

## Problem Set 7 – The Particle Filter

The goal of this problem set is to use the particle filter in combination with Metropolis-Hastings to estimate parameters from an observed time series.

The variable  $X_t$  evolves according to an ARMA(2, 2) process:

$$X_t = \rho_1 X_{t-1} + \rho_2 X_{t-2} + \phi_1 \varepsilon_{t-1} + \phi_2 \varepsilon_{t-2} + \varepsilon_t.$$

Unfortunately we cannot observe  $X_t$  directly. Instead, every period we observe only data  $(A_t, B_t)$  which is related to  $X_t$  in the following way:

$$\begin{aligned} A_t &= \exp(X_t + \nu_t^A) \\ B_t &= \beta X_t^2 + \nu_t^B \end{aligned}$$

The repository contains the observed data series  $\{(A_t, B_t)\}_{t=1}^T$  for a  $T = 400$ .

1. Write the problem in terms of notation used in class, that is define the transition function  $g$ , the observation equation  $h$ , the state  $S_t$ , observables  $Y_t$  and the shocks  $W_t$  and  $V_t$  to state variables and observables, respectively. Which parameters that we need to estimate does the parameter vector  $\theta$  contain?
2. Use the particle filter to approximate the likelihood function  $p(Y_t|\theta)$  for a given set of parameters  $\theta$ .
3. Incorporate the routine from 2. into a Metropolis-Hastings algorithm to find posterior distributions for all parameters.