

Link-preserving channel assignment game for wireless mesh networks

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SIMULATION PROGRAM

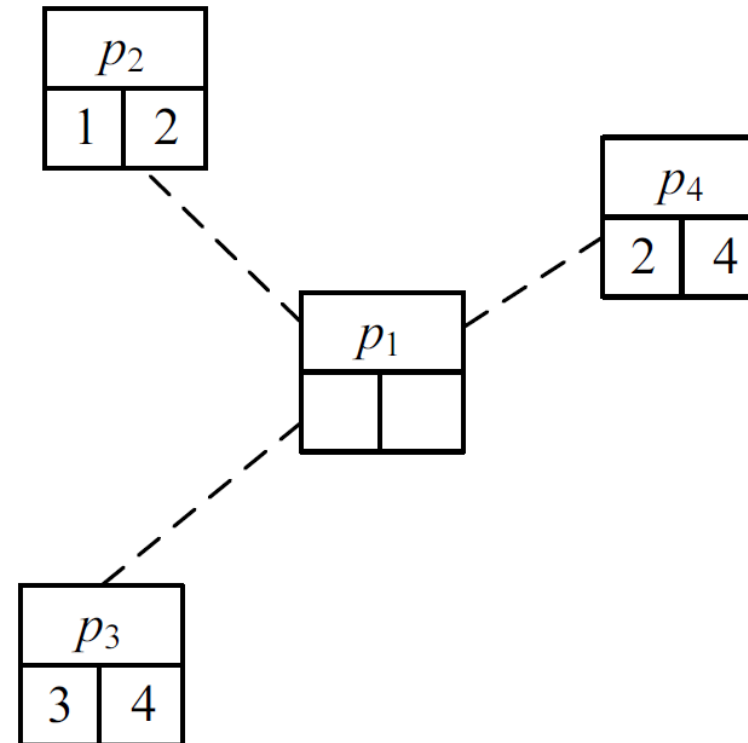
Outline

- Introduction
- Implementation of LPIM
- Simulation
- Conclusion

Introduction

Link-Preserving Interference-Minimization (LPIM)

- A channel assign game
- Exact potential game
=> always stabilizes
- Link-Preserving



Define of the game

Players: the set of mesh stations, $P = \{p_1, p_2, \dots, p_n\}$

Channels: set of orthogonal channels, $C = \{k_1, k_2, \dots, k_m\}$


Strategy: $s_i = (c_1^i, c_2^i, \dots, c_m^i)$ for p_i , where $c_j^i = 1$ or 0 indicating whether p_i assigns channel k_j to one of its

Number of interface: $r_i = \min(r_{max}, |N_i|)$, N_i number of neighbor, r_{max} max number of interface

Assume the number of available channels is at least as many as the number of interfaces

Impact of co-channel interference.

$s_i \cdot s_j$: the number of common channels assigned by both p_i and p_j

$$I_i(S) = - \sum_{p_j \in N_i} (s_i \cdot s_j)$$


Gains of connectivity

$$L_i(s) = \sum_{p_j \in N_i} C_i(s_i \cdot s_j),$$

Where $C_i(\mathbf{s}_i, \mathbf{s}_j) = \begin{cases} -|N_i| & \text{if } \mathbf{s}_i \cdot \mathbf{s}_j = 0 \\ 0 & \text{otherwise} \end{cases}$

For a particular strategy profile S

Combining previous two formula

β : a constant, where $\beta > r_{max}$

$$t_i(S) = \beta L_i(S) + I_i(S)$$

Utility and Potential function

Utility:

$$u_i(S) = t_i(S) + \sum_{p_j \in N_i} t_j(S)$$

Potential function:

$$\phi(S) = \sum_i t_i(S)$$

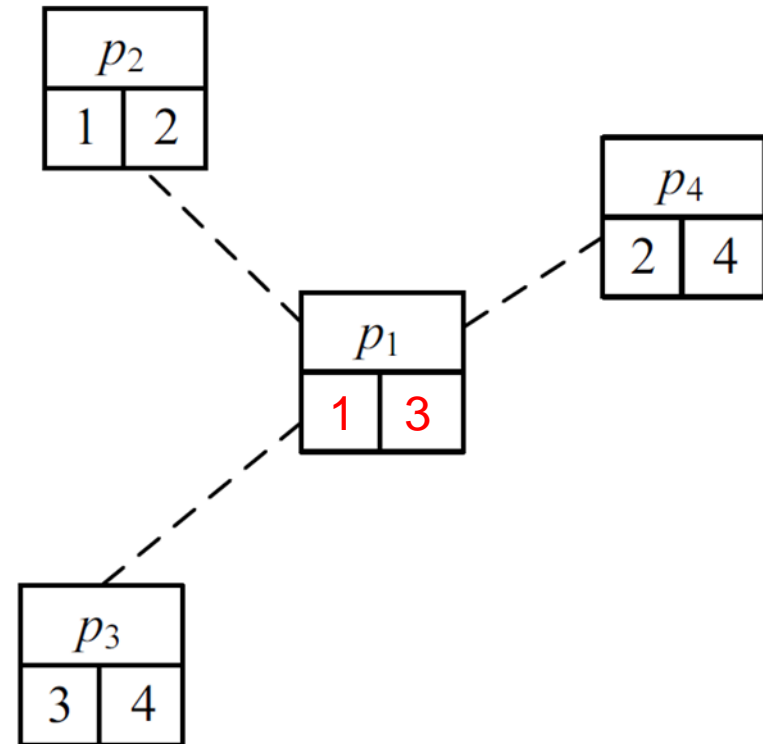
Utility example (1/2)

$$L_1(S) = 0 + 0 + (-3) = -3$$

$$I_1(S) = (-1) + (-1) + 0 = -2$$

$$t_1(S) = 5 \times (-3) + (-2) = -17, \beta = 5$$

$$u_i(S) = -17 + (-1) + (-1) + (-5) = -24$$



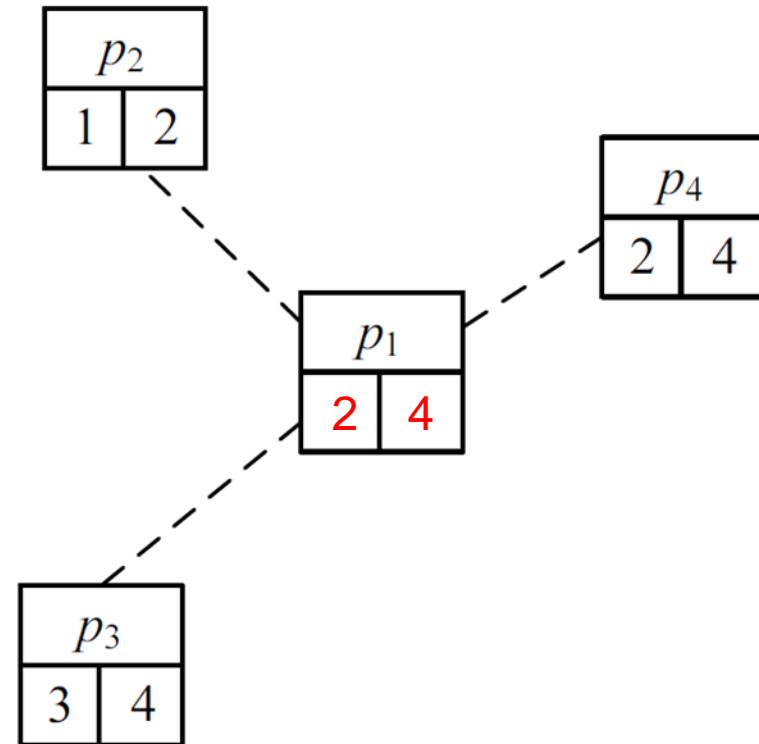
Utility example (2/2)

$$L_1(S) = 0 + 0 + 0 = 0$$

$$I_1(S) = (-1) + (-1) + (-2) = -4$$

$$t_1(S) = 5 \times (0) + (-4) = -4, \beta = 5$$

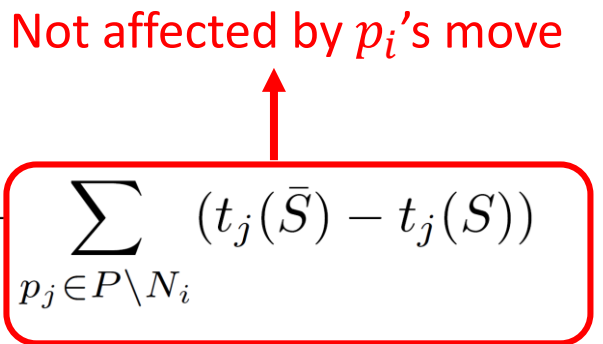
$$u_i(S) = -4 + (-1) + (-1) + (-2) = -8$$



Exact potential game

$$\begin{aligned}\phi(\bar{S}) - \phi(S) &= t_i(\bar{S}) - t_i(S) + \sum_{p_j \in N_i} (t_j(\bar{S}) - t_j(S)) + \sum_{p_j \in P \setminus N_i} (t_j(\bar{S}) - t_j(S)) \\ &= t_i(\bar{S}) - t_i(S) + \sum_{p_j \in N_i} (t_j(\bar{S}) - t_j(S)) \\ &= u_i(\bar{S}) - u_i(S)\end{aligned}$$

Not affected by p_i 's move



Best-response rule and Nash equilibrium

Player p_i selects strategy s_i^* only if

$$s_i^* = \operatorname{argmax}_{s_i \in S_i} u_i(s_i, s_{-i})$$

Nash equilibrium $S = (s_1, s_2, \dots, s_n)$ **Not unique**

If $u_i(s_i, s_{-i}) \geq u_i(s_i^*, s_{-i})$, $\forall i \in \{1, 2, \dots, n\}$
 $\forall s_i^* \in S_i$

Link-Preserving

Highest interference value of p_i :

$$I_i(S) = - \sum_{p_j \in N_i} \min(r_i, r_j) \geq -r_{\max} |N_i|$$

$r_i = \min(r_{\max}, |N_i|)$

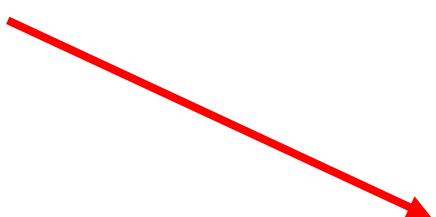
P_i no common channel on some neighbors :

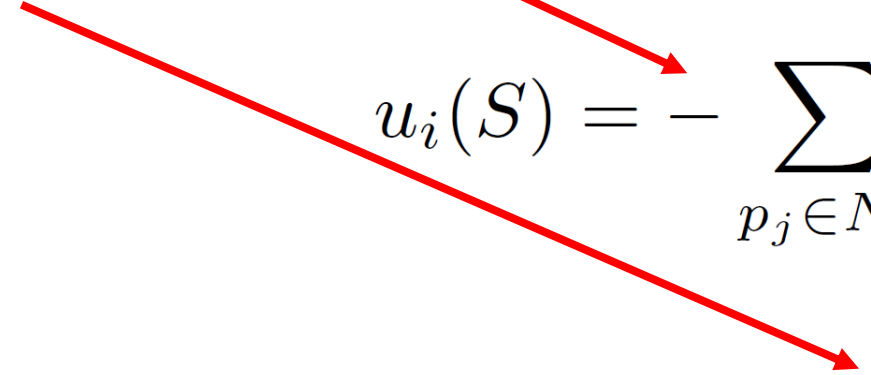
$$L_i(S) \leq -|N_i| \Rightarrow \beta L_i(S) \leq -\beta |N_i| < -r_{\max} |N_i|$$

$\beta > r_{\max}$

LPIM(PP)

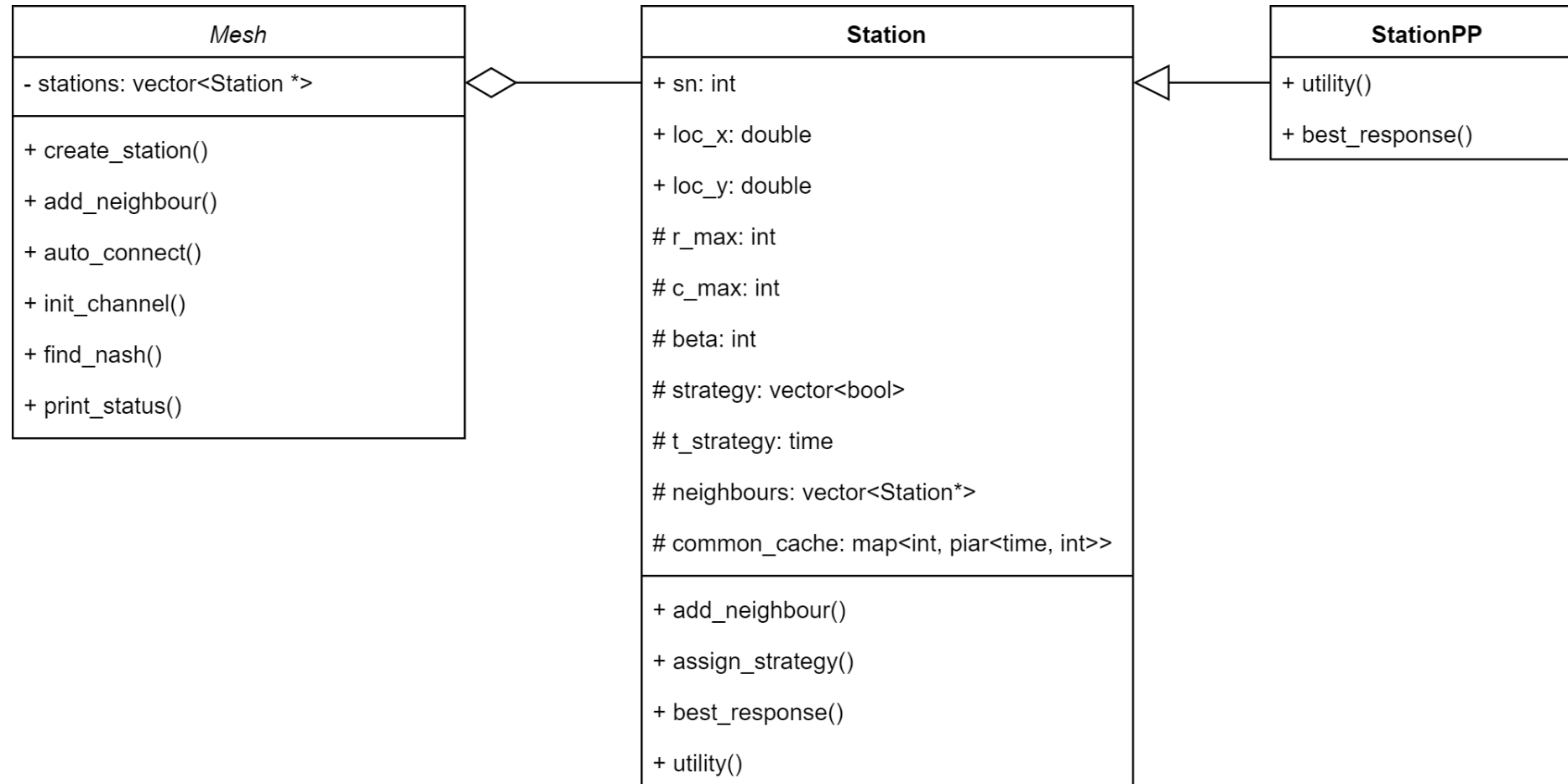
- A variant of LPIM
- Considers only the impact of interference
- Adheres to the Pigeonhole principle
- Exact potential game
- New utility function:


$$u_i(S) = - \sum_{p_j \in N_i} (s_i \cdot s_j)$$

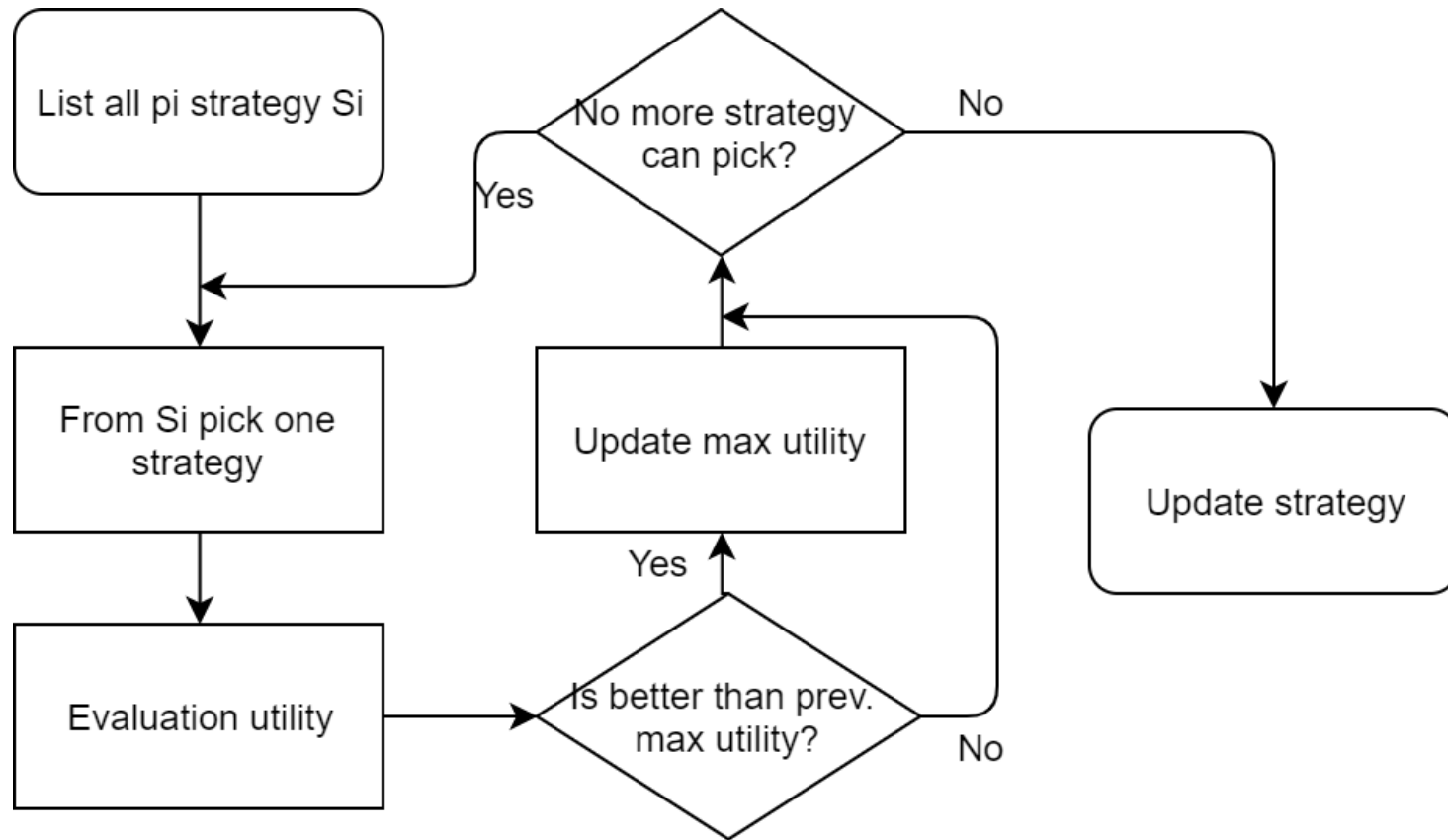

$$c_k^i = 0, \forall p_i \in P \text{ and } k > \min_{p_j \in N_i} \{r_i + r_j - 1\}$$

Implementation of LPIM

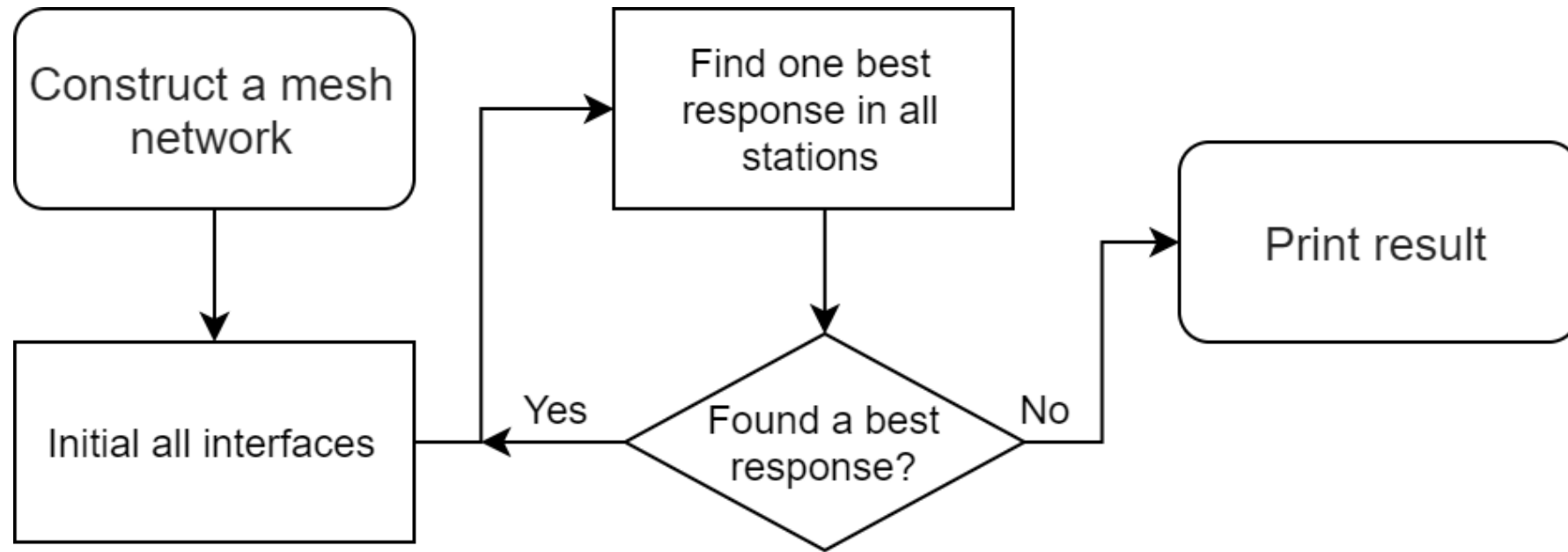
UML



Flow Chart for finding BP of p_i



Flow Chart for finding Nash equilibrium



Simulation

A five-station mesh network example

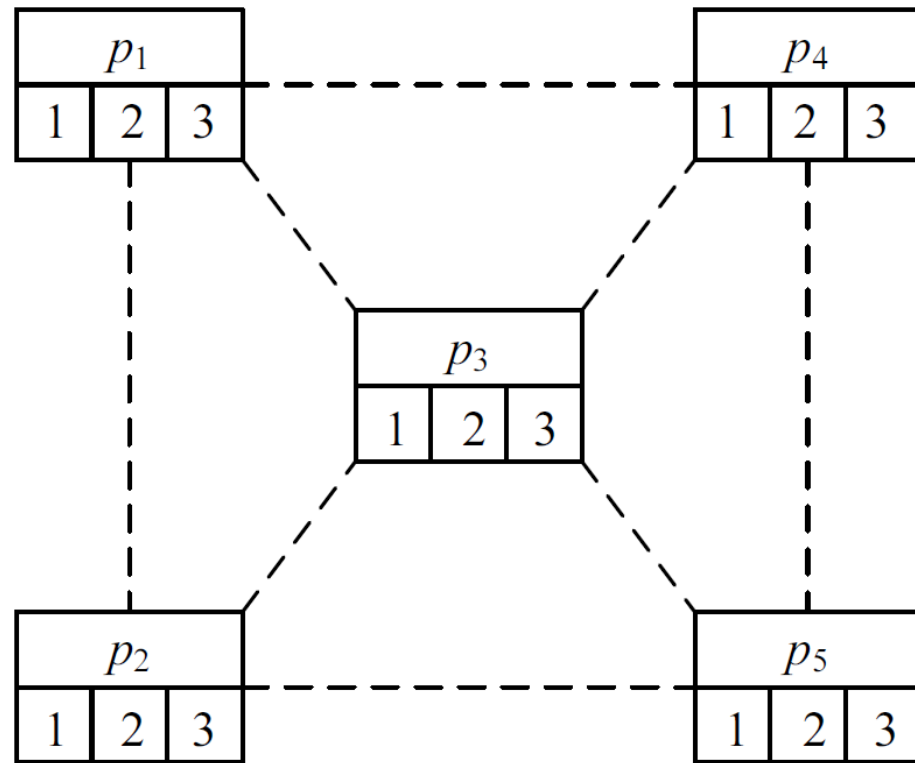


Fig. A five-station mesh network

- 5 stations(p_1 、 p_2 ... p_5)
- Max number of interfaces: 3
- Number of channel: 7

Best-reply path

Step	s_1	s_2	s_3	s_4	s_5
0	{1, 2, 3}	{1, 2, 3}	{1, 2, 3}	{1, 2, 3}	{1, 2, 3}
1	{1, 2, 3}	{1, 2, 3}	<u>{1, 4, 5}</u>	{1, 2, 3}	{1, 2, 3}
2	{1, 2, 3}	{1, 2, 3}	<u>{1, 4, 5}</u>	<u>{2, 4, 6}</u>	{1, 2, 3}
3	{1, 2, 3}	{1, 2, 3}	{1, 4, 5}	<u>{2, 4, 6}</u>	<u>{3, 5, 6}</u>
4	<u>{2, 5, 7}</u>	{1, 2, 3}	{1, 4, 5}	{2, 4, 6}	<u>{3, 5, 6}</u>

Both strategy profile are
Nash equilibrium

```
ceMinimization\x64\Release>LinkPreservingInterferenceMinimization.exe
{ 1 2 3} { 1 2 3} { 1 2 3} { 1 2 3} { 1 2 3}
{ 3 4 7} { 1 2 3} { 1 2 3} { 1 2 3} { 1 2 3}
{ 3 4 7} { 2 4 6} { 1 2 3} { 1 2 3} { 1 2 3}
{ 3 4 7} { 2 4 6} { 1 4 5} { 1 2 3} { 1 2 3}
{ 3 4 7} { 2 4 6} { 1 4 5} { 1 6 7} { 1 2 3}
{ 3 4 7} { 2 4 6} { 1 4 5} { 1 6 7} { 1 2 3}
```

Fig. Best-reply path in LPIM

Best-reply path(PP)

```
{ 1 2 3} { 1 2 3} { 1 2 3} { 1 2 3} { 1 2 3}
{ 1 4 5} { 1 2 3} { 1 2 3} { 1 2 3} { 1 2 3}
{ 1 4 5} { 2 4 5} { 1 2 3} { 1 2 3} { 1 2 3}
{ 1 4 5} { 2 4 5} { 3 4 5} { 1 2 3} { 1 2 3}
{ 1 4 5} { 2 4 5} { 3 4 5} { 1 2 3} { 1 2 3}
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Fig. Best-reply path in LPIM(PP)

Simulation

- Simulations on unit disk graphs
- Area: 1000 m X 1000 m = 1000,000 m^2
- Randomly placed n mesh nodes
- $r_{\text{max}} = 3$
- Communication range = 200 m
- Total number of Channel: m

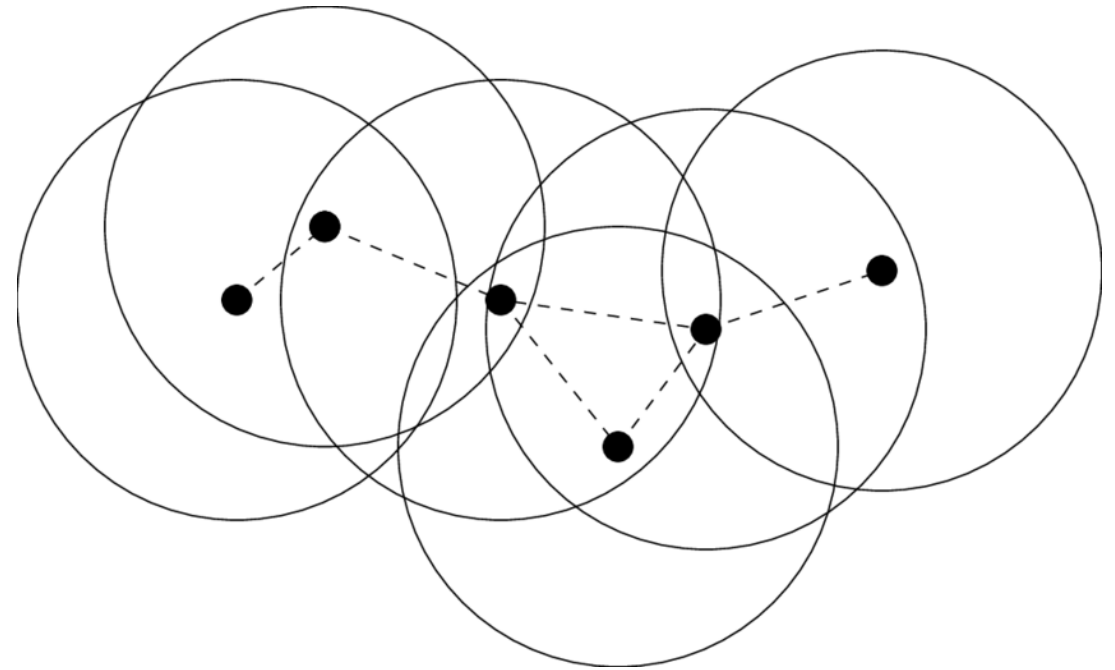
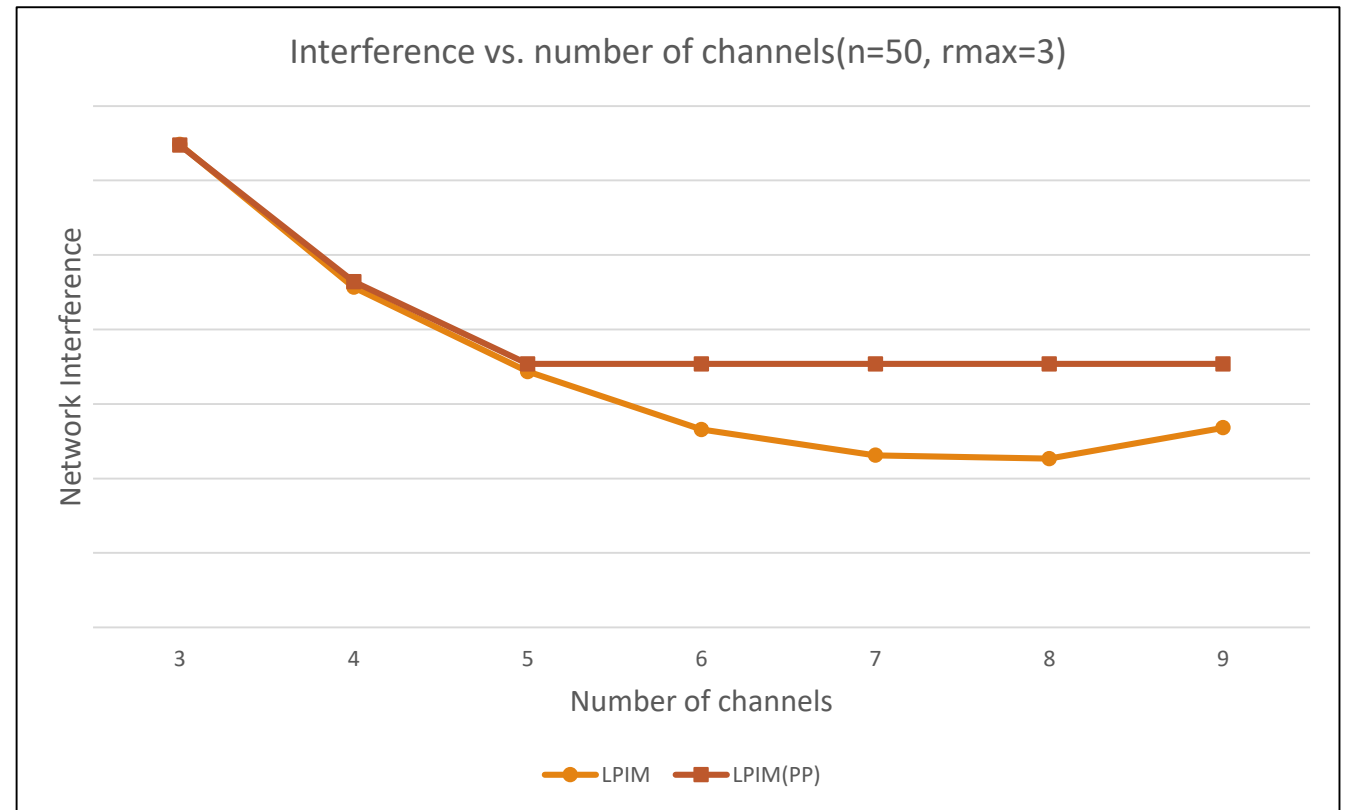


Fig. Unit disk graph model

Simulation – interference vs. channels

- Node: 50
- r_{max} : 3
- Channel: 3-9
- lower is better



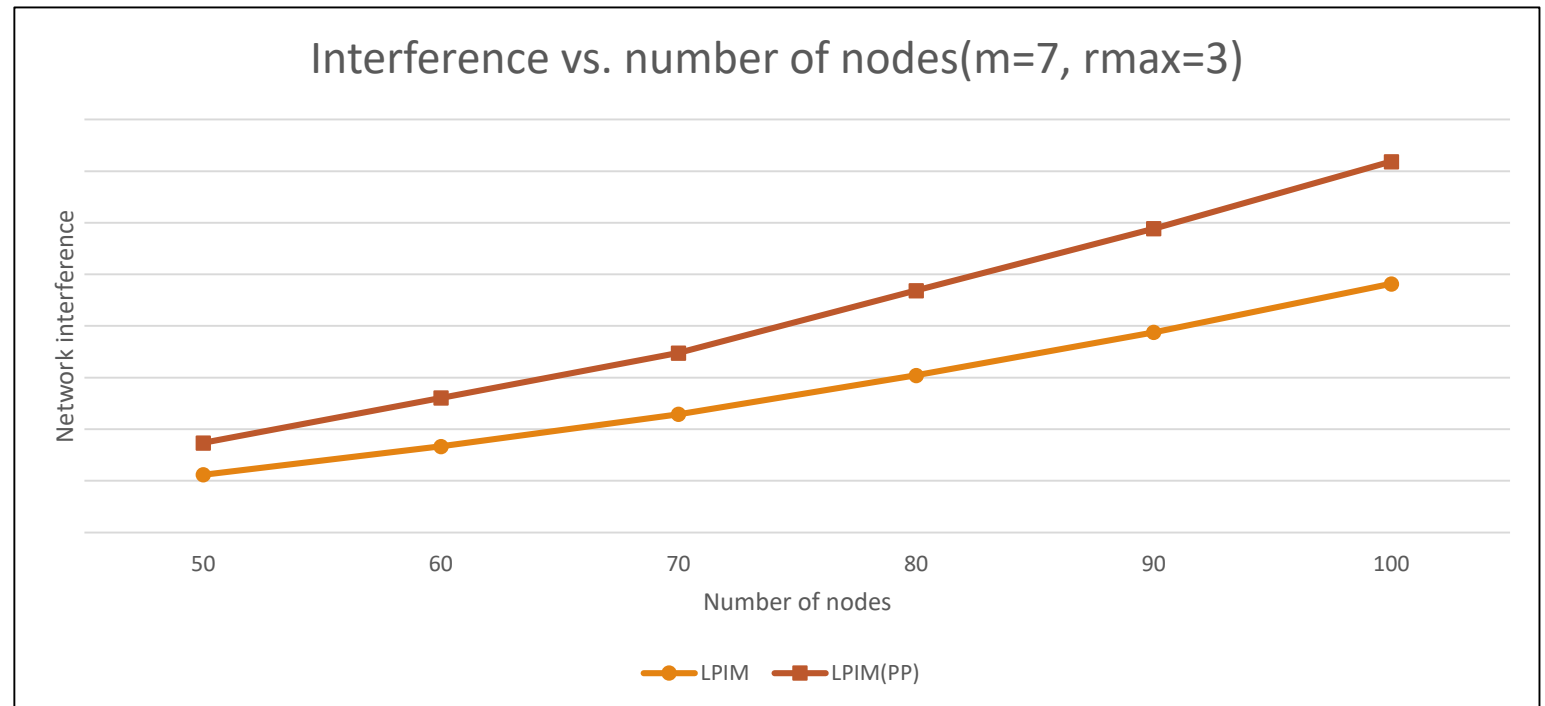
Simulation – interference vs. nodes

➤ Node: 50-100 (step 10)

➤ r_{max} : 3

➤ Channel: 7

➤ lower is better



Conclusions

- ✓ A non-cooperative game design for the channel assignment problem in WMNs
- ✓ First non-cooperative game approach that ensures link connectivity
- ✓ Eventually enters a Nash equilibrium regardless of initial channel configuration
- ✓ Link-preserving
- ✓ This approach generally better than the other approaches when a moderate number of channels are available

Thank you for your attention
