(B_1 \bigcup \cdots \bigcup B_N\right) \leq \sum_{j=1}^N \mathbb{P}(B_j).$$

Let  $B_j$  be the event that  $|P_n(A_j) - P(A_j)| > \epsilon$ . From Hoeffding's inequality,  $\mathbb{P}(B_j) \leq 2e^{-2n\epsilon^2}$ . Then

$$\mathbb{P}\left(\sup_{A\in\mathcal{A}}|P_n(A) - P(A)| > \epsilon\right) = \mathbb{P}\left(B_1 \bigcup \cdots \bigcup B_N\right) \\
\leq \sum_{j=1}^N \mathbb{P}(B_j) \leq \sum_{j=1}^N 2e^{-n\epsilon^2} = 2Ne^{-2n\epsilon^2}.$$

Thus we have shown that

$$\mathbb{P}\left(\sup_{A\in\mathcal{A}}|P_n(A) - P(A)| > \epsilon\right) \le 2\kappa e^{-n\epsilon^2}$$

where  $\kappa = |\mathcal{A}|$ .

To extend these ideas to infinite classes like  $\mathcal{A} = \{(-\infty, t] : t \in \mathbb{R}\}$  we need to introduce a few more concepts.

# 3 Shattering

Let  $\mathcal{A}$  be a class of sets. Some examples are:

- 1.  $\mathcal{A} = \{(-\infty, t] : t \in \mathbb{R}\}.$
- 2.  $A = \{(a, b) : a \leq b\}.$
- 3.  $A = \{(a, b) \cup (c, d) : a \le b \le c \le d\}.$
- 4.  $\mathcal{A} = \text{all discs in } \mathbb{R}^d$ .
- 5.  $\mathcal{A} = \text{all rectangles in } \mathbb{R}^d$ .
- 6.  $\mathcal{A} = \text{all half-spaces in } \mathbb{R}^d = \{x : \beta^T x \ge 0\}.$
- 7.  $\mathcal{A} = \text{all convex sets in } \mathbb{R}^d$ .

Let  $F = \{x_1, \ldots, x_n\}$  be a finite set. Let G be a subset of F. Say that  $\mathcal{A}$  picks out G if

$$A \cap F = G$$

for some  $A \in \mathcal{A}$ . For example, let  $\mathcal{A} = \{(a,b) : a \leq b\}$ . Suppose that  $F = \{1,2,7,8,9\}$  and  $G = \{2,7\}$ . Then  $\mathcal{A}$  picks out G since  $A \cap F = G$  if we choose A = (1.5,7.5) for example. Let  $S(\mathcal{A},F)$  be the number of these subsets picked out by  $\mathcal{A}$ . Of course  $S(\mathcal{A},F) \leq 2^n$ .

**Example 4** Let  $A = \{(a, b) : a \leq b\}$  and  $F = \{1, 2, 3\}$ . Then A can pick out:

$$\emptyset$$
,  $\{1\}$ ,  $\{2\}$ ,  $\{3\}$ ,  $\{1,2\}$ ,  $\{2,3\}$ ,  $\{1,2,3\}$ .

So s(A, F) = 7. Note that  $7 < 8 = 2^3$ . If  $F = \{1, 6\}$  then A can pick out:

$$\emptyset$$
,  $\{1\}$ ,  $\{6\}$ ,  $\{1,6\}$ .

In this case  $s(A, F) = 4 = 2^2$ .

We say that F is **shattered** if  $s(A, F) = 2^n$  where n is the number of points in F.

Let  $\mathcal{F}_n$  denote all finite sets with n elements.

#### Define the **shatter coefficient**

$$s_n(\mathcal{A}) = \sup_{F \in \mathcal{F}_n} s(\mathcal{A}, F).$$

Note that  $s_n(\mathcal{A}) \leq 2^n$ .

The following theorem is due to Vapnik and Chervonenis. The proof is beyond the scope of the course. (If you take 10-702/36-702 you will learn the proof.)

**Theorem 5** Let A be a class of sets. Then

$$\mathbb{P}\left(\sup_{A\in\mathcal{A}}|P_n(A) - P(A)| > \epsilon\right) \le 8 \ s_n(\mathcal{A}) \ e^{-n\epsilon^2/32}.\tag{1}$$

This partly solves one of our problems. But, how big can  $s_n(\mathcal{A})$  be? Sometimes  $s_n(\mathcal{A}) = 2^n$  for all n. For example, let  $\mathcal{A}$  be all polygons in the plane. Then  $s_n(\mathcal{A}) = 2^n$  for all n. But, in many cases, we will see that  $s_n(\mathcal{A}) = 2^n$  for all n up to some integer d and then  $s_n(\mathcal{A}) < 2^n$  for all n > d.

Class $\mathcal{A}$	VC dimension $V_{\mathcal{A}}$
$\mathcal{A} = \{A_1, \dots, A_N\}$	$\leq \log_2 N$
Intervals $[a, b]$ on the real line	2
Discs in $\mathbb{R}^2$	3
Closed balls in $\mathbb{R}^d$	$\leq d+2$
Rectangles in $\mathbb{R}^d$	2d
Half-spaces in $\mathbb{R}^d$	d+1
Convex polygons in $\mathbb{R}^2$	$\infty$
Convex polygons with $d$ vertices	2d + 1

Table 1: The VC dimension of some classes A.

**Example 6** Let  $A = \{(a, b) : a, b \in \mathbb{R}, a \leq b\}$ . Then we have:

n	$2^n$	$s_n$
1	2	2
2	4	4
3	8	$\gamma$
4	16	11
:	:	:

So  $s_n = 2^n$  for n = 1, 2. For n > 2 we have  $s_N < 2^n$ .

The Vapnik-Chervonenkis (VC) dimension is

$$d = d(\mathcal{A}) = \text{ largest n such that } s_n(\mathcal{A}) = 2^n.$$

In other words, d is the size of the largest set that can be shattered.

Thus,  $s_n(\mathcal{A}) = 2^n$  for all  $n \leq d$  and  $s_n(\mathcal{A}) < 2^n$  for all n > d. The VC dimensions of some common examples are summarized in Table 1. Now here is an interesting question: for n > d how does  $s_n(\mathcal{A})$  behave? It is less than  $2^n$  but how much less?

**Theorem 7 (Sauer's Theorem)** Suppose that A has finite VC dimension d. Then, for all  $n \geq d$ ,

$$s(\mathcal{A}, n) \le (n+1)^d. \tag{2}$$

Sauer's Theorem is very surprising. It says there is a phase transition from exponential to polynomial. We conclude that:

**Theorem 8** Let A be a class of sets with VC dimension  $d < \infty$ . Then

$$\mathbb{P}\left(\sup_{A\in\mathcal{A}}|P_n(A) - P(A)| > \epsilon\right) \le 8 (n+1)^d e^{-n\epsilon^2/32}.$$
 (3)

**Example 9** Let's return to our first example. Suppose that  $X_1, \ldots, X_n$  have cdf F. Let

$$F_n(t) = \frac{1}{n} \sum_{i=1}^n I(X_i \le t).$$

We would like to bound  $\mathbb{P}(\sup_t |F_n(t) - F(t)| > \epsilon)$ . Notice that  $F_n(t) = P_n(A)$  where  $A = (-\infty, t]$ . Let  $A = \{(-\infty, t] : t \in \mathbb{R}\}$ . This has VC dimension d = 1. So

$$\mathbb{P}(\sup_{t} |F_n(t) - F(t)| > \epsilon) = \mathbb{P}\left(\sup_{A \in \mathcal{A}} |P_n(A) - P(A)| > \epsilon\right) \le 8 (n+1) e^{-n\epsilon^2/32}.$$

In fact, there is a tighter bound in this case called the DKW (Dvoretsky-Kiefer-Wolfowitz) inequality:

$$\mathbb{P}(\sup_{t} |F_n(t) - F(t)| > \epsilon) \le 2e^{-2n\epsilon^2}.$$