```
train, test, id2label, label2id = VisionDataset.fromImageFolder(
       "./hirise-map-proj-v3/data/",
       test_ratio = 0.15,
       balanced
                  = False,
       augmentation = True,
    );
   C:\Anaconda\envs\CEML\lib\site-packages\tqdm\auto.py:22: TqdmWarning: IProgress
   not found. Please update jupyter and ipywidgets. See
   https://ipywidgets.readthedocs.io/en/stable/user install.html
     from .autonotebook import tqdm as notebook_tqdm
   C:\Anaconda\envs\CEML\lib\site-
   packages\torchvision\transforms\transforms.py:333: UserWarning: Argument
   interpolation should be of type InterpolationMode instead of int. Please, use
   InterpolationMode enum.
     "Argument interpolation should be of type InterpolationMode instead of int. "
   C:\Anaconda\envs\CEML\lib\site-
   packages\torchvision\transforms\transforms.py:333: UserWarning: Argument
   interpolation should be of type InterpolationMode instead of int. Please, use
   InterpolationMode enum.
     "Argument interpolation should be of type InterpolationMode instead of int."
   Split Datasets...
   train ds: 8886
   +-----
   ---+----+
   | Dataset | bright_dune | crater | dark_dune | impact_ejecta | other |
   slope streak | spider | swiss cheese | Total |
   ---+----+
                       l 755 l
     Train |
                299
                                  445
                                             16
                                                 | 7005 |
                                                                 218
      42
         ĺ
               106
                       | 8886 |
    Test |
                55
                       l 115
                                   87
                                              4
                                                     l 1240 l
                                                                  42
                       | 1569 |
                16
   ---+----+
[2]: huggingface model = 'google/vit-base-patch16-224-in21k'
[3]: from hugsvision.nnet.VisionClassifierTrainer import VisionClassifierTrainer
    from transformers import ViTFeatureExtractor, ViTForImageClassification
    model_name = "HIRISE_5EPOCH_BATCH16"
    trainer = VisionClassifierTrainer(
       model_name = model_name,
                 = train,
       train
```

test

= test,

```
output_dir = "hirise-map-proj-v3/out/",
   max_epochs = 5,
   batch_size
                = 16, # On RTX 2080 Ti
                 = 2e-5,
   lr
   model = ViTForImageClassification.from_pretrained(
       huggingface_model,
       num_labels = len(label2id),
        label2id
                 = label2id,
        id2label = id2label
   ),
    feature_extractor = ViTFeatureExtractor.from_pretrained(
       huggingface_model,
   ),
)
```

Some weights of the model checkpoint at google/vit-base-patch16-224-in21k were not used when initializing ViTForImageClassification: ['pooler.dense.bias', 'pooler.dense.weight']

- This IS expected if you are initializing ViTForImageClassification from the checkpoint of a model trained on another task or with another architecture (e.g. initializing a BertForSequenceClassification model from a BertForPreTraining model).
- This IS NOT expected if you are initializing ViTForImageClassification from the checkpoint of a model that you expect to be exactly identical (initializing a BertForSequenceClassification model from a BertForSequenceClassification model).

Some weights of ViTForImageClassification were not initialized from the model checkpoint at google/vit-base-patch16-224-in21k and are newly initialized: ['classifier.bias', 'classifier.weight']

You should probably TRAIN this model on a down-stream task to be able to use it for predictions and inference.

C:\Anaconda\envs\CEML\lib\site-packages\transformers\optimization.py:309: FutureWarning: This implementation of AdamW is deprecated and will be removed in a future version. Use the PyTorch implementation torch.optim.AdamW instead, or set `no_deprecation_warning=True` to disable this warning

FutureWarning,

```
***** Running training *****
Num examples = 8886
Num Epochs = 5
Instantaneous batch size per device = 16
Total train batch size (w. parallel, distributed & accumulation) = 16
Gradient Accumulation steps = 1
Total optimization steps = 2780

{'O': 'bright_dune', '1': 'crater', '2': 'dark_dune', '3': 'impact_ejecta', '4': 'other', '5': 'slope_streak', '6': 'spider', '7': 'swiss_cheese'}
{'bright_dune': '0', 'crater': '1', 'dark_dune': '2', 'impact_ejecta': '3', 'other': '4', 'slope_streak': '5', 'spider': '6', 'swiss_cheese': '7'}
```

```
Trainer builded!
    Start Training!
    <IPython.core.display.HTML object>
    ***** Running Evaluation *****
      Num examples = 1569
      Batch size = 16
    ***** Running Evaluation *****
      Num examples = 1569
      Batch size = 16
    ***** Running Evaluation *****
      Num examples = 1569
      Batch size = 16
    ***** Running Evaluation *****
      Num examples = 1569
      Batch size = 16
    ***** Running Evaluation *****
      Num examples = 1569
      Batch size = 16
    Training completed. Do not forget to share your model on huggingface.co/models
    =)
    Saving model checkpoint to hirise-map-
    proj-v3/out/HIRISE_5EPOCH_BATCH16/5_2022-05-09-11-27-21/trainer/
    Configuration saved in hirise-map-
    proj-v3/out/HIRISE_5EPOCH_BATCH16/5_2022-05-09-11-27-21/trainer/config.json
    Model weights saved in hirise-map-proj-v3/out/HIRISE_5EPOCH_BATCH16/5_2022-05-09
    -11-27-21/trainer/pytorch model.bin
    Configuration saved in hirise-map-
    proj-v3/out/HIRISE_5EPOCH_BATCH16/5_2022-05-09-11-27-21/model/config.json
    Model weights saved in hirise-map-
    proj-v3/out/HIRISE 5EPOCH BATCH16/5 2022-05-09-11-27-21/model/pytorch model.bin
    Feature extractor saved in hirise-map-proj-v3/out/HIRISE_5EPOCH_BATCH16/5_2022-0
    5-09-11-27-21/feature extractor/preprocessor config.json
    Model saved at: hirise-map-
    proj-v3/out/HIRISE_5EPOCH_BATCH16/5_2022-05-09-11-27-21
[5]: import pandas as pd
     import seaborn as sn
     import matplotlib.pyplot as plt
     from sklearn.metrics import confusion matrix
     cm = confusion matrix(ref, hyp)
```

Confusion Matrix saved to ./hirise-map-proj-v3/out/HIRISE_5EPOCH_BATCH16/conf_matrix_1.jpg

1.5 4. Evaluate CNN vs ViT - WIP

```
[4]: # Evaluate the ViT
ref, hyp = trainer.evaluate_f1_score()
```

100% | 1569/1569 [08:03<00:00, 3.25it/s]

	precision	recall	f1-score	support
bright_dune	0.9123	0.9455	0.9286	55
crater	0.8814	0.9043	0.8927	115
dark_dune	0.9535	0.9425	0.9480	87
<pre>impact_ejecta</pre>	0.0000	0.0000	0.0000	4
other	0.9839	0.9847	0.9843	1240
${ t slope_streak}$	0.8837	0.9048	0.8941	42
spider	0.8889	0.8000	0.8421	10
swiss_cheese	1.0000	0.9375	0.9677	16
accuracy			0.9688	1569
macro avg	0.8130	0.8024	0.8072	1569
weighted avg	0.9665	0.9688	0.9676	1569

Logs saved at: hirise-map-

proj-v3/out/HIRISE_5EPOCH_BATCH16/5_2022-05-09-11-27-21