

HW0

September 11, 2025

1 HW0 - Turn your favorite photo a rotating video

Total Points: 100

Assignment Due: Sep 11th Thursday 11:59 PM EST

In this assignment, you will: - Implement rotation using **forward mapping** (origin & arbitrary center) - Implement rotation using **inverse mapping** (origin & arbitrary center) - Animate your image rotating and export as an MP4 video

Please submit the following files on Canvas: - The original .ipynb notebook - A PDF version of the .ipynb notebook - rotation.mp4 - rotating_favorite_video.mp4 - rotating_favorite_creative_video.mp4

Allowed libraries: **numpy, matplotlib (plt), imageio, opencv-python (cv2)**

```
[1]: !pip install numpy matplotlib imageio opencv-python
```

```
Requirement already satisfied: numpy in /usr/local/lib/python3.12/dist-packages (2.0.2)
```

```
Requirement already satisfied: matplotlib in /usr/local/lib/python3.12/dist-packages (3.10.0)
```

```
Requirement already satisfied: imageio in /usr/local/lib/python3.12/dist-packages (2.37.0)
```

```
Requirement already satisfied: opencv-python in /usr/local/lib/python3.12/dist-packages (4.12.0.88)
```

```
Requirement already satisfied: contourpy>=1.0.1 in /usr/local/lib/python3.12/dist-packages (from matplotlib) (1.3.3)
```

```
Requirement already satisfied: cycler>=0.10 in /usr/local/lib/python3.12/dist-packages (from matplotlib) (0.12.1)
```

```
Requirement already satisfied: fonttools>=4.22.0 in /usr/local/lib/python3.12/dist-packages (from matplotlib) (4.59.2)
```

```
Requirement already satisfied: kiwisolver>=1.3.1 in /usr/local/lib/python3.12/dist-packages (from matplotlib) (1.4.9)
```

```
Requirement already satisfied: packaging>=20.0 in /usr/local/lib/python3.12/dist-packages (from matplotlib) (25.0)
```

```
Requirement already satisfied: pillow>=8 in /usr/local/lib/python3.12/dist-packages (from matplotlib) (11.3.0)
```

```
Requirement already satisfied: pyparsing>=2.3.1 in /usr/local/lib/python3.12/dist-packages (from matplotlib) (3.2.3)
```

Requirement already satisfied: python-dateutil>=2.7 in
/usr/local/lib/python3.12/dist-packages (from matplotlib) (2.9.0.post0)
Requirement already satisfied: six>=1.5 in /usr/local/lib/python3.12/dist-
packages (from python-dateutil>=2.7->matplotlib) (1.17.0)

Use `imageio.imread` to load the sample image.

```
[2]: import imageio
import matplotlib.pyplot as plt

img = imageio.imread('Lenna.png')
plt.imshow(img)
plt.axis('off')
plt.show()
```

/tmp/ipython-input-3604052135.py:4: DeprecationWarning: Starting with ImageIO v3 the behavior of this function will switch to that of `io.v3.imread`. To keep the current behavior (and make this warning disappear) use ``import imageio.v2 as imageio`` or call ``imageio.v2.imread`` directly.

```
img = imageio.imread('Lenna.png')
```



1.1 Part A. Forward Mapping (30 points)

1.1.1 Explanation

- **Equation:**

$$x_d = R(\theta) x_s$$

where

$$R(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

- **Insight:** *Where will the pixel land in the destination? (Throwing pixels forward).*
- **Pseudocode:**

```
for each pixel (x_s, y_s) in source:
    [x_d, y_d] = R(theta) * [x_s, y_s]
    put source(x_s, y_s) into destination(round(x_d), round(y_d))
```

1.1.2 Q1-1. Implement forward_mapping_origin (15 points)

Write a function that rotates around the origin using forward mapping.

```
[3]: # Some stuff that is commented out was very slow during video
      # generation, switched to vectorized operations on all tasks
      # for faster execution
```

```
[4]: # import numpy as np

      # def forward_mapping_origin(img, theta_deg):
      #     # TODO: Implement forward mapping around origin
      #     theta_rad = np.deg2rad(theta_deg)
      #     src_h, src_w = img.shape[:2]
      #     dst_h = src_h
      #     dst_w = src_w

      #     out = np.zeros((dst_h, dst_w, 3), dtype=np.uint8)

      #     # YOUR CODE HERE
      #     for c in range(img.shape[2]):
      #         for x_s in range(src_w):
      #             for y_s in range(src_h):
      #                 cur = np.array([x_s, y_s])
      #                 R = np.array([[np.cos(theta_rad), -np.sin(theta_rad)],
      #                               [np.sin(theta_rad), np.cos(theta_rad)]])

      #                 dest = (R @ cur).astype(int)
      #                 x_d, y_d = dest[0], dest[1]

      #                 if 0 <= x_d < dst_w and 0 <= y_d < dst_h:
```

```
#             out[y_d, x_d, c] = img[y_s, x_s, c]

#     return out
```

```
[5]: import numpy as np

def forward_mapping_origin(img, theta_deg):
    # TODO: Implement forward mapping around origin
    theta_rad = np.deg2rad(theta_deg)
    src_h, src_w = img.shape[:2]
    dst_h = src_h
    dst_w = src_w

    out = np.zeros((dst_h, dst_w, 3), dtype=np.uint8)

    # YOUR CODE HERE
    R = np.array([[np.cos(theta_rad), -np.sin(theta_rad)],
                  [np.sin(theta_rad),  np.cos(theta_rad)]])

    ys, xs = np.indices((src_h, src_w))
    coords = np.stack([xs.ravel(), ys.ravel()], axis=-1) # shape (N, 2)

    # vectorized rotate
    dest = (coords @ R.T).round().astype(int)
    xd, yd = dest[:, 0], dest[:, 1]

    mask = (0 <= xd) & (xd < dst_w) & (0 <= yd) & (yd < dst_h)
    out[yd[mask], xd[mask]] = img[coords[mask, 1], coords[mask, 0]]

    return out
```

1.1.3 Q1-2. Rotate by 30 degrees and display (5 points)

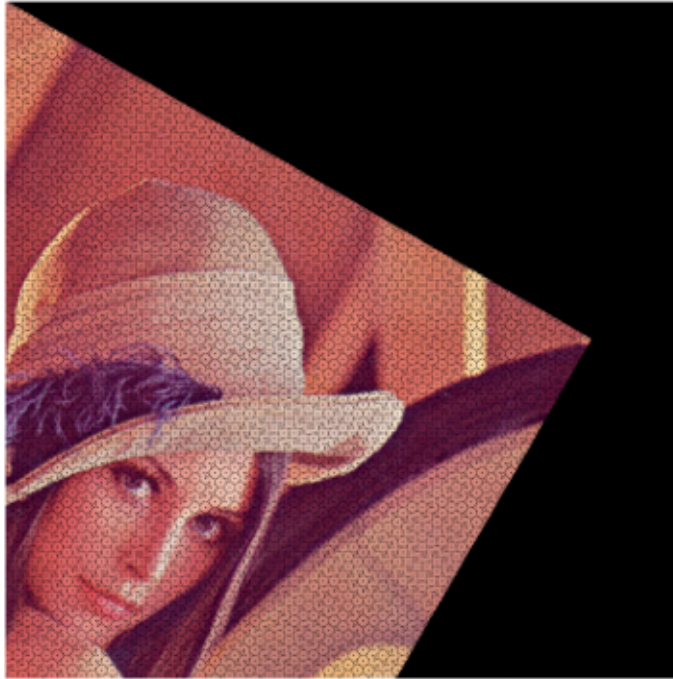
The image should look like it is rotated by -30 degree because in a Numpy array, the y-axis increases downward, whereas in Cartesian coordinates, the y-axis increases upward.

The expected output looks as follows:

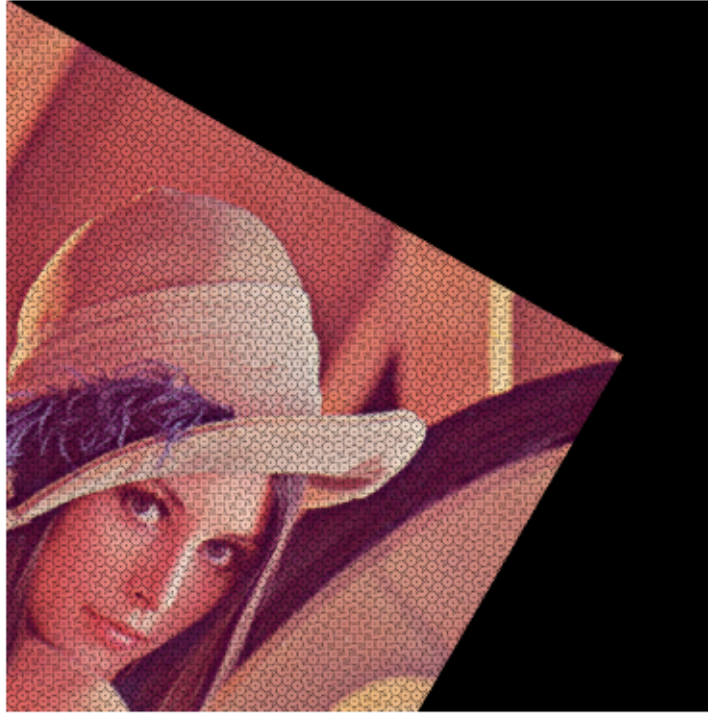
```
[6]: expected_output = imageio.imread('HW0_Q1_2_expected_output.png')
plt.imshow(expected_output)
plt.axis('off')
plt.show()
```

/tmp/ipython-input-188146722.py:1: DeprecationWarning: Starting with ImageIO v3 the behavior of this function will switch to that of iio.v3.imread. To keep the current behavior (and make this warning disappear) use `import imageio.v2 as imageio` or call `imageio.v2.imread` directly.

```
expected_output = imageio.imread('HW0_Q1_2_expected_output.png')
```



```
[7]: # Plot the output here.  
rotated = forward_mapping_origin(img, 30)  
plt.imshow(rotated)  
plt.axis('off')  
plt.show()
```



1.1.4 Q1-3. Implement rotation around arbitrary coordinate (15 points)

Hint: shift coordinates so that the chosen point is treated as the origin before rotation.

```
[8]: # def forward_mapping_arbitrary(img, theta_deg, cx, cy):
#     # TODO: Implement forward mapping around arbitrary point (cx, cy)
#     theta_rad = np.deg2rad(theta_deg)
#     src_h, src_w = img.shape[:2]
#     dst_h = src_h
#     dst_w = src_w

#     out = np.zeros((dst_h, dst_w, 3), dtype=np.uint8)

#     # YOUR CODE HERE
#     for c in range(img.shape[2]):
#         for x_s in range(src_w):
#             for y_s in range(src_h):
#                 cur = np.array([x_s, y_s])
#                 R = np.array([[np.cos(theta_rad), -np.sin(theta_rad)],
#                               [np.sin(theta_rad), np.cos(theta_rad)]])
```

```

#         dest = (R @ (cur - np.array([cx, cy])) + np.array([cx, cy])).
#         ↪astype(int)
#         x_d, y_d = dest[0], dest[1]

#         if 0 <= x_d < dst_w and 0 <= y_d < dst_h:
#             out[y_d, x_d, c] = img[y_s, x_s, c]

#     return out

```

```

[9]: import numpy as np

def forward_mapping_arbitrary(img, theta_deg, cx, cy):
    # TODO: Implement forward mapping around arbitrary point (cx, cy)
    theta_rad = np.deg2rad(theta_deg)
    src_h, src_w = img.shape[:2]
    dst_h = src_h
    dst_w = src_w

    out = np.zeros((dst_h, dst_w, 3), dtype=np.uint8)

    # YOUR CODE HERE
    R = np.array([[np.cos(theta_rad), -np.sin(theta_rad)],
                  [np.sin(theta_rad),  np.cos(theta_rad)]])

    ys, xs = np.indices((src_h, src_w))
    coords = np.stack([xs.ravel(), ys.ravel()], axis=-1) # shape (N, 2)

    # vectorized rotate around (cx, cy)
    dest = ((coords - np.array([cx, cy])) @ R.T + np.array([cx, cy])).round().
    ↪astype(int)
    xd, yd = dest[:, 0], dest[:, 1]

    mask = (0 <= xd) & (xd < dst_w) & (0 <= yd) & (yd < dst_h)
    out[yd[mask], xd[mask]] = img[coords[mask, 1], coords[mask, 0]]

    return out

```

1.1.5 Q1-4. Rotate with center (x=256, y=256), =30° and display (5 points)

The expected output looks as follows:

```

[10]: expected_output = imageio.imread('HW0_Q1_4_expected_output.png')
plt.imshow(expected_output)
plt.axis('off')
plt.show()

```



```
/tmp/ipython-input-107794347.py:1: DeprecationWarning: Starting with ImageIO v3
the behavior of this function will switch to that of iio.v3.imread. To keep the
current behavior (and make this warning disappear) use `import imageio.v2 as
imageio` or call `imageio.v2.imread` directly.
```

```
expected_output = imageio.imread('HW0_Q1_4_expected_output.png')
```



```
[11]: # Plot the output here.
rotated = forward_mapping_arbitrary(img, 30, 256, 256)
plt.imshow(rotated)
plt.axis('off')
plt.show()
```




Problems with forward mapping: holes (gap in the image) - they appear because some destination pixels are not assigned a value when multiple source pixels map to the same location or when no source pixel maps to a destination pixel. That is why we use **inverse mapping**.

1.2 Part B. Inverse Mapping (30 points)

1.2.1 Explanation

- **Equation:**

$$x_s = R(-\theta) x_d$$

where

$$R(-\theta) = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$

- **Insight:** *Walk over each destination pixel and ask: where should I pull the color from in the source?*
- **Pseudocode:**

```
for each pixel (x_d, y_d) in destination:
    [x_s, y_s] = R(-theta) * [x_d, y_d]
    destination(x_d, y_d) = sample_from_source(x_s, y_s)
```

1.2.2 Q2-1. Implement `inverse_mapping_origin` (15 points)

```
[12]: # def inverse_mapping_origin(img, theta_deg):
#      # TODO: Implement inverse mapping rotation around origin
#      theta_rad = np.deg2rad(theta_deg)
#      src_h, src_w = img.shape[:2]
#      dst_h = src_h
#      dst_w = src_w
#
#      out = np.zeros((dst_h, dst_w, 3), dtype=np.uint8)
#
#      # YOUR CODE HERE
#      for c in range(img.shape[2]):
#          for x_d in range(dst_w):
#              for y_d in range(dst_h):
#                  cur = np.array([x_d, y_d])
#                  R = np.array([[np.cos(theta_rad), np.sin(theta_rad)],
#                                [-np.sin(theta_rad), np.cos(theta_rad)]])
#
#                  dest = (R @ cur).astype(int)
#                  x_s, y_s = dest[0], dest[1]
#
#                  if 0 <= x_s < src_w and 0 <= y_s < src_h:
#                      out[y_d, x_d, c] = img[y_s, x_s, c]
#
#      return out
```

```
[13]: import numpy as np

def inverse_mapping_origin(img, theta_deg):
    # TODO: Implement inverse mapping rotation around origin
    theta_rad = np.deg2rad(theta_deg)
    src_h, src_w = img.shape[:2]
    dst_h = src_h
    dst_w = src_w

    out = np.zeros((dst_h, dst_w, 3), dtype=np.uint8)

    # YOUR CODE HERE
    R = np.array([[np.cos(theta_rad), np.sin(theta_rad)],
                  [-np.sin(theta_rad), np.cos(theta_rad)]])

    ys, xs = np.indices((dst_h, dst_w))
    coords = np.stack([xs.ravel(), ys.ravel()], axis=-1) # shape (N, 2)

    # vectorized inverse rotate
    dest = (coords @ R.T).round().astype(int)
```

```

xs_s, ys_s = dest[:, 0], dest[:, 1]

mask = (0 <= xs_s) & (xs_s < src_w) & (0 <= ys_s) & (ys_s < src_h)
out[coords[mask, 1], coords[mask, 0]] = img[ys_s[mask], xs_s[mask]]

return out

```

1.2.3 Q2-2. Display rotation ($=30^\circ$) (5 points)

The expected output looks as follows:

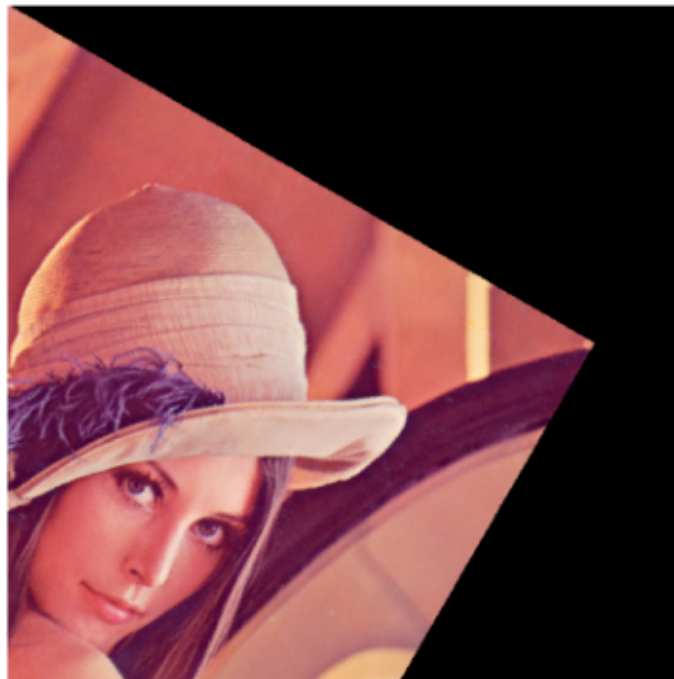
```

[14]: expected_output = imageio.imread('HW0_Q2_2_expected_output.png')
plt.imshow(expected_output)
plt.axis('off')
plt.show()

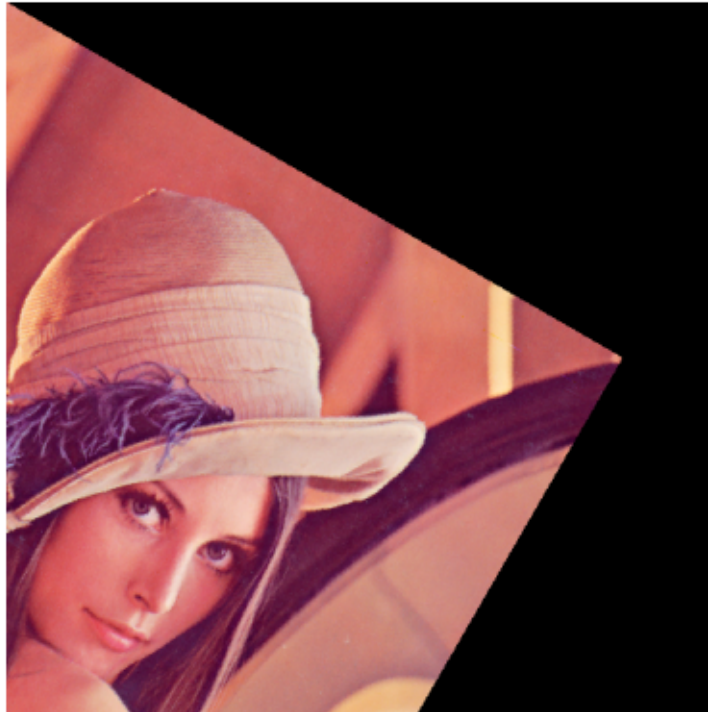
```

/tmp/ipython-input-4232865078.py:1: DeprecationWarning: Starting with ImageIO v3 the behavior of this function will switch to that of `iio.v3.imread`. To keep the current behavior (and make this warning disappear) use ``import imageio.v2 as imageio`` or call ``imageio.v2.imread`` directly.

```
expected_output = imageio.imread('HW0_Q2_2_expected_output.png')
```



```
[15]: # Plot the output here.
rotated = inverse_mapping_origin(img, 30)
plt.imshow(rotated)
plt.axis('off')
plt.show()
```



1.2.4 Q2-3. Implement rotation around arbitrary center (15 points)

```
[16]: # def inverse_mapping_arbitrary(img, theta_deg, cx, cy):
#     # TODO: Implement inverse mapping around arbitrary point (cx, cy)
#     theta_rad = np.deg2rad(theta_deg)
#     src_h, src_w = img.shape[:2]
#     dst_h = src_h
#     dst_w = src_w
#
#     out = np.zeros((dst_h, dst_w, 3), dtype=np.uint8)
#
#     # YOUR CODE HERE
#     for c in range(img.shape[2]):
#         for x_d in range(dst_w):
#             for y_d in range(dst_h):
#                 cur = np.array([x_d, y_d])
#                 R = np.array([[np.cos(theta_rad), np.sin(theta_rad)],
```

```

#                                     [-np.sin(theta_rad), np.cos(theta_rad)]]

#                                     dest = (R @ (cur - np.array([cx, cy])) + np.array([cx, cy])).
↳ astype(int)
#                                     x_s, y_s = dest[0], dest[1]

#                                     if 0 <= x_s < src_w and 0 <= y_s < src_h:
#                                     out[y_d, x_d, c] = img[y_s, x_s, c]

#                                     return out

```

```

[17]: import numpy as np

def inverse_mapping_arbitrary(img, theta_deg, cx, cy):
    # TODO: Implement inverse mapping around arbitrary point (cx, cy)
    theta_rad = np.deg2rad(theta_deg)
    src_h, src_w = img.shape[:2]
    dst_h = src_h
    dst_w = src_w

    out = np.zeros((dst_h, dst_w, 3), dtype=np.uint8)

    # YOUR CODE HERE
    R = np.array([[np.cos(theta_rad), np.sin(theta_rad)],
                  [-np.sin(theta_rad), np.cos(theta_rad)]])

    ys, xs = np.indices((dst_h, dst_w))
    coords = np.stack([xs.ravel(), ys.ravel()], axis=-1) # shape (N, 2)

    # vectorized inverse rotate around (cx, cy)
    dest = ((coords - np.array([cx, cy])) @ R.T + np.array([cx, cy])).round().
↳ astype(int)
    xs_s, ys_s = dest[:, 0], dest[:, 1]

    mask = (0 <= xs_s) & (xs_s < src_w) & (0 <= ys_s) & (ys_s < src_h)
    out[coords[mask, 1], coords[mask, 0]] = img[ys_s[mask], xs_s[mask]]

    return out

```

1.2.5 Q2-4. Display result (x=256, y=256, =30°) (5 points)

The expected output looks as follows:

```

[18]: expected_output = imageio.imread('HW0_Q2_4_expected_output.png')
plt.imshow(expected_output)
plt.axis('off')
plt.show()

```

```
/tmp/ipython-input-431391595.py:1: DeprecationWarning: Starting with ImageIO v3
the behavior of this function will switch to that of iio.v3.imread. To keep the
current behavior (and make this warning disappear) use `import imageio.v2 as
imageio` or call `imageio.v2.imread` directly.
```

```
expected_output = imageio.imread('HW0_Q2_4_expected_output.png')
```



```
[19]: # Plot the output here
rotated = inverse_mapping_arbitrary(img, 30, 256, 256)
plt.imshow(rotated)
plt.axis('off')
plt.show()
```



1.3 Part C. Animation (40 points)

1.3.1 Q3-1. Rotation animation (15 points)

Implement a function to rotate the image continuously around the center and save as an MP4.

```
[20]: import cv2

def make_rotation_video(img, seconds=3, fps=24, out_file='rotation.mp4'):
    h, w = img.shape[:2]
    center = (w//2, h//2)
    fourcc = cv2.VideoWriter_fourcc(*'mp4v')
    writer = cv2.VideoWriter(out_file, fourcc, fps, (w, h))

    # YOUR CODE HERE
    N = fps * seconds

    for t in range(N):

        theta = 360 * t / N

        frame = inverse_mapping_arbitrary(img, theta, *center)
        frame_bgr = cv2.cvtColor(frame, cv2.COLOR_RGB2BGR)
        writer.write(frame_bgr)
```



```
writer.release()

make_rotation_video(img, seconds=3, fps=24)
```

1.3.2 Q3-2. Turn Your Favorite Photo a Rotating Video (10 points)

```
[21]: # Load your own favorite photo
favorite_photo = imageio.imread('f40_wheel.jpg')
make_rotation_video(favorite_photo, seconds=3, fps=24,
    ↪out_file='rotating_favorite_photo.mp4')
```

/tmp/ipython-input-2606092892.py:2: DeprecationWarning: Starting with ImageIO v3 the behavior of this function will switch to that of `imageio.v3.imread`. To keep the current behavior (and make this warning disappear) use `import imageio.v2 as imageio` or call `imageio.v2.imread` directly.

```
favorite_photo = imageio.imread('f40_wheel.jpg')
```

1.3.3 Q3-3. Creative Animation (15 points)

Create your own fun animation ('rotating_favorite_photo_creative.mp4'). For example: - Image flying out of frame - Zoom in/out while rotating - Add trails or effects Be creative!

```
[22]: import numpy as np

def spiral_inverse_mapping_arbitrary(img, theta_deg, cx, cy, spiral_factor=0.
    ↪05):
    theta_rad_base = np.deg2rad(theta_deg)
    src_h, src_w = img.shape[:2]
    dst_h = src_h
    dst_w = src_w

    out = np.zeros((dst_h, dst_w, 3), dtype=np.uint8)

    ys, xs = np.indices((dst_h, dst_w))
    coords = np.stack([xs.ravel(), ys.ravel()], axis=-1) # shape (N, 2)

    # spiral angle setup based on radius
    dists = np.linalg.norm(coords - np.array([cx, cy]), axis=1)
    thetas = theta_rad_base + spiral_factor * dists

    # compute rotation for each pixel
    cos_t = np.cos(thetas)
    sin_t = np.sin(thetas)

    # vectorized rotation
    dx = coords[:, 0] - cx
```

```

dy = coords[:, 1] - cy

xs_s = (cos_t * dx + sin_t * dy + cx).round().astype(int)
ys_s = (-sin_t * dx + cos_t * dy + cy).round().astype(int)

mask = (0 <= xs_s) & (xs_s < src_w) & (0 <= ys_s) & (ys_s < src_h)
out[coords[mask, 1], coords[mask, 0]] = img[ys_s[mask], xs_s[mask]]

return out

```

```

[23]: import cv2

def make_rotation_spiral_video(img, seconds=3, fps=24,
                               spiral_factor=0.05,
                               out_file='rotating_favorite_photo_creative.mp4'):

    h, w = img.shape[:2]
    center = (w//2, h//2)
    fourcc = cv2.VideoWriter_fourcc(*'mp4v')
    writer = cv2.VideoWriter(out_file, fourcc, fps, (w, h))

    # YOUR CODE HERE
    N = fps * seconds

    for t in range(N):

        theta = 360 * t / N

        frame = spiral_inverse_mapping_arbitrary(img, theta, *center,
                                                  spiral_factor=spiral_factor *
        t / (2*N))
        frame_bgr = cv2.cvtColor(frame, cv2.COLOR_RGB2BGR)
        writer.write(frame_bgr)
    writer.release()

make_rotation_spiral_video(img, seconds=3, fps=24)

```

```

[39]: !apt-get update -qq
      !apt-get install -y texlive-xetex texlive-fonts-recommended
      !texlive-plain-generic pandoc
      !apt-get install -y pandoc
      !pip install nbconvert

```

W: Skipping acquire of configured file 'main/source/Sources' as repository 'https://r2u.stat.illinois.edu/ubuntu jammy InRelease' does not seem to provide it (sources.list entry misspelt?)

Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
pandoc is already the newest version (2.9.2.1-3ubuntu2).
The following additional packages will be installed:
dvisvgm fonts-droid-fallback fonts-lato fonts-lmodern fonts-noto-mono
fonts-texgyre fonts-urw-base35 libapache-pom-java libcommons-logging-java
libcommons-parent-java libfontbox-java libgs9 libgs9-common libidn12
libijs-0.35 libjbig2dec0 libkpathsea6 libpdfbox-java libptexenc1 libruby3.0
libsynctex2 libteckit0 libtexlua53 libtexluajit2 libwoff1 libzzip-0-13
lmodern poppler-data preview-latex-style rake ruby ruby-net-telnet
ruby-rubygems ruby-webrick ruby-xmlrpc ruby3.0 rubygems-integration t1utils
teckit tex-common tex-gyre texlive-base texlive-binaries texlive-latex-base
texlive-latex-extra texlive-latex-recommended texlive-pictures tipa
xfonts-encodings xfonts-utils
Suggested packages:
fonts-noto fonts-freefont-otf | fonts-freefont-ttf libavalon-framework-java
libcommons-logging-java-doc libexcalibur-logkit-java liblog4j1.2-java
poppler-utils ghostscript fonts-japanese-mincho | fonts-ipafont-mincho
fonts-japanese-gothic | fonts-ipafont-gothic fonts-arphic-ukai
fonts-arphic-uming fonts-nanum ri ruby-dev bundler debhelper gv
| postscript-viewer perl-tk xpdf | pdf-viewer xzdec
texlive-fonts-recommended-doc texlive-latex-base-doc python3-pygments
icc-profiles libfile-which-perl libspreadsheet-parseexcel-perl
texlive-latex-extra-doc texlive-latex-recommended-doc texlive-luatex
texlive-pstricks dot2tex prerex texlive-pictures-doc vprerex
default-jre-headless tipa-doc
The following NEW packages will be installed:
dvisvgm fonts-droid-fallback fonts-lato fonts-lmodern fonts-noto-mono
fonts-texgyre fonts-urw-base35 libapache-pom-java libcommons-logging-java
libcommons-parent-java libfontbox-java libgs9 libgs9-common libidn12
libijs-0.35 libjbig2dec0 libkpathsea6 libpdfbox-java libptexenc1 libruby3.0
libsynctex2 libteckit0 libtexlua53 libtexluajit2 libwoff1 libzzip-0-13
lmodern poppler-data preview-latex-style rake ruby ruby-net-telnet
ruby-rubygems ruby-webrick ruby-xmlrpc ruby3.0 rubygems-integration t1utils
teckit tex-common tex-gyre texlive-base texlive-binaries
texlive-fonts-recommended texlive-latex-base texlive-latex-extra
texlive-latex-recommended texlive-pictures texlive-plain-generic
texlive-xetex tipa xfonts-encodings xfonts-utils
0 upgraded, 53 newly installed, 0 to remove and 45 not upgraded.
Need to get 182 MB of archives.
After this operation, 571 MB of additional disk space will be used.
Get:1 <http://archive.ubuntu.com/ubuntu> jammy/main amd64 fonts-droid-fallback all
1:6.0.1r16-1.1build1 [1,805 kB]
Get:2 <http://archive.ubuntu.com/ubuntu> jammy/main amd64 fonts-lato all 2.0-2.1
[2,696 kB]
Get:3 <http://archive.ubuntu.com/ubuntu> jammy/main amd64 poppler-data all
0.4.11-1 [2,171 kB]

Get:4 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 tex-common all 6.17 [33.7 kB]
Get:5 <http://archive.ubuntu.com/ubuntu> jammy/main amd64 fonts-urw-base35 all 20200910-1 [6,367 kB]
Get:6 <http://archive.ubuntu.com/ubuntu> jammy-updates/main amd64 libgs9-common all 9.55.0~dfsg1-0ubuntu5.12 [753 kB]
Get:7 <http://archive.ubuntu.com/ubuntu> jammy-updates/main amd64 libidn12 amd64 1.38-4ubuntu1 [60.0 kB]
Get:8 <http://archive.ubuntu.com/ubuntu> jammy/main amd64 libijs-0.35 amd64 0.35-15build2 [16.5 kB]
Get:9 <http://archive.ubuntu.com/ubuntu> jammy/main amd64 libjbig2dec0 amd64 0.19-3build2 [64.7 kB]
Get:10 <http://archive.ubuntu.com/ubuntu> jammy-updates/main amd64 libgs9 amd64 9.55.0~dfsg1-0ubuntu5.12 [5,031 kB]
Get:11 <http://archive.ubuntu.com/ubuntu> jammy-updates/main amd64 libkpathsea6 amd64 2021.20210626.59705-1ubuntu0.2 [60.4 kB]
Get:12 <http://archive.ubuntu.com/ubuntu> jammy/main amd64 libwoff1 amd64 1.0.2-1build4 [45.2 kB]
Get:13 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 dvisvgm amd64 2.13.1-1 [1,221 kB]
Get:14 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 fonts-lmodern all 2.004.5-6.1 [4,532 kB]
Get:15 <http://archive.ubuntu.com/ubuntu> jammy/main amd64 fonts-noto-mono all 20201225-1build1 [397 kB]
Get:16 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 fonts-texgyre all 20180621-3.1 [10.2 MB]
Get:17 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 libapache-pom-java all 18-1 [4,720 B]
Get:18 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 libcommons-parent-java all 43-1 [10.8 kB]
Get:19 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 libcommons-logging-java all 1.2-2 [60.3 kB]
Get:20 <http://archive.ubuntu.com/ubuntu> jammy-updates/main amd64 libptexenc1 amd64 2021.20210626.59705-1ubuntu0.2 [39.1 kB]
Get:21 <http://archive.ubuntu.com/ubuntu> jammy/main amd64 rubygems-integration all 1.18 [5,336 B]
Get:22 <http://archive.ubuntu.com/ubuntu> jammy-updates/main amd64 ruby3.0 amd64 3.0.2-7ubuntu2.11 [50.1 kB]
Get:23 <http://archive.ubuntu.com/ubuntu> jammy-updates/main amd64 ruby-rubygems all 3.3.5-2ubuntu1.1 [228 kB]
Get:24 <http://archive.ubuntu.com/ubuntu> jammy/main amd64 ruby amd64 1:3.0~exp1 [5,100 B]
Get:25 <http://archive.ubuntu.com/ubuntu> jammy/main amd64 rake all 13.0.6-2 [61.7 kB]
Get:26 <http://archive.ubuntu.com/ubuntu> jammy/main amd64 ruby-net-telnet all 0.1.1-2 [12.6 kB]
Get:27 <http://archive.ubuntu.com/ubuntu> jammy-updates/main amd64 ruby-webrick all 1.7.0-3ubuntu0.2 [52.5 kB]

Get:28 <http://archive.ubuntu.com/ubuntu> jammy-updates/main amd64 ruby-xlrbpc all
 0.3.2-1ubuntu0.1 [24.9 kB]
 Get:29 <http://archive.ubuntu.com/ubuntu> jammy-updates/main amd64 libruby3.0
 amd64 3.0.2-7ubuntu2.11 [5,114 kB]
 Get:30 <http://archive.ubuntu.com/ubuntu> jammy-updates/main amd64 libsinctex2
 amd64 2021.20210626.59705-1ubuntu0.2 [55.6 kB]
 Get:31 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 libteckit0 amd64
 2.5.11+ds1-1 [421 kB]
 Get:32 <http://archive.ubuntu.com/ubuntu> jammy-updates/main amd64 libtexlua53
 amd64 2021.20210626.59705-1ubuntu0.2 [120 kB]
 Get:33 <http://archive.ubuntu.com/ubuntu> jammy-updates/main amd64 libtexluajit2
 amd64 2021.20210626.59705-1ubuntu0.2 [267 kB]
 Get:34 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 libzzip-0-13 amd64
 0.13.72+dfsg.1-1.1 [27.0 kB]
 Get:35 <http://archive.ubuntu.com/ubuntu> jammy/main amd64 xfonts-encodings all
 1:1.0.5-0ubuntu2 [578 kB]
 Get:36 <http://archive.ubuntu.com/ubuntu> jammy/main amd64 xfonts-utils amd64
 1:7.7+6build2 [94.6 kB]
 Get:37 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 lmodern all
 2.004.5-6.1 [9,471 kB]
 Get:38 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 preview-latex-style
 all 12.2-1ubuntu1 [185 kB]
 Get:39 <http://archive.ubuntu.com/ubuntu> jammy/main amd64 t1utils amd64
 1.41-4build2 [61.3 kB]
 Get:40 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 teckit amd64
 2.5.11+ds1-1 [699 kB]
 Get:41 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 tex-gyre all
 20180621-3.1 [6,209 kB]
 Get:42 <http://archive.ubuntu.com/ubuntu> jammy-updates/universe amd64 texlive-
 binaries amd64 2021.20210626.59705-1ubuntu0.2 [9,860 kB]
 Get:43 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 texlive-base all
 2021.20220204-1 [21.0 MB]
 Get:44 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 texlive-fonts-
 recommended all 2021.20220204-1 [4,972 kB]
 Get:45 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 texlive-latex-base
 all 2021.20220204-1 [1,128 kB]
 Get:46 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 libfontbox-java all
 1:1.8.16-2 [207 kB]
 Get:47 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 libpdfbox-java all
 1:1.8.16-2 [5,199 kB]
 Get:48 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 texlive-latex-
 recommended all 2021.20220204-1 [14.4 MB]
 Get:49 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 texlive-pictures
 all 2021.20220204-1 [8,720 kB]
 Get:50 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 texlive-latex-extra
 all 2021.20220204-1 [13.9 MB]
 Get:51 <http://archive.ubuntu.com/ubuntu> jammy/universe amd64 texlive-plain-
 generic all 2021.20220204-1 [27.5 MB]

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Get:52 http://archive.ubuntu.com/ubuntu jammy/universe amd64 tipa all 2:1.3-21
[2,967 kB]
Get:53 http://archive.ubuntu.com/ubuntu jammy/universe amd64 texlive-xetex all
2021.20220204-1 [12.4 MB]
Fetched 182 MB in 6s (29.7 MB/s)
Extracting templates from packages: 100%
Preconfiguring packages ...
Selecting previously unselected package fonts-droid-fallback.
(Reading database ... 126599 files and directories currently installed.)
Preparing to unpack .../00-fonts-droid-fallback_1%3a6.0.1r16-1.1build1_all.deb
...
Unpacking fonts-droid-fallback (1:6.0.1r16-1.1build1) ...
Selecting previously unselected package fonts-lato.
Preparing to unpack .../01-fonts-lato_2.0-2.1_all.deb ...
Unpacking fonts-lato (2.0-2.1) ...
Selecting previously unselected package poppler-data.
Preparing to unpack .../02-poppler-data_0.4.11-1_all.deb ...
Unpacking poppler-data (0.4.11-1) ...
Selecting previously unselected package tex-common.
Preparing to unpack .../03-tex-common_6.17_all.deb ...
Unpacking tex-common (6.17) ...
Selecting previously unselected package fonts-urw-base35.
Preparing to unpack .../04-fonts-urw-base35_20200910-1_all.deb ...
Unpacking fonts-urw-base35 (20200910-1) ...
Selecting previously unselected package libgs9-common.
Preparing to unpack .../05-libgs9-common_9.55.0~dfsg1-0ubuntu5.12_all.deb ...
Unpacking libgs9-common (9.55.0~dfsg1-0ubuntu5.12) ...
Selecting previously unselected package libidn12:amd64.
Preparing to unpack .../06-libidn12_1.38-4ubuntu1_amd64.deb ...
Unpacking libidn12:amd64 (1.38-4ubuntu1) ...
Selecting previously unselected package libijs-0.35:amd64.
Preparing to unpack .../07-libijs-0.35_0.35-15build2_amd64.deb ...
Unpacking libijs-0.35:amd64 (0.35-15build2) ...
Selecting previously unselected package libjbig2dec0:amd64.
Preparing to unpack .../08-libjbig2dec0_0.19-3build2_amd64.deb ...
Unpacking libjbig2dec0:amd64 (0.19-3build2) ...
Selecting previously unselected package libgs9:amd64.
Preparing to unpack .../09-libgs9_9.55.0~dfsg1-0ubuntu5.12_amd64.deb ...
Unpacking libgs9:amd64 (9.55.0~dfsg1-0ubuntu5.12) ...
Selecting previously unselected package libkpathsea6:amd64.
Preparing to unpack .../10-libkpathsea6_2021.20210626.59705-1ubuntu0.2_amd64.deb
...
Unpacking libkpathsea6:amd64 (2021.20210626.59705-1ubuntu0.2) ...
Selecting previously unselected package libwoff1:amd64.
Preparing to unpack .../11-libwoff1_1.0.2-1build4_amd64.deb ...
Unpacking libwoff1:amd64 (1.0.2-1build4) ...
Selecting previously unselected package dvisvgm.
Preparing to unpack .../12-dvisvgm_2.13.1-1_amd64.deb ...

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Unpacking dvisvgm (2.13.1-1) ...
Selecting previously unselected package fonts-lmodern.
Preparing to unpack .../13-fonts-lmodern_2.004.5-6.1_all.deb ...
Unpacking fonts-lmodern (2.004.5-6.1) ...
Selecting previously unselected package fonts-noto-mono.
Preparing to unpack .../14-fonts-noto-mono_20201225-1build1_all.deb ...
Unpacking fonts-noto-mono (20201225-1build1) ...
Selecting previously unselected package fonts-texgyre.
Preparing to unpack .../15-fonts-texgyre_20180621-3.1_all.deb ...
Unpacking fonts-texgyre (20180621-3.1) ...
Selecting previously unselected package libapache-pom-java.
Preparing to unpack .../16-libapache-pom-java_18-1_all.deb ...
Unpacking libapache-pom-java (18-1) ...
Selecting previously unselected package libcommons-parent-java.
Preparing to unpack .../17-libcommons-parent-java_43-1_all.deb ...
Unpacking libcommons-parent-java (43-1) ...
Selecting previously unselected package libcommons-logging-java.
Preparing to unpack .../18-libcommons-logging-java_1.2-2_all.deb ...
Unpacking libcommons-logging-java (1.2-2) ...
Selecting previously unselected package libptexenc1:amd64.
Preparing to unpack .../19-libptexenc1_2021.20210626.59705-1ubuntu0.2_amd64.deb
...
Unpacking libptexenc1:amd64 (2021.20210626.59705-1ubuntu0.2) ...
Selecting previously unselected package rubygems-integration.
Preparing to unpack .../20-rubygems-integration_1.18_all.deb ...
Unpacking rubygems-integration (1.18) ...
Selecting previously unselected package ruby3.0.
Preparing to unpack .../21-ruby3.0_3.0.2-7ubuntu2.11_amd64.deb ...
Unpacking ruby3.0 (3.0.2-7ubuntu2.11) ...
Selecting previously unselected package ruby-rubygems.
Preparing to unpack .../22-ruby-rubygems_3.3.5-2ubuntu1.1_all.deb ...
Unpacking ruby-rubygems (3.3.5-2ubuntu1.1) ...
Selecting previously unselected package ruby.
Preparing to unpack .../23-ruby_1%3a3.0~exp1_amd64.deb ...
Unpacking ruby (1:3.0~exp1) ...
Selecting previously unselected package rake.
Preparing to unpack .../24-rake_13.0.6-2_all.deb ...
Unpacking rake (13.0.6-2) ...
Selecting previously unselected package ruby-net-telnet.
Preparing to unpack .../25-ruby-net-telnet_0.1.1-2_all.deb ...
Unpacking ruby-net-telnet (0.1.1-2) ...
Selecting previously unselected package ruby-webrick.
Preparing to unpack .../26-ruby-webrick_1.7.0-3ubuntu0.2_all.deb ...
Unpacking ruby-webrick (1.7.0-3ubuntu0.2) ...
Selecting previously unselected package ruby-xmlrpc.
Preparing to unpack .../27-ruby-xmlrpc_0.3.2-1ubuntu0.1_all.deb ...
Unpacking ruby-xmlrpc (0.3.2-1ubuntu0.1) ...
Selecting previously unselected package libruby3.0:amd64.

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Preparing to unpack .../28-libruby3.0_3.0.2-7ubuntu2.11_amd64.deb ...
Unpacking libruby3.0:amd64 (3.0.2-7ubuntu2.11) ...
Selecting previously unselected package libsyntax2:amd64.
Preparing to unpack .../29-libsyntax2_2021.20210626.59705-1ubuntu0.2_amd64.deb
...
Unpacking libsyntax2:amd64 (2021.20210626.59705-1ubuntu0.2) ...
Selecting previously unselected package libteckit0:amd64.
Preparing to unpack .../30-libteckit0_2.5.11+ds1-1_amd64.deb ...
Unpacking libteckit0:amd64 (2.5.11+ds1-1) ...
Selecting previously unselected package libtexlua53:amd64.
Preparing to unpack .../31-libtexlua53_2021.20210626.59705-1ubuntu0.2_amd64.deb
...
Unpacking libtexlua53:amd64 (2021.20210626.59705-1ubuntu0.2) ...
Selecting previously unselected package libtexluaajit2:amd64.
Preparing to unpack
.../32-libtexluaajit2_2021.20210626.59705-1ubuntu0.2_amd64.deb ...
Unpacking libtexluaajit2:amd64 (2021.20210626.59705-1ubuntu0.2) ...
Selecting previously unselected package libzzip-0-13:amd64.
Preparing to unpack .../33-libzzip-0-13_0.13.72+dfsg.1-1.1_amd64.deb ...
Unpacking libzzip-0-13:amd64 (0.13.72+dfsg.1-1.1) ...
Selecting previously unselected package xfonts-encodings.
Preparing to unpack .../34-xfonts-encodings_1%3a1.0.5-0ubuntu2_all.deb ...
Unpacking xfonts-encodings (1:1.0.5-0ubuntu2) ...
Selecting previously unselected package xfonts-utils.
Preparing to unpack .../35-xfonts-utils_1%3a7.7+6build2_amd64.deb ...
Unpacking xfonts-utils (1:7.7+6build2) ...
Selecting previously unselected package lmodern.
Preparing to unpack .../36-lmodern_2.004.5-6.1_all.deb ...
Unpacking lmodern (2.004.5-6.1) ...
Selecting previously unselected package preview-latex-style.
Preparing to unpack .../37-preview-latex-style_12.2-1ubuntu1_all.deb ...
Unpacking preview-latex-style (12.2-1ubuntu1) ...
Selecting previously unselected package t1utils.
Preparing to unpack .../38-t1utils_1.41-4build2_amd64.deb ...
Unpacking t1utils (1.41-4build2) ...
Selecting previously unselected package teckit.
Preparing to unpack .../39-teckit_2.5.11+ds1-1_amd64.deb ...
Unpacking teckit (2.5.11+ds1-1) ...
Selecting previously unselected package tex-gyre.
Preparing to unpack .../40-tex-gyre_20180621-3.1_all.deb ...
Unpacking tex-gyre (20180621-3.1) ...
Selecting previously unselected package texlive-binaries.
Preparing to unpack .../41-texlive-
binaries_2021.20210626.59705-1ubuntu0.2_amd64.deb ...
Unpacking texlive-binaries (2021.20210626.59705-1ubuntu0.2) ...
Selecting previously unselected package texlive-base.
Preparing to unpack .../42-texlive-base_2021.20220204-1_all.deb ...
Unpacking texlive-base (2021.20220204-1) ...

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Selecting previously unselected package texlive-fonts-recommended.
Preparing to unpack .../43-texlive-fonts-recommended_2021.20220204-1_all.deb ...
Unpacking texlive-fonts-recommended (2021.20220204-1) ...
Selecting previously unselected package texlive-latex-base.
Preparing to unpack .../44-texlive-latex-base_2021.20220204-1_all.deb ...
Unpacking texlive-latex-base (2021.20220204-1) ...
Selecting previously unselected package libfontbox-java.
Preparing to unpack .../45-libfontbox-java_1%3a1.8.16-2_all.deb ...
Unpacking libfontbox-java (1:1.8.16-2) ...
Selecting previously unselected package libpdfbox-java.
Preparing to unpack .../46-libpdfbox-java_1%3a1.8.16-2_all.deb ...
Unpacking libpdfbox-java (1:1.8.16-2) ...
Selecting previously unselected package texlive-latex-recommended.
Preparing to unpack .../47-texlive-latex-recommended_2021.20220204-1_all.deb ...
Unpacking texlive-latex-recommended (2021.20220204-1) ...
Selecting previously unselected package texlive-pictures.
Preparing to unpack .../48-texlive-pictures_2021.20220204-1_all.deb ...
Unpacking texlive-pictures (2021.20220204-1) ...
Selecting previously unselected package texlive-latex-extra.
Preparing to unpack .../49-texlive-latex-extra_2021.20220204-1_all.deb ...
Unpacking texlive-latex-extra (2021.20220204-1) ...
Selecting previously unselected package texlive-plain-generic.
Preparing to unpack .../50-texlive-plain-generic_2021.20220204-1_all.deb ...
Unpacking texlive-plain-generic (2021.20220204-1) ...
Selecting previously unselected package tipa.
Preparing to unpack .../51-tipa_2%3a1.3-21_all.deb ...
Unpacking tipa (2:1.3-21) ...
Selecting previously unselected package texlive-xetex.
Preparing to unpack .../52-texlive-xetex_2021.20220204-1_all.deb ...
Unpacking texlive-xetex (2021.20220204-1) ...
Setting up fonts-lato (2.0-2.1) ...
Setting up fonts-noto-mono (20201225-1build1) ...
Setting up libwoff1:amd64 (1.0.2-1build4) ...
Setting up libtexlua53:amd64 (2021.20210626.59705-1ubuntu0.2) ...
Setting up libijs-0.35:amd64 (0.35-15build2) ...
Setting up libtexluajit2:amd64 (2021.20210626.59705-1ubuntu0.2) ...
Setting up libfontbox-java (1:1.8.16-2) ...
Setting up rubygems-integration (1.18) ...
Setting up libzip-0-13:amd64 (0.13.72+dfsg.1-1.1) ...
Setting up fonts-urw-base35 (20200910-1) ...
Setting up poppler-data (0.4.11-1) ...
Setting up tex-common (6.17) ...
update-language: texlive-base not installed and configured, doing nothing!
Setting up libjbig2dec0:amd64 (0.19-3build2) ...
Setting up libteckit0:amd64 (2.5.11+ds1-1) ...
Setting up libapache-pom-java (18-1) ...
Setting up ruby-net-telnet (0.1.1-2) ...
Setting up xfonts-encodings (1:1.0.5-0ubuntu2) ...

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Setting up tlutils (1.41-4build2) ...
Setting up libidn12:amd64 (1.38-4ubuntu1) ...
Setting up fonts-texgyre (20180621-3.1) ...
Setting up libkpathsea6:amd64 (2021.20210626.59705-1ubuntu0.2) ...
Setting up ruby-webrick (1.7.0-3ubuntu0.2) ...
Setting up fonts-lmodern (2.004.5-6.1) ...
Setting up fonts-droid-fallback (1:6.0.1r16-1.1build1) ...
Setting up ruby-xmlrpc (0.3.2-1ubuntu0.1) ...
Setting up libsynchronet2:amd64 (2021.20210626.59705-1ubuntu0.2) ...
Setting up libgs9-common (9.55.0~dfsg1-0ubuntu5.12) ...
Setting up teckit (2.5.11+ds1-1) ...
Setting up libpdfbox-java (1:1.8.16-2) ...
Setting up libgs9:amd64 (9.55.0~dfsg1-0ubuntu5.12) ...
Setting up preview-latex-style (12.2-1ubuntu1) ...
Setting up libcommons-parent-java (43-1) ...
Setting up dvisvgm (2.13.1-1) ...
Setting up libcommons-logging-java (1.2-2) ...
Setting up xfonts-utils (1:7.7+6build2) ...
Setting up libptexenc1:amd64 (2021.20210626.59705-1ubuntu0.2) ...
Setting up texlive-binaries (2021.20210626.59705-1ubuntu0.2) ...
update-alternatives: using /usr/bin/xdvi-xaw to provide /usr/bin/xdvi.bin
(xdvi.bin) in auto mode
update-alternatives: using /usr/bin/bibtex.original to provide /usr/bin/bibtex
(bibtex) in auto mode
Setting up lmodern (2.004.5-6.1) ...
Setting up texlive-base (2021.20220204-1) ...
/usr/bin/ucfr
/usr/bin/ucfr
/usr/bin/ucfr
/usr/bin/ucfr
mktexlsr: Updating /var/lib/texmf/ls-R-TEXLIVEDIST...
mktexlsr: Updating /var/lib/texmf/ls-R-TEXMFMAIN...
mktexlsr: Updating /var/lib/texmf/ls-R...
mktexlsr: Done.
tl-paper: setting paper size for dvips to a4:
/var/lib/texmf/dvips/config/config-paper.ps
tl-paper: setting paper size for dvipdfmx to a4:
/var/lib/texmf/dvipdfmx/dvipdfmx-paper.cfg
tl-paper: setting paper size for xdvi to a4: /var/lib/texmf/xdvi/XDvi-paper
tl-paper: setting paper size for pdftex to a4: /var/lib/texmf/tex/generic/tex-
ini-files/pdftexconfig.tex
Setting up tex-gyre (20180621-3.1) ...
Setting up texlive-plain-generic (2021.20220204-1) ...
Setting up texlive-latex-base (2021.20220204-1) ...
Setting up texlive-latex-recommended (2021.20220204-1) ...
Setting up texlive-pictures (2021.20220204-1) ...
Setting up texlive-fonts-recommended (2021.20220204-1) ...
Setting up tipa (2:1.3-21) ...

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Setting up texlive-latex-extra (2021.20220204-1) ...
Setting up texlive-xetex (2021.20220204-1) ...
Setting up rake (13.0.6-2) ...
Setting up libruby3.0:amd64 (3.0.2-7ubuntu2.11) ...
Setting up ruby3.0 (3.0.2-7ubuntu2.11) ...
Setting up ruby (1:3.0~exp1) ...
Setting up ruby-rubygems (3.3.5-2ubuntu1.1) ...
Processing triggers for man-db (2.10.2-1) ...
Processing triggers for mailcap (3.70+nmu1ubuntu1) ...
Processing triggers for fontconfig (2.13.1-4.2ubuntu5) ...
Processing triggers for libc-bin (2.35-0ubuntu3.8) ...
/sbin/ldconfig.real: /usr/local/lib/libur_loader.so.0 is not a symbolic link

/sbin/ldconfig.real: /usr/local/lib/libur_adapter_opencl.so.0 is not a symbolic
link

/sbin/ldconfig.real: /usr/local/lib/libtcm.so.1 is not a symbolic link

/sbin/ldconfig.real: /usr/local/lib/libur_adapter_level_zero.so.0 is not a
symbolic link

/sbin/ldconfig.real: /usr/local/lib/libumf.so.0 is not a symbolic link

/sbin/ldconfig.real: /usr/local/lib/libtcm_debug.so.1 is not a symbolic link

/sbin/ldconfig.real: /usr/local/lib/libtbbbind_2_0.so.3 is not a symbolic link

/sbin/ldconfig.real: /usr/local/lib/libur_adapter_level_zero_v2.so.0 is not a
symbolic link

/sbin/ldconfig.real: /usr/local/lib/libtbbmalloc.so.2 is not a symbolic link

/sbin/ldconfig.real: /usr/local/lib/libtbbbind.so.3 is not a symbolic link

/sbin/ldconfig.real: /usr/local/lib/libtbb.so.12 is not a symbolic link

/sbin/ldconfig.real: /usr/local/lib/libtbbmalloc_proxy.so.2 is not a symbolic
link

/sbin/ldconfig.real: /usr/local/lib/libtbbbind_2_5.so.3 is not a symbolic link

/sbin/ldconfig.real: /usr/local/lib/libhwloc.so.15 is not a symbolic link

Processing triggers for tex-common (6.17) ...
Running upmap-sys. This may take some time... done.
Running mktexlsr /var/lib/texmf ... done.
Building format(s) --all.
    This may take some time... done.

```

Reading package lists... Done
 Building dependency tree... Done
 Reading state information... Done
 pandoc is already the newest version (2.9.2.1-3ubuntu2).
 0 upgraded, 0 newly installed, 0 to remove and 45 not upgraded.
 Requirement already satisfied: nbconvert in /usr/local/lib/python3.12/dist-packages (7.16.6)
 Requirement already satisfied: beautifulsoup4 in /usr/local/lib/python3.12/dist-packages (from nbconvert) (4.13.5)
 Requirement already satisfied: bleach!=5.0.0 in /usr/local/lib/python3.12/dist-packages (from bleach[css]!=5.0.0->nbconvert) (6.2.0)
 Requirement already satisfied: defusedxml in /usr/local/lib/python3.12/dist-packages (from nbconvert) (0.7.1)
 Requirement already satisfied: jinja2>=3.0 in /usr/local/lib/python3.12/dist-packages (from nbconvert) (3.1.6)
 Requirement already satisfied: jupyter-core>=4.7 in /usr/local/lib/python3.12/dist-packages (from nbconvert) (5.8.1)
 Requirement already satisfied: jupyterlab-pygments in /usr/local/lib/python3.12/dist-packages (from nbconvert) (0.3.0)
 Requirement already satisfied: markupsafe>=2.0 in /usr/local/lib/python3.12/dist-packages (from nbconvert) (3.0.2)
 Requirement already satisfied: mistune<4,>=2.0.3 in /usr/local/lib/python3.12/dist-packages (from nbconvert) (3.1.4)
 Requirement already satisfied: nbclient>=0.5.0 in /usr/local/lib/python3.12/dist-packages (from nbconvert) (0.10.2)
 Requirement already satisfied: nbformat>=5.7 in /usr/local/lib/python3.12/dist-packages (from nbconvert) (5.10.4)
 Requirement already satisfied: packaging in /usr/local/lib/python3.12/dist-packages (from nbconvert) (25.0)
 Requirement already satisfied: pandocfilters>=1.4.1 in /usr/local/lib/python3.12/dist-packages (from nbconvert) (1.5.1)
 Requirement already satisfied: pygments>=2.4.1 in /usr/local/lib/python3.12/dist-packages (from nbconvert) (2.19.2)
 Requirement already satisfied: traitlets>=5.1 in /usr/local/lib/python3.12/dist-packages (from nbconvert) (5.7.1)
 Requirement already satisfied: webencodings in /usr/local/lib/python3.12/dist-packages (from bleach!=5.0.0->bleach[css]!=5.0.0->nbconvert) (0.5.1)
 Requirement already satisfied: tinycss2<1.5,>=1.1.0 in /usr/local/lib/python3.12/dist-packages (from bleach[css]!=5.0.0->nbconvert) (1.4.0)
 Requirement already satisfied: platformdirs>=2.5 in /usr/local/lib/python3.12/dist-packages (from jupyter-core>=4.7->nbconvert) (4.4.0)
 Requirement already satisfied: jupyter-client>=6.1.12 in /usr/local/lib/python3.12/dist-packages (from nbclient>=0.5.0->nbconvert) (7.4.9)
 Requirement already satisfied: fastjsonschema>=2.15 in /usr/local/lib/python3.12/dist-packages (from nbformat>=5.7->nbconvert) (2.21.2)

Requirement already satisfied: jsonschema>=2.6 in /usr/local/lib/python3.12/dist-packages (from nbformat>=5.7->nbconvert) (4.25.1)
 Requirement already satisfied: soupsieve>1.2 in /usr/local/lib/python3.12/dist-packages (from beautifulsoup4->nbconvert) (2.8)
 Requirement already satisfied: typing-extensions>=4.0.0 in /usr/local/lib/python3.12/dist-packages (from beautifulsoup4->nbconvert) (4.15.0)
 Requirement already satisfied: attrs>=22.2.0 in /usr/local/lib/python3.12/dist-packages (from jsonschema>=2.6->nbformat>=5.7->nbconvert) (25.3.0)
 Requirement already satisfied: jsonschema-specifications>=2023.03.6 in /usr/local/lib/python3.12/dist-packages (from jsonschema>=2.6->nbformat>=5.7->nbconvert) (2025.4.1)
 Requirement already satisfied: referencing>=0.28.4 in /usr/local/lib/python3.12/dist-packages (from jsonschema>=2.6->nbformat>=5.7->nbconvert) (0.36.2)
 Requirement already satisfied: rpds-py>=0.7.1 in /usr/local/lib/python3.12/dist-packages (from jsonschema>=2.6->nbformat>=5.7->nbconvert) (0.27.1)
 Requirement already satisfied: entrypoints in /usr/local/lib/python3.12/dist-packages (from jupyter-client>=6.1.12->nbclient>=0.5.0->nbconvert) (0.4)
 Requirement already satisfied: nest-asyncio>=1.5.4 in /usr/local/lib/python3.12/dist-packages (from jupyter-client>=6.1.12->nbclient>=0.5.0->nbconvert) (1.6.0)
 Requirement already satisfied: python-dateutil>=2.8.2 in /usr/local/lib/python3.12/dist-packages (from jupyter-client>=6.1.12->nbclient>=0.5.0->nbconvert) (2.9.0.post0)
 Requirement already satisfied: pyzmq>=23.0 in /usr/local/lib/python3.12/dist-packages (from jupyter-client>=6.1.12->nbclient>=0.5.0->nbconvert) (26.2.1)
 Requirement already satisfied: tornado>=6.2 in /usr/local/lib/python3.12/dist-packages (from jupyter-client>=6.1.12->nbclient>=0.5.0->nbconvert) (6.4.2)
 Requirement already satisfied: six>=1.5 in /usr/local/lib/python3.12/dist-packages (from python-dateutil>=2.8.2->jupyter-client>=6.1.12->nbclient>=0.5.0->nbconvert) (1.17.0)

```
[40]: !jupyter nbconvert --to pdf "HW0(2).ipynb"
```

```
[NbConvertApp] Converting notebook HW0(2).ipynb to pdf
[NbConvertApp] Support files will be in HW0(2)_files/
[NbConvertApp] Making directory ./HW0(2)_files
[NbConvertApp] Writing 84042 bytes to notebook.tex
[NbConvertApp] Building PDF
[NbConvertApp] Running xelatex 3 times: ['xelatex', 'notebook.tex', '-quiet']
[NbConvertApp] Running bibtex 1 time: ['bibtex', 'notebook']
[NbConvertApp] WARNING | bibtex had problems, most likely because there were no citations
[NbConvertApp] PDF successfully created
[NbConvertApp] Writing 1978178 bytes to HW0(2).pdf
```

[]: