

Weekly Progress Report

May 3-14th, 2021

Presented by Yannis (Yiming) He 84189287

Noah's Ark | Autonomous Driving Lab
LiDAR Domain Adaptation

Manager: Bingbing Liu 00435285
Supervisor: Eduardo Corral Soto 00407762



- May 3rd (Mon)
 - Set up accounts
 - Dayforce
 - Laptop
 - Orientation
 - Finished training for new hires
 - Waiting for next steps from Bingbing Liu
 - Find research paper
 - Deep Domain Adaptation: A survey
 - Semantic Segmentation Survey

- May 4th (Tue)
 - Completed
 - Select Domain Adaptation team
 - Meet with Eduardo from 3-4pm
 - Intro to ADL
 - Intro to Domain Adaptation
 - To do:
 - Read papers:
 - Deep DA survey
 - KITTI Paper
 - Isola image to image paper
 - CycleGAN paper
 - LiDAR few-shot DA via integrated CycleGAN and 3D obj detect
 - View Dataset
 - KITTI
 - NuScence
 - Request for Gitlab and servers
 - Figure out who is my mentor

- May 5th (Wed)
 - Stand up meeting 9-10am
 - Get gitlab access
 - Weekly report
 - Lcpss
 - Udass
 - Read papers: deep visual DA: a survey
 - Make reading analysis
- May 6th & 7th (Thur, Fri):
 - Standup meeting 9-10am
 - Read and finished reading the Survey and finish paper analysis
- May 10th (Mon):
 - Read and make paper analysis for KITTI dataset paper
- May 11th (Tue):
 - Read and make paper analysis for nuScenes dataset paper
- May 12th (Wed)
 - view weekly report
 - Bingbing:
 - Big_perception.v0.1.pptx
 - Kyber_Lidar_Perception_plan_2019_v0.3English.pptx
 - LP2020_v3.pptx
 - Eduardo:
 -
 - Edit research analysis and add TODO papers
 - Papers listed in kyber-perception > Wiki > LiDAR Domain Adaptation Papers
 - Read kyber-perception > Wiki > Domain Adaptation Goals

Paper Analysis Screenshot (part of the notes):

SLIDE 1: PAPER ANALYSIS

Abstract: Image forgery detection is a category of tampering detection. This paper proposes a new third-order adaptive R-net for image forgery detection. The proposed R-net is a deep convolutional neural network (DCNN) based on the third-order adaptive R-net. The proposed R-net is a deep convolutional neural network (DCNN) based on the third-order adaptive R-net. The proposed R-net is a deep convolutional neural network (DCNN) based on the third-order adaptive R-net.

Introduction: Image forgery detection is a category of tampering detection. This paper proposes a new third-order adaptive R-net for image forgery detection. The proposed R-net is a deep convolutional neural network (DCNN) based on the third-order adaptive R-net. The proposed R-net is a deep convolutional neural network (DCNN) based on the third-order adaptive R-net.

Related Work: Image forgery detection is a category of tampering detection. This paper proposes a new third-order adaptive R-net for image forgery detection. The proposed R-net is a deep convolutional neural network (DCNN) based on the third-order adaptive R-net. The proposed R-net is a deep convolutional neural network (DCNN) based on the third-order adaptive R-net.

Methodology: Image forgery detection is a category of tampering detection. This paper proposes a new third-order adaptive R-net for image forgery detection. The proposed R-net is a deep convolutional neural network (DCNN) based on the third-order adaptive R-net. The proposed R-net is a deep convolutional neural network (DCNN) based on the third-order adaptive R-net.

Conclusion: Image forgery detection is a category of tampering detection. This paper proposes a new third-order adaptive R-net for image forgery detection. The proposed R-net is a deep convolutional neural network (DCNN) based on the third-order adaptive R-net. The proposed R-net is a deep convolutional neural network (DCNN) based on the third-order adaptive R-net.

[illegible][illegible]

- May 13, 14th (Thur, Friday)
 - Reading
 - Domain_Adaptation_NCRN_2021_Presentation.pdf | Eduardo
 - Weekly Report - Eduardo:
 - Content > General
 - Update Slides
 - Updated Plans: LiDAR_CycleGAN_plan_Aug_2020.pdf
 - Update_May_3_2021.pdf
 - Update_Apr_26_2021.pdf
 - Weekly Report - Amir
 - intro.pptx
 - report-April-30-2021.pptx
 - Domain Adaptation Blog (Chinese sources)
 - <https://blog.csdn.net/ltochange/article/details/78773476>
 - <https://baike.baidu.com/item/%E9%A2%86%E5%9F%9F%E8%87%AA%E9%80%82%E5%BA%94/22778550?fr=aladdin>
 - <https://zhuanlan.zhihu.com/p/50710267>

End of May 14th, Weekly Report

Weekly Progress Report

May 17-21st, 2021

Presented by Yannis (Yiming) He 84189287

Noah's Ark | Autonomous Driving Lab
LiDAR Domain Adaptation

Manager: Bingbing Liu 00435285
Supervisor: Eduardo Corral Soto 00407762



- May 17 (Monday)
 - Confirmed sub-topic (mentor: Eduardo)
 - Setting up gitlab for weekly report
 - Getting access to GPU server (talk to Arash)
 - Discuss with Eduardo for next step
 - Waiting for access to GPU server. In the meantime:
 - Read CycleGAN paper again
 - Read CycCADA paper
 - Once GPU server is setup
 - meet Eduardo again
 - Copy his data
 - Hear the explanation for CycCADA architectures
 - Investigate issue behind multiGPU
- May 18 (Tuesday):
 - Finished reading CycleGAN with Paper reading analysis
 - Attend NCRN day 1
 - Contact Arash for server setup
 - Start reading CycCADA
- May 19 (Wed):
 - Upload paper analysis under my wiki pages
 - Attend NCRN day 2
 - Clearpath
 - Huawei
 - UofT - Steven Waslander
 - Reading CycCADA

- May 20 (Thur)
 - Attend NCRN day 3
 - Finished reading CycCADA
- - May 21 (Friday)
 - Standup meeting
 - Meeting with Yang to learn about Simulation setting and pipeline
 - Attend Co-op meeting hosted by Sylvia
 - Learn dockers
 - Start reading LiDAR Semantic Segmentation: A Review by Ehsan Taghavi, et al.

End of May 21st, Weekly Report

Weekly Progress Report

May 24-28th, 2021

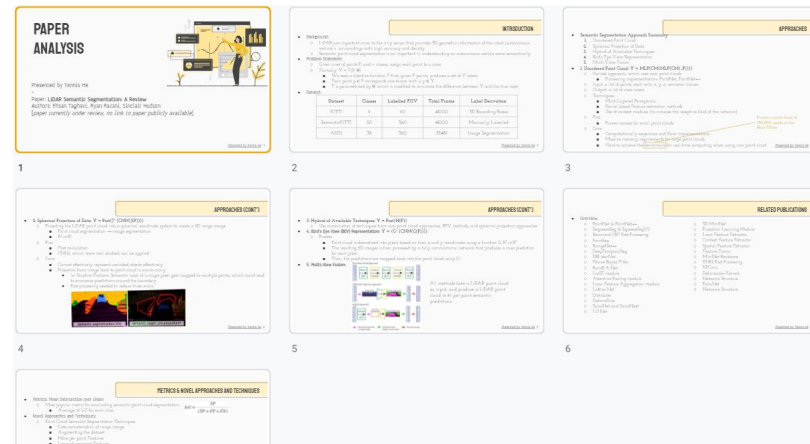
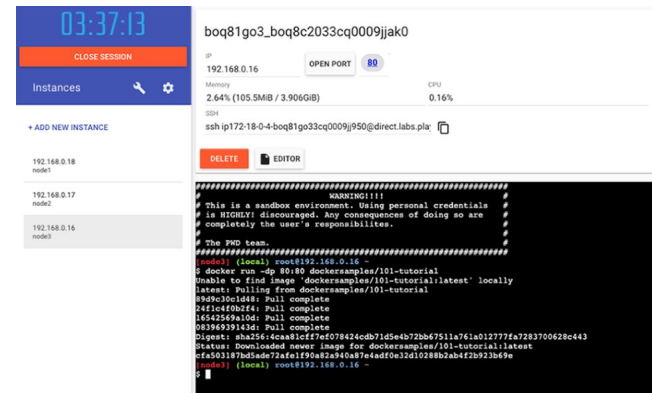
Presented by Yannis (Yiming) He 84189287

Noah's Ark | Autonomous Driving Lab
LiDAR Domain Adaptation

Manager: Bingbing Liu 00435285
Supervisor: Eduardo Corral Soto 00407762



- May 24 (Monday)
 - Victoria Holiday (no work)
- May 25 (Tuesday)
 - Learn docker
 - Finished Docker 101 Tutorial via "Play-with-docker" platform →
 - <https://www.docker.com/101-tutorial>
 - Meet Yang Liu for Simulation Setting
 - Carla Python API
 - Go through code for synthetic data collection
 - Code to be edited:
 - No_noise -> has_noise
- May 25 (Wednesday)
 - Read paper: LiDAR Semantic Segmentation: A Review
 - By Ehsan Taghavi, Ryan Razani, Sinclair Hudson
- May 26 (Thursday)
 - Setup server (gx6), shared with Eduardo
 - Still waiting for my own server 😞
 - Meeting with Eduardo
 - server usage
 - Next step tasks
 - Ran my first training (cycleGAN)
- ➡ - May 28 (Friday)
 - Try fixing the permission issue in my docker VM
 - Read cycleGAN code
 - Coffee talk for HouseGAN
 - Meet Eduardo for next step discussion



End of May 28th, Weekly Report

Weekly Progress Report

May 31- June 4th, 2021

Presented by Yannis (Yiming) He 84189287

Noah's Ark | Autonomous Driving Lab
LiDAR Domain Adaptation

Manager: Bingbing Liu 00435285
Supervisor: Eduardo Corral Soto 00407762



- May 31 (Monday):
 - Running LCPSS pipeline from STEP1 to STEP3 (currently on STEP 2)
 - Running STEP1 (running)
 - Executed STEP2 using checkpoint epoch 5
 - Study the single GPU code before working towards multi-gpu CycleGAN code
 - Meeting with Eduardo and learn how to run the STEP1 & 2 for multiGPU (udass)
- June 1 (Tuesday):
 - Check LCPSS STEP2 result, ask for instruction for STEP3 if Eduardo has time
 - ICRA public conference:
 - 11-12pm Tecent AI Lab (live.bilibili.com/23041569)
 - 12-13pm Continuum Robotics Lab
 - Meeting with Eduardo for lcpss STEP3
 - Make inference (lcpss STEP2) for checkpoint15 epoch
 - Train udass with 1 GPU (to compare with lcpss, which is also using 1 GPU) (running)
 - Compare and contrast LCPSS vs UDASS code
- June 2 (Wed):
 - Run lcpss STEP3 with checkpoint 15 (Appendix 1)
 - Studying Code for udass vs lcpss
- June 3 (Thursday):
 - Studying code for udass vs lcpss
 - Record hyper-parameters to make comparison
- ➡ - June 4 (Friday)
 - Run STEP2 for udass
 - Compare code/hyper-parameters
 - Attend new intern event at 12pm organized by Terry Li

End of June 4th, Weekly Report